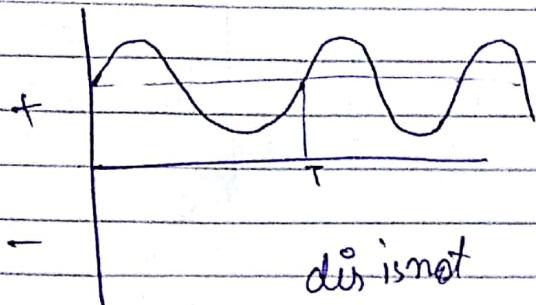


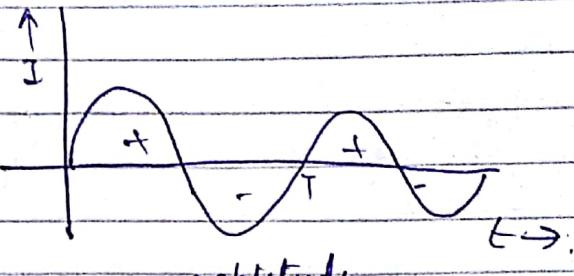
Alternating current (AC)

Time varying periodic current is said to be alternating if

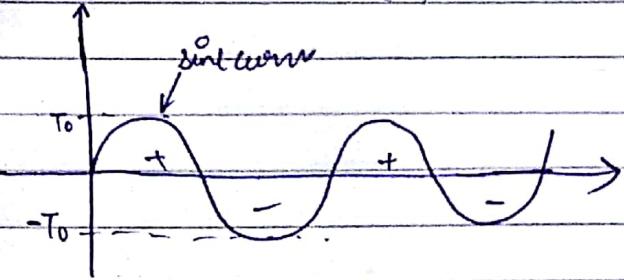
- 1) its amplitude is const.
- 2) its alternate half cycles are (+ve) & (-ve)



dir is not
Changer
AC(X)



amplitude
is changing
AC(X)



AC(✓)

$$I = I_0 \sin \omega t$$

$$\omega = 2\pi f$$

frequency

$$(f = \frac{1}{T})$$

I_0 = plot value / Amplitude

$T = \text{time period}$

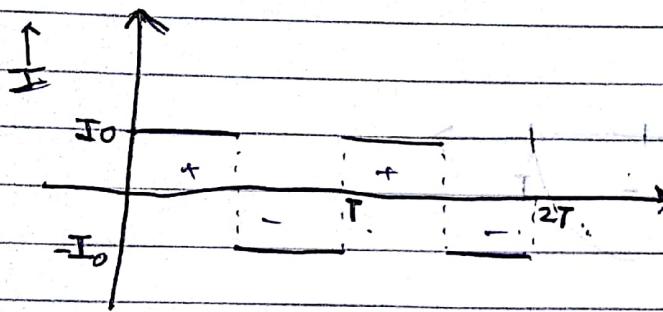
$$\text{Average value of current} = \frac{2I_0}{\pi}$$

alternating voltage

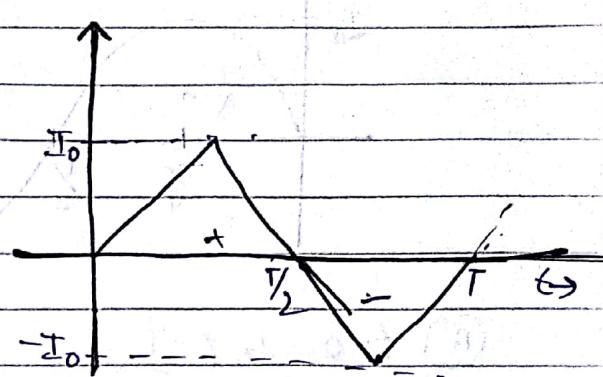
$$V = V_0 \sin \omega t$$

$$V = V_0 \sin(\omega t + \phi)$$

ϕ = phase const.



Complex AC $\rightarrow \sqrt{ }$



Complex AC $\rightarrow \sqrt{ }$

Average value of current

(in a time interval)

$$I_{\text{avg}} = \frac{1}{T} \int_{t_1}^{t_2} I \cdot dt = \frac{\text{Total charge flown}}{T} = \frac{I_0 \sin \omega t}{\omega} \Big|_{t_1}^{t_2}$$

$$\text{i.e. } I = I_0 \sin \omega t$$

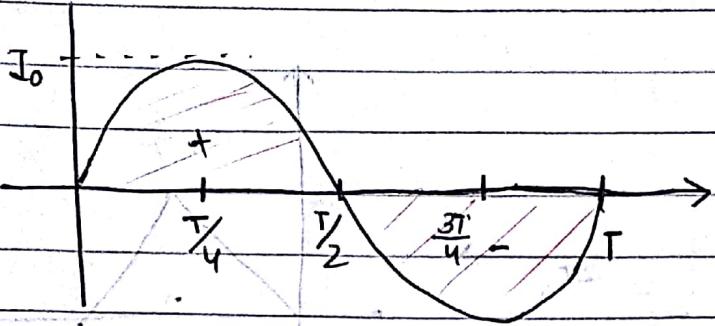
$$t=0 \text{ to } t=\frac{T}{2}$$

$$I_{\text{avg}} = \frac{1}{T/2} \int_{t_1}^{t_2} I_0 \sin \omega t \cdot dt = \frac{I_0}{\omega} \left[\frac{1 - \cos \omega t}{2} \right]_{t_1}^{t_2}$$

$$= \frac{I_0}{\omega} \left(\frac{1 - \cos \omega \frac{T}{2}}{2} - \frac{1 - \cos \omega t_1}{2} \right) = \frac{I_0}{\omega} \left(\frac{1 - \cos \pi}{2} - \frac{1 - \cos \omega t_1}{2} \right) = \frac{I_0}{\omega} \left(\frac{1 - (-1)}{2} - \frac{1 - \cos \omega t_1}{2} \right) = \frac{I_0}{\omega} \left(1 - \frac{1 - \cos \omega t_1}{2} \right) = \frac{I_0}{\omega} \left(\frac{1 + \cos \omega t_1}{2} \right) = \frac{I_0}{\omega} \sin^2 \frac{\omega t_1}{2}$$

$$\text{as } \omega = \frac{Q\pi}{T}$$

$$= \frac{2I_0}{\pi} \quad \text{dy}$$



(A) $t=0$ to $t=\frac{T}{2}$

$$\frac{2I_0}{\pi}$$

(B) $t=\frac{T}{2}$ to $t=T$ $-\frac{2I_0}{\pi}$

(C) $t=\frac{T}{4}$ to $t=\frac{3T}{4}$

$$I_{avg}=0$$

(D) $t=0$ to $t=T$

in one time period

or in one cycle

$$I_{avg}=0$$

$$I_{\text{rms}} = \frac{I_0}{\sqrt{2}}$$

Root mean Square Value. I_{rms} or (effective value.)

