

# Stochastic Differential Equations and Applications

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#### **Preliminaries**

#### $\sigma$ -algebra

Let  $\Omega$  be a non-empty set. A  $\sigma$ -algebra on  $\Omega$  is a collection  $\mathcal{F}$  of subsets of  $\Omega$  satisfying the following properties:

- $\Omega \in \mathcal{F}$ .
- $A \subseteq \Omega$  and  $A \in \mathcal{F}, \Rightarrow A^C \in \mathcal{F}$ .
- If  $A_1, A_2, \dots \in \mathcal{F}, \Rightarrow \bigcup_{i=1}^{\infty} A_k \in \mathcal{F}$ .

### **Probability Function**

Given a  $\sigma$ -algebra  $\mathcal{F}$  on  $\Omega$ . A real valued set function  $P \colon \mathcal{F} \to [0,1]$  defined on  $\mathcal{F}$  is said to be a probability function/measure if

- $P(\Omega) = 1.$
- $P(\emptyset) = 0.$
- Countable Additivity: Given a sequence of events  $A_1, A_2, ...$  which are pairwise disjoint  $(A_i \cap A_j \ \forall \ i \neq j)$  then

$$P\left(\bigcup_{k=1}^{\infty} A_k\right) = \sum_{k=1}^{\infty} P(A_k)$$

#### **Probability Space**

Probability space or a probability triple  $(\Omega, \mathcal{F}, P)$  is a mathematical construct that provides a formal model of a random process or "experiment" where  $\Omega$  is sample space,  $\mathcal{F}$  is  $\sigma$ -algebra (event space) and P is probability function as defined above.

#### Random Variable

A random variable X is a  $\{\mathcal{F},\mathcal{B}\}$  measurable function  $X:\Omega\to\mathbb{R}$  from a sample space  $\Omega$  as a set of possible outcomes. The technical axiomatic definition requires the sample space  $\Omega$  to be a sample space of a probability triple  $(\Omega,\mathcal{F},P)$ .

#### **Stochastic Process**

A collection  $\{X(t)|t\geq 0\}$  of random variables is called a Stochastic process. Let  $(\Omega, \mathcal{F}, P)$  be a probability space. A stochastic process is a measurable function  $X(t,\omega)$  defined on the product space  $[0,\infty)\times\Omega$ .

# **Brownian Motion**

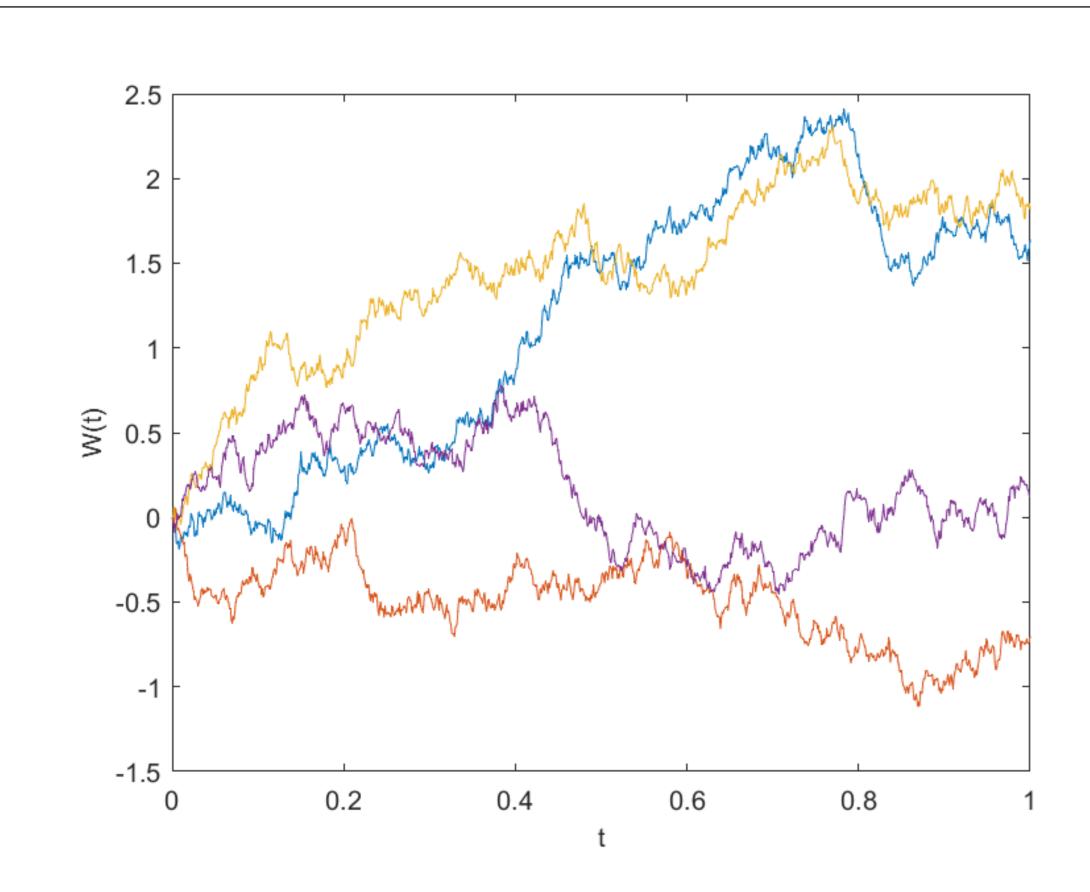
It is a continuous time-space Stochastic process.

