

Exercise-3: Handling Parallel I/O Ports

- P0 / P1 / P2 / P3 – Detailed pin and port internal descriptions and functionalities

Sample Hands-on exercises for IO ports:

- Send 8b hex number to port 0
- Send 8b binary numbers (0 – 9) to port 2 repetitively
- Send ASCII characters 'A' '@', '!', '*' to P0, p1, p 2, p3
- Toggle 8b of port 1
- Toggle Alternate bits of port1
- Toggle MSB bit of Port1
- Toggle LSB bit of Port 1
- Left shift data at port 1 repetitively
- Receive 8b data from P0 and p1. AND data and send result to port 2
- Receive 1b data from P0.0 and P1.3. AND the bits and send result to P2.0
- Receive 1b data from P0.0 and P1.2. AND the bits and send result to P2.7
- (Rx and check condition) Rx data from port0; if 20H send FFH to port2 else send 00H to port3

Bubble Sort

- Pseudocode
- Debugging and output in keil
- Hands On
 - Debugging of bubble sort in keil
 - Watch Window
 - Memory Window
 - Stepping through the code
 - Call Stack
 - Disassembly
 - Performance Analyzer
 - Logic Analyzer
 - Output view on ports and memory window

Generate a Square wave on a port pin

```
#include <REGx51.h> //header file for 89C51
void main(){
    //main function starts
    unsigned int i;
    //Initializing Port1 pin1
    P1_1 = 0; //Make Pin1 o/p
    while(1){
        //Infinite loop main application
        //comes here
        for(i=0;i<1000;i++)
            ; //delay loop
        P1_1 = ~P1_1;
        //complement Port1.1
        //this will blink LED connected on Port1.1
    }
}
```

Write a program to make 8 to 1 multiplexer with enable signal

```
#include<reg51.h>

sbit D0 = P0^0;           // set P0.0-P0.7 (D0-D7) as input pins of mux
sbit D1 = P0^1;
sbit D2 = P0^2;
sbit D3 = P0^3;
sbit D4 = P0^4;
sbit D5 = P0^5;
sbit D6 = P0^6;
sbit D7 = P0^7;
sbit S0 = P1^0;           // set P1.0-P1.2(S0-S2) as select pins of mux
sbit S1 = P1^1;
sbit S2 = P1^2;
sbit EN = P1^7;           // set P1.7 as enable pin
sbit pin = P3^5;          // set P3.5 as output

main()
{
    P3=0x00;P0=0xFF;      // clear op and set all ips
    TMOD = 0x01;          // set timer 0 for 16 bit timer
next:TL0 = 0xAF;           // load count
    TH0 = 0x3C;
    while(EN==1){ }       // wait till enable pin becomes 0
    if((S0==0)&&(S1==0)&&(S2==0)) pin = D0;          // if select inputs are 000 op is
first ip
    else if((S0==1)&&(S1==0)&&(S2==0)) pin = D1;      // if select inputs are 001 op is
second ip
    else if((S0==0)&&(S1==1)&&(S2==0)) pin = D2;      // same as above
    else if((S0==1)&&(S1==1)&&(S2==0)) pin = D3;
    else if((S0==0)&&(S1==0)&&(S2==1)) pin = D4;
    else if((S0==1)&&(S1==0)&&(S2==1)) pin = D5;
    else if((S0==0)&&(S1==1)&&(S2==1)) pin = D6;
    else if((S0==1)&&(S1==1)&&(S2==1)) pin = D7;
    else pin = 0;          // by default op is cleared
    TR0 = 1;              // start timer 0
    while(TF0==0){ }      // wait until overflow means
50ms
    TR0 = 0;              // stop timer
    goto next;            // go for next input
}
```

Take parallel input from port P1 convert it into serial and send it via P0.0

```
#include<reg51.h>
sbit sout = P0^0;           // serial out on P0.0
sbit D0 = P1^0;             // parallal input from P1 (D0-D7)
sbit D1 = P1^1;
sbit D2 = P1^2;
sbit D3 = P1^3;
sbit D4 = P1^4;
sbit D5 = P1^5;
sbit D6 = P1^6;
sbit D7 = P1^7;
int i;
void delay(void);           // 1 ms delay

main()
{
    for(i=0;i<8;i++)        // rotate loop for 8 times
    {
        sout = D0;          // first bit out
        D0 = D1;            // shift all bits in sequence
        D1 = D2;
        D2 = D3;
        D3 = D4;
        D4 = D5;
        D5 = D6;
        D6 = D7;
        delay();            // generate 1 ms delay after each bit shifted
    }
}

void delay()
{
    int k
    for(k=0;k<1000;k++);
}
```

Write a program to transmit and receive data via ports as well as control a load by reading switch input

```
#include <REGX51.H>

sbit DIPswitch = P1^4;      // DIP switch input on Port 1 bit 4
sbit greenLED = P1^5;       // green LED output on Port 1 bit 5

void main (void)
{
    unsigned char inval;

    inval = 0;               // initial value for inval
    while (1)
    {
        if (DIPswitch == 1)
        {
            // check if input P1.4 is high
            inval = P1 & 0x0F; // read bit 0 .. 3 from P1
            greenLED = 0;      // set output P1.5 to low
        }
        else
        {
            // if input P1.4 is low
            greenLED = 1;      // set output P1.5 to high
        }
        P3 = (P3 & 0xF0) | inval; // output inval to P3.0 .. P3.3
    }
}
```

Detect an external interrupt (by means of inputs) on P3.2 and P3.3. Indicate on LEDs connected on P0.0 & P0.1 (assume switches connected to P3 pins and LED connected to P0 pins) (Try it based on above code)

Take input from P0. Count no of 1 in input – Parity Checker

```
#include <reg51.h>
sbit D0 = B^0; // define D0-D7 as bits of reg B
sbit D1 = B^1;
sbit D2 = B^2;
sbit D3 = B^3;
sbit D4 = B^4;
sbit D5 = B^5;
sbit D6 = B^6;
sbit D7 = B^7;
unsigned bdata reg; // define reg as bit addressable variable
sbit b = reg^0; // define b as bit 0 of reg
void main()
{
    unsigned int i,c=0; // initialize counter
    B=P0; // take input from P0 to B
    b=0;
    for(i=0;i<8;i++) // rotate bits of reg B
    { // 8 times
        b=D7;
        D7=D6;
        D6=D5;
        D5=D4;
        D4=D3;
        D3=D2;
        D2=D1;
        D1=D0;
        if(b==1)c++; // check every bit if 1
    }
    while(1); // loop continue
}
```

Assume a key is connected with P3.2. Count no of key press and display it on other port