$$I_{\text{rms}} = \sqrt{\langle I^2 \rangle}$$

$$I = I_0 \sin \omega t$$

$$\rightarrow I^2 = I_0^2 \sin^2 \omega t$$

$$\rightarrow \langle I^2 \rangle = \frac{\int_0^T I_0^2 \sin^2 \omega t dt}{T} = \frac{I_0^2}{T} \int_0^T \sin^2 \omega t dt$$

$$= \frac{I_0^2}{2}$$

$$\rightarrow \sqrt{\frac{I_0^2}{2}} \quad \left\{ \langle \sin^2 \omega t \rangle, \langle \cos^2 \omega t \rangle = \frac{1}{2} \right\}$$

$$\boxed{\frac{I_0}{\sqrt{2}}} = I_{\text{rms}}$$

Ques → Find root mean Sq. value of current. $I = 3 + 4 \sin \omega t$

$$I^2 = (3 + 4 \sin \omega t)^2$$

$$= 9 + 16 \sin^2 \omega t + 24 \sin \omega t$$

$$\langle I^2 \rangle = \int_0^T (9 + 16 \sin^2 \omega t + 24 \sin \omega t) dt$$

$$= \frac{9t}{2} + \frac{16}{2} \cdot \frac{\omega t}{2} + \frac{24}{2} = \frac{9t^2}{2} + 8t + 12$$

$$I_{\text{RMS}} = \sqrt{\frac{I_1^2 + I_2^2}{2}}$$

$$\langle I^2 \rangle = \langle 9 \rangle + 16 \langle \sin^2 \omega t \rangle + 24 \langle \sin \omega t \rangle$$

$$= 9 + 16 \frac{1}{2} + 0 = 17$$

$$I_{\text{RMS}} = \sqrt{17} \text{ A. Ans}$$

Q- Find the effective value of current in I_{tot} .

$$I = 2 \sin 100\pi t + 2 \cos(100\pi t + 30^\circ)$$

$$\langle I^2 \rangle = 4 \sin^2 100\pi t + 4 \cos^2(100\pi t + 30^\circ)$$

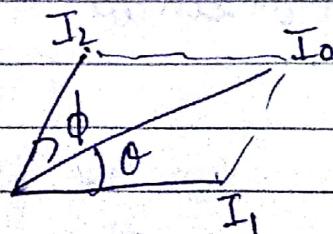
$$\langle I^2 \rangle = \frac{4}{2} +$$

as we know.

$$I = I_1 \sin \omega t + I_2 \sin(\omega t + \phi)$$

$$I = I_0 \sin(\omega t + \phi)$$

$$I_0 = \sqrt{I_1^2 + I_2^2 + 2I_1 I_2 \cos \phi}$$



$$I = 2 \sin 100\pi t + 2 \sin(100\pi t + 30^\circ + 90^\circ)$$

$$I_1 = I_2 = 2, \quad \phi = 120^\circ$$

$$I_0 = ?$$

$$I_{\text{RMS}} = \frac{I_0}{\sqrt{2}}$$

$$I_0 = \sqrt{2^2 + 2^2 + 2 \times 2 \times 2 \times \cos 120^\circ}$$

$$= \sqrt{8 + 8 \cos 120^\circ}$$

$$= \sqrt{8 - 1 \times 8} = \sqrt{8}$$

$$\cos 110^\circ \\ \cos(180^\circ - 60^\circ)$$

$$\sin 120^\circ$$

$$(180^\circ - 60^\circ) = \frac{1}{2}$$

$$\frac{1}{2}$$

$$\frac{1}{2}$$

$$I_0 = 2$$

$$= \frac{2}{\sqrt{2}} = \sqrt{2} \text{ Ams}$$

$$I_{\text{RMS}} = \frac{I_0}{\sqrt{2}}$$

$$A_h = \sqrt{2} A_m$$

Power delivered in AC circuit

$$V = V_{\text{max}} \sin \omega t$$

$$I = I_{\text{max}} \sin(\omega t + \phi)$$

when $\phi = \text{phase diff between current & voltage}$.

Instantaneous power

$$P_t = VI$$

$$= V_{\text{max}} I_{\text{max}} \sin \omega t [\sin \omega t \cos \phi + \cos \omega t \sin \phi]$$

$$= V_{\text{max}} I_{\text{max}} \cos \phi \frac{\sin^2 \omega t}{2} + V_{\text{max}} I_{\text{max}} \sin \phi \frac{\sin 2 \omega t}{2}$$

cos φ is power factor

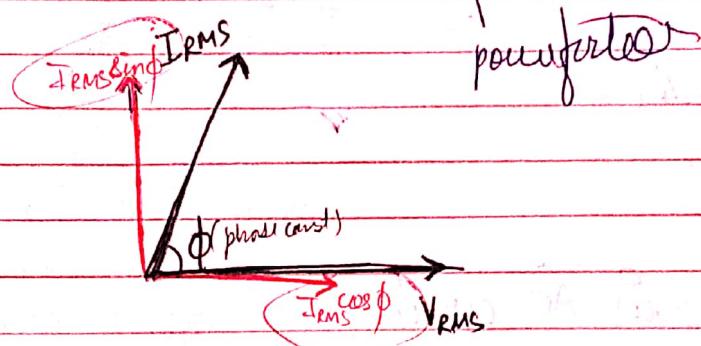
average power in one cycle

$$P_{avg} = \frac{1}{2} V_m \cdot I_m \cos \phi.$$

$$= \frac{V_m}{\sqrt{2}} \times \frac{I_m \cos \phi}{\sqrt{2}}$$

$$\langle P \rangle = V_{rms} \times I_{rms} \cos \phi$$

$$\langle P \rangle = I_{rms} V_{rms} \cos \phi$$



Component

$I_{rms} \sin \phi$ called

$I_{rms} \sin \phi$ as useless current

(जो कोई power produce नहीं करता है)

Representation of AC Source

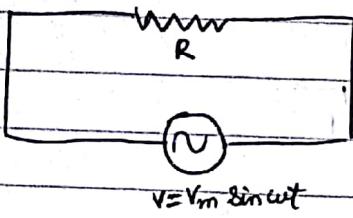


$$V = V_m \sin \omega t$$

RMS value → 220V 50Hz
Effective value

All different AC circuit

1) Circuit containing only resistors (pure resistive circuit)



