Storage

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Motivation

Secondary Storage

- ► Main memory is usually too small.
- Computer systems must provide secondary storage to back up main memory.

► The file system can be viewed logically as three parts:

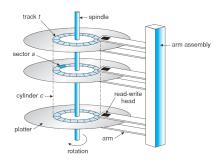
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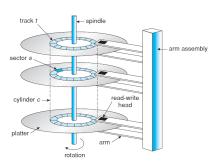
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 - The file systems at the lowest level: the structure of secondary storage.
 - The user and programmer interface to the file system.
 - The internal data structures and algorithms used by the OS to implement this interface.

Overview of Mass-Storage Structure

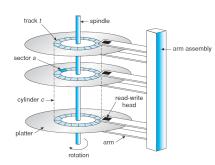
Magnetic disks: bulk of secondary storage



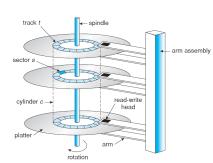
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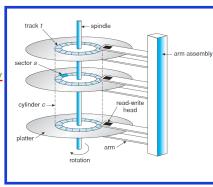


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6 / 64

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- ► The surface of a platter is <u>logically</u> divided into <u>circular tracks</u>, which are subdivided into <u>sectors</u>.
- ► The <u>set of tracks</u> that are at <u>one</u> <u>arm position</u> makes up a <u>cylinder</u>.



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- ► <u>Head crash</u> results from <u>disk head</u> making <u>contact</u> with the <u>disk</u> <u>surface</u>.

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- A disk controller is built into each disk drive.
- ► Host controller in computer uses bus to talk to disk controller built into drive or storage array.

Hard Disks

- ▶ Platters range from 0.85" to 14" (historically).
- ► Commonly 3.5", 2.5", and 1.8".
- ► Range from 30GB to 3TB per drive.

The First Commercial Disk Drive

- ► IBM, 1956
- ▶ 350 disk storage system
- ► 5M
- ightharpoonup Access time ≤ 1 second



Solid-State Disks (SSDs)

- ► Non-volatile memory used like a hard drive.
- ► More expensive per MB.
- Maybe have <u>shorter life span</u>.
- <u>Less capacity</u>, but much <u>faster</u>.
- No moving parts, so no seek time or rotational latency.

Magnetic Tape

- Early secondary-storage medium.
- ► <u>Relatively permanent</u> and holds <u>large quantities of data</u>.
- ► Access time slow.
- ► Random access ~ 1000 times slower than disk.
- Mainly used for backup, storage of infrequently-used data.
- ▶ Once data under head, transfer rates comparable to disk.

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 - Mapping proceeds in order through that track, then the rest of the tracks in that cylinder, and then through the rest of the cylinders from outermost to innermost.
- Logical to physical address should be easy.
 - Except for bad sectors.
 - Non-constant num. of sectors per track via constant angular velocity.

Disk Attachment

Disk Attachment

- ► Host-attached storage
- ► Network-attached storage (NAS)
- ► Storage-area network (SAN)

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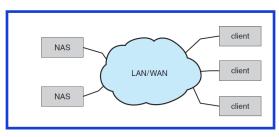
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- SCSI is a bus, up to 16 devices on one cable.
- ► <u>Fiber Channel (FC) is high-speed serial architecture.</u>

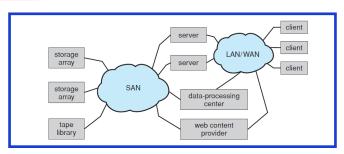
Network-Attached Storage

- ► Network-attached storage (NAS) is storage made available over a network rather than over a local connection.
- ► Remotely attaching to file systems.
- NFS and CIFS are common protocols.
- ► Implemented via remote procedure calls (RPCs) between host and storage over typically TCP or UDP on IP network.



Storage-Area Network

- ► Storage-area network (SAN) is common in large storage environments.
- ► <u>Multiple hosts attached to multiple storage arrays.</u>
- Storage arrays and Hosts are connected to one or more Fibre Channel switches.



Disk Scheduling

- ▶ Having a fast access time and disk bandwidth.
- ► Minimize seek time.
- ► Seek time ≈ seek distance
- ▶ <u>Disk bandwidth</u> is the total number of bytes transferred, divided by the total time between the first request for service and the completion of the last transfer.

