

In [5]:

```
import torch
import torchvision
import numpy as np
import matplotlib.pyplot as plt
import torch.nn as nn
import torch.nn.functional as F

from torchvision.transforms import import ToTensor
from torchvision.utils import import make_grid
from torch.utils.data.dataloader import import DataLoader
from torch.utils.data import import random_split
import os
from torchvision.datasets import import ImageFolder
import torchvision.transforms as tr
from tqdm import tqdm
from torch.utils.data.dataloader import import DataLoader
import torch.nn as nn
import torch.nn.functional as F
import matplotlib.pyplot as plt
matplotlib inline
```

In [7]:

```
! pip install -q kaggle
from google.colab import files
files.upload()
! mkdir ~/.kaggle
! cp kaggle.json ~/.kaggle/
! chmod 600 ~/.kaggle/kaggle.json
```

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Saving kaggle.json to kaggle.json

In [8]:

```
! kaggle datasets download grassknotted/asl-alphabet
! unzip asl-alphabet.zip
```


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```
def validation_err(self, batch):
    images, labels = batch
    images, labels = images.to(device), labels.to(device)
    out = self(images)           # Generate predictions
    loss = F.cross_entropy(out, labels)   # Calculate loss
    acc = accuracy(out, labels)   # Calculate accuracy
    return ('val_loss': loss.detach(), 'val_acc': acc)

def validation_epoch_end(self, outputs):
    bt_loss = [x['val_loss'] for x in outputs]
```

```

        ep_loss = torch.stack(bt_loss).mean() # Combine losses
        bt_accuracy = [x['val_acc'] for x in outputs]
        ep_accuracy = torch.stack(bt_accuracy).mean() # Combine accuracies
        return {'val_loss': ep_loss.item(), 'val_acc': ep_accuracy.item()}

def epoch_end(self, epoch, result):
    print(f"Epoch [{epoch}, result['lrs']={lrs}]" )
    print(f"Last lr: {result['train_loss']}")
    print(f"train_loss: {result['val_loss']}")
    print(f"val_acc: {result['val_acc']}")

def conv_block(in_channels, out_channels, pool=False):
    layers = [
        nn.Conv2d(in_channels, out_channels, kernel_size=3, padding=1),
        nn.BatchNorm2d(out_channels),
        nn.ReLU(inplace=True)]
    if pool: layers.append(nn.MaxPool2d(2))
    return nn.Sequential(*layers)

class ResNet(ImageClassificationBase):
    def __init__(self, in_channels, num_cls):
        super().__init__()

        self.conv1 = conv_block(in_channels, 64)
        self.conv2 = conv_block(64, 128, pool=True)
        self.res1 = nn.Sequential(conv_block(128, 128), conv_block(128, 128))

        self.conv3 = conv_block(128, 256, pool=True)
        self.conv4 = conv_block(256, 512, pool=True)
        self.res2 = nn.Sequential(conv_block(512, 512), conv_block(512, 512))

        self.classifier = nn.Sequential(nn.MaxPool2d(4),
                                       nn.Flatten(),
                                       nn.Linear(512, num_cls))

    def forward(self, xb):
        xb = xb.to(device)
        out = self.conv1(xb)
        out = self.conv2(out)
        out = self.res1(out) + out
        out = self.conv3(out)
        out = self.conv4(out)
        out = self.res2(out) + out
        out = self.classifier(out)
        return out

def get_default_device():
    if torch.cuda.is_available():
        return torch.device('cuda')
    else:
        return torch.device('cpu')

def to_device(data, device):
    if isinstance(data, (list,tuple)):
        return [to_device(x, device) for x in data]
    return data.to(device, non_blocking=True)

device = get_default_device()
model = to_device(ResNet(3, 29), device)

@torch.no_grad()
def evaluate(model, v_l):
    model.eval()
    outputs = [model.validation_step(batch) for batch in tqdm(v_l)]
    return model.validation_epoch_end(outputs)

def get_lr(optimizer):
    for param_group in optimizer.param_groups:
        return param_group['lr']

def fit_one_cycle(epochs, max_lr, model, t_l, v_l,
                 weight_decay=0, grad_clip=None, opt_func=torch.optim.SGD):
    torch.cuda.empty_cache()
    history = []
    optimizer = opt_func(model.parameters(), max_lr, weight_decay=weight_decay)
    sched = torch.optim.lr_scheduler.OneCycleLR(optimizer, max_lr, epochs=epochs,
                                                steps_per_epoch=len(t_l))

    for epoch in range(epochs):
        model.train()
        train_losses = []
        lrs = []
        for batch in tqdm(t_l):
            loss = model.training_step(batch)
            train_losses.append(loss)
            loss.backward()
            if grad_clip:
                nn.utils.clip_grad_value_(model.parameters(), grad_clip)
            optimizer.step()
            optimizer.zero_grad()
            lrs.append(get_lr(optimizer))
            sched.step()
            result = evaluate(model, v_l)
            result['train_loss'] = torch.stack(train_losses).mean().item()
            result['lrs'] = lrs
            model.epoch_end(epoch, result)
            history.append(result)
        return history
    model = to_device(ResNet(3, 29), 'cuda')
    history = [evaluate(model, train_dl)]