$v = V_m \sin \omega t$



current in resistance $I = \frac{V}{R} = \frac{V_m \sin \omega t}{R}$

$$I = I_0 \sin \omega t$$

$V_m \sin \omega t$
 R
 $v = I_0$

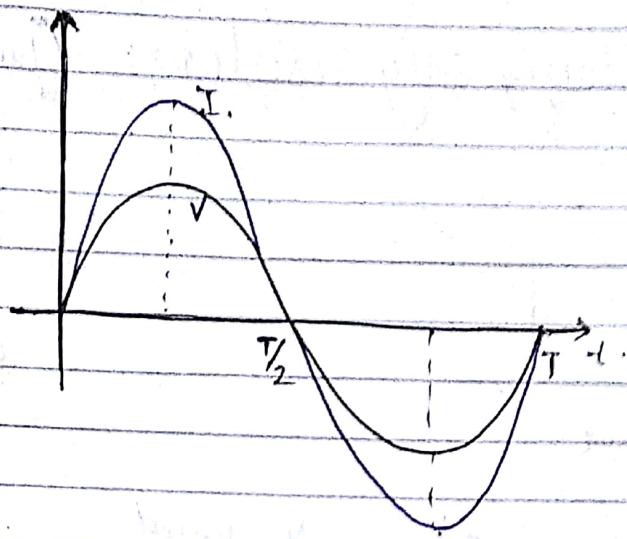
A-C → All solved examples till pure resistance

$E_r \rightarrow$ See A & B

Part 1

Part 2
See A & B

$$I = I_m \sin \omega t$$



phase difference

$$\phi = 0$$

$$\begin{array}{c} \rightarrow \\ I_m \\ \downarrow \\ V_m \end{array}$$

$$L \cdot I_m = \frac{V_m}{R}$$

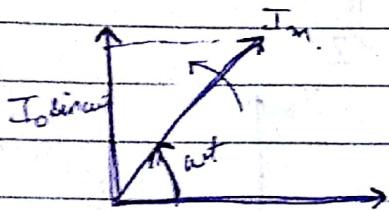
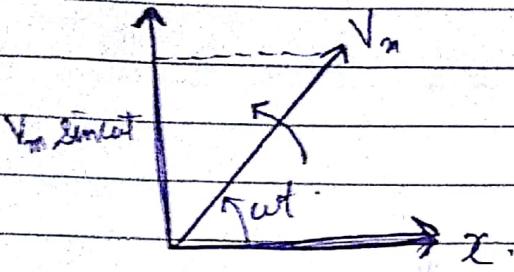
$$I_{rms} = \frac{V_{rms}}{R}$$

average power

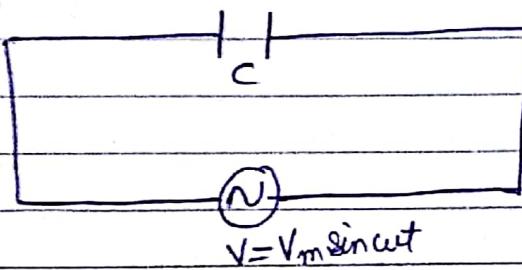
$$\langle P \rangle = V_{rms} I_{rms} \cos \phi \text{ or } V_{rms} I_{rms} \cos 0^\circ$$

$$\boxed{\langle P \rangle = I_{rms}^2 \cdot R}$$

Note → Phaser diagram



Circuit containing only Capacitor



charge on plates of capr

$$\frac{V}{X} = \frac{I}{q} \quad q = CV \\ = C V_m \sin \omega t \quad \text{--- (1)}$$

$$I = \frac{dq}{dt}$$

$$= \frac{d(C V_m \sin \omega t)}{dt} = C V_m \omega \cos \omega t$$

$$\left(\frac{V_m}{X_C} \right) \cos \omega t$$

$$I = I_m \cos \omega t$$

$$X_C = \frac{1}{\omega C}$$

current voltage are not in same phase

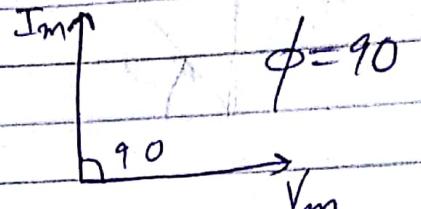
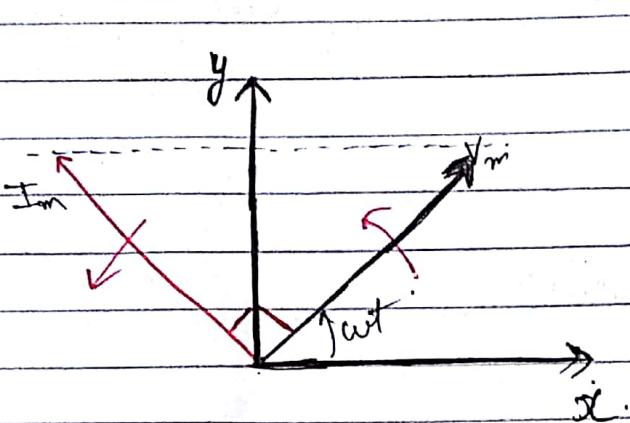
$$\text{phase diff } \frac{\pi}{2}$$

Capacitance resistor

$$I = I_m \sin(\omega t + \frac{\pi}{2})$$

~~from circuit~~

Current leads Voltage by angle $\frac{\pi}{2}$



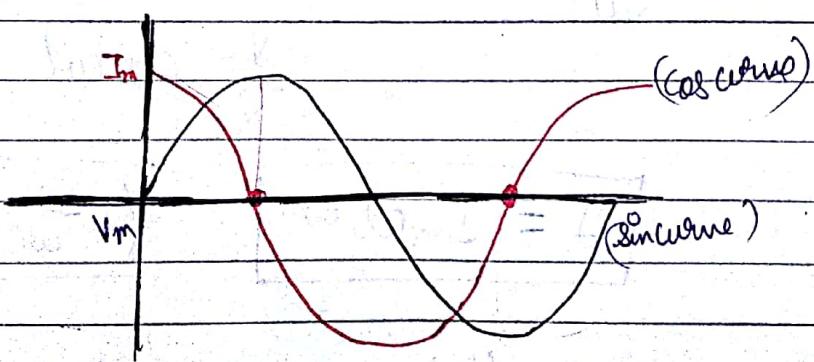
I_m & V_m are 90° out of phase
i.e. V_m lags I_m by 90°
or I_m leads V_m by 90°

Note - $I_m = \frac{V_m}{X_C}$

$I_{rms} = \frac{V_{rms}}{X_C}$ but $I \neq \frac{V}{X_C}$ b/c. I & V are not in same phase.

