

MEDIATEK

INTERNAL USE

Introduction to SDK 1.2.0 for MT7687/7697

Maxx Chen
ACS/ACS7/AE5
2016/03/03



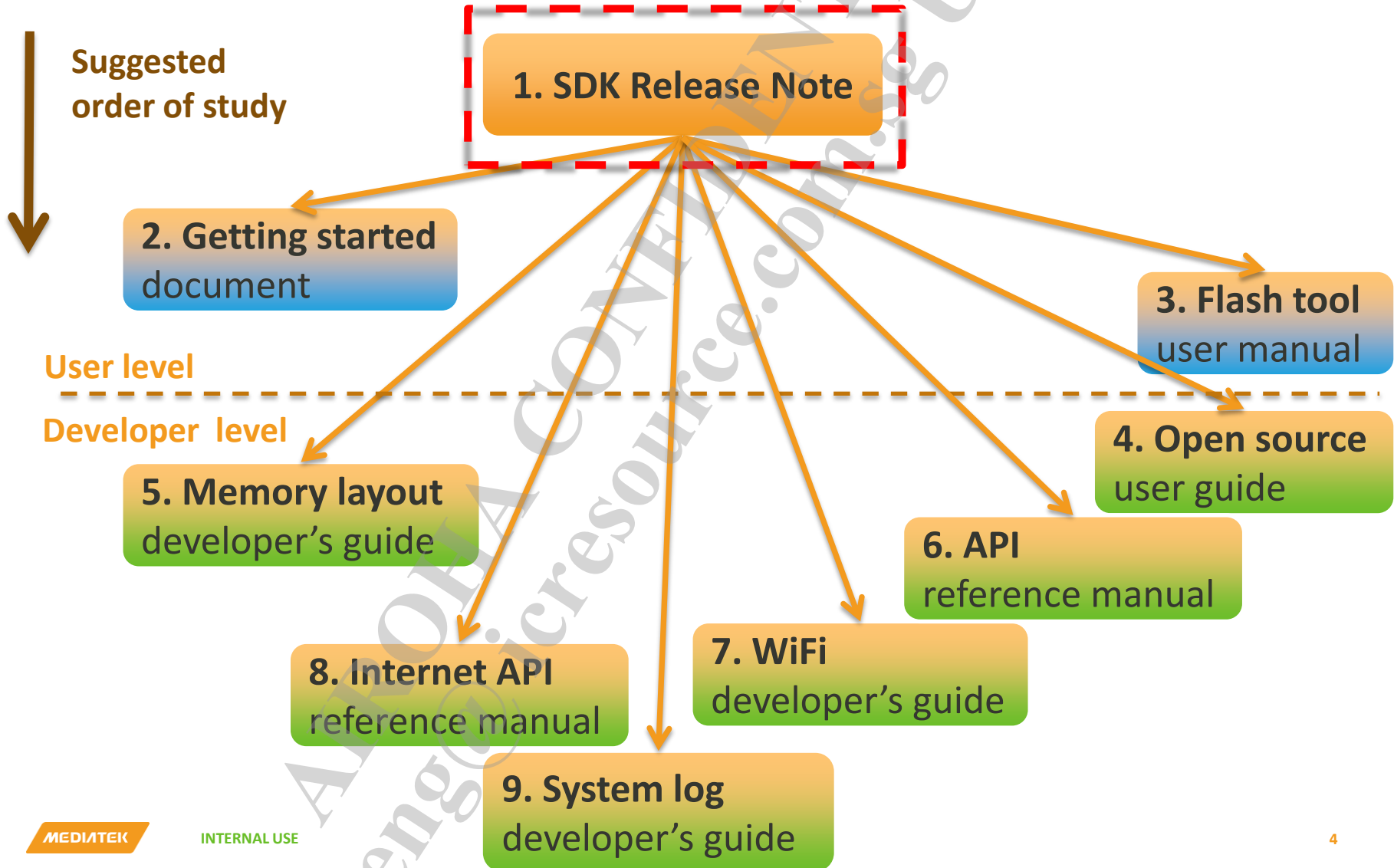
Outline

- MT7687/7697 Family
- A map to SDK
- Getting started with SDK
- Application demo - Smart connection
- Create your own project
- Add a module into Middleware

High-Level Feature – MT7687/MT7697/MT7697D

	MT7687F	MT7697	MT7697D
	Pin to Pin & SW Compatible		
Process	40nm RFCMOS technology	40nm RFCMOS technology	40nm RFCMOS technology
Package	QFN68(8x8)	QFN68(8x8)	QFN68(8x8)
Apps CPU	ARM Cortex-M4 MCU with FPU up to 192MHz clock speed	ARM Cortex-M4 MCU with FPU up to 192MHz clock speed	ARM Cortex-M4 MCU with FPU up to 192MHz clock speed
Memory	Embedded 352KB SRAM 64KB boot ROM	Embedded 352KB SRAM 64KB boot ROM	Embedded 352KB SRAM 64KB boot ROM
Flash	Embedded 2MB Supports eXecute In Place (XIP) on flash	External SPI Flash support (QPI mode) Supports eXecute In Place (XIP) on flash	External SPI Flash support (QPI mode) Supports eXecute In Place (XIP) on flash
Lower power RTC	Low power RTC mode with 32KHz crystal support	Low power RTC mode with 32KHz crystal support	Low power RTC mode with 32KHz crystal support
Security Boot & Crypto Engine	Security Boot supported Hardware crypto engines (AES, DES/3DES and SHA2)	Security Boot supported Hardware crypto engines (AES, DES/3DES and SHA2)	Security Boot supported Hardware crypto engines (AES, DES/3DES and SHA2)
RF	1x1n 2.4G	1x1n 2.4G BLE	1x1n 2.4G/5G BLE
Connectivity	SPI, UART, I2C, I2S, PWM, ADC, IrDA, GPIO	SPI, UART, I2C, I2S, PWM, ADC, IrDA, GPIO	SPI, UART, I2C, I2S, PWM, ADC, IrDA, GPIO

A map to SDK



Getting started with SDK

Getting started with SDK

- **Getting started document**
 - “Getting_Started_with_SDK_vX.X_on_MTXXXXX.pdf”
 - this document includes the feature lists and step by step to setup the environment for the SDK.

Main features-WiFi

Table 1 Wi-Fi station features

Item	Features
Standard	802.11 b/g/n station
Channel	Channel 1~13
Personal Security	Open, WEP-Open, WPA, WPA2
Enterprise Security	N/A
WPS	Enrollee (PBC / PIN)
Advanced	AMPDU, Rx-Filter, DTIM

Table 2 Wi-Fi AP features

Item	Features
Standard	802.11 b/g/n Soft AP
Channel	Channel 1~13
Personal Security	Open, WEP-Open, WPA, WPA2
Support Clients	9 STAs(AP only mode)
WPS	Registrar (PBC/PIN) , Enrollee (PIN)
Enterprise Security	N/A

Main features-Network

Table 3 Supported network protocols

Item	Features
IP Stack	<ul style="list-style-type: none">• IPv4 (LWIP)• TCP, UDP• ICMP• DHCP Client/Server• DNS Client• NETCONN• SOCKET
SNTP	<ul style="list-style-type: none">• Simple Network Time Protocol• RFC4330• Support SNTP receive timeout• Support SNTP update delay• Support SNTP max server
HTTP	<ul style="list-style-type: none">• HTTP 1.1• Client (Post/Get)
HTTPS	<ul style="list-style-type: none">• HTTP 1.1• Client (Post/Get)
SSL/TLS	<ul style="list-style-type: none">• mbedTLS• Client, Server (not test)• SSL3.0, TLS1.0, 1.1, 1.2• AES, 3DES, DES, ARC4• MD5, SHA-1, SHA-256• RSA/PKCS#1 v1.5

Main features-Peripheral

Table 4 Supported peripheral drivers

Item	Features
GPIO	<ul style="list-style-type: none">• GPIO OUT/IN mode• Set Pull Up/Down for GPIO IN mode
PWM	<ul style="list-style-type: none">• 256 Duty Cycle range• 32KHz, 2MHz, XTAL clock for PWM frequency reference
UART	<ul style="list-style-type: none">• 2 Full Set (Tx/Rx) UART support• Baud rate up to 921600
Flash	<ul style="list-style-type: none">• Default 2MB SIP Flash• Support external flash up to 16MB
ADC	<ul style="list-style-type: none">• Analog to Digital Convert• 12bit, 4channel, 125KHz sample rate
I2C-Master	<ul style="list-style-type: none">• I2C * 2• Support 50/100/200/400 KHz Transmit Rate
IrDA	<ul style="list-style-type: none">• Tx (NEC, RC5, RC6, Pulse Width)• Rx (RC5,PulseWidth)
GPC	<ul style="list-style-type: none">• General Purpose Counter• Support 1MHz pulse detection

Main features-Peripheral

Item	Features
WDT	<ul style="list-style-type: none">• Support H/W, S/W watchdog• Support whole chip reset
I2S-Slave	<ul style="list-style-type: none">• Support sample rate: 8k/12k/16k/24k/32k/48k• Support mono and stereo mode
SPI-Master	<ul style="list-style-type: none">• Serial Peripheral Interface
RTC	<ul style="list-style-type: none">• Real Time Clock
GDMA	<ul style="list-style-type: none">• General Purpose DMA
Security	<ul style="list-style-type: none">• SHA1, SHA2 (256, 384, 512), MD5, AES, 3DES
TRNG	<ul style="list-style-type: none">• Truly Random Number Generator• Generate 32bit random number

Advanced features

Table 5 Advanced feature list

Item	Features
XML	<ul style="list-style-type: none">• Mini-xml• Support Entity• Support Get/Set• Support Index• Support Search
JSON	<ul style="list-style-type: none">• cJSON• JSON string parser
Smart Connection	<ul style="list-style-type: none">• MTK smart connection
CLI command	<ul style="list-style-type: none">• CLI command parser

SDK on MT7687 architecture layout

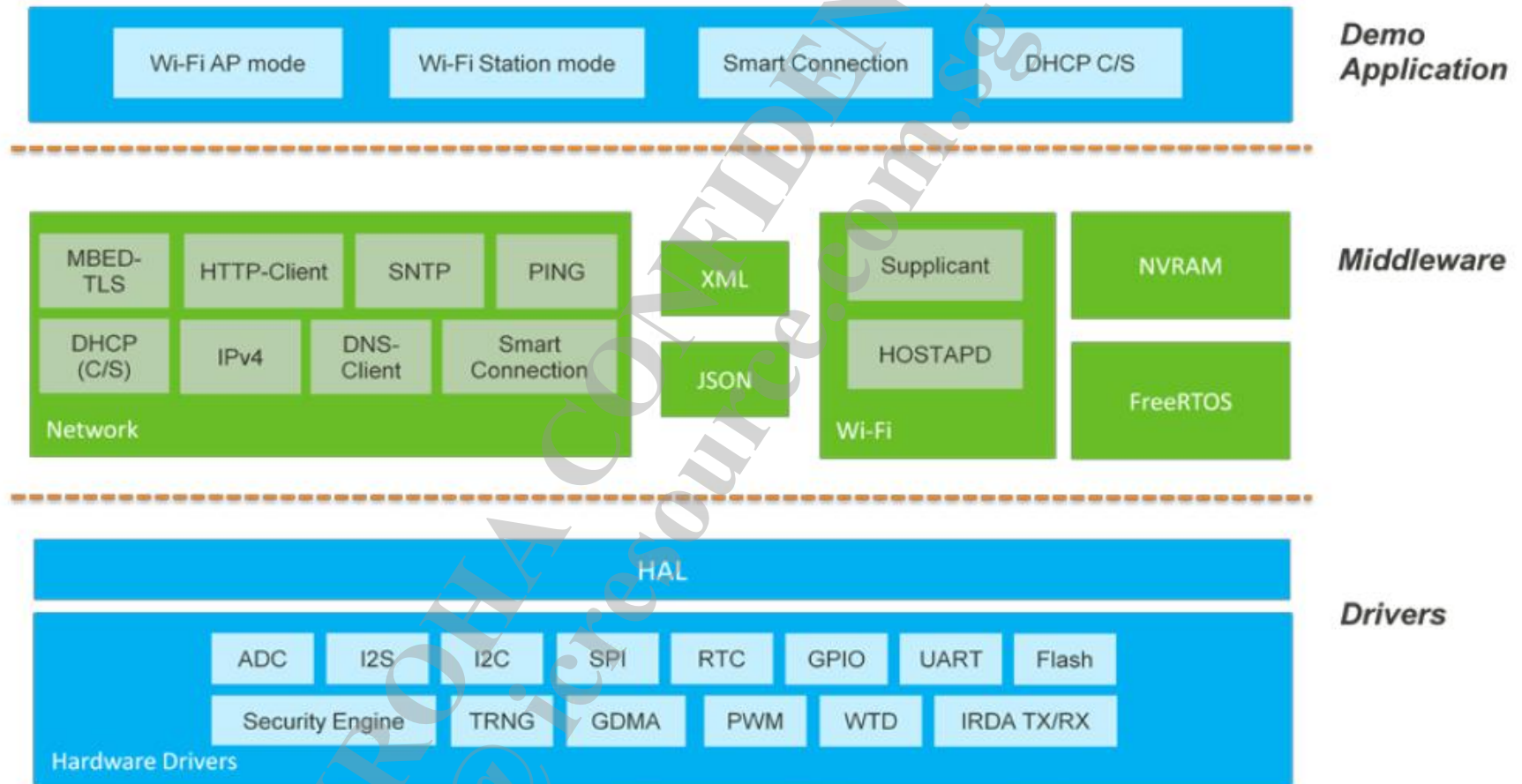


Figure 1 SDK on MT7687 architecture

System requirement

- Building the project on **Linux OS**.
- Downloading the project on **Windows OS**
- The default **GCC toolchain** is supported on the following versions of the **Linux 32/64 bits** hosts
 - Ubuntu 8.x or later (tarball).
 - Ubuntu LTS 10.04 or later (PPA).
 - RHEL 4/5/6 (tarball).