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28%	<div><div></div></div>	618/2175 [00:27<01:09, 22.27it/s]
29%	<div><div></div></div>	621/2175 [00:27<01:10, 22.12it/s]
29%	<div><div></div></div>	624/2175 [00:27<01:09, 22.31it/s]
29%	<div><div></div></div>	627/2175 [00:28<01:10, 22.04it/s]
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29%	<div><div></div></div>	633/2175 [00:28<01:09, 22.05it/s]
29%	<div><div></div></div>	636/2175 [00:28<01:09, 22.21it/s]
29%	<div><div></div></div>	639/2175 [00:28<01:08, 22.40it/s]
30%	<div><div></div></div>	642/2175 [00:28<01:09, 22.11it/s]
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31%	<div><div></div></div>	669/2175 [00:29<01:09, 21.80it/s]
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35%	<div><div></div></div>	771/2175 [00:34<01:04, 21.76it/s]
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54%	<div></div>	1185/2175 [00:53<00:44, 22.30it/s]
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98%	<div></div>		2121/2175	[01:36<00:02, 21.351t/s]
98%	<div></div>		2124/2175	[01:37<00:02, 20.771t/s]
98%	<div></div>		2127/2175	[01:37<00:02, 20.261t/s]
98%	<div></div>		2130/2175	[01:37<00:02, 20.791t/s]
98%	<div></div>		2133/2175	[01:37<00:01, 21.011t/s]
98%	<div></div>		2136/2175	[01:37<00:01, 21.281t/s]
98%	<div></div>		2139/2175	[01:37<00:01, 21.571t/s]
98%	<div></div>		2142/2175	[01:37<00:01, 21.631t/s]
99%	<div></div>		2145/2175	[01:38<00:01, 21.441t/s]
99%	<div></div>		2148/2175	[01:38<00:01, 21.471t/s]
99%	<div></div>		2151/2175	[01:38<00:01, 21.651t/s]
99%	<div></div>		2154/2175	[01:38<00:00, 21.701t/s]
99%	<div></div>		2157/2175	[01:38<00:00, 21.811t/s]
99%	<div></div>		2160/2175	[01:38<00:00, 21.841t/s]
99%	<div></div>		2163/2175	[01:38<00:00, 21.811t/s]
100%	<div></div>		2166/2175	[01:39<00:00, 21.511t/s]
100%	<div></div>		2169/2175	[01:39<00:00, 21.631t/s]
100%	<div></div>		2172/2175	[01:39<00:00, 21.591t/s]
100%	<div></div>		2175/2175	[01:39<00:00, 21.861t/s]

In [27]:
epochs = 10
max_lr = 0.01
grad_clip = 0.1
weight_decay = 1e-3
opt_func = torch.optim.Adam
history = fit_one_cycle(epochs, max_lr, model, train_dl, val_dl,
grad_clip=grad_clip, weight_decay=weight_decay,
opt_func=opt_func)

100%	<div></div>		2175/2175	[01:41<00:00, 21.341t/s]
100%	<div></div>		136/136	[00:13<00:00, 11.851t/s]
Epoch [6, 0.002798665629987097] last_lr: 0.067774448184967 train_loss: 0.0770070352839277 Val_Acc: 0.9766544103622437				
100%	<div></div>		2175/2175	[01:41<00:00, 21.441t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.951t/s]
Epoch [7, 0.007199312223111261] last_lr: 0.1365942806005478 train_loss: 0.19132007638481598 Val_Acc: 0.932182087174619				
100%	<div></div>		2175/2175	[01:41<00:00, 21.491t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.971t/s]
Epoch [8, 0.011] last_lr: 0.1645561009645462 train_loss: 0.18587693572044373 Val_Acc: 0.941130518913269				
100%	<div></div>		2175/2175	[01:41<00:00, 21.461t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.841t/s]
Epoch [9, 0.0153204813598565] train_loss: 0.420965313911439 Val_Acc: 0.8651731014251709				
100%	<div></div>		2175/2175	[01:41<00:00, 21.401t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.981t/s]
Epoch [4, 0.008117456394976311] last_lr: 0.13089573383113 train_loss: 0.1570256401090622 Val_Acc: 0.9456341862678528				
100%	<div></div>		2175/2175	[01:41<00:00, 21.371t/s]
100%	<div></div>		136/136	[00:13<00:00, 12.041t/s]
Epoch [5, 0.0061126202193628929] last_lr: 0.105443902004242 train_loss: 0.05997134745121002 Val_Acc: 0.9821920990943909				
100%	<div></div>		2175/2175	[01:46<00:00, 20.341t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.511t/s]
Epoch [6, 0.00188258340602377] last_lr: 0.03509835364127159 train_loss: 0.0695546492934227 Val_Acc: 0.9713455771160274				
100%	<div></div>		2175/2175	[01:44<00:00, 20.811t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.921t/s]
Epoch [7, 0.00188258340602377] last_lr: 0.03509835364127159 train_loss: 0.0595978832244873 Val_Acc: 0.995978832244873				
100%	<div></div>		2175/2175	[01:41<00:00, 21.391t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.961t/s]
Epoch [8, 0.0044951936798652628] last_lr: 0.01259528752161723 train_loss: 0.00473833391342177 Val_Acc: 0.999540481807817				
100%	<div></div>		2175/2175	[01:41<00:00, 21.461t/s]
100%	<div></div>		136/136	[00:11<00:00, 11.901t/s]
Epoch [9, 4e-08] last_lr: 0.004993821028620003 train_loss: 0.002878863455694914 Val_Acc: 0.999885082244873				