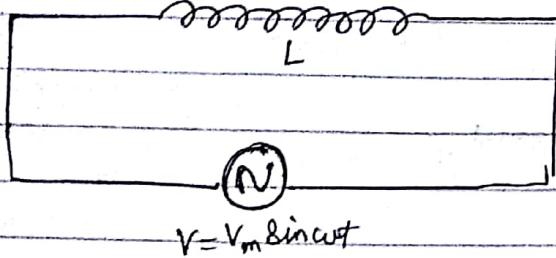
~~$P_{avg} = V_{rms} I_{rm} \cos 90^\circ = 0$~~

no power consumed.



jab tak max heat to dusra
oh
& vice versa

Circuit containing only inductor



$$L \frac{dI}{dt} = V_m \sin \omega t$$

$$\int dI = \frac{V_m}{L} \int \sin \omega t dt$$

$$I = \frac{V_m}{\omega L} (-\cos \omega t) + C \quad (\text{const of integration})$$

$$I = -\frac{V_m}{\omega L} \cos \omega t$$

$\times L \rightarrow$ inductive reactance

{ current & AC at any value of cycle is 0, thus const of 0 is all 0 }

Avg value of current = $\langle I \rangle = 0$

$$I = I_m \sin(\omega t - \frac{\pi}{2})$$

$$\therefore C = 0$$

$$X_L = \omega L$$

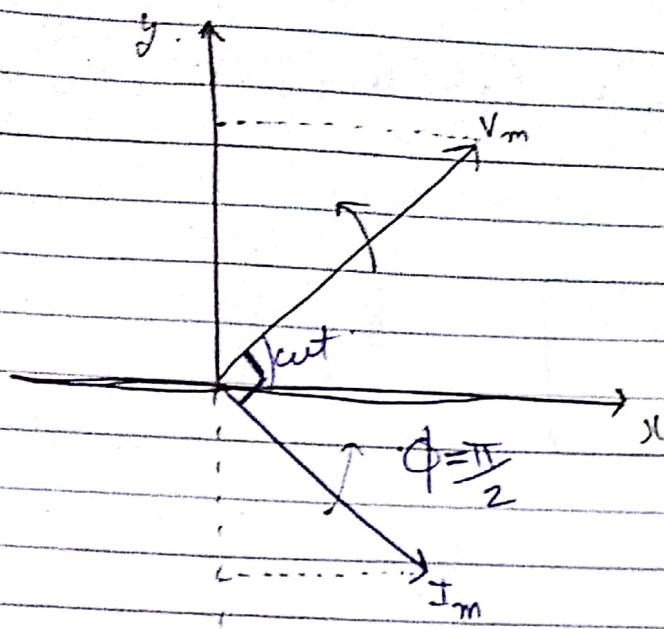
cycle
 $I = I_m \sin \omega t$
 X_L

$$I = -\frac{V_m}{X_L} \cos \omega t$$

$$X_L = \omega L$$

inductive reactance

now phasor diagram



Avg Power = 0.

$$\langle P \rangle = 0$$

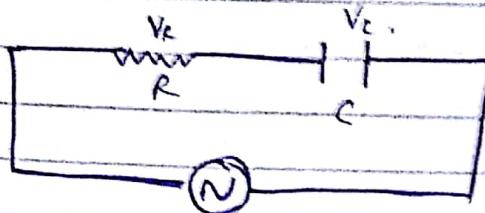
Net $\rightarrow I_m = \frac{V_m}{X_L}$

$$I_{rms} = \frac{V_{rms}}{X_L}$$

$$I \neq \frac{V_{rms}}{X_L}$$

{ V & I are not in same
phase -
phase diff }

Circuit containing a resistor and a capacitor

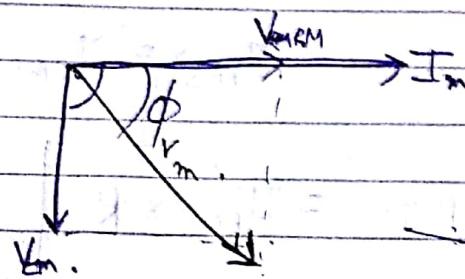


$$V = V_m \sin \omega t$$

Inst. voltage -

$$V = V_R + V_C$$

Phaser diagram



$$\left. \begin{array}{l} V_{Rm} = I_m R \\ V_{cm} = I_m X_L \end{array} \right\}$$

$$\begin{aligned} V_{Rm} &= I_m R \\ V_{cm} &= I_m X_C \end{aligned}$$

$$\cos \phi = \frac{V_{Rm}}{V_m} = \frac{R \times I_m}{I_m \times Z}$$

$$V_m = \sqrt{(V_{Rm})^2 + (V_{cm})^2}$$

$$\boxed{\cos \phi = \frac{R}{Z}}$$

$$\sqrt{I_m^2 R^2 + I_m^2 X_C^2}$$

$$\left(\frac{V_m}{I_m} \right) = \sqrt{R^2 + X_C^2}$$

$$\boxed{Z = \sqrt{R^2 + X_C^2}}$$

$$\therefore Z = \frac{V_m}{I_m} = \frac{V_{rms}}{I_{rms}}$$

impedance

$$V_{rms} = \sqrt{V_{rms R}^2 + V_{rms C}^2}$$

(charge pr. discharge hwa diwde higher sat tak current hoy
 ab hi chalte they.
 of phase diff)

$$\frac{I}{Z} \neq \frac{V}{Z}$$

Average power

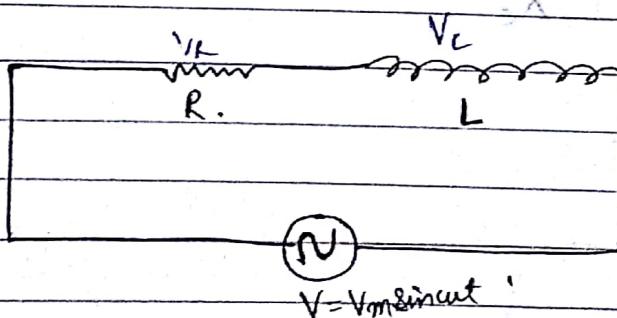
$$\langle P \rangle = V_{rms} I_{rms} \cos \phi$$

$$= V_{rms} I_{rms} \left(\frac{R}{Z} \right)$$

$$= (I_{rms}^2 R) + I_{rms}^2 \left(\frac{R}{Z} \right)$$

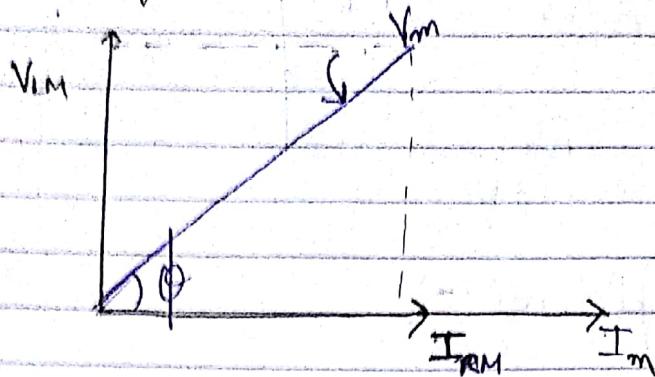
$$\boxed{\langle P \rangle = I_{rms}^2 R}$$