- $(W_0) = 0$  almost surely in P.
- Independent increments: The random variable  $(W_v) (W_u)$  and  $(W_t) (W_s)$  are independent whenever  $u \le v \le s \le t$ . (u,v) and (s,t) are disjoint random variable.
- Normal increments:

$$(W_{t+s})-(W_s) \sim N(0,t) \text{ or } (W_t)-(W_0) \sim N(0,t) \text{ where } t>0, x \in \mathbb{R}$$
 
$$f(x;0,t)=\frac{1}{(2\pi t)^{1/2}}e^{\frac{-(x)^2}{2t}}$$

- Continuous Sample space: With probability 1, the function  $t \mapsto W(t, \omega)$  is continuous almost sure and it doesn't have any jumps or discontinuities.
- Markov property: This property of Brownian motion states that the future behavior of the process depends only on its current state and is independent of past history.
- Self-similarity: It is a property of Brownian motion where the statistical properties of the process are similar at different time scales.

# **Graph of Brownian Motion**



# **Stochastic Integrals**

#### Filtration

Increasing family of sub  $\sigma$ -algebras  $\{\mathcal{F}_t\}$  of  $\mathcal{F}$  $\mathcal{F}_0 \subseteq \mathcal{F}_s \subseteq \mathcal{F}_t \subseteq \mathcal{F}$  if  $0 \le s \le t$ .

## Wiener Integral

• Suppose f is a step function given by  $f = \sum_{i=1}^n a_i \cdot \mathbf{1}_{[t_{i-1},t_i]}$ , where  $t_0 = 0$  and  $t_n = T$ . In this case, define

$$\mathbf{I}(f) = \int_0^T f(t) dW_t = \sum_{i=1}^n a_i \cdot (W(t_i) - W(t_{i-1}))$$

where  $f \in L^2[0,T]$  is a step process.

• Let  $f \in L^2[0,T]$ . The limit  $\mathbf{I}(f) = \lim_{n \to \infty} \mathbf{I}(f_n)$  in  $L^2(\Omega)$  is called the Wiener integral of f. The Wiener integral  $\mathbf{I}(f)$  of f will be denoted by:

$$\mathbf{I}(f)(\omega) = \int_0^T f(t) \, dW(t)(\omega)$$

where  $f_n \in L^2[0,T]$  is a sequence of step process.

#### **Properties of Wiener Integral**

 $\mathbf{I}(f) = \int_0^T f(t) dW_t$  is a **Normal Random variable** with mean 0 and variance  $\int_0^T f(t)^2 dt$ .

- 1.  $E[\int_0^T f(t) dW_t] = 0$ .
- 2.  $E[(\int_0^T f(t) dW_t)^2] = \int_0^T f^2(t) dt$ .
- 3. Let  $f \in L^2[0,T]$ . Then the stochastic process

$$M_t = \int_0^t f(s) \, dW(s), \ 0 \le t \le T,$$

is a Martingale with respect to  $\mathcal{F}_t$ , where  $\mathcal{F}_t = \sigma\{W_s : 0 \le s \le t\}$ .