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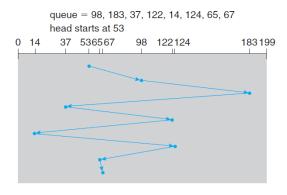
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- ► Note that <u>drive controllers</u> <u>have small buffers</u> and can <u>manage a</u> <u>queue of I/O requests.</u>

Disk Scheduling Algorithms

- ► First Come First Serve (FCFS)
- ► Shortest Seek Time First (SSTF)
- ► SCAN
- C-SCAN
- ► C-Look

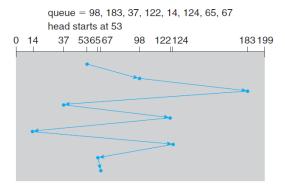
FCFS

- ► Request queue (0-199): 98, 183, 37, 122, 14, 124, 65, 67
- ► Head pointer 53



FCFS

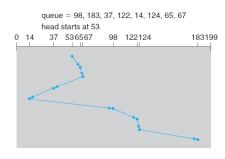
- ► Request queue (0-199): 98, 183, 37, 122, 14, 124, 65, 67
- Head pointer 53
- ► Total head movement: 640 cylinders



► Selects the request with the minimum seek time from the current head position.

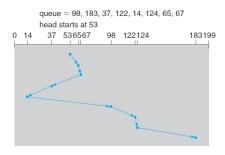
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- ► Selects the request with the minimum seek time from the current head position.
- SSTF scheduling is a <u>form of SJF scheduling</u>; <u>may cause starvation</u> <u>of some requests.</u>
- ► Total head movement: 236 cylinders.

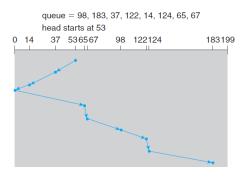


SCAN

- ► Starts from one end of the disk, and moves toward the other end.
 - Servicing requests until it gets to the other end of the disk.
 - At the end of the dist, the head movement is reversed and servicing continues.
- ► SCAN algorithm sometimes is called the elevator algorithm.

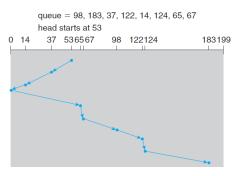
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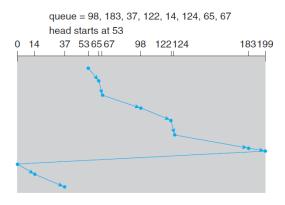
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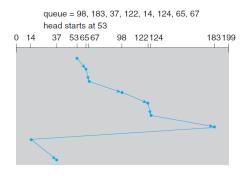
C-SCAN

- ▶ Provides a more uniform wait time than SCAN.
- When it <u>reaches the end</u>, it <u>immediately returns to the beginning of</u> <u>the disk</u> <u>without servicing any requests</u> on the <u>return trip</u>.



Look

- ► LOOK is a version of SCAN, C-LOOK is a version of C-SCAN.
- Arm only goes as far as the last request in each direction, then reverses direction immediately, without first going all the way to the end of the disk.



Selecting a Disk-Scheduling Algorithm

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- ▶ Performance depends on the number and types of requests.

Disk Management

Disk Management

- Disk formatting
- ► Boot block
- ► Bad blocks

- Low-level formatting, or physical formatting: dividing a disk into sectors that the disk controller can read and write.
- ► <u>Each sector can hold header information</u>, <u>data</u>, and <u>error correction</u> <u>code</u> (ECC).
- ▶ Usually 512 bytes of data but can be selectable.

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- Raw disk
 - Use a disk partition as a large sequential array of logical blocks, without any file-system data structures.

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- ► The full bootstrap program is stored in the boot blocks at a fixed location on the disk.

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 - Whenever the system requests logical block 87, the request is translated into the replacement sector's address by the controller.

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- ▶ Less common now due to memory capacity increases.
- It is safer to over-estimate than to under-estimate the amount of swap space

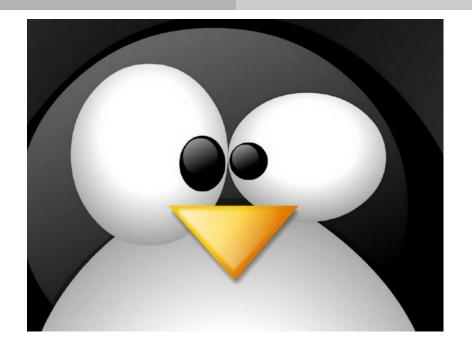
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- It can be in a separate disk partition.
 - A separate raw partition.
 - Optimized for speed rather than for storage efficiency.