Circuit containing a resistor & Inductor



$$\text{Inst Voltage } V = V_R + V_L$$

Phase diagram



$$V_{RM} = I_m \times R$$

$$V_{LM} = I_m \times X_L$$

(max voltage across L)

$$V_m = \sqrt{(V_{RM})^2 + (V_{LM})^2}$$

$$\tan \phi = \frac{V_{LM}}{V_{RM}} = \frac{X_L}{R}$$

$$\frac{V_m}{I_m} = \sqrt{R^2 + (X_L)^2}$$

$$\tan \phi = \frac{X_L}{R}$$

$$Z = \sqrt{R^2 + X_L^2}$$

$$\cos \phi = \frac{R}{Z}$$

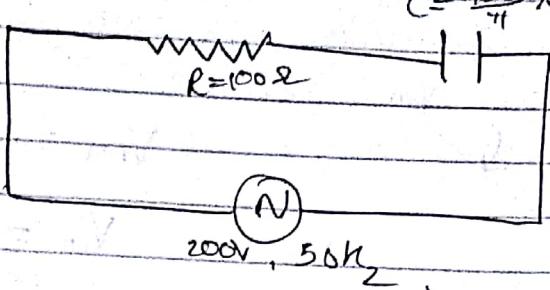
impedance

$$\text{cosec } \phi = V_{rms} = \sqrt{(V_{rms} R)^2 + (V_{rms})^2}$$

Vrms across R Vrms across L

NOTE →

Q.



Calculate : i) Impedance (Z).

- 1) I_{rms}
- 2) $(V_{\text{rms}})_R$ & $(V_{\text{rms}})_C$
- 3) Power factor
- 4) Power loss across R , power across C & $\langle P \rangle$
 $\langle P_R \rangle, \langle P_C \rangle, \langle P \rangle$

ii) if $V = 200\sqrt{2} \sin(2\pi 50t + 30^\circ)$,

then find $I(t)$, $V_R(t)$, $V_C(t)$.

i) $X_C = \frac{1}{\omega C} = \frac{1}{2\pi f C} = \frac{1}{2\pi(50) \times \frac{100}{\pi} \times 10^{-6}} = 100\Omega$

$$X_C = 100\Omega$$

$$Z = \sqrt{R^2 + X_C^2}$$

$$= 100\sqrt{2} \Omega$$

200+

ii)

$$I_{\text{rms}} = \frac{V_{\text{rms}}}{Z} \rightarrow \frac{200}{100\sqrt{2}} \rightarrow \sqrt{2} \text{ A.}$$

$$3). (V_{rms})_R = \frac{E_R}{Z} I_{rms} R.$$

$$\sqrt{2} \times 100 \\ = 100\sqrt{2} V$$

$$(V_{rms})_C \rightarrow I_{rms} \times X_C \\ = \sqrt{2} 100 \\ = 100\sqrt{2} V$$

$$4) \text{ Power factor. } \cos \phi = \frac{R}{Z}$$

$$= \frac{100}{100\sqrt{2}} = \frac{1}{\sqrt{2}}$$

$$\phi = 45^\circ$$

$$5). \langle P_c \rangle = 0, \langle P_R \rangle = I_{rms}^2 R \quad \langle P \rangle = 200W$$

no power comp

$$= (\sqrt{2})^2 \times 100$$

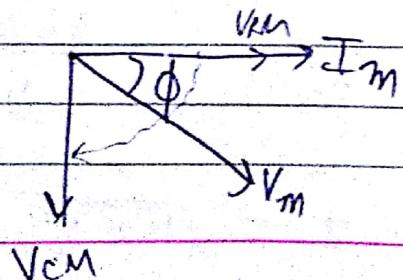
$$= 200W$$

$$6) V = 200\sqrt{2} \sin(2\pi(50)t + 30^\circ)$$

freq. ω

V_m I_m ϕ

ye uper wala question ka
but eq at form me



$$I = I_m \sin(2\pi(50)t + 30^\circ + \phi)$$

$$\therefore I_m = \frac{V_m}{Z} = \frac{200\sqrt{2}}{100} = 200\sqrt{2} A$$

$$\therefore V_a(t) = V_m \sin \{ \omega t + 30^\circ + 45^\circ \}$$

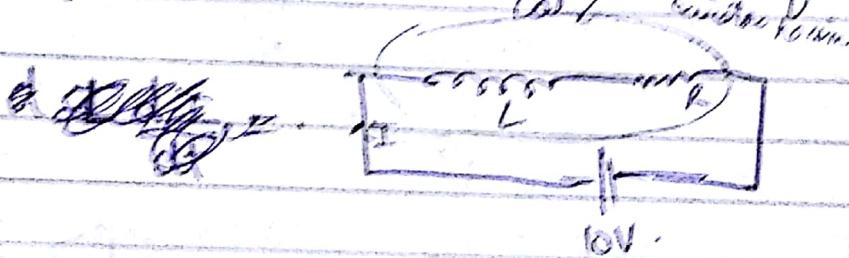
$$= 200 \sin \{ \omega t + 75^\circ \}$$

$$\therefore V_a(t) = V_m \sin \{ \omega t + 30^\circ + 45^\circ - 90^\circ \}$$

as $\sin(\theta - 90^\circ) = -\sin \theta$

$$= V_m \sin \{ \omega t - 15^\circ \}$$

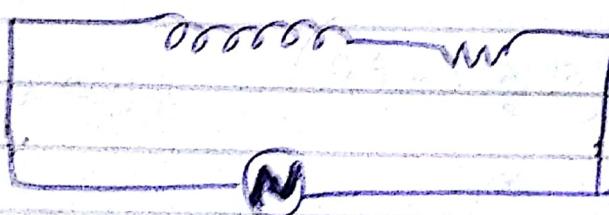
Ques - When an inductor coil is connected to a battery of emf 10V, 2.5A current flows in the circuit.
 When same coil is connected to AC source of 10V & 50Hz (AC source) then current in circuit becomes 3A (approx). find impedance of that coil.



