Assignment 1

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Download all python codes from

https://github.com/varunireddy/EE3025_IDP/codes

and latex-tikz codes from

https://github.com/varunireddy/EE3025_IDP

1 Problem

(5.3) The system h(n) is said to be stable if

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty \tag{1.0.1}$$

Is the system defined by (3.2) stable for impulse response in (5.1)?

2 Solution

We know the system is defined by.,

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2) \tag{2.0.1}$$

$$y(n) = 0 \text{ for } y < 0 \tag{2.0.2}$$

Applying Z-Transform,

$$H(z) = \frac{Y(z)}{X(z)} \tag{2.0.3}$$

$$H(z) = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}} \tag{2.0.4}$$

$$H(z) = \frac{2(z^2 + 1)}{z(2z + 1)} \tag{2.0.5}$$

We know,

$$\sum_{n=-\infty}^{\infty} |h(n)| < \infty \tag{2.0.6}$$

for the system to be stable. The above equation can be rewritten as.,

$$\sum_{n=-\infty}^{\infty} |h(n)| \left|z^{-n}\right|_{|z|=1} < \infty \tag{2.0.7}$$

$$\sum_{n=-\infty}^{\infty} \left|h(n)z^{-n}\right|_{|z|=1} < \infty \tag{2.0.8}$$

We know from triangle inequality.,

$$\sum_{n=-\infty}^{\infty} \left|h(n)z^{-n}\right|_{|z|=1} < \left|\sum_{n=-\infty}^{\infty} h(n)z^{-n}\right|_{|z|=1} \tag{2.0.9}$$

$$\implies |H(n)|_{|z|=1} < \infty \tag{2.0.10}$$

Therefore, the ROC (region of convergence) should include the unit circle.
Since, h(n) is right sided the ROC is outside the outermost pole. From the equation.2.0.5

$$\textbf{Poles:-}\ z = -\frac{1}{2}, 0 \tag{2.0.11}$$

From the above poles, ROC is $|z| > \frac{1}{2}$ H(z) is plotted in z-plane in python. From the figure.0, we can observe that ROC includes the unit circle $|z| = 1$, which implies the given IIR filter is stable, because h(n) is absolutely summable.

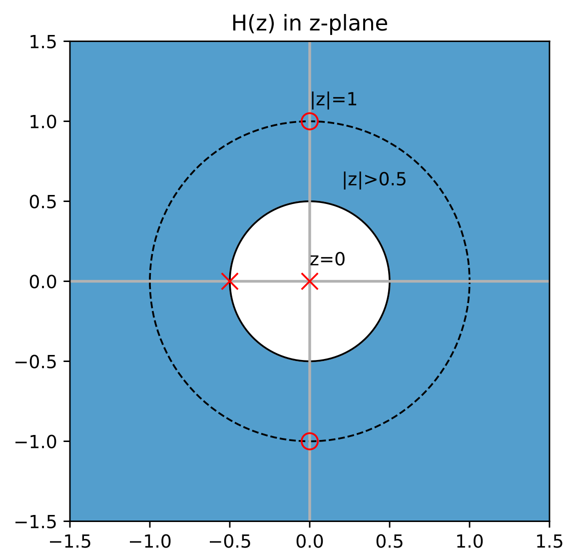

Fig. 0: H(z) in z-plane