Source Folder

Directories

- **doc/** : documents
- **driver/** : source code of drivers
- **kernel/** : source code of RTOS and system services
- **middleware/** : source code of middleware
- **project/** : user projects
 - `<board> /apps/<project>/GCC`
 - `<board> /apps/<project>/GCC/Makefile`
 - `<board> /apps/<project>/GCC/feature.mk`
- **config/** : config files of chips, boards, and projects
 - `chip/<ic_name>/chip.mk`
 - `board/<board_name>/board.mk`
 - `project/<board>/<project script>`

Project makefile, the main file that trigger other makefile listed in **chip.mk** to generate libs and form the final bin file

Project's feature option are defined in this file

Compiler, CFLAGS, Middleware Module Path are defined in this file

Extra CFLAGS used for each board are defined in this file

Files

- **build.sh** : build command see the next page

Build Image

- `./build.sh` would list all available <board> <project> can be built

```
Usage: ./build.sh <board> <project> [bl|libs|clean]
available boards & projects:
    mt7687_evb_E2
        apps
        hal_examples
        iot_sdk
        mt7687_bl
    mt7697_evb
        iot_sdk
available modules:
    freertos
[libs] - only build libs .a
[bl] - build bootloader
[clean] - Clean...
Usage: ./build.sh clean : delete all
Usage: ./build.sh <board> clean : delete all projects in <board>
Usage: ./build.sh <board> <project> clean : delete a project in <board>
```

```
autogen
flash_download.ini
flash_download.txt
iot_eal.cmm
lib
log
mt7687_bootloader.bin
mt7687_iot_sdk_xip.bin
mt7687_iot_sdk_xip.elf
mt7687_iot_sdk_xip.elf.s
mt7687_iot_sdk_xip.hex
mt7687_iot_sdk_xip.map
obi
WIFI_RAM_CODE_MT7687_in_flash.bin
```

- `./build.sh <board> <project>`
 - `./build.sh mt7687_evb_E2 iot_sdk`
 - 1. run the script `config/project/mt7687_evb_E2/iot_sdk`
 - 2. build in `project/mt7687_evb_E2/apps/iot_sdk/GCC`
 - -> to make libs .a in Makefile
 - -> build image
 - 3. Result is in `out/mt7687_evb_E2/iot_sdk/`

Firmware upgrade (Step 1/5)

- Set the jumper J25 on to FLASH Recovery mode

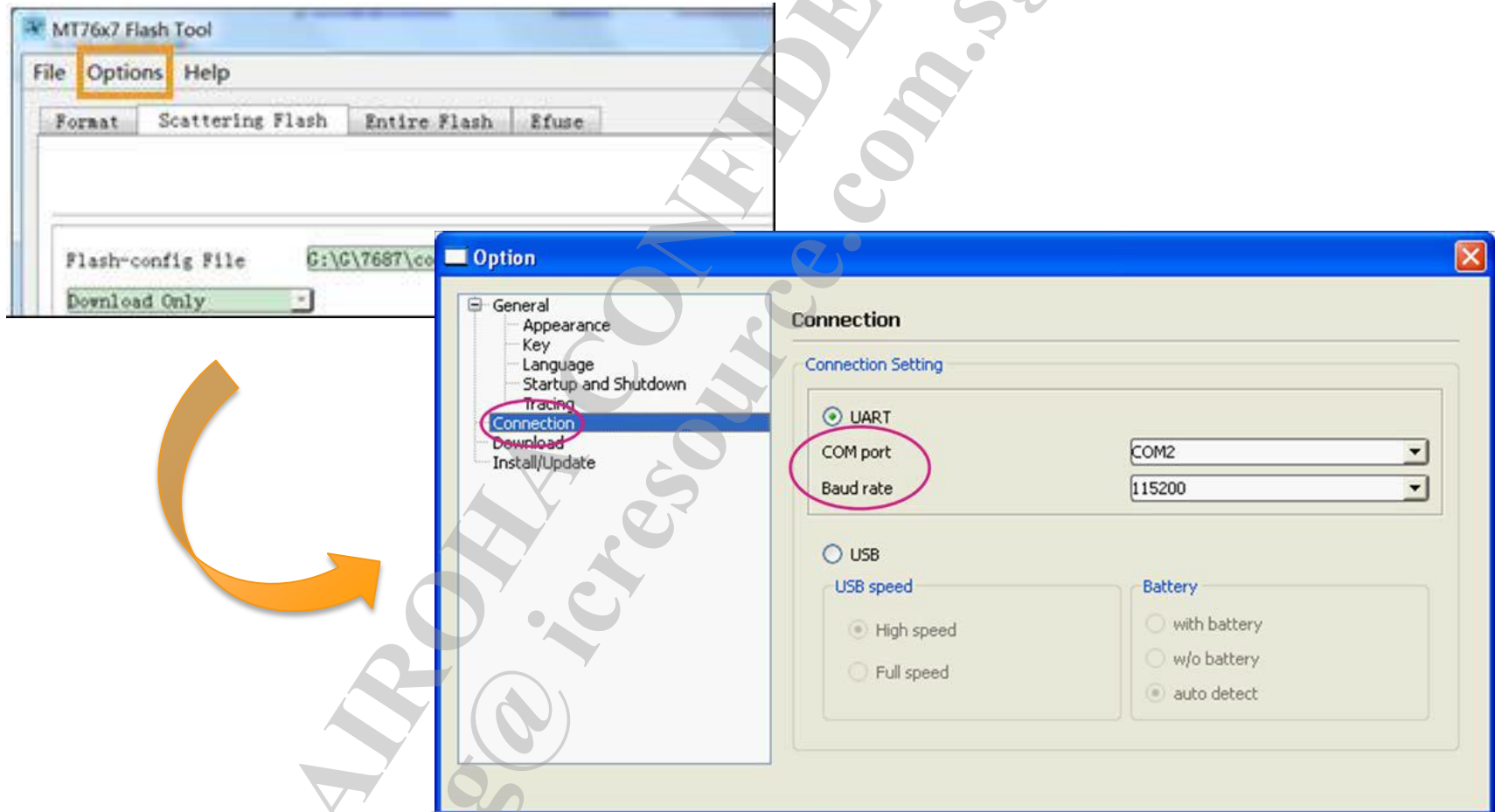


Firmware upgrade (Step 2/5)

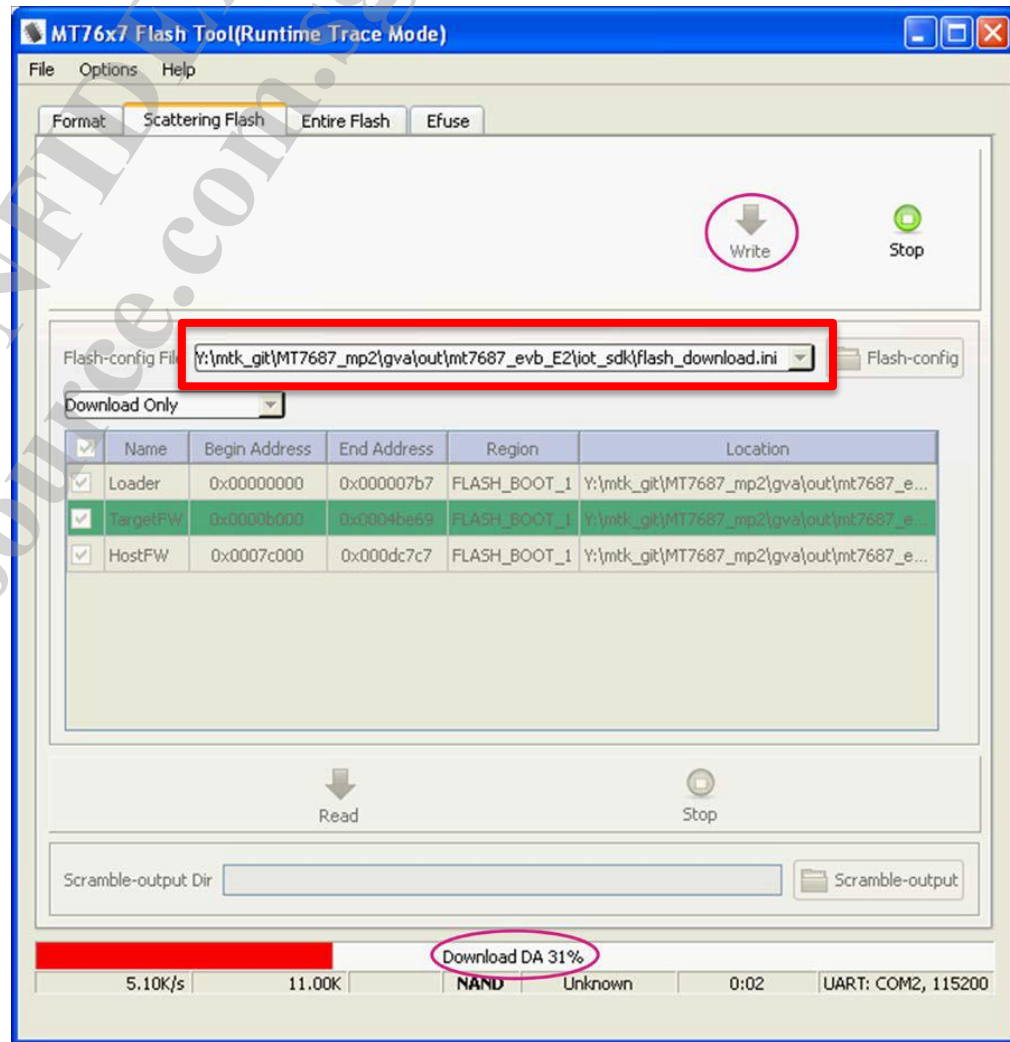
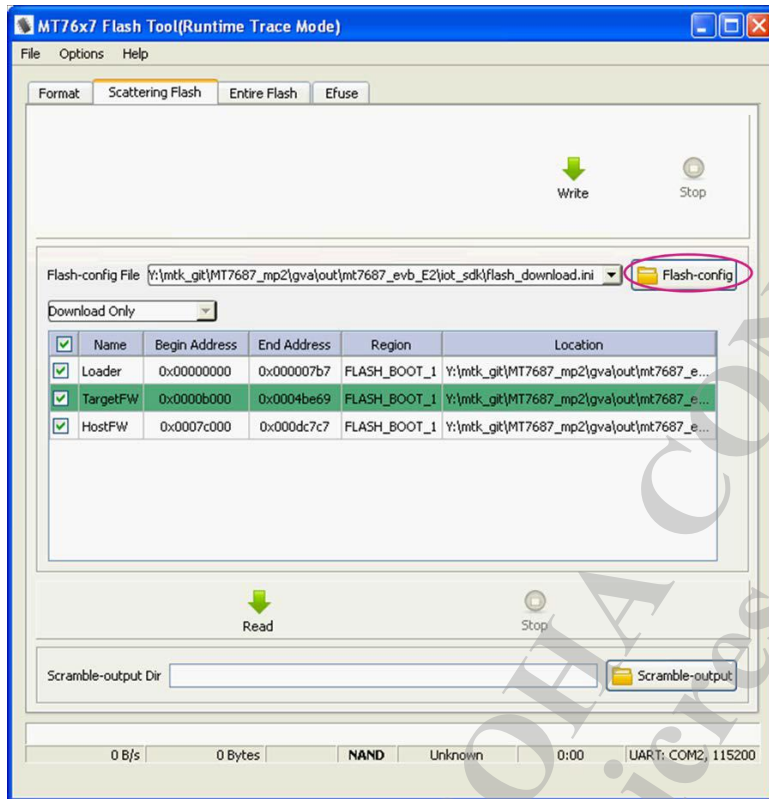
- Connect MT7687 reference board to PC using micro-USB cable.

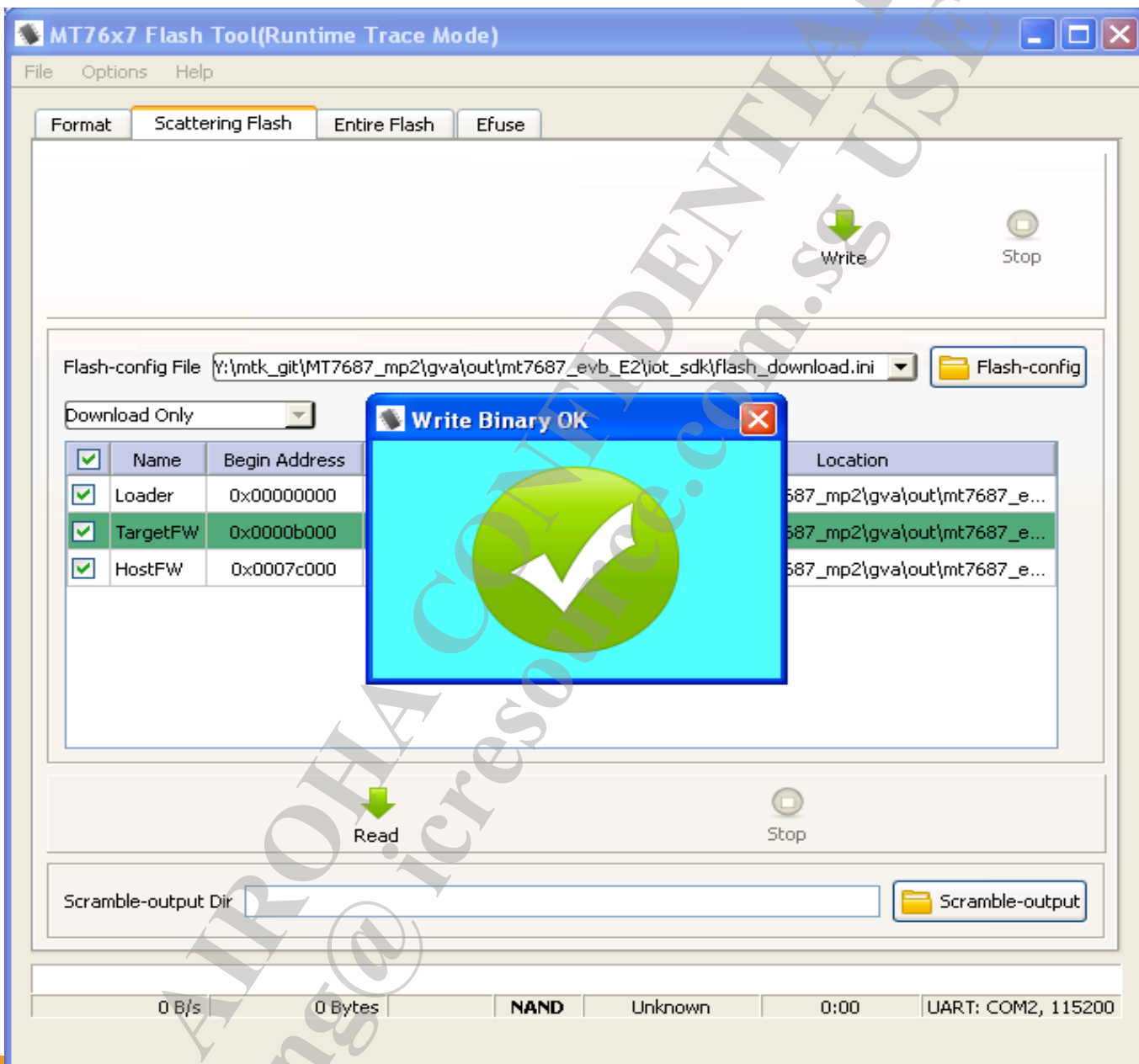


Firmware upgrade (Step 3/5)



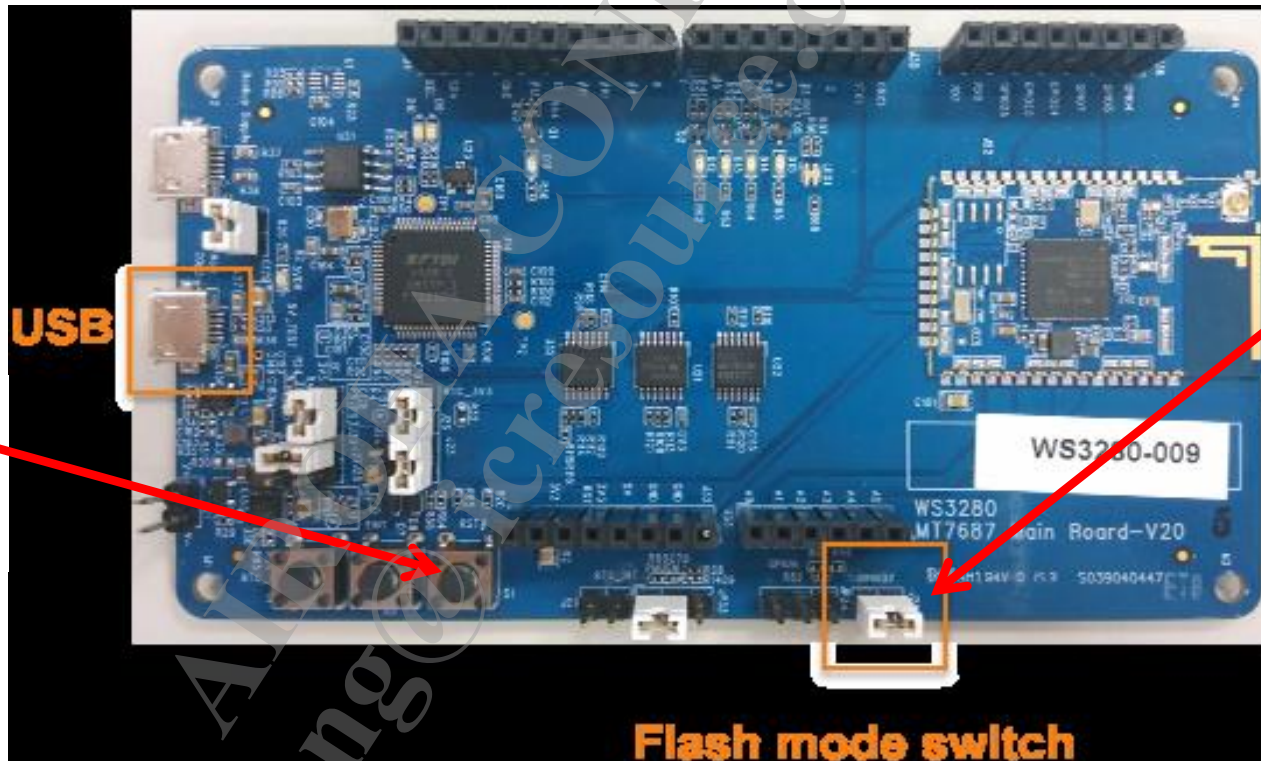
Firmware upgrade (Step 4/5)





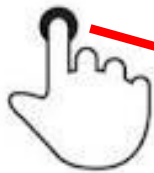
Firmware upgrade (Step 5/5)

- Set the MT7687 reference board to **FLASH Normal mode** by removing **J25**



Step 5.1
Remove it !