$$I = \frac{10}{R} = 0.5$$

$$R = 20\Omega$$

now connect source



$$I_{rms} = \frac{V_{rms}}{Z} = \frac{10}{5\Omega} = 2A$$

$$Z = \sqrt{R^2 + X^2}$$

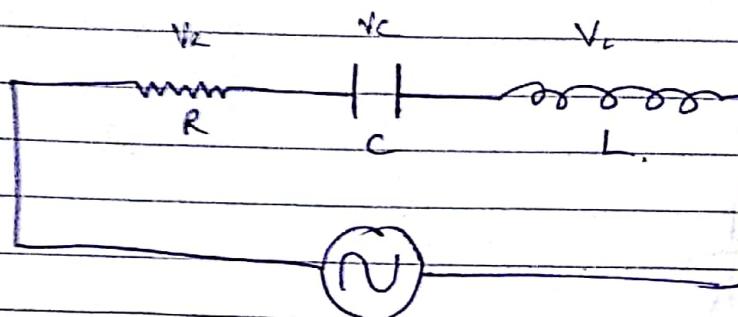
$$X_L = 3 \Omega$$

$$X_L = 2\pi(50)L$$

$$\omega L = X_L$$

$$L = \frac{3}{100\pi} \text{ H}$$

Series LCR circuit



$$V = V_R + V_C + V_L \quad | \text{ for any instant voltage}$$

Initial voltage

phasor diagram

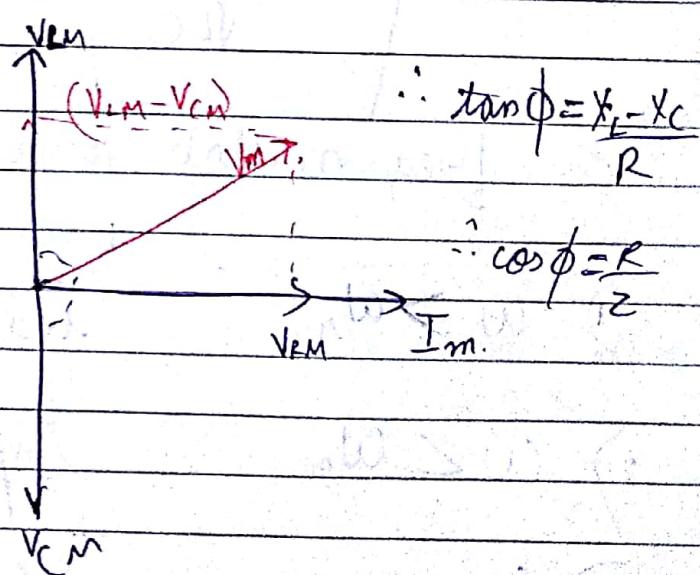
inductance

$$V_m = \sqrt{(V_{RM})^2 + (V_{IM} - V_{CM})^2}$$

$$\frac{V_m}{I_m} = \sqrt{R^2 + (X_L - X_C)^2}$$

$$\rightarrow Z = \sqrt{R^2 + (X_L - X_C)^2}$$

induced



Condition of Resonance

$$\text{if } V_{LM} = V_{CM}$$

$$X_L = X_C$$

$$(Z \rightarrow \text{minimum}) = R.$$

$Z_{\min} = R$

$$I_m \rightarrow \text{max.}$$

$$(I_{rms} \rightarrow \text{max.})$$

$$I_{rms} = \frac{V_{rms}}{\sqrt{R^2 + (X_L - X_C)^2}}$$

$$\omega L = \frac{1}{\omega C}$$

$$\omega = \frac{1}{\sqrt{LC}} \rightarrow \text{resonating angular frequency.}$$

$$\omega_r = \frac{1}{\sqrt{LC}}$$

resonant

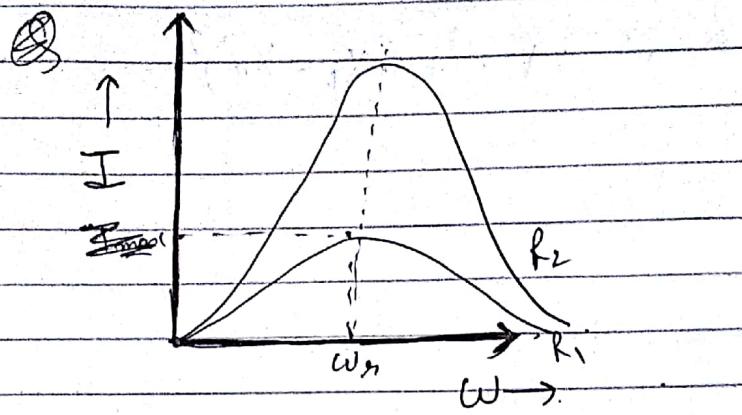
thus freq match ~~and~~ ~~to~~ amplitude increases

behaviour of circuit

1) $\omega > \omega_r$ inductive

2) $\omega < \omega_r$ capacitive

3) $\omega = \omega_r$ resistive

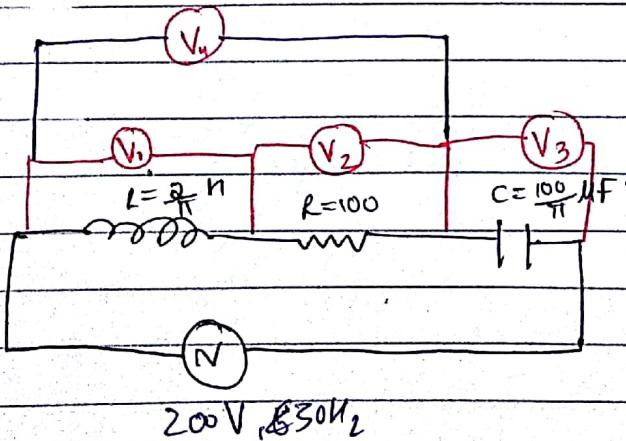
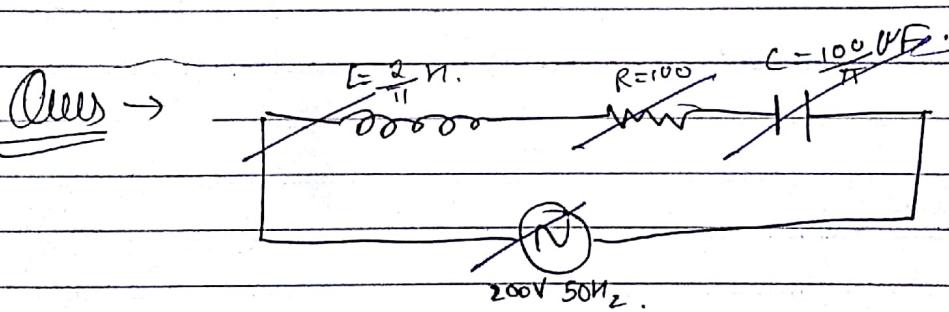
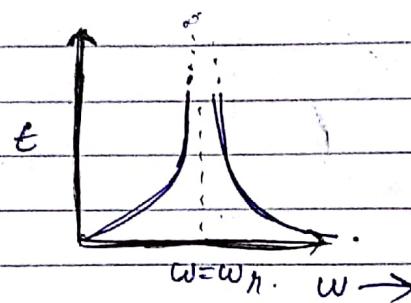


$$R_2 < R_1$$

for ideal saturator $R = 0$.