# Itô Integral

- Fix a Brownian motion W(t) and filtration  $\{\mathcal{F}_t;\ 0 \le t \le T\}$  satisfying the following conditions:
- 1. For each t, W(t) is  $\mathcal{F}_t$ -measurable.
- 2. For any  $s \leq t$ , the random variable W(t) W(s) is independent of the  $\sigma$ -algebra  $\mathcal{F}_s$ .
- We will use  $L^2_{ad}([0,T] \times \Omega)$  to denote the space of all stochastic process  $f(t,\omega), \ 0 \le t \le T, \ \omega \in \Omega$  satisfying the following conditions: 1.  $f(t,\omega)$  is adapted to the filtration  $\{\mathcal{F}_t\}$ .
- 2.  $\int_0^T E(|f(t)|^2) dt < \infty$ .

$$f(t,\omega) = \sum_{i=1}^{n} a_{i-1}(\omega) \mathbf{1}_{[t_{i-1},t_i]}(t)$$

$$\mathbf{I}(f) = \int_0^T f(t, \omega) \, dW_t(\omega) = \sum_{i=1}^n a_{i-1}(W(t_i) - W(t_{i-1}))$$

# Properties of Itô Integral

 $f \in L^2_{ad}([0,T] \times \Omega)$ .  $\mathbf{I}(f) = \lim_{n \to \infty} \mathbf{I}(f_n)$  where  $\{f_n(t,\omega); n \ge 1\}$  is a sequence of adapted step stochastic process.

- 1.  $E[\int_0^T f(t) dW] = 0.$
- 2.  $E[(\int_0^T f(t) dW_t)^2] = E[\int_0^T f^2(t) dt]$
- 3. If  $f \in L^2_{ad}[(0,T) \times \Omega]$ , then the indefinite integral  $\mathbf{I}(\cdot)$  is a **Martingale**. Furthermore,  $\mathbf{I}(\cdot)$  has a version with continuous sample paths a.s.

# Itô formula

ullet  $X(\cdot)$  is a real-valued stochastic process satisfying

$$X(r) = X(s) + \int_{-r}^{r} F dt + \int_{-r}^{r} G dW$$

for some  $F \in L^1_{ad}[(0,T) \times \Omega], G \in L^2_{ad}[(0,T) \times \Omega]$  and all times  $0 \le s \le r \le T.$ We say that  $X(\cdot)$  has the stochastic differential

$$dX = Fdt + GdW$$

for  $0 \le t \le T$ 

•  $X(\cdot)$  has a stochastic differential

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for  $F \in L^1_{\mathrm{ad}}[(0,T) \times \Omega], G \in L^2_{\mathrm{ad}}[(0,T) \times \Omega].$  Assume

 $u\colon \mathbb{R}\times [0,T] \to \mathbb{R}, u=u(x,t)$  is continuous and that its partial derivatives

 $u_t = \frac{\partial u}{\partial t}, u_x = \frac{\partial u}{\partial x}$  and  $u_{xx} = \frac{\partial^2 u}{\partial x^2}$  exist and are continuous.

Then Y(t):=u(X(t),t) has the stochastic differential

$$du(X,t) = u_t dt + u_x dX + \frac{1}{2} u_{xx} G^2 dt$$
  
=  $(u_t + u_x F + \frac{1}{2} u_{xx} G^2) dt + u_x G dW$ 

# **Stochastic Differential Equation**

$$dX(t) = f(t, X(t)) dt + \sigma(t, X(t)) dW_t, \quad t \in (0, T)$$

$$X(0) = X_0 \quad \dots \quad (1)$$

$$X(t) = X_0 + \int_0^t f(s, X(s)) \, ds + \int_0^t \sigma(s, X(s)) \, dW_s \quad \text{almost surely in } P.$$

#### **Definition of solution of SDE**

A stochastic process  $X \colon [0,T] \times \Omega \to \mathbb{R}$  is called a solution of the SDE (1) if

- $X(\cdot)$  is progressively measurable.(i.e.  $X: [0,t] \times \Omega \to \mathbb{R}$  is  $\mathcal{B}[0,t] \times \mathcal{F}_t$  measurable for all  $t \geq 0$ ).
- $f(\cdot, X(\cdot)) \in L^1_{\mathrm{ad}}([0, T] \times \Omega)$ .
- $\sigma(\cdot, X(\cdot)) \in L^2_{\mathrm{ad}}([0, T] \times \Omega).$
- $\forall t \in [0,T], X(t)$  satisfies

$$X(t) = X_0 + \int_0^t f(s, X(s)) \, ds + \int_0^t \sigma(s, X(s)) \, dW_s \quad \text{almost surely in } P.$$