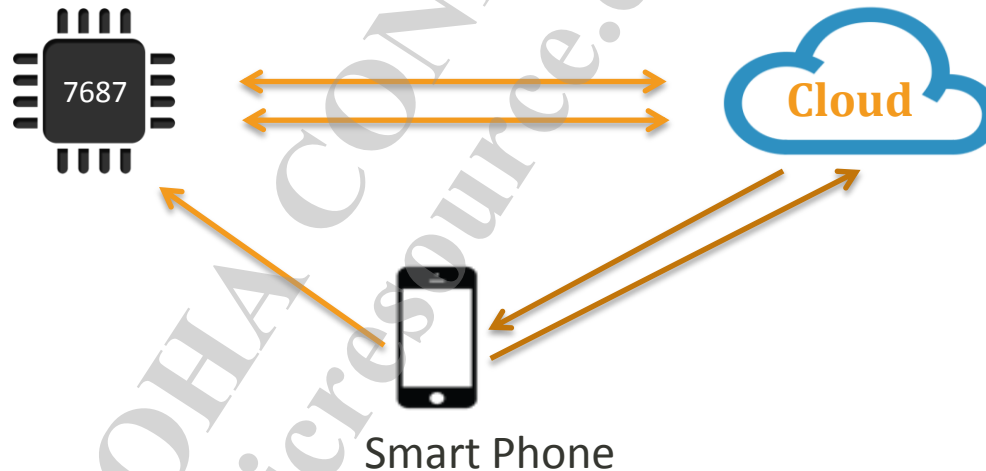
Step 5.2
Press Reset
Button



Application demo - Smart connection

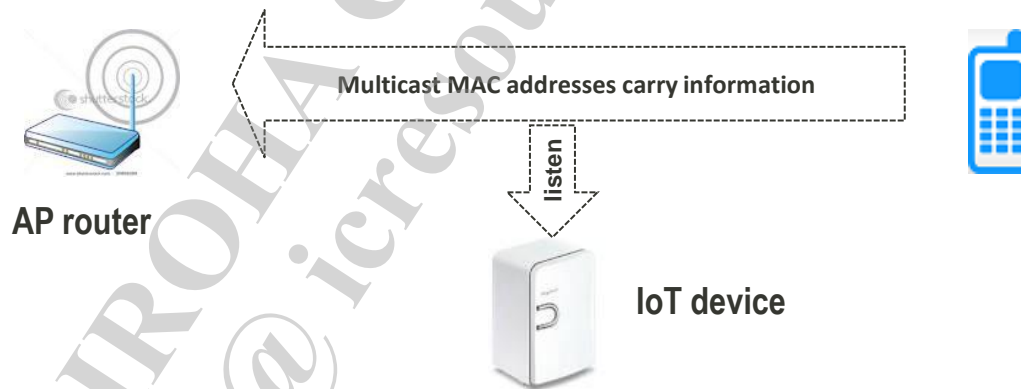
Background

- IoT device will need to connect to Wi-Fi network
- IoT device doesn't have any input interface



MTK smart connection protocol

- IoT device Wi-Fi set as sniffer mode, capture the packets in the air.
- In sniffer mode, IoT device doesn't have the AP's password and it can't decrypt the data.
- Solution: encode data in 802.11 packet MAC address
 - 802.11 packet header is not encrypted.
 - IPv4 multicast address low-order 23 bits same as MAC address low-order 23 bits.



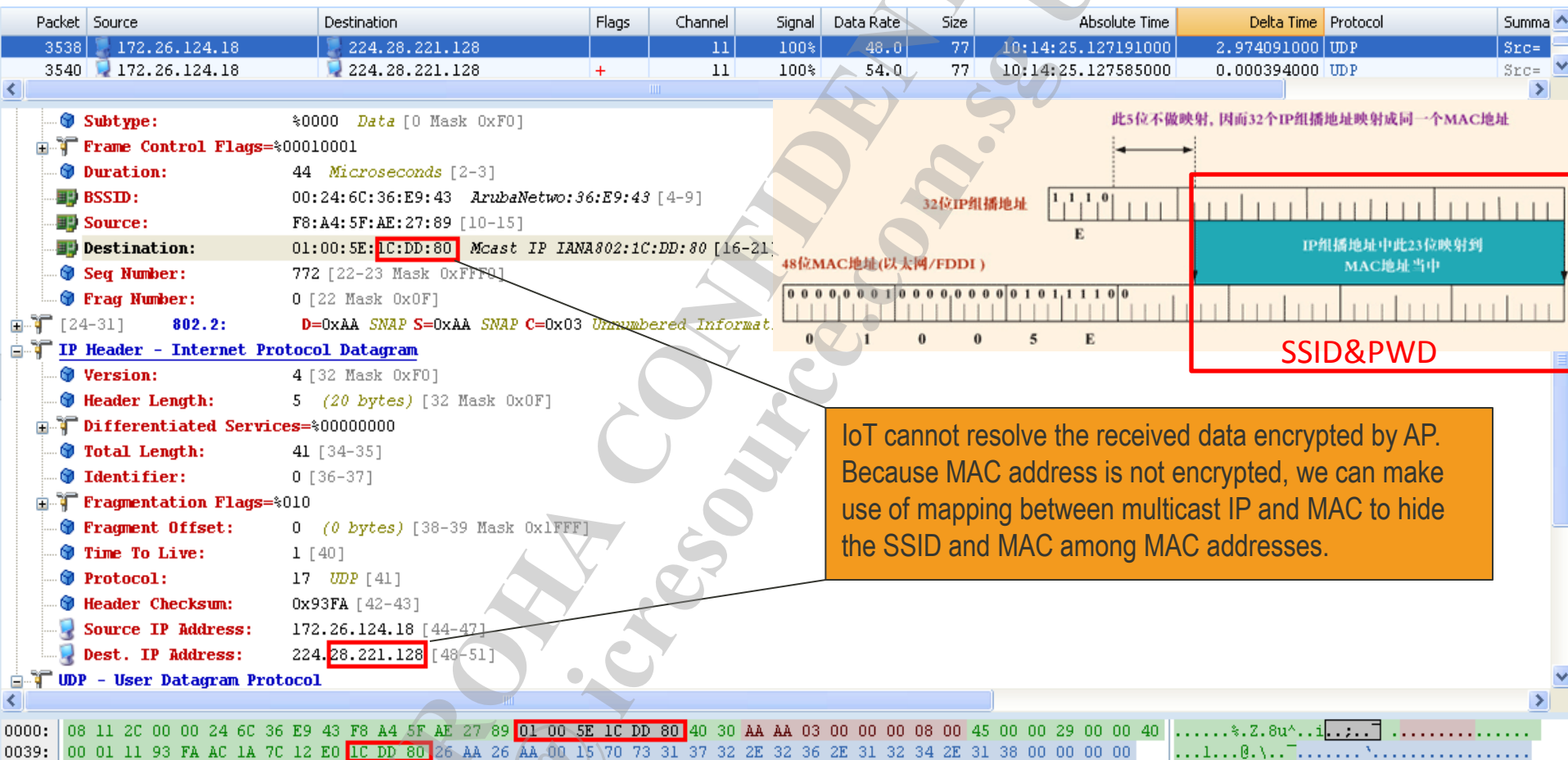
MTK smart connection protocol

IPv4 multicast address and MAC address mapping

		4bits	5bits	23bits
IPv4		1110	The 5 bits not used	Multicast group ID
MAC	00000001 00000000 01011110 0			Multicast group ID
	25bits			Low-order 23 bits of multicast group ID are copied to Ethernet address

- IPv4 multicast address mapping MAC address range:
01:00:5e:00:00:00 ~ 01:00:5e:7f:ff:ff
- IPv4 multicast address low-order 23 bits are copied to Ethernet MAC address low-order 23 bits.
- encode data in IPv4 multicast address low-order 23 bits (SSID, PWD...).

MTK smart connection protocol



MTK smart connection protocol

acket	Source	Destination	BSSID	Transmitter
117	60:E7:01:6D:07:5E	Mcast IP IANA802:12:12:12	JumpIndust:9C:...	60:E7:01:6D:07:5E
119	60:E7:01:6D:07:5E	Mcast IP IANA802:13:13:13	JumpIndust:9C:...	60:E7:01:6D:07:5E
120	60:E7:01:6D:07:5E	Mcast IP IANA802:14:14:14	JumpIndust:9C:...	60:E7:01:6D:07:5E
121	60:E7:01:6D:07:5E	Mcast IP IANA802:15:FF:FF	JumpIndust:9C:...	60:E7:01:6D:07:5E
122	60:E7:01:6D:07:5E	Mcast IP IANA802:17:FF:FF	JumpIndust:9C:...	60:E7:01:6D:07:5E
123	60:E7:01:6D:07:5E	Mcast IP IANA802:18:32:07	JumpIndust:9C:...	60:E7:01:6D:07:5E
124	60:E7:01:6D:07:5E	Mcast IP IANA802:19:08:08	JumpIndust:9C:...	60:E7:01:6D:07:5E
126	60:E7:01:6D:07:5E	Mcast IP IANA802:1A:65:73	JumpIndust:9C:...	60:E7:01:6D:07:5E
127	60:E7:01:6D:07:5E	Mcast IP IANA802:1B:E0:7F	JumpIndust:9C:...	60:E7:01:6D:07:5E
128	60:E7:01:6D:07:5E	Mcast IP IANA802:1D:B7:7B	JumpIndust:9C:...	60:E7:01:6D:07:5E
129	60:E7:01:6D:07:5E	Mcast IP IANA802:1E:05:38	JumpIndust:9C:...	60:E7:01:6D:07:5E
131	60:E7:01:6D:07:5E	Mcast IP IANA802:1F:11:4C	JumpIndust:9C:...	60:E7:01:6D:07:5E
133	60:E7:01:6D:07:5E	Mcast IP IANA802:22:3B:A4	JumpIndust:9C:...	60:E7:01:6D:07:5E
134	60:E7:01:6D:07:5E	Mcast IP IANA802:23:20:D9	JumpIndust:9C:...	60:E7:01:6D:07:5E
135	60:E7:01:6D:07:5E	Mcast IP IANA802:24:7A:D5	JumpIndust:9C:...	60:E7:01:6D:07:5E
137	60:E7:01:6D:07:5E	Mcast IP IANA802:25:0B:7D	JumpIndust:9C:...	60:E7:01:6D:07:5E
138	60:E7:01:6D:07:5E	Mcast IP IANA802:26:E9:10	JumpIndust:9C:...	60:E7:01:6D:07:5E
139	60:E7:01:6D:07:5E	Mcast IP IANA802:27:17:D5	JumpIndust:9C:...	60:E7:01:6D:07:5E
140	60:E7:01:6D:07:5E	Mcast IP IANA802:28:52:77	JumpIndust:9C:...	60:E7:01:6D:07:5E
141	60:E7:01:6D:07:5E	Mcast IP IANA802:29:32:55	JumpIndust:9C:...	60:E7:01:6D:07:5E
142	60:E7:01:6D:07:5E	Mcast IP IANA802:2A:A1:E9	JumpIndust:9C:...	60:E7:01:6D:07:5E
143	60:E7:01:6D:07:5E	Mcast IP IANA802:2B:19:A4	JumpIndust:9C:...	60:E7:01:6D:07:5E
144	60:E7:01:6D:07:5E	Mcast IP IANA802:2B:19:A4	JumpIndust:9C:...	60:E7:01:6D:07:5E
145	60:E7:01:6D:07:5E	Mcast IP IANA802:2B:19:A4	JumpIndust:9C:...	60:E7:01:6D:07:5E
147	60:E7:01:6D:07:5E	Mcast IP IANA802:2C:AF:EC	JumpIndust:9C:...	60:E7:01:6D:07:5E

MTK smart connection protocol

IPv4 multicast address and MAC address mapping

7bits	8bits	8bits	Payload
idx	C0	C1	payload

Encode format:

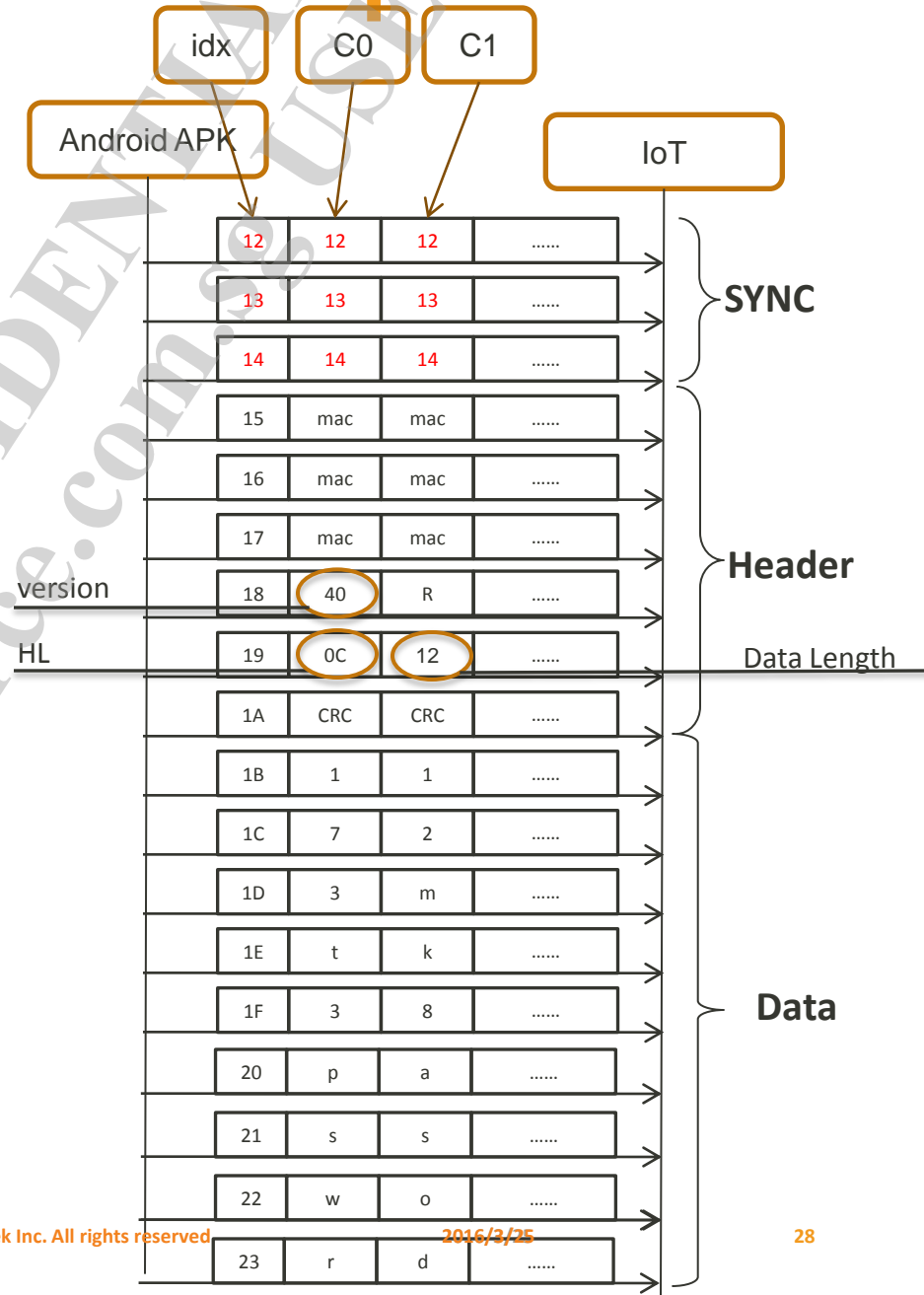
- Bits[0~15] : carry information
- Bit[16~23] : index