$\omega = \omega_2$, then plotting current

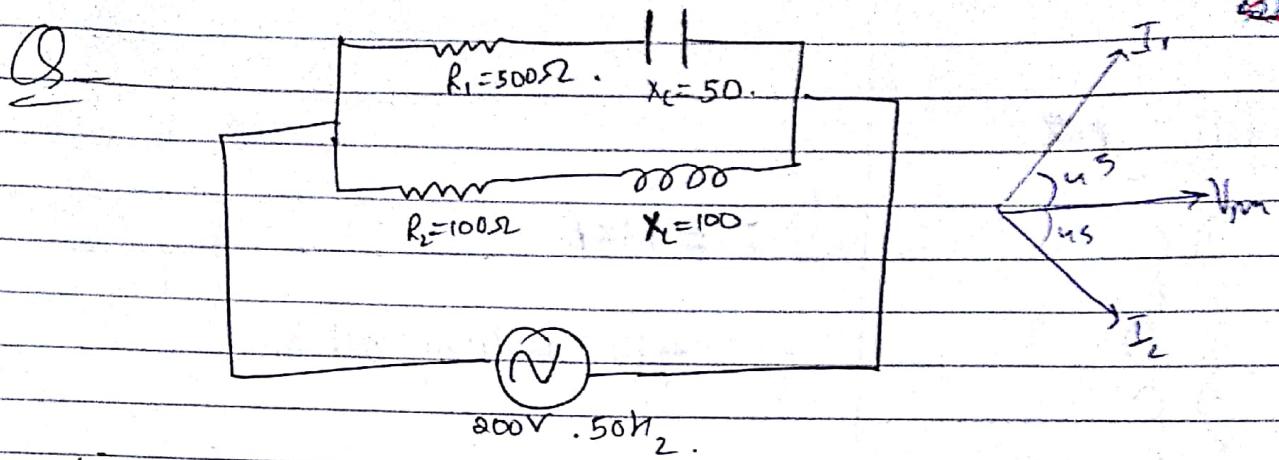
Resonance
logo



Find

- 1) reactance
- 2) Impedance
- 3) reading of Ac voltin
 V_1, V_2, V_3, V_4

See me in last slide
for more I understand



Find effective current flowing through source.

upper circuit $\therefore I_1 =$

$$Z_1 = \sqrt{R_1^2 + X_C^2} = 50\sqrt{2}$$

$$I_1 = \frac{V_{rms}}{Z_1} = \frac{200}{50\sqrt{2}} = 2\sqrt{2} A$$

similar

$$Z_2 = \sqrt{R_2^2 + X_L^2} = 100\sqrt{2}$$

$$I_2 = \frac{V_{rms}}{Z_2} = \frac{200}{100\sqrt{2}} = \sqrt{2} A$$

Now

$$I = \sqrt{I_1^2 + I_2^2}$$

$$= \sqrt{(2\sqrt{2})^2 + (\sqrt{2})^2}$$

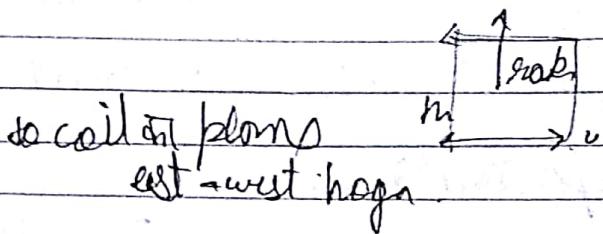
$$\approx \sqrt{10} A$$

DPP - 03

- 1) C
- 2) B
- 3) D
- 4) C
- 5) B
- 6) A
- 7) B
- 8) B
- 9) A
- 10) D.

6) $\tau \equiv M \times B = 0.426$

magnetic field of due me okiruk



7) $B = \frac{\mu_0}{4\pi} \frac{2\pi I}{R}$ Meaning = Specular
 $i = Fxg$

$\frac{V_A}{V_B}$ ratio of load
 $\frac{V_A}{V_B}$ mag field ratio

10) $M \times B$

area bada doya ist $M \times B \uparrow$ noga

mu D \uparrow noga fix

EMI discussion

H₂ - jaise KVL me chali ho rahi chali

H₃ - ~~I²R = 3~~ heat attu min. $I^2 R = 3$

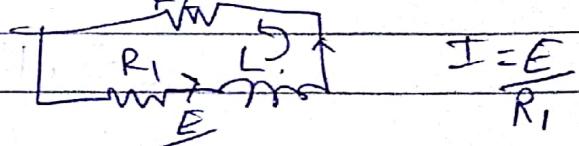
Puri duram = 5 running \Rightarrow

$$N_4 \rightarrow \frac{b^2}{2\mu_0} \times V_A$$

$$N_5 \rightarrow B = \frac{\mu_0}{4\pi} \left(\frac{iC_V}{g_1^2} \right) \quad ① \quad U_B = \frac{B^2}{2\mu_0} \quad \text{length} \frac{r_h}{2\pi}$$

$$\frac{1}{4\pi\epsilon_0} \frac{E^2}{r^2} = \frac{m v^2}{r} \quad \text{find } r \text{ & put in } \textcircled{1}.$$

I₈) at $t=0$, switch open niche battery part bekar.



R1 decay circuit hoy

decay cur $\frac{I(R_1)}{R_2}$

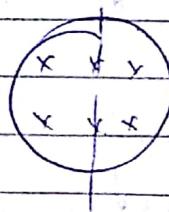
at time

$$I =$$

I₉) ~~(H=0)~~ supercond. means resistance is zero

$$\text{ahfis } \phi_1 = B \pi R^2$$

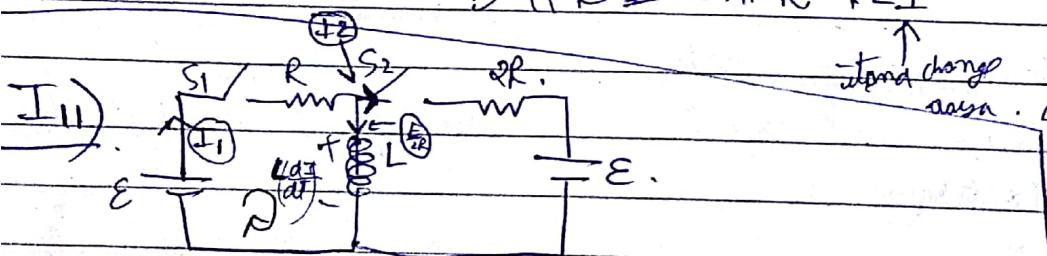
after rotating



$$\phi_2 = -B \cdot \pi R^2 \text{ (anti clockwise)}$$

in supercon ϕ constant rehta ho & net induced emf = 0 hotta ho

$$B \pi R^2 = -B \pi R^2 + L I$$



S₂ is closed. Time ek current ooye hoye $\frac{dI}{dt}$ mili of dis no

internal charge
area. odd chg
it's induced emf
and charge maha
against supercond.
no planet earth

S₁ is close chg. this time current achanak nahi badley.