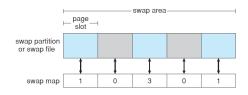


Swap-Space On Linux (1/2)

- ► Either a swap file on a regular file system or a dedicated swap partition.
- ► The swap space is used only for anonymous memory.
 - It is more efficient to reread a page from the file system than to write it to swap space and then reread it from there.

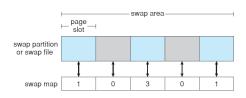
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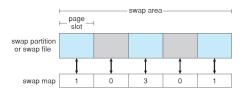
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 - 0: the page slot is available.
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- ► The value indicates the number of mappings to the swapped page.
 - E.g., a value of 3 indicates that the swapped page is mapped to three different processes.



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- A <u>logical disk</u> consists of two physical disks, and <u>every write is carried</u> <u>out on both disks</u>.
- ▶ If one of the disks in the volume fails, the data can be read from the other.

Mean Time to Failure of A Mirrored Volume

- ► Depends on two factors:
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- Example
 - The mean time to failure of a single disk: 100,000 hours
 - The mean time to repair: 10 hours
 - The mean time to data loss of a mirrored disk system: $100,000^2/(2\times10)=500\times10^6$ hours, or 57,000 years!

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 - E.g., if we have an array of eight disks, we write bit *i* of each byte to disk *i*.
- ► <u>Block-level striping</u>: <u>blocks of a file are striped across multiple disks</u>.
 - E.g., with n disks, block i of a file goes to disk $(i \mod n) + 1$.

RAID Levels

- ► RAID is arranged into six different levels.
- RAID schemes improve performance and improve the reliability of the storage system by storing redundant data.

RAID Level 0

► <u>Disk arrays with striping at the level of blocks but without any redundancy.</u>



Disk mirroring



- ► Error-correcting code (ECC)
- ► Each byte is associated with a parity bit
- ▶ It indicates whether the number of bits in the byte set to 1 is even (parity = 0) or odd (parity = 1).



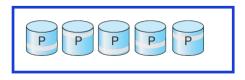
- ► A single parity bit can be used for error detection and correction.
- ▶ If one of the <u>sectors is damaged</u>, <u>we know exactly which sector it is</u>
- We can figure out whether any bit in the sector is a 1 or a 0 by computing the parity of the corresponding bits from sectors in the other disks.



- Block-level striping, as in RAID 0.
- ► Keeps a parity block on a separate disk for corresponding blocks from N other disks.



► Spreads data and parity among all N+1 disks, rather than storing data in N disks and parity in one disk.

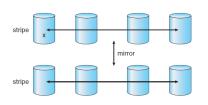


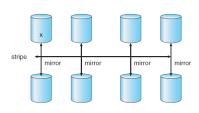
► <u>Like RAID level 5</u> but stores extra redundant information to guard against multiple disk failures.



RAID Level 0 + 1 and 1 + 0

- ▶ 0 + 1: RAID 0 provides the performance, while RAID 1 provides the reliability.
- ▶ 1 + 0: disks are mirrored in pairs and then the resulting mirrored pairs are striped.





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- Write-ahead log (WAL) scheme requires stable storage.
- ► In a system using WAL, <u>all modifications are written to a log before they are applied.</u>

- ► To implement stable storage:
- ► Replicate information on more than one nonvolatile storage media with independent failure modes.
- Update information in a controlled manner to ensure that we can recover the stable data after any failure during data transfer or recovery.

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- ► <u>Total failure</u>: the <u>failure</u> occurred <u>before the disk write started</u>, so the previous data values on the disk remain intact.

► If failure occurs during block write, recovery procedure restores block to consistent state.

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- System maintains two physical blocks per logical block and does the following:
 - Write to 1st physical
 - 2 When successful, write to 2nd physical
 - 3 <u>Declare complete</u> only after then second write completes successfully

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- ► RAID: RAID0-RAID6

Questions?

Acknowledgements

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