Example

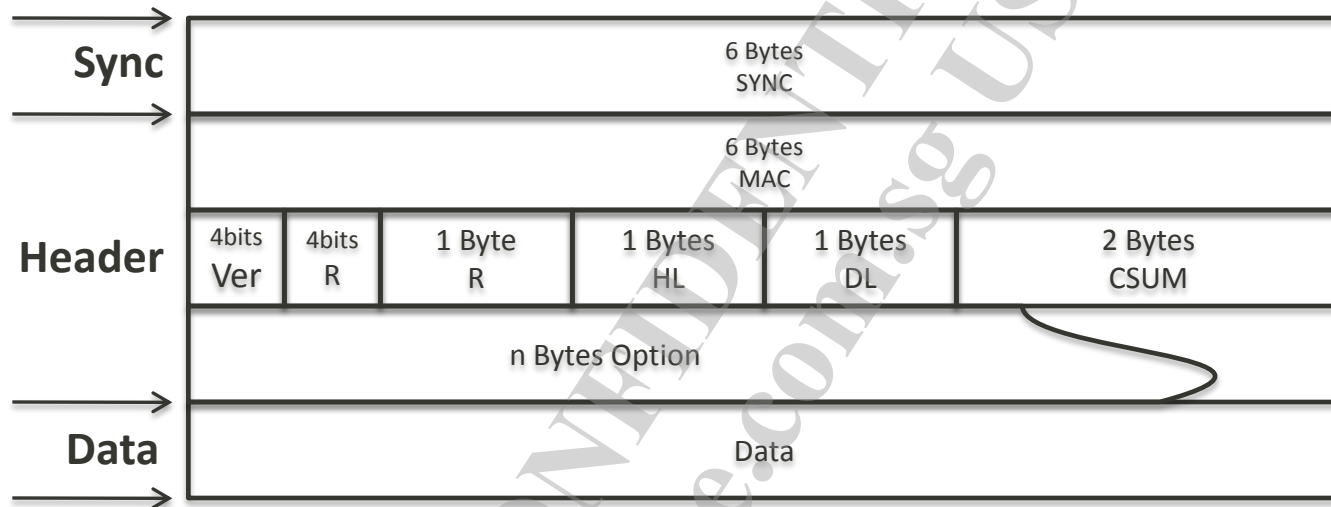
- ssid = "mtk"
- pwd = "password"

Notes:

1. SYNC and MAC ADDR repeat 3 times.
2. Length of data field is fixed, used as a filter.
3. Idx start from **0x15**.
4. All above digits are hexadecimal.
5. mac field used to configure which device to receive the packets, set to FF:FF:FF:FF:FF:FF means configuring all IoT devices.



MTK smart connection protocol



Sync field: 0x12, 0x12, 0x13, 0x13, 0x14, 0x14

MAC field: Target device MAC address

Ver: version code

R: reserved, default set to 0

HL: Header Length

DL: Data Length

CRC: CRC16 for Header & Data

Option: For protocol extension if needed

Data: APP Layer Data.

Source Files

smt_conn.c

smtcn_init
smtcn_start
smtcn_lock_channel
smtcn_rx_timeout
smtcn_done

- Initialize timer
- Switch channel
- Lock channel

elian.c

smtcn_proto_ops efunc_table

init	report_evt
cleanup	start_timer
rx_handler	stop_timer
switch_channel_rst	aes128_decrypt

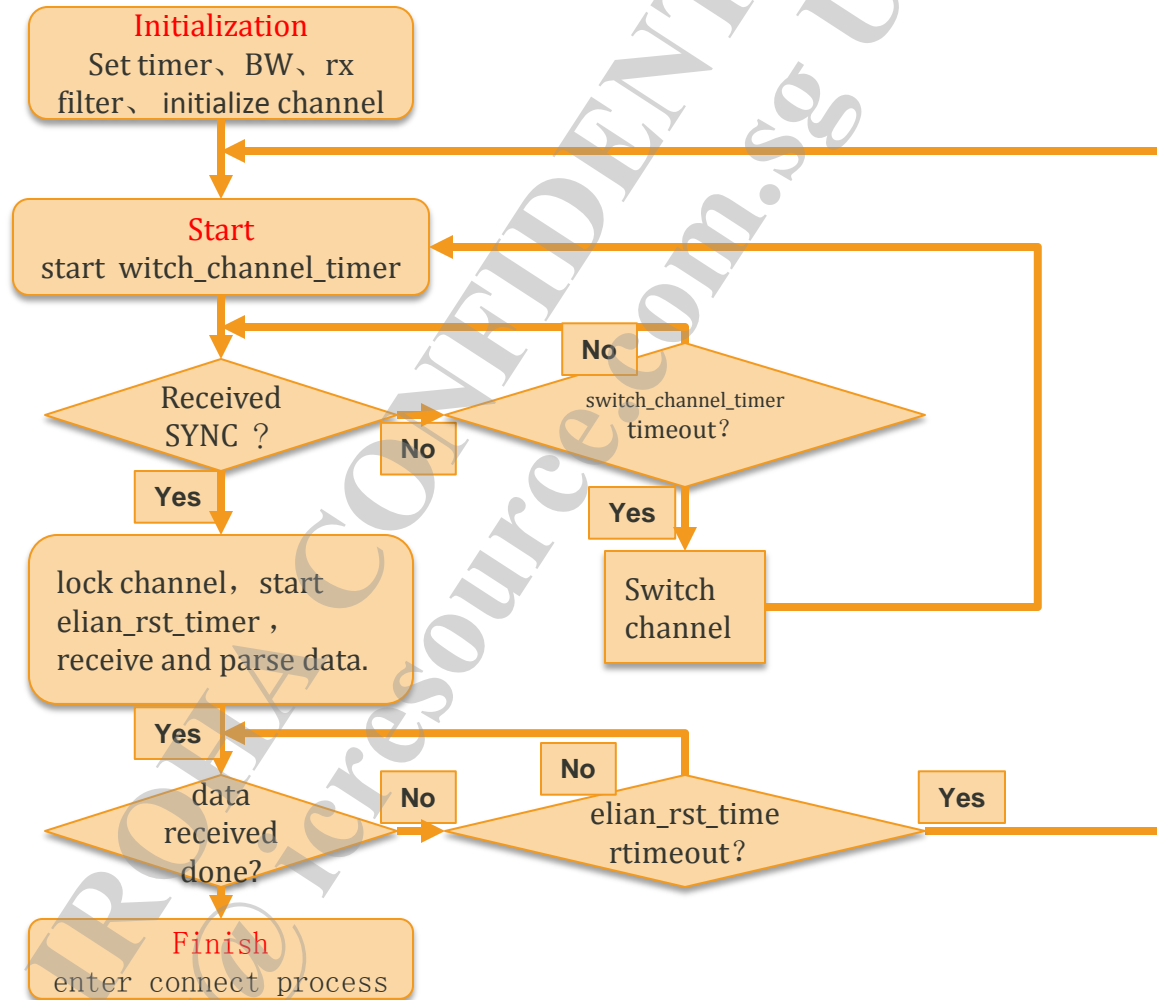
- Adapter
- smtcn_proto_ops
- efunc_table

core.c

elian_input
elian_init
elian_stop
elian_rst

- Decoding data
- Get information
- **Binary release**

Code Flow



Demo – phone with Elian



EliaN

Version:1.0.17, libVersion:15, protocolVersion:4

SSID

Password

custom

Demo – IOT device

```
$ 'smart connect
$ smart_config_mutex:0x2001ed28

>>>>> mtk_smart_connection begin <<<<<<

channel locked at 1, scanned 14 times
sync succeed.
ssid:AE5/3, passwd:12345678/8
unregister rx handler finished.
set hot channel:[1]
original hot 1:[11], hot 2:[1], hot 3:[6]
Smart connection finished.
Now start scan and connect.

>>>>> start scan <<<<<<

Ch  SSID                      BSSID          Auth   Cipher  RSSI    WPS
1   AE5                        28:c6:8e:8f:7b:2b  7      6      -27     1
scan finished!
ssid:[AE5], channel:[1], authMode:[7], encrypt_type:[6], psk:[12345678]
wifi_config_set_ssid - ssid = AE5, ssid_length = 3
wifi_config_set_security_mode - auth_mode = 7, encrypt_type = 6

>>>>> sc_connect <<<<<<:

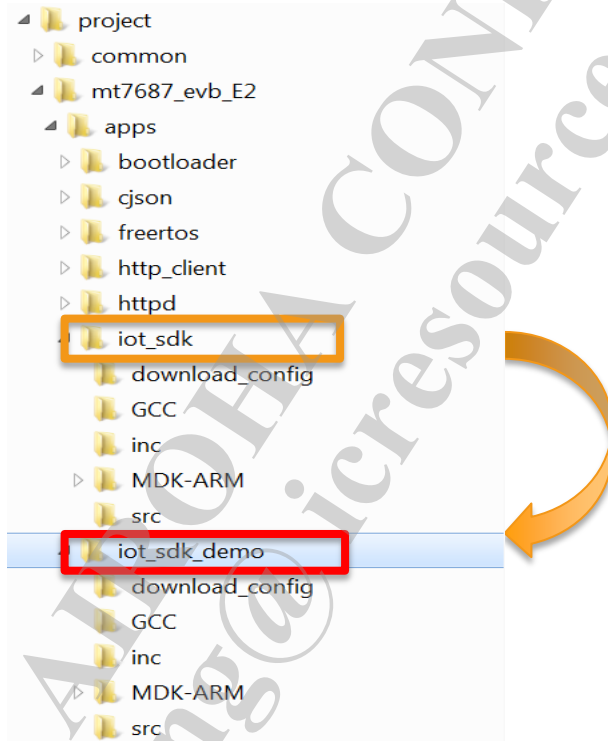
wifi_config_reload_setting
give smart_config_mutex:[0x2001ed28]
[T: 93984 M: inband C: WARNING F: inband_evt_handler L: 393]: WARN! u2PacketType(0xe000), ucEID(0x76), ucSeqNum(0x0) not handled!
IW_ASSOC_EVENT_FLAG: CONNECTED MAC - 28:c6:8e:8f:7b:2b
wifi connect, 3
[T: 96011 M: common C: INFO F: ip_change_call_back L: 209]: *****
[T: 96018 M: common C: INFO F: ip_change_call_back L: 210]: DHCP got IP:192.168.1.3
[T: 96026 M: common C: INFO F: ip_change_call_back L: 211]: *****

(00:02:00)      3166
```

Create your own project

How to create a project (1/5)

- Here we showing how to create a project named `iot_sdk_demo` on board `mt7687_evb_E2`
- Create a folder under `project/mt7687_evb_E2/apps/` named `iot_sdk_demo`
- Copy `download_config`, `GCC`, `inc`, `MDK-ARM`, and `src` folder under `project/mt7687_evb_E2/apps/iot_sdk` to your project folder

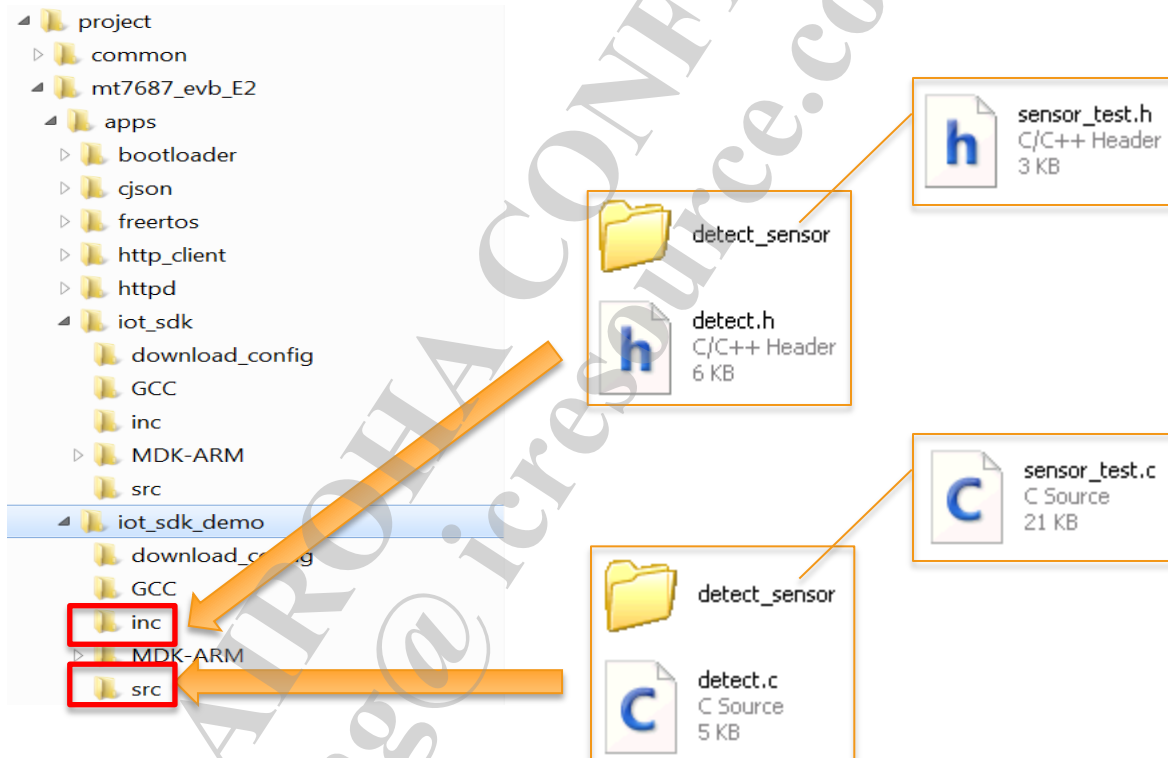


How to create a project (2/5)

- Add your project files

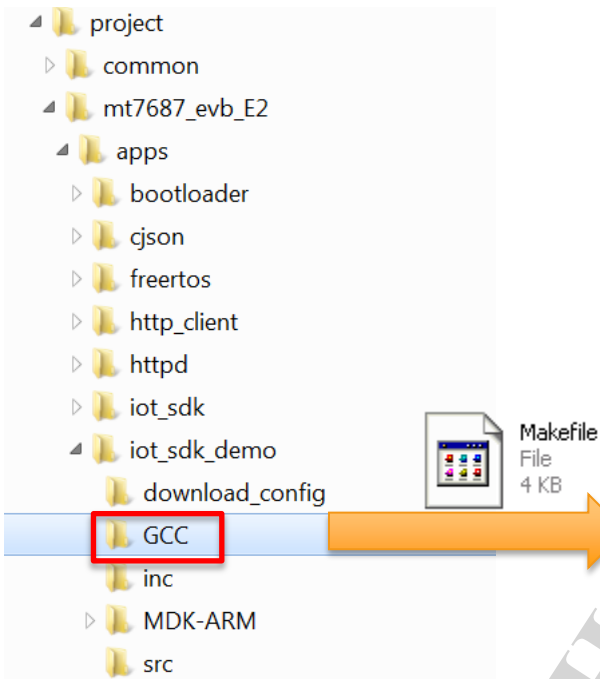
- inc folder: header files
- src folder: source files