In [28]: torch.save(model.state_dict(), 'reset9.pth')
#this model is used in realtime prediction

In [30]: model = to_device(netlet(3, 29), 'cuda')
model.load_state_dict(torch.load('reset9.pth', map_location='cpu'))
model.eval()
print(evaluate(model, val_dl))

0%	<div></div>		0/136	[00:00<00:0, 71t/s]
1%	<div></div>		2/136	[00:00<00:012, 10.671t/s]
4%	<div></div>		4/136	[00:00<00:015, 8.491t/s]
6%	<div></div>		6/136	[00:00<00:015, 9.441t/s]
7%	<div></div>		8/136	[00:00<00:012, 10.301t/s]
9%	<div></div>		10/136	[00:00<00:011, 10.571t/s]
12%	<div></div>		12/136	[00:01<00:011, 10.651t/s]
14%	<div></div>		14/136	[00:01<00:011, 10.731t/s]
16%	<div></div>		16/136	[00:01<00:010, 10.971t/s]
18%	<div></div>		18/136	[00:01<00:010, 11.201t/s]
20%	<div></div>		20/136	[00:01<00:010, 11.211t/s]
22%	<div></div>		22/136	[00:02<00:010, 11.311t/s]
24%	<div></div>		24/136	[00:02<00:009, 11.401t/s]
26%	<div></div>		26/136	[00:02<00:009, 11.391t/s]
28%	<div></div>		28/136	[00:02<00:009, 11.231t/s]
30%	<div></div>		30/136	[00:02<00:009, 11.231t/s]
32%	<div></div>		32/136	[00:02<00:009, 11.431t/s]
34%	<div></div>		34/136	[00:03<00:008, 11.401t/s]
36%	<div></div>		36/136	[00:03<00:008, 11.541t/s]
38%	<div></div>		38/136	[00:03<00:008, 11.491t/s]
40%	<div></div>		40/136	[00:03<00:007, 11.551t/s]
42%	<div></div>		42/136	[00:04<00:007, 11.581t/s]
44%	<div></div>		44/136	[00:04<00:007, 11.521t/s]
46%	<div></div>		46/136	[00:04<00:007, 11.331t/s]
48%	<div></div>		48/136	[00:04<00:007, 11.171t/s]
50%	<div></div>		50/136	[00:05<00:007, 11.221t/s]
52%	<div></div>		52/136	[00:05<00:006, 11.371t/s]
54%	<div></div>		54/136	[00:05<00:006, 11.361t/s]
56%	<div></div>		56/136	[00:05<00:006, 11.341t/s]
58%	<div></div>		58/136	[00:05<00:005, 11.451t/s]
60%	<div></div>		60/136	[00:05<00:005, 11.361t/s]
62%	<div></div>		62/136	[00:05<00:004, 11.521t/s]
64%	<div></div>		64/136	[00:05<00:004, 11.371t/s]
66%	<div></div>		66/136	[00:05<00:004, 11.031t/s]
68%	<div></div>		68/136	[00:05<00:003, 11.181t/s]
70%	<div></div>		70/136	[00:05<00:003, 11.311t/s]
72%	<div></div>		72/136	[00:05<00:003, 11.361t/s]
74%	<div></div>		74/136	[00:05<00:002, 11.461t/s]
76%	<div></div>		76/136	[00:05<00:002, 11.591t/s]
78%	<div></div>		78/136	[00:05<00:002, 11.351t/s]
80%	<div></div>		80/136	[00:05<00:002, 11.491t/s]
82%	<div></div>		82/136	[00:05<00:002, 11.511t/s]
84%	<div></div>		84/136	[00:05<00:001, 11.371t/s]
86%	<div></div>		86/136	[00:05<00:001, 11.261t/s]
88%	<div></div>		88/136	[00:05<00:001, 11.401t/s]
90%	<div></div>		90/136	[00:05<00:001, 11.201t/s]
92%	<div></div>		92/136	[00:05<00:001, 11.401t/s]
94%	<div></div>		94/136	[00:05<00:001, 11.521t/s]
96%	<div></div>		96/136	[00:05<00:001, 11.331t/s]
98%	<div></div>		98/136	[00:05<00:001, 11.481t/s]
100%	<div></div>		100/136	[00:05<00:000, 11.281t/s]
!Val_loss: 0.002872863455694914, 'val_acc': 0.999885082244873				

In []: