# EE5121 CVX Assignment Report

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#### 1 Implementation Details

- All questions have been done in **python 3.6**
- Run as : python q\_x.py
- Install packages as: pip install -r requirements.txt
- All plots are saved to the **logs** directory.

#### 2 Q1

We formulate the problem as follows:

$$\min_{x} \qquad \min||y - x||^2 \tag{1a}$$

subject to 
$$||Ax||_1 \le b.$$
 (1b)

This is not in the standard SOCP form. In order to recast it appropriately, we modify it as: (mainly in the epigraph form)

$$\min_{t}$$
 $(2a)$ 

$$\min_{t} \qquad t \tag{2a}$$
 subject to 
$$||y-x||^2 < t^2, \tag{2b}$$

$$||a_j^T x||_1 <= t_i \quad \forall i \in \{1, 2, ..., n-1\},$$
 (2c)

$$\sum_{i=1}^{n-1} t_i <= b. (2d)$$

We tune b such that only 20 jumps are observed in the resultant estimate. (Notice that b=20is an overestimate of the constraint, since the L1 convex relaxation is a slack approximation to L0).

Here, A is the matrix as indicated in the question's hint. We observe the following plot with b = 5.3825. The error is around 15.211 and the L1 value is around b. Note that as b decreases, the error increases. Hence, there is a trade-off between MSE and jumps in the signal (very much similar to the bias-variance trade-off). So we choose the maximum b which preserves 20 jumps. We

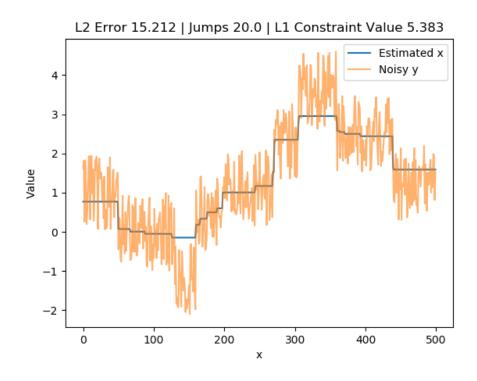


Figure 1: Plot of  $\hat{x}$  and noisy y. We have indicated the error and L1 constraint value.

```
Terminal: Local × +

Consumption levels: [50.5 94.5 100. 100. 100.]

INFO - q2-LP - Completed after 0:00:00

(torch) [~/Documents/SEM-6/convex_optim/cvx_assign]$ python q1.py

wARNING - q1-SOCP - No observers have been added to this run

INFO - q1-SOCP - Running command 'main'

INFO - q1-SOCP - Started

(499, 500)

20.0

Status: optimal

L2 Error 15.211570633234606

L1 Constraint Value 5.3825000046806455

L1 Constraint Value 5.3825000046806455

L1 Constraint Value 5.3825000046806455

L1 Constraint Value 5.38250000468064509

No of jumps 20.0
```

Figure 2: Screen-shot of question 1

arrive at our chosen value of b via a binary grid-search.

Notice the fact that computing jumps visually is slightly ambiguous, the "jumps" are of order 0.8. So we do this by  $||Ax||_0$ , using numpy, an d consider anything > 0.01 as a jump (ie... tolerance is 0.01).

## 3 Q2

We formulate the following LP:

```
Terminal: Local x +

No of jumps 20.0

INFO - q1-50CP - Completed after 0:00:30
(torch) [-/Documents/SEM-6/convex_optim/cvx_assign]$ python q2.py

WARNING - q2-LP - No observers have been added to this run

INFO - q2-LP - Started

Status: optimal

Revenue: 192.5

Activity Levels: [ 4. 22.5 31. 1.5]

Revenue per component: [ 12. 32.5 139. 9. ]

Average price per unit for each activity level [ 3. [ 1.4444444 4.48387097 6. ]

Consumption levels: [ 50.5 94.5 100. 100. 100. ]

INFO - q2-LP - Completed after 0:00:00

(torch) [ -/Documents/SEM-6/convex_optim/cvx_assign]$

rvm:
```

Figure 3: Screen-shot of question 2

$$\min_{t,x} 1^{T}t \qquad (3a)$$
subject to 
$$t_{j} \leq p_{j} * x_{j} \quad \forall j \in \{1, 2, 3, 4\}, \qquad (3b)$$

$$t_{j} \leq p_{j} * q_{j} + p_{disc} * (x_{j} - q_{j}) \quad \forall j \in \{1, 2, 3, 4\}, \qquad (3c)$$

$$Ax \leq c_{max}, \qquad (3d)$$

$$0 \leq x. \qquad (3e)$$

We obtain the following optimal values:

- Revenue: 192.5
- Activity Levels: [4, 22.5, 31., 1.5]
- Revenue per component: [12., 32.5, 139., 9.]
- Average price per unit for each activity level: [3., 1.4444444, 4.48387097, 6.]

We make the following observations:

- Consumption levels are met for  $c_{3,4,5}$ .
- Discounted price is used for  $x_{2,3}$ . By noting the average price per unit activity.
- Activity levels cross the threshold for  $x_{2,3}$ .
- Further, revenue per component is max for  $x_{2,3}$ .

### 4 Q3

With the convex relaxation of rank and the lemma provided to constrain rank, we obtain the following SDP formulation:

```
Terminal: Local × +

INFO - q2-LP - Completed after 0:00:01
(torch) [-/Documents/SEM-6/convex_optim/cvx_assign]$ python q3.py
WARRING - q3-SDP - No observers have been added to this run
INFO - q3-SDP - Running command 'main'
INFO - q3-SDP - Started
(88, 88)
Status: optimal
Value of r: 337.1089691146928
Actual rank (via np.linalg): 19
INFO - q3-SDP - Completed after 0:00:00
(torch) [-/Documents/SEM-6/convex_optim/cvx_assign]$
rvm:
```

Figure 4: Screen-shot of question 3

$$\min_{r,\hat{X},Y,Z} \qquad r \tag{4a}$$

subject to 
$$tr(Y) + tr(Z) \le 2r$$
 (4b)

$$\hat{X}_{i,j} = X_{i,j} \quad \forall i, j \in J \quad \text{set of non-zero entries of } X,$$
 (4c)

$$\begin{pmatrix} Y & X \\ X^T & Z \end{pmatrix} \ge 0, \tag{4d}$$

$$Y \ge 0. \tag{4e}$$

$$Z \ge 0. \tag{4f}$$

We obtain the rank to be 19, by using **np.linalg.matrix\_rank** by thresholding to 1e - 6.

Note that the optimisation formulation is cast in the epigraph form - we may also eliminate r entirely and recast as:

$$\min_{\hat{X},Y,Z} tr(Y) + tr(Z)$$
(5a)

$$\hat{X}_{i,j} = X_{i,j} \quad \forall i, j \in J \quad \text{set of non-zero entries of } X,$$
 (5b)

$$\begin{pmatrix} Y & X \\ X^T & Z \end{pmatrix} \ge 0, \tag{5c}$$

$$Y \ge 0. \tag{5d}$$

$$Z \ge 0.$$
 (5e)