P.S. you can create your own folder under inc & src if needed



How to create a project (3/5)

- Modify the red colored part in Makefile to your own



gva/project/mt7687_evb_E2/apps/iot_sdk_demo/Makefile

```
....
SOURCE_DIR = ../../../../..
BINPATH = $(SOURCE_DIR)/tools/gcc/gcc-arm-none-eabi/bin
....
BUILD_DIR = $(PWD)/Build
# Project name
PROJ_NAME = iot_sdk_demo
PROJ_PATH = $(PWD)
....
# Main APP files
APP_PATH = project/mt7687_evb_E2/apps/iot_sdk_demo
APP_PATH_SRC = $(APP_PATH)/src

APP_FILES = $(APP_PATH_SRC)/main.c \
            $(APP_PATH_SRC)/cli_def.c \
            $(APP_PATH_SRC)/io_def.c \
            $(APP_PATH_SRC)/task_def.c \
            $(APP_PATH_SRC)/net_init.c \
            $(APP_PATH)/GCC/syscalls.c
            $(APP_PATH_SRC)/detect.c \
            $(APP_PATH_SRC)/detect_sensor/sensor_test.c

....
#####
# include path
CFLAGS += -I$(SOURCE_DIR)/$(APP_PATH)/inc
CFLAGS += -I$(SOURCE_DIR)/driver/chip/mt7687/inc
CFLAGS += -I$(SOURCE_DIR)/driver/chip/inc
CFLAGS += -I$(SOURCE_DIR)/middleware/lwip/src/include
CFLAGS += -I$(SOURCE_DIR)/middleware/lwip/ports/include
CFLAGS += -I$(SOURCE_DIR)/$(APP_PATH)/inc/detect_sensor
#####
```

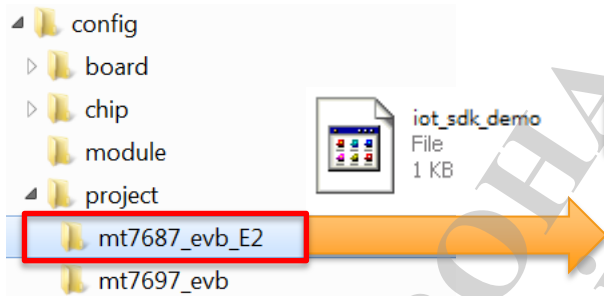
Root directory (gva)

Add file path of your project source files here

Add include path of your project header files here

How to create a project (4/5)

- Add a project config file named `iot_sdk_demo` to `config/project/mt7687_evb_E2` folder
- Copy the example below & paste into `iot_sdk_demo`
- modify the `red colored` part to your own



iot_sdk_demo
File
1 KB

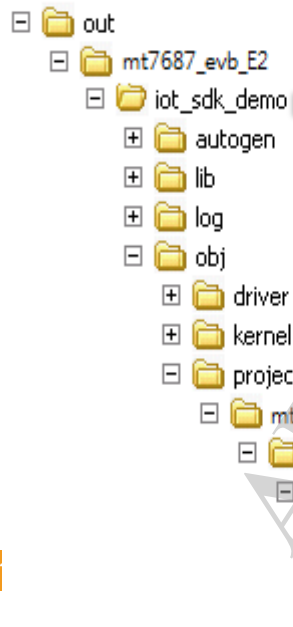
`gva/config/project/mt7687_evb_E2/iot_sdk_demo`

```
#!/bin/bash  
  
echo "Config...iot_sdk_demo"  
export TARGET_PATH=project/mt7687_evb_E2/apps/iot_sdk_demo/GCC  
export FREERTOS_CONFIG_PATH=$PWD/project/mt7687_evb_E2/apps/iot_sdk_demo/inc
```

How to create a project (5/5)

- Now you can build your project and see if the bin file of your project generated successfully
 - Build project:
 - `./build.sh mt7687_evb_E2 iot_sdk_demo`

- Check if bin file exists:



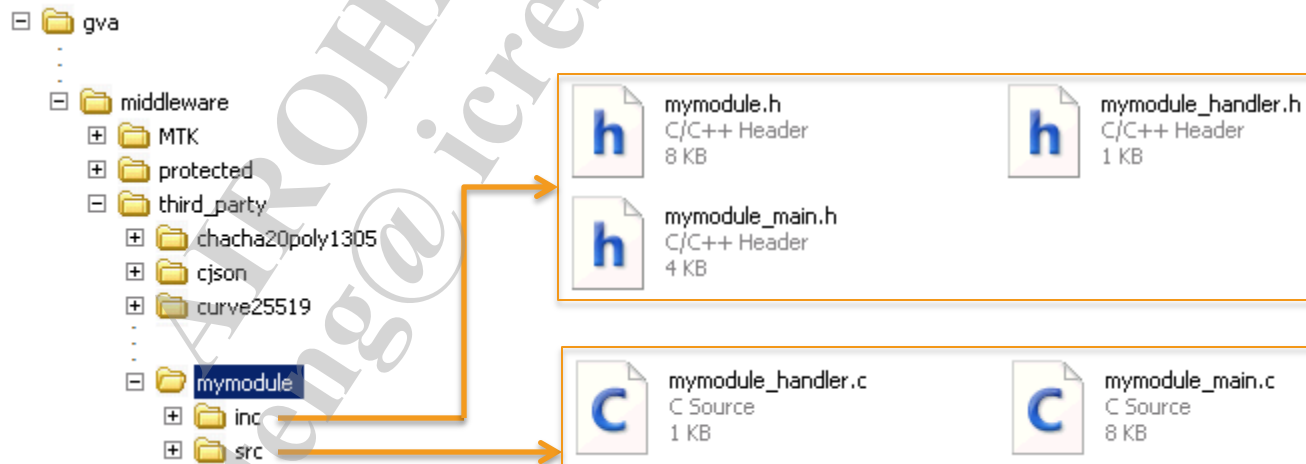
```
autogen
flash_download.ini
flash_download.txt
iot_eal.cmm
lib
log
mt7687_bootloader.bin
mt7687_iot_sdk_demo_xip.bin
mt7687_iot_sdk_demo_xip.elf
mt7687_iot_sdk_demo_xip.elf.s
mt7687_iot_sdk_demo_xip.hex
mt7687_iot_sdk_demo_xip.map
obj
WIFI_RAM_CODE_MT7687_in_flash.bin
```

The .o and .d files of your project files will be placed under the corresponding folder

Add a module into Middleware

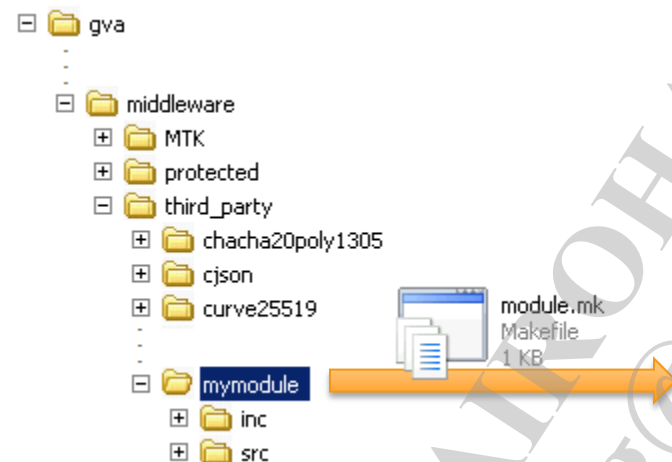
How to add a module into middleware (1/5)

- Here we showing how to add a module named **mymodule** into project **iot_sdk_demo** on board **mt7687_evb_E2**
- Create a folder under **middleware/third_party** named **mymodule**
- Add your module files
 - inc folder: header files
 - src folder: source files



How to add a module into middleware (2/5)

- Create a file named **module.mk** under module folder
 - Copy the example below & paste into **module.mk**
 - modify the **red colored** part to your own



gva/middleware/third_party/mymodule/module.mk

#module path

MYMODULE_SRC = middleware/third_party/mymodule

#source file

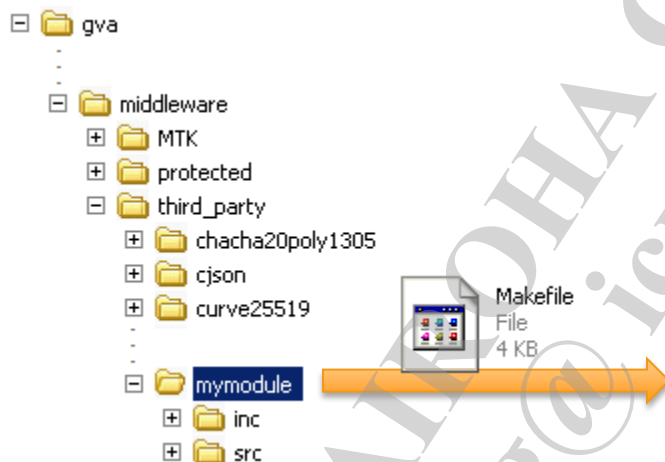
C_FILES += \$(MYMODULE_SRC)/src/mymodule_main.c \
\$(MYMODULE_SRC)/src/mymodule_handler.c

#include path

CFLAGS += -I\$(SOURCE_DIR)/middleware/third_party/mymodule/inc

How to add a module into middleware (3/5)

- Create a file named **Makefile** under module folder
 - Copy the example below & paste into **Makefile**
 - modify the **red colored** part to your own



gva/middleware/third_party/mymodule/Makefile

```
SOURCE_DIR = ../../..  
BINPATH   = ~/gcc-arm-none-eabi/bin  
PROJ_PATH = ../../..project/mt7687_evb_E2/apps/iot_sdk_demo/GCC  
CONFIG_PATH ?=
```

the path to your project folder that contains project Makefile

```
CFLAGS += -I$(PROJ_PATH)/../inc  
CFLAGS += -I$(SOURCE_DIR)/$(CONFIG_PATH)
```

```
FEATURE ?= feature.mk  
include $(PROJ_PATH)/$(FEATURE)
```

Global Config

```
-include $(SOURCE_DIR)/.config
```

IC Config

```
-include $(SOURCE_DIR)/config/chip/$(IC_CONFIG)/chip.mk
```

Board Config

```
-include $(SOURCE_DIR)/config/board/$(BOARD_CONFIG)/board.mk
```

Project name

```
TARGET_LIB=libmymodule
```

the lib name for the added module

```
BUILD_DIR = Build
```

```
OUTPATH = Build
```

Sources

```
include module.mk
```

```
C_OBJS = $(C_FILES:%.c=$(BUILD_DIR)/%.o)
```

```
.PHONY: $(TARGET_LIB).a
```

```
all: $(TARGET_LIB).a
```

```
@echo Build $< Done
```

```
include $(SOURCE_DIR)/.rule.mk
```

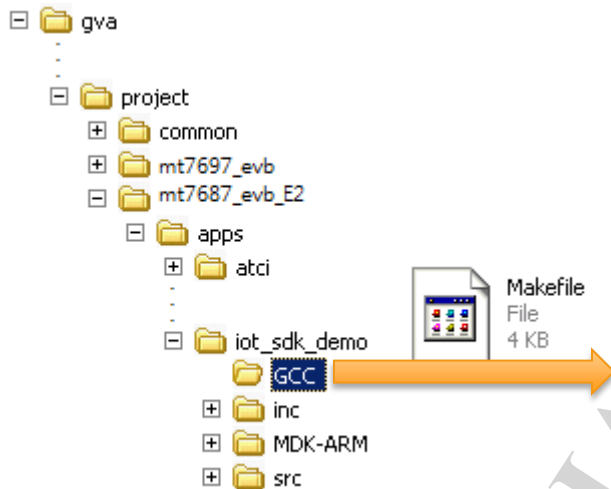
clean:

```
rm -rf $(OUTPATH)/$(TARGET_LIB).a
```

```
rm -rf $(BUILD_DIR)
```

How to add a module into middleware (4/5)

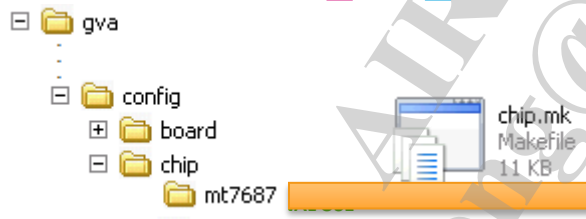
- Add module to linking LIBS & make command in project **Makefile**



gva/project/mt7687_evb_E2/apps/iot_sdk_demo/Makefile

```
....  
# HAL driver files  
LIBS += $(OUTPATH)/libbsp.a  
LIBS += $(OUTPATH)/libhal.a  
  
LIBS += $(OUTPATH)/libmymodule.a  
....  
MOD_EXTRA = BUILD_DIR=$(BUILD_DIR) OUTPATH=$(OUTPATH) PROJ_PATH=$(PROJ_PATH)  
  
libs:  
    make -C $(DRV_CHIP_PATH) $(MOD_EXTRA)  
    make -C $(DRV_BSP_PATH) $(MOD_EXTRA)  
    make -C $(MID_MY_MODULE_PATH) $(MOD_EXTRA)  
  
proj: $(OUTPATH)/$(PROJ_NAME).elf  
....
```

- Add **\$(MID_MY_MODULE_PATH)** definition to project related **chip.mk**

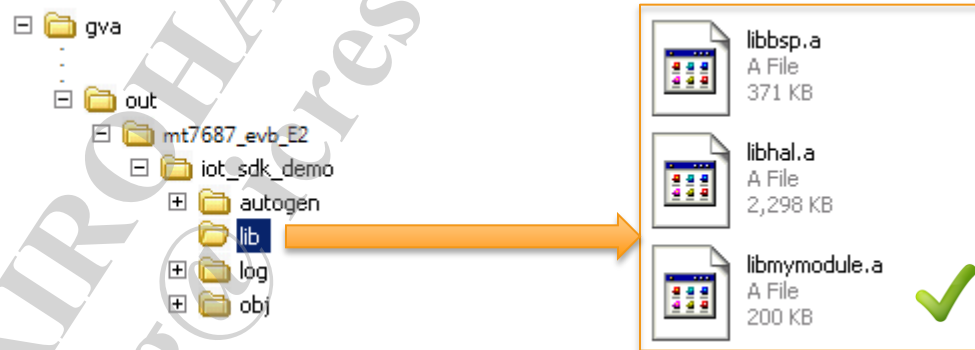


gva/config/chip/mt7687/chip.mk

```
....  
#Middleware Module Path  
DRV_BSP_PATH = $(SOURCE_DIR)/driver/board/mt76x7_evb  
KRL_OS_PATH = $(SOURCE_DIR)/kernel/rtos/FreeRTOS  
KRL_SRV_PATH = $(SOURCE_DIR)/kernel/service  
MID_MY_MODULE_PATH = $(SOURCE_DIR)/middleware/third_party/mymodule
```

How to add a module into middleware (5/5)

- Now you can build your project and see if the lib of the added module generate successfully
 - Build project:
 - `./build.sh mt7687_evb_E2 iot_sdk_demo`
 - Check if the lib exists