the $\frac{dI}{dt}$ to badhega



$$I_1 = I_2 + \frac{E}{2R}$$

Galvanic cell KVL
laid down

$$I_1 = I_2 + \frac{E}{QR} \quad (1)$$

$$E = I_1 R - 2I_2 R - E = 0$$

$$-I_1 R = 2I_2 R \quad (2)$$

find I_1 & I_2

$\left(\frac{dI}{dt}\right)$ member of left loop use \oint KVL \Rightarrow loop k

$$E - I_1 R - L \left(\frac{dI}{dt} \right) = 0 \quad (2)$$

now solve it

(1) & (2) put in $\left(\frac{dI}{dt} \right)$ member

~~in eqn 3~~ L bolo karna ho
badal \rightarrow QUIT ETC \rightarrow Certe mo
~~max field mba~~

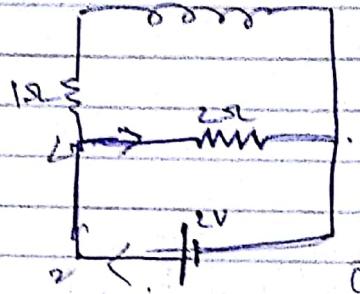
K2) jab slid stales one capacity char
S2 closed \rightarrow LC circuit ban jayega nich wala.
because

~~be part II~~

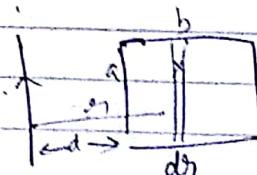
$$H_1 \rightarrow \left(M_0 n^2 \right) A \times f.$$

$R_{\text{loop}} \rightarrow I_5 \rightarrow$ just after remove
L \rightarrow not ho jayegi & flux paral to z axis
current badi jayega
self induction \rightarrow ho jayegi

I_S)



J_2)

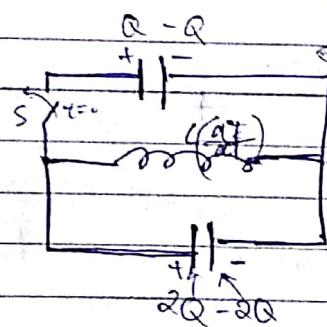


$$\phi_2 = (J) I_1$$

$$\phi_2 = \int_a^{d+b} da J_1 b$$

$$\phi_2 = J_1 ab(d+b-d)$$

L_2)



$$: \frac{Q^2}{2C} \quad \frac{(Q)^2}{2(\mu C)}$$

done sum to

charge only.

2 m no
polari
in polari change
badaya

$$V = \frac{Q^2}{2C}$$

done

$$\frac{dI}{dt} = \frac{Q}{C}$$

$$\frac{dI}{dt} = \frac{Q}{CL}$$

donot Polari diff sum he current $dI = 0$

$$\frac{Q^2}{2C} + \frac{QQ^2}{2\mu C}$$

then sum ene
inducti \rightarrow Q^2 / CL

$$8) \quad v = \frac{1}{\alpha} L I^2$$

$$\frac{dv}{dt} = \frac{1}{\alpha} L \cancel{\left(\frac{dI}{dt} \right)}$$

$$L \times \frac{E}{R} \times (1 - e^{-t/\tau}) \cdot \frac{1}{R} \cdot \frac{E}{L} I^2 e^{t/\tau}$$

$$\frac{dv}{dt} = \frac{e^2}{R} (e^{-t/\tau} - e^{-2t/\tau})$$

rate every stored charge is released

$$\text{for max rate} \rightarrow \text{diff } \frac{d^2v}{dt^2} = 0.$$

$$\cdot \frac{1}{\tau} e^{-t/\tau} + \frac{1.2}{\tau} e^{-2t/\tau} = 0$$

$$\frac{1}{t} e^{-t/\tau} [-1 + 2e^{-t/\tau}] = 0$$

yeo nahi hots
ye hoga = 0

$$e^{-t/\tau} = \frac{1}{2}$$

$$\text{then } \frac{t^2}{2\tau} = \frac{(\theta)^2}{2+1} = 1$$

max
rate cushion.

current out will be $1A e^{t/\tau} \text{ at } 1 \text{ daJ}$

Step up \rightarrow low \rightarrow high voltage $\Rightarrow \frac{N_s}{N_p} > 1$

Step down \rightarrow high \rightarrow low voltage $\Rightarrow \frac{N_p}{N_s} > 1$

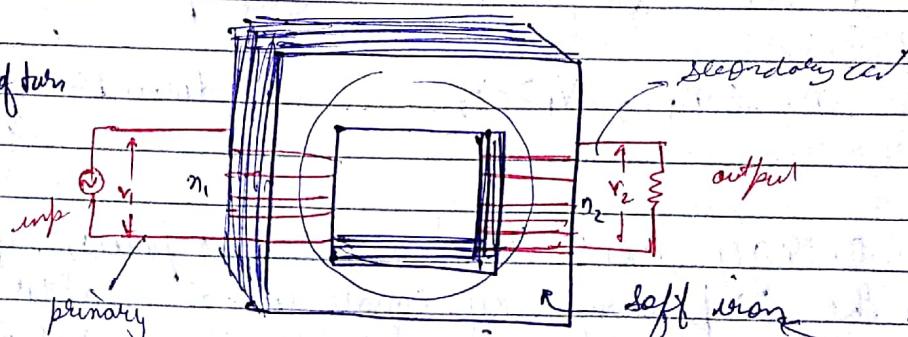
Transformers

note (\uparrow values (voltage))

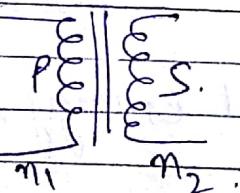
It works only in AC circuit.

It is based on a its working is based on principle of mutual induction

$n_1, n_2 = \text{no. of turn}$



copper binding



$$e_1 = -N_1 \left(\frac{d\phi_B}{dt} \right)$$

$$e_2 = N_2 \left(\frac{d\phi_B}{dt} \right)$$

$$\frac{e_2}{e_1} = \frac{N_2}{N_1}$$

flux per unit for primary & Secondary coil is same

→

if primary & secondary have ~~negligible~~ resistance then
 terminal voltage across primary & secondary
 coil are equal to their emf respectively.

$$\boxed{\frac{V_2}{V_1} = \frac{n_2}{n_1}}$$

$n_2 > n_1, V_2 > V_1$

step up transform

$n_2 < n_1, V_1 > V_2$

step down transform

from energy considerations, the power given
 to the primary coil equals to that taken out
 from the secondary coil. if (there is no loss in energy.)

$$V_1 I_1 = V_2 I_2$$

Real transformer always have some energy losses

efficiency of transformer

$$\eta \% = \frac{\text{output power}}{\text{input power}} \times 100$$

energy loss : Energy loss

) Copper loss → energy loss in copper winding

