

# CS 1511 Homework 22

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Fri, April 5

**43.**

**44 a.** Alice can perform rotations that are multiples of  $\pi/4$ . Take the value of  $x$  and  $y$  combined and use those to determine how many degrees to rotate the qubit by. Say  $x=0$ ,  $y=0$ , then rotate the qubit by 0 degrees.  $x=0$ ,  $y=1$ , then rotate by  $\pi/4$  degrees. If  $x=1$ ,  $y=0$ , rotate by  $2\pi/4$ . If  $x=1$ ,  $y=1$ , rotate by  $3\pi/4$  degrees.

**44 b.** The state of  $b$  will be unchanged, because Alice performed rotations only on the first qubit. The state of  $a$  will now be dependent on the value of  $x$  and  $y$ .

**44 c.**

If  $a = 0^n$ , Simon's algorithm still works. This is because if the function is one-to-one, and  $a = 0^n$ , after we compute  $|xz\rangle \rightarrow |x(y \oplus f(x))\rangle$  we can measure  $|x \oplus a\rangle$  and see that it's equivalent to  $x$ . This will let us know that  $a = 0^n$ . We will therefore have correctly computed  $a$ . Or, if we continue Simon's algorithm, we will eventually be finding  $k$  linear equations for  $y \odot a = 0$  with a uniform string for  $y$  that makes this true. In this case, every single one of these  $y$ 's will work. Solving the linear equations will give us that all values of  $a$  are 0, which is true.

**44 a.** To get the Bell state  $1/\sqrt{2} |0\rangle + 1/\sqrt{2} |1\rangle$ , Alice can perform a rotation of  $\pi/4$  to her qubit. This could be when  $x=0$  and  $y=0$ .

To get the Bell state  $1/\sqrt{2} |0\rangle - 1/\sqrt{2} |1\rangle$ , Alice can perform a rotation of  $-\pi/4$  to her qubit. This could be when  $x=0$  and  $y=1$ .

To get the Bell state  $-1/\sqrt{2} |0\rangle + 1/\sqrt{2} |1\rangle$ , Alice can perform a rotation of  $3\pi/4$  to her qubit. This could be when  $x=1$  and  $y=0$ .

To get the Bell state  $-1/\sqrt{2} |0\rangle - 1/\sqrt{2} |1\rangle$ , Alice can perform a rotation of  $-3\pi/4$  to her qubit. This could be when  $x=1$  and  $y=1$ .

So basically, Alice will want to rotate by  $\pi/4$  when  $x=0$  and rotate by  $3\pi/4$  when  $x=1$ . If  $y=1$  then this rotation is negative, otherwise it's positive.

**44 b.**

The state of  $a$  and  $b$  will be as described above, depending on the values of  $x$  and  $y$ .

**44 c.**

If we apply a hadamard operation to the state of  $a$  and  $b$ , we can find  $x$  from examining the vector that is created after the operation. We can find  $y$  by taking the negation of  $x$ .