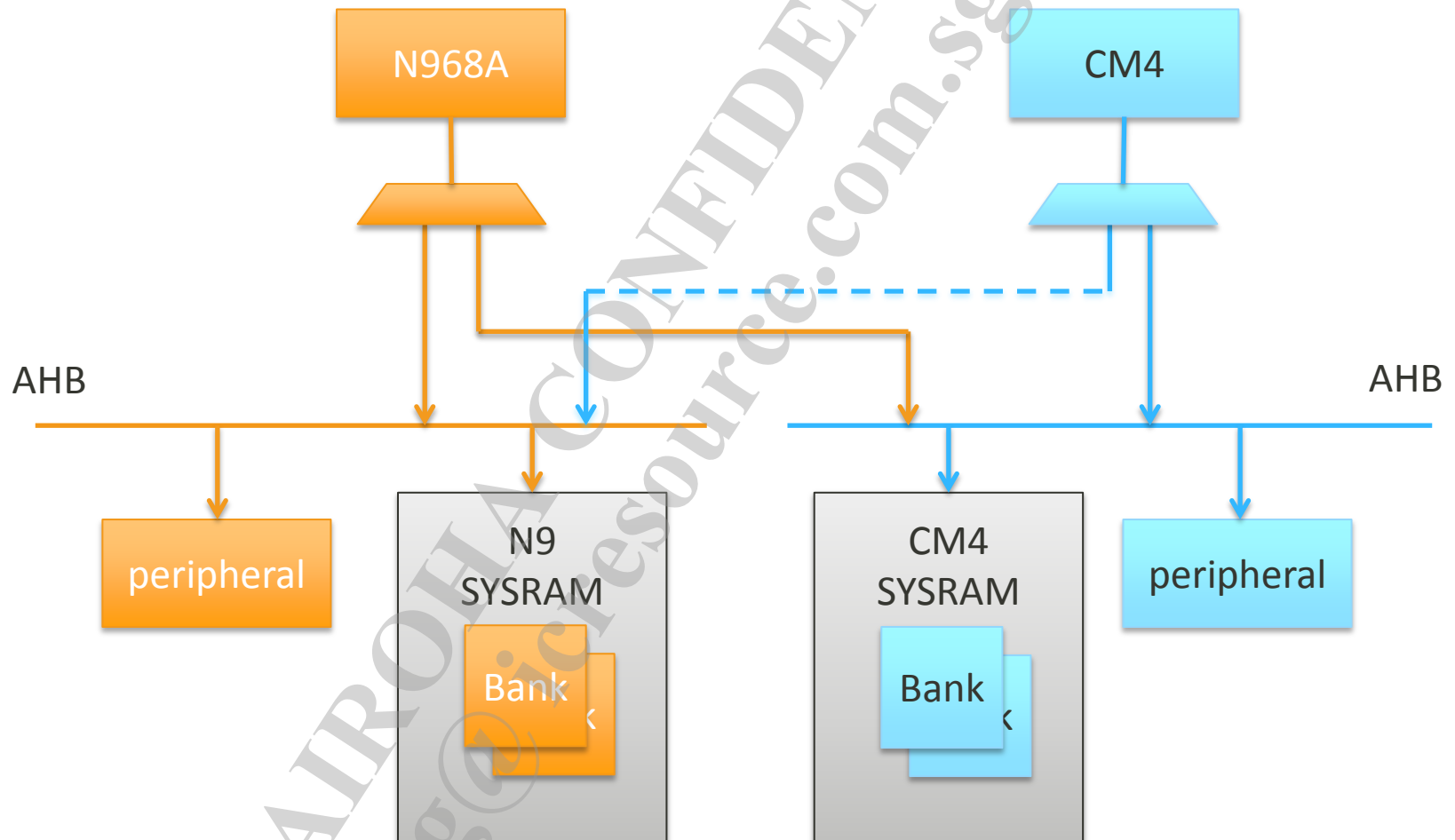
MEDIATEK

everyday genius

Appendix 1

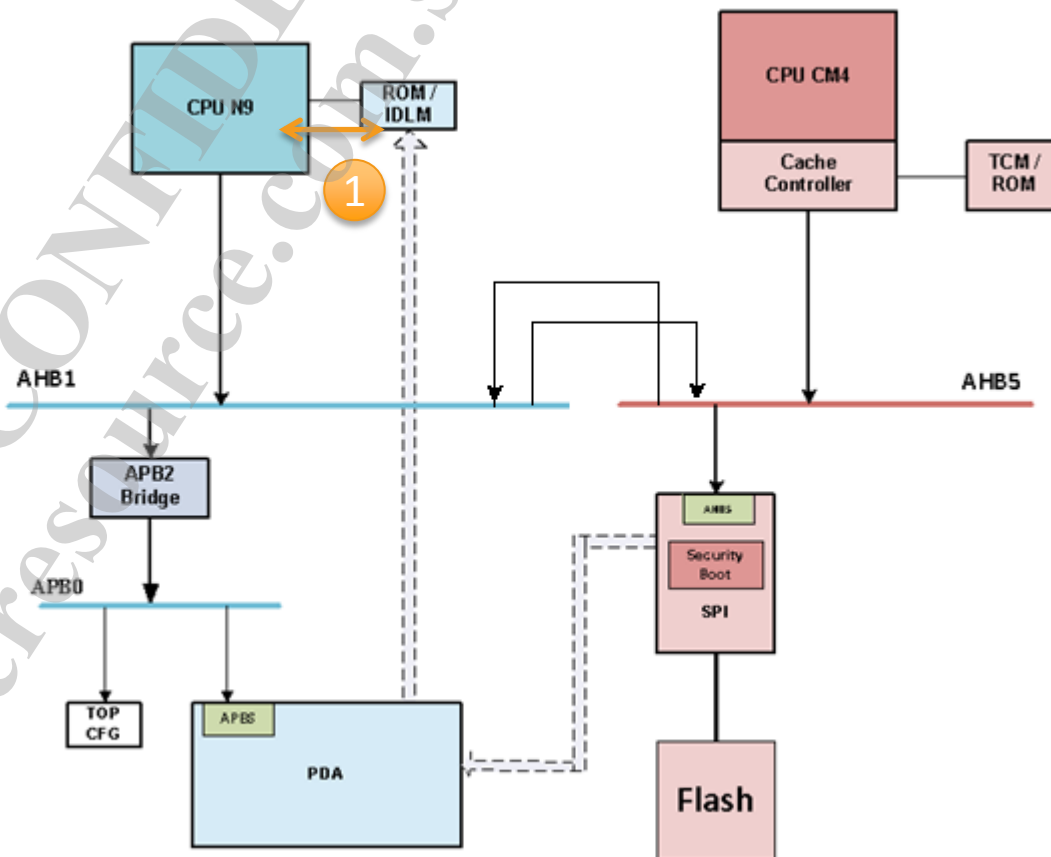
Boot up sequence of MT7687

H/W Architecture (dual core)



Dual-core platform power sequence

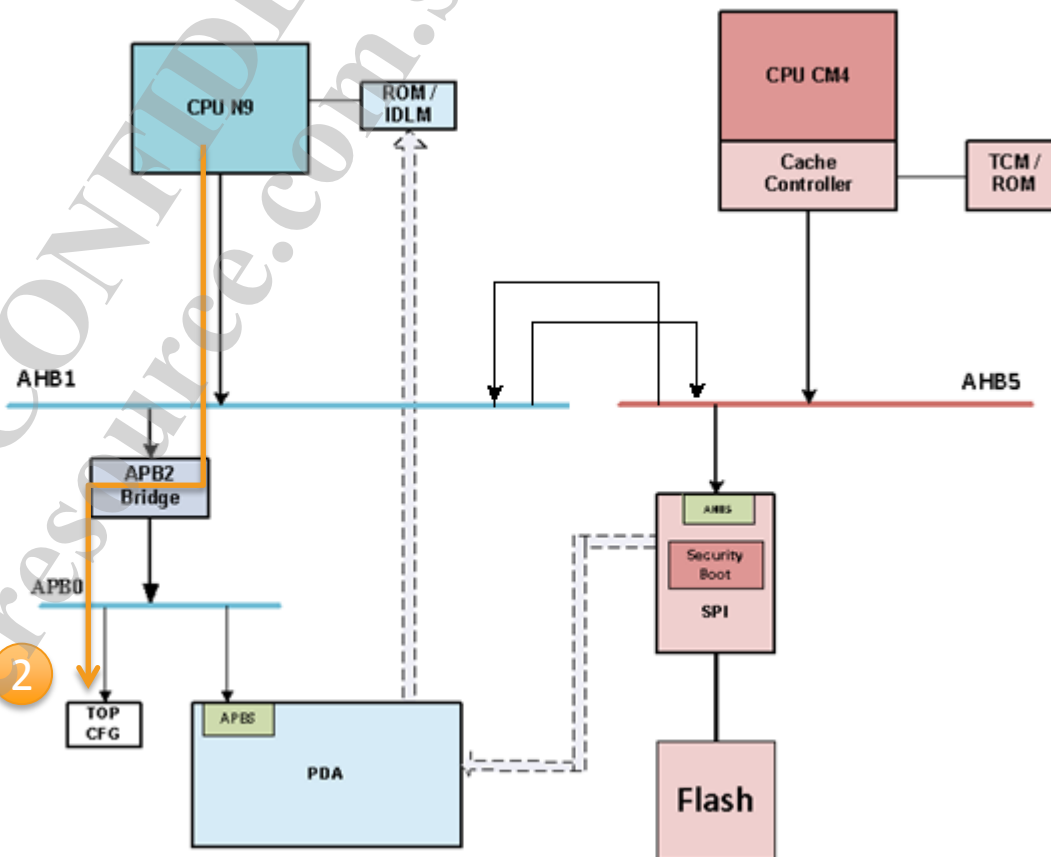
- Step 1:
 - Chip power on
 - N9 :
 - boot from N9-ROM
 - CM4 : reset asserted



Dual-core platform power sequence

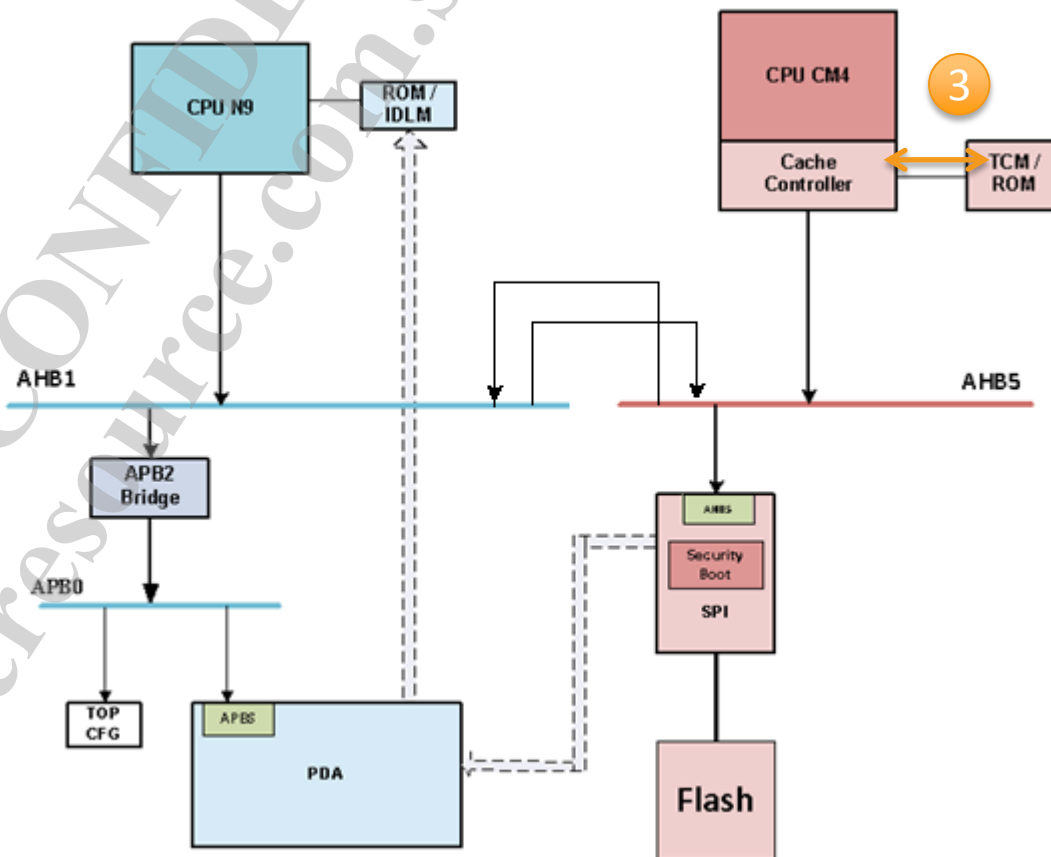
Step 2:

- N9 :
 - Setting TOP cfg. registers (PLL setting, etc.)
 - de-assert reset signal of CM4



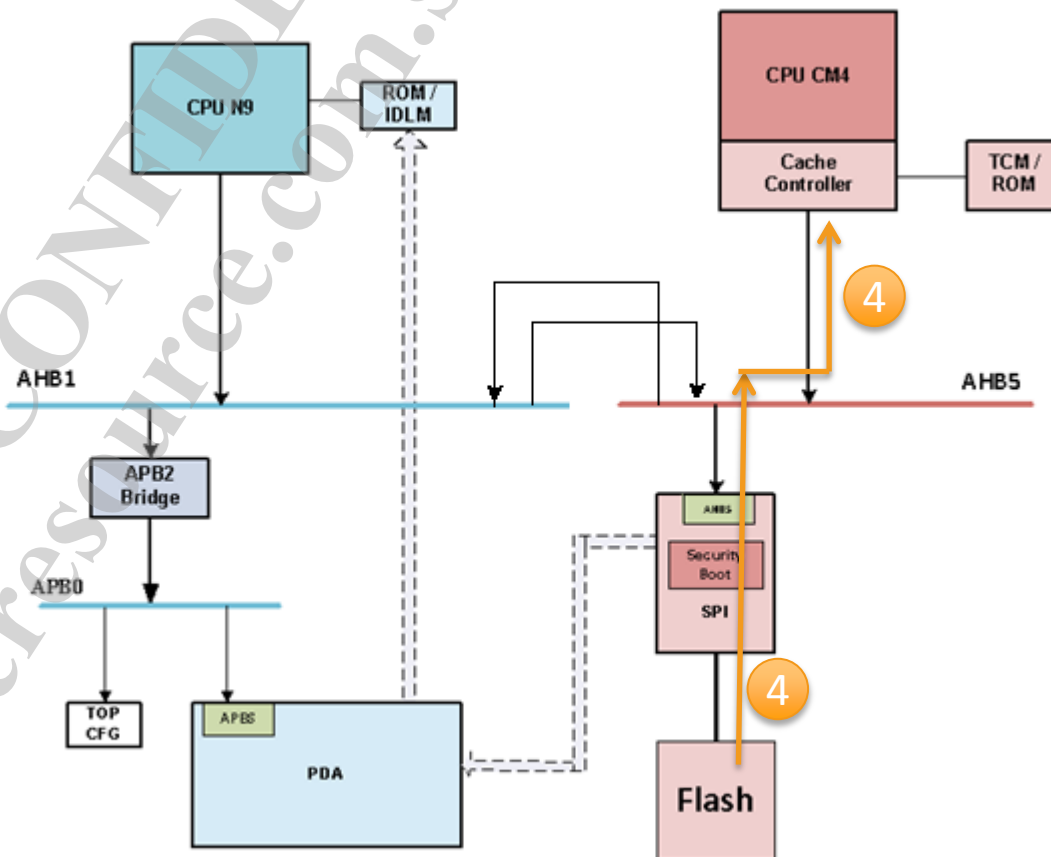
Dual-core platform power sequence

- Step 3:
 - CM4 :
 - boot from CM4-ROM



Dual-core platform power sequence

- Step 4:
 - CM4 :
 - get F/W download information of N9 from external Flash

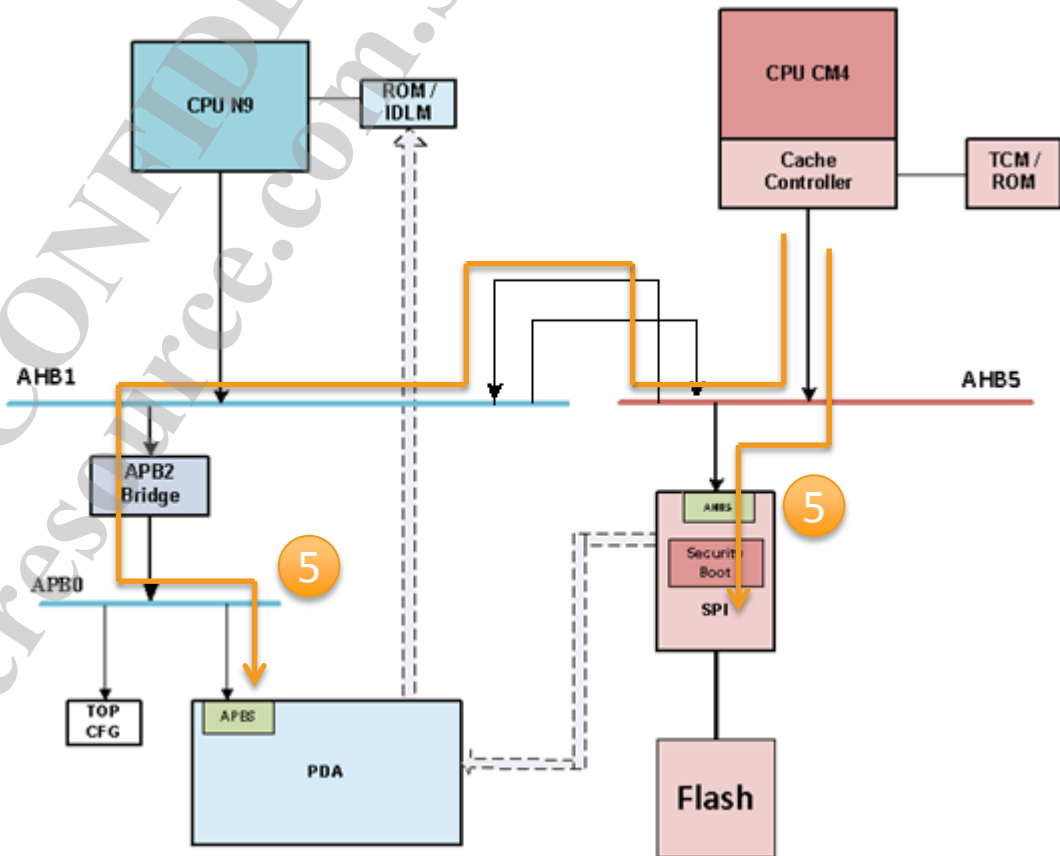


Dual-core platform power sequence

■ Step 5:

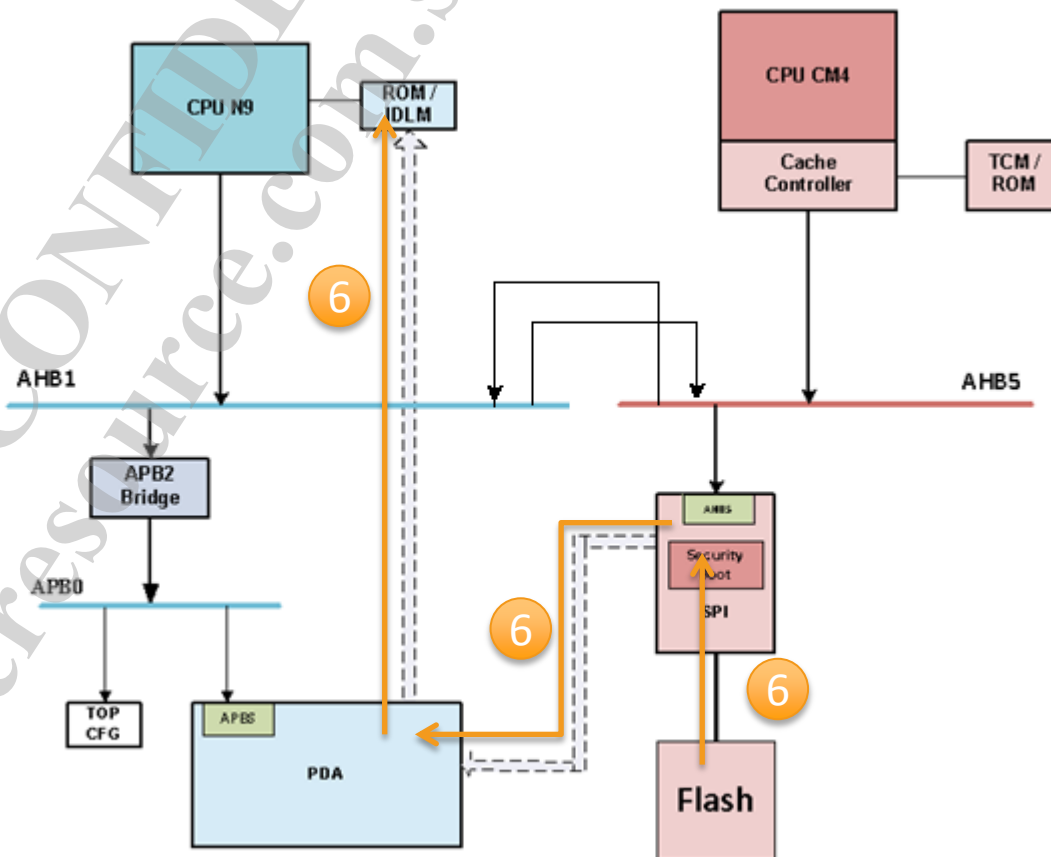
- CM4 :

- set PDA (Patch Decryption Accelerator) cfg. registers for prepare to F/W download
- set SPI cfg. registers for prepare to F/W download



Dual-core platform power sequence

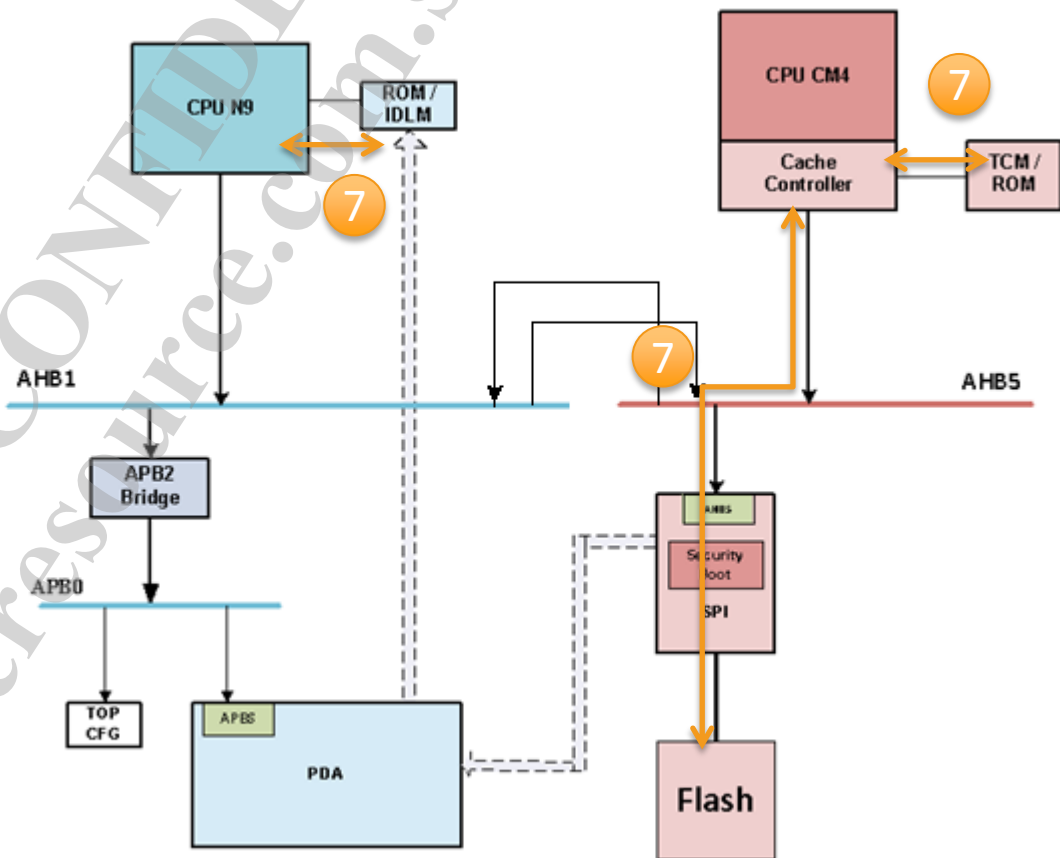
- Step 6:
 - N9 :
 - PDA F/W download, from external flash memory to N9-IDLM.



Dual-core platform power sequence

■ Step 7:

- N9 :
 - execute instructions from IDLM
- CM4 :
 - execute instructions from cache or external flash memory



MT7687 Boot-Up Flow

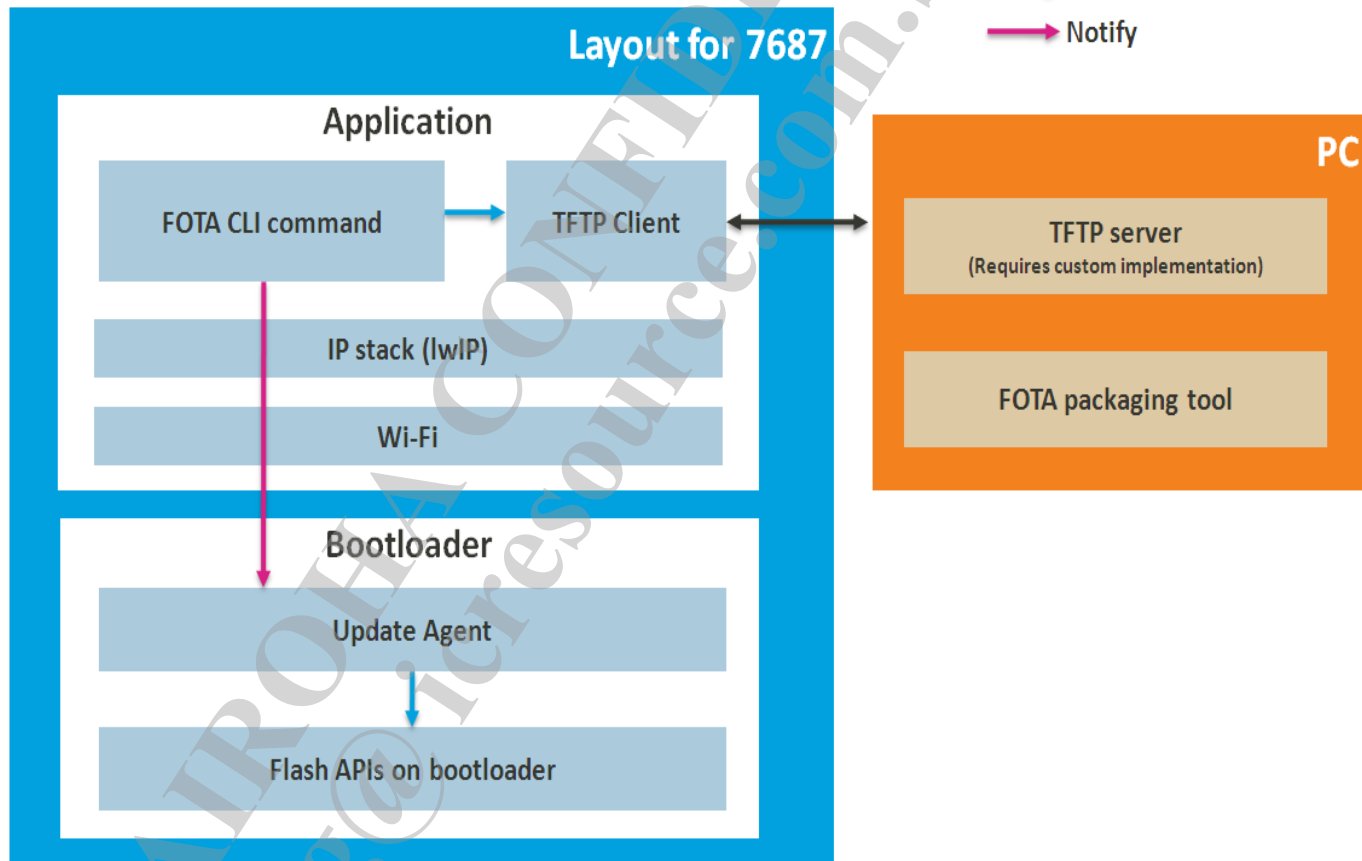


- Step1: ROM Code--- bootstrap check
- Step2: ROM Code--- load loader Image from Flash to RAM
- Step3: Loader --- start run XIP Host driver
- Step4: Host --- load Wi-Fi Firmware to RAM
- Step5: Firmware --- initial Wi-Fi Register start Wi-Fi State Machine
- Step6: Host --- Run Host Task

Appendix 2

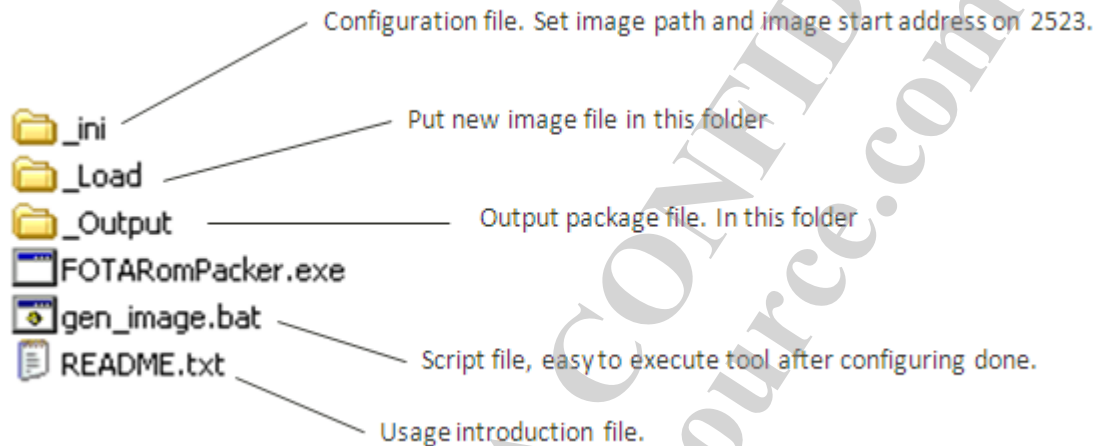
FOTA of MT7687

FOTA architecture layout



Generate Package File

- FOTARomPacker Tool (Win OS)