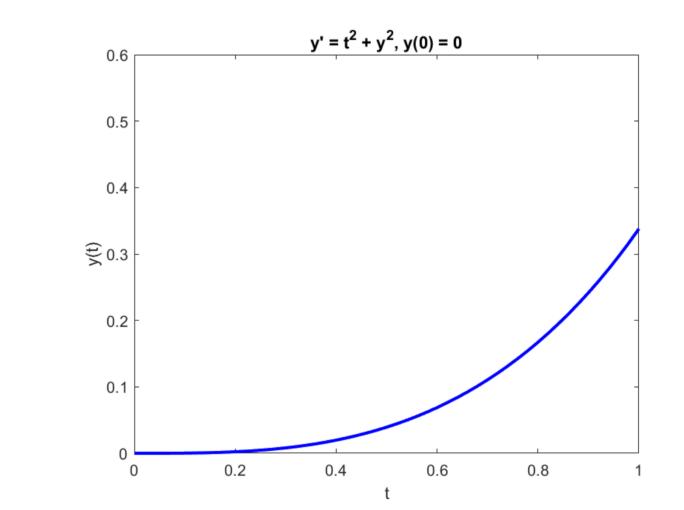
#### **Existence and Uniqueness Theorem**

Let  $f: [0,T] \times \mathbb{R} \to \mathbb{R}$  and  $\sigma: [0,T] \times \mathbb{R} \to \mathbb{R}$  are continuous and for some L > 0 satisfies

$$|f(t,x) - f(t,y)| \le L |x - y|, |\sigma(t,x) - \sigma(t,y)| \le L |x - y|$$
  
 $|f(t,x)| \le L(1+|x|), |\sigma(t,x)| \le L(1+|x|) \ \forall t \in [0,T], x \in \mathbb{R}$ 

Let  $X_0: \Omega \to \mathbb{R}$  be random variable,  $E|X_0|^2 < \infty$ . Then, there exists a unique solution  $X \in L^2_{ad}([0,T] \times \Omega)$  of SDE(1).

# Deterministic vs Stochastic Differential Equation



(a)  $dy(t) = (t^2 + y^2) dt$ Euler's scheme to solve the ODE:

$$\frac{dy}{dt} = f(t, y(t)), \ 0 \le t \le T$$
$$y(0) = y_0$$

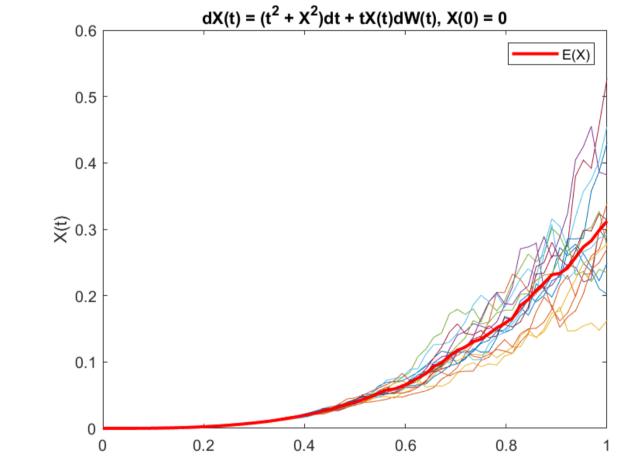
is given by:

$$\omega_0 = y_0$$

$$\omega_{n+1} = \omega_n + hf(t_n, \omega_n),$$

 $n = 0, 1, \dots, N - 1$ 

where  $h = \frac{T}{N}, \ t_n = nh$ 



(b)  $dX(t) = (t^2 + X^2) dt + tX(t) dW(t)$ Euler-Maruyama scheme to solve the SODE:

$$dX(t) = f(t, X(t)) dt + \sigma(t, X(t)) dW_t, \ 0 \le t \le T$$
$$X(0) = X_0$$

is given by: 
$$X_{n+1} = X_n + hf(t_n, X_n) + \sigma(t_n, X_n) \Delta dW_n,$$

 $n=0,1,\dots,N-1$  where  $h=\frac{T}{N},\ t_n=nh,$   $\Delta W_n=W(t_{n+1})-W(t_n)\approx \sqrt{h}N(0,1)$ 

# Examples

• Stock Price: Let S(t) denote the stock prices at time t. The evolution of S(t) is given by the SDE:

$$\frac{dS(t)}{S(t)} = \mu \, dt + \sigma \, dW_t$$

 $t > 0, \ S(0) = S_0, \ \mu > 0, \ \sigma \in \mathbb{R}$ 

Brownian Bridge:

$$dB(t) = \frac{-B}{1 - t}dt + dW_t$$
$$0 < t < 1, \ B(0) = 0$$

Langevin's Equation:

$$dX(t) = -bX(t) dt + \sigma dW_t$$
$$t > 0, \ X(0) = X_0$$

# References

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- Oksendal B-Stochastic Differential Equations-Springer (2000)
- Evans L. C. An Introduction to Stochastic Differential Equations (2014)