Path: gva/tools/fota

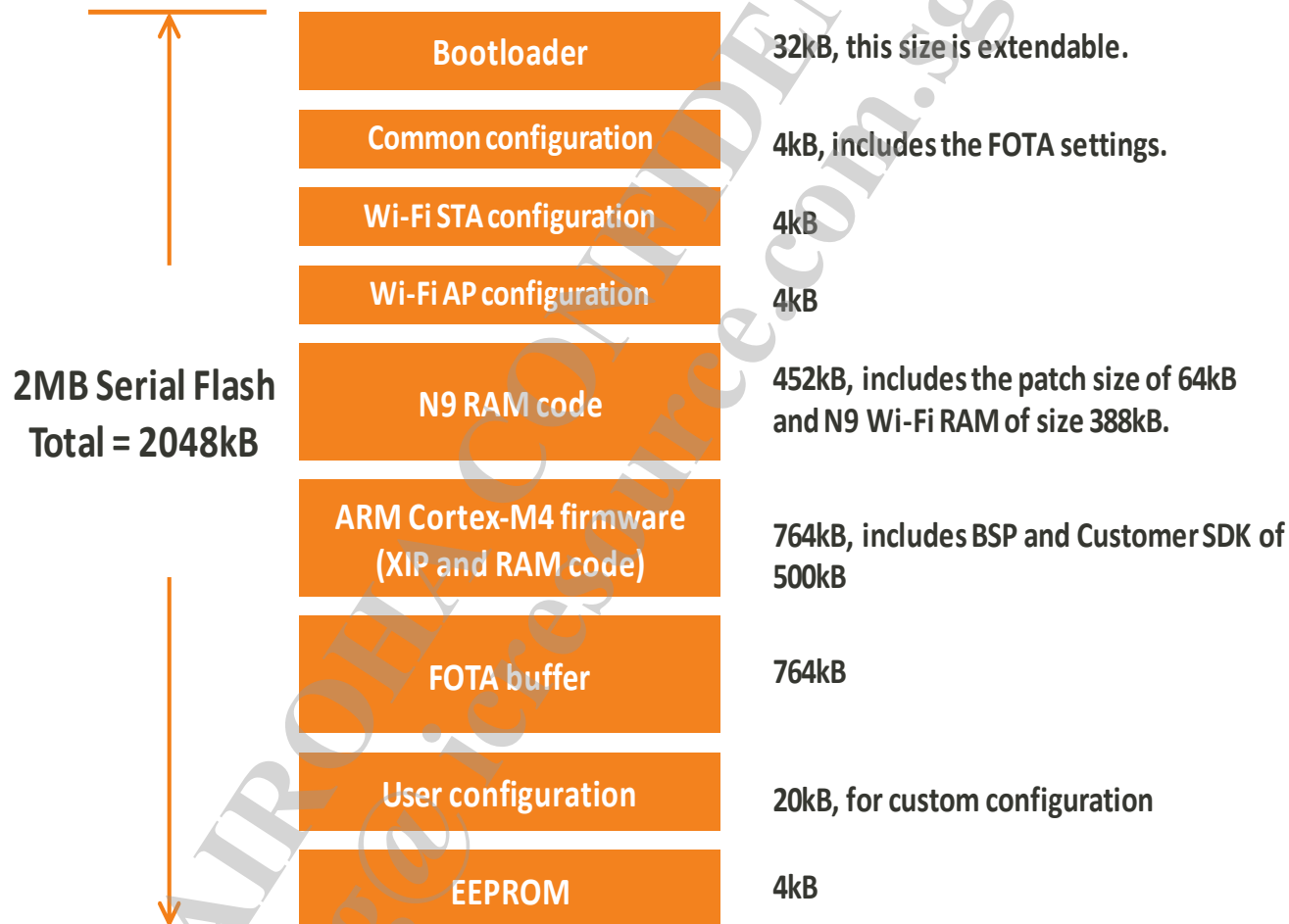
- Follow these steps as below:

- 1. Put new bin in "_Load" folder.
- 2. Configure FOTARomPacker.ini file in "_ini" folder.
 - a) set load path in "general setting" line.
 - b) set bin file name and the start address of this bin in flash. (For 7687, CM4 start addr is 0x7c000)
- 3. Click "gen_image.bat", find the generated FOTA package file in "_Output folder".

Compile options for the FOTA update

Option	Description	Build the ARM Cortex-M4	Build the bootloader
MTK_FOTA_ENABLE	FOTA module on/off	=y	=y
MTK_TFTP_ENABLE	TFTP module on/off	=y	=n
MTK_FOTA_CLI_ENABLE	Command line on/off	=y	=n
MTK_BL_FOTA_LOG_ENABLE	Bootloader logging on/off	=n	=y
MTK_HAL_PLAIN_LOG_ENABLE	HAL debug	=n	=y

FOTA buffer partition configuration

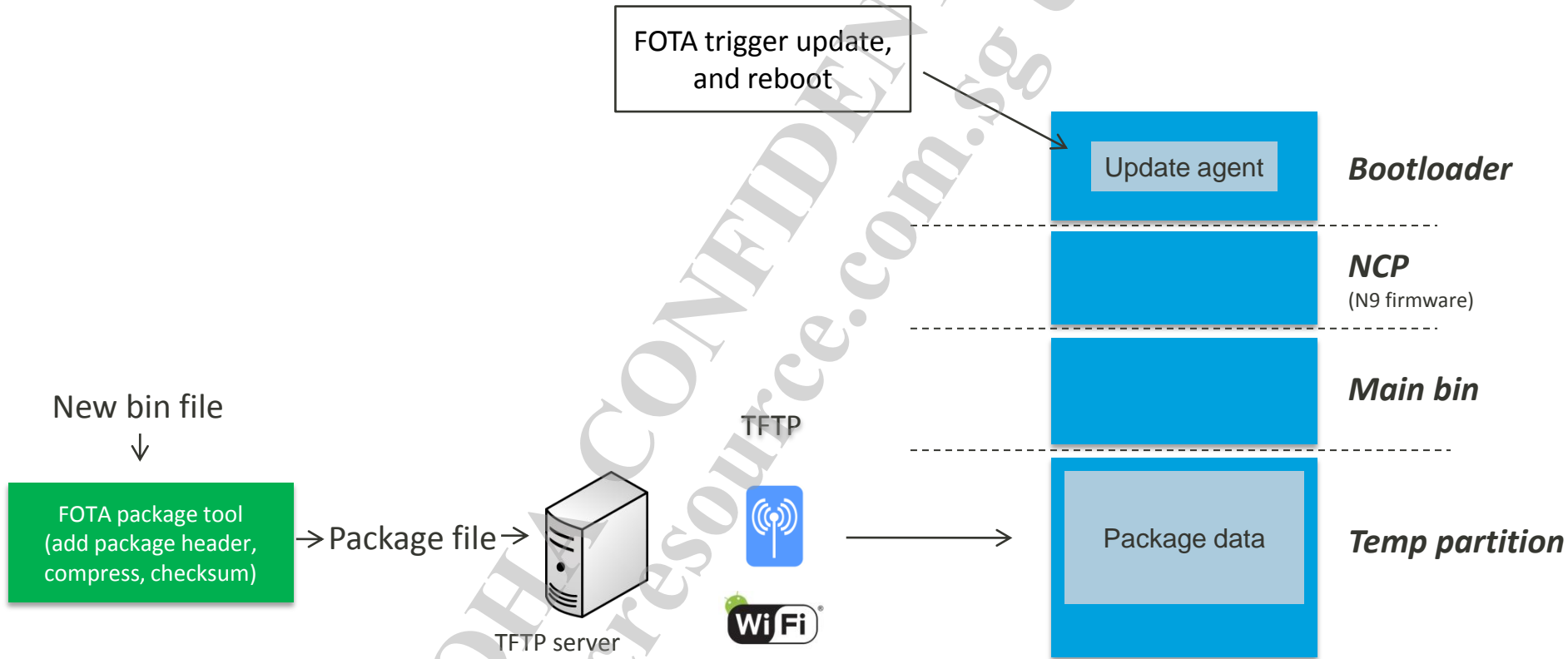


Change the start address and length of the FOTA buffer

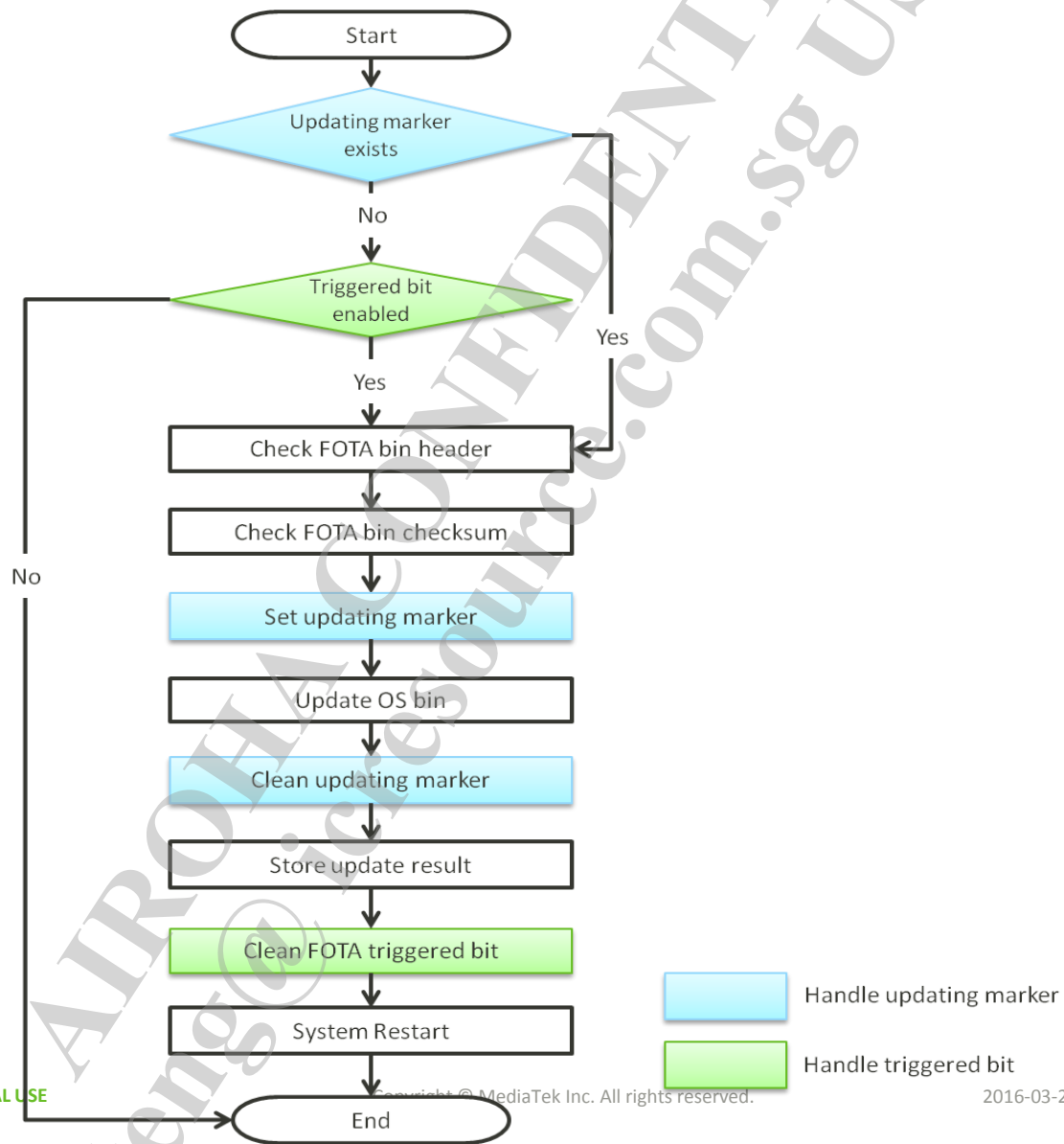
- driver\chip\mt7687\inc\flash_map.h

```
#define FLASH_LOADER_SIZE          0x8000      /* 32kB */
#define FLASH_COMM_CONF_SIZE       0x1000      /* 4kB */
#define FLASH_STA_CONF_SIZE        0x1000      /* 4kB */
#define FLASH_AP_CONF_SIZE         0x1000      /* 4kB */
#define FLASH_N9_RAM_CODE_SIZE     0x71000     /* 452kB */
#define FLASH_CM4_XIP_CODE_SIZE    0xBF000     /* 764kB */
#define FLASH_TMP_SIZE             0xBF000     /* 764kB */
#define FLASH_USR_CONF_SIZE        0x5000      /* 20kB */
#define FLASH_EEPROM_SIZE          0x1000      /* 4kB */
#define CM4_FLASH_LOADER_ADDR      0x0
#define CM4_FLASH_COMM_CONF_ADDR   (CM4_FLASH_LOADER_ADDR + FLASH_LOADER_SIZE)
#define CM4_FLASH_STA_CONF_ADDR    (CM4_FLASH_COMM_CONF_ADDR + FLASH_COMM_CONF_SIZE)
#define CM4_FLASH_AP_CONF_ADDR     (CM4_FLASH_STA_CONF_ADDR + FLASH_STA_CONF_SIZE)
#define CM4_FLASH_N9_RAMCODE_ADDR  (CM4_FLASH_AP_CONF_ADDR + FLASH_AP_CONF_SIZE)
#define CM4_FLASH_CM4_ADDR         (CM4_FLASH_N9_RAMCODE_ADDR + FLASH_N9_RAM_CODE_SIZE)
#define CM4_FLASH_TMP_ADDR         (CM4_FLASH_CM4_ADDR + FLASH_CM4_XIP_CODE_SIZE)
#define CM4_FLASH_USR_CONF_ADDR    (CM4_FLASH_TMP_ADDR + FLASH_USR_CONF_SIZE)
#define CM4_FLASH_EEPROM_ADDR      (CM4_FLASH_USR_CONF_ADDR + FLASH_EEPROM_SIZE)
```

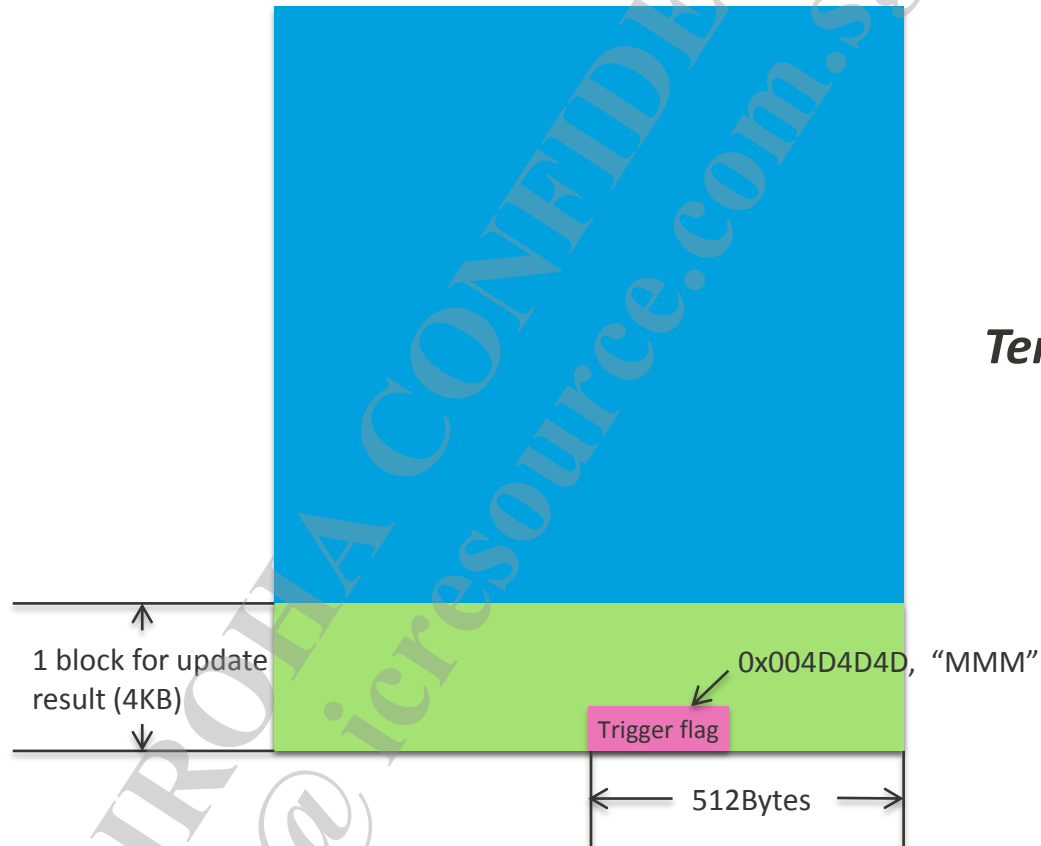
7687 FOTA Scenario



Bootloader Update Flow



Trigger Flag & Update Result



Temp partition

Update result structure:

```
typedef struct {  
    int32_t m_ver;  
    int32_t m_error_code;  
    int32_t m_behavior;  
    int32_t m_is_read;  
    char m_marker[32];  
    int32_t reserved[4];  
} fota_update_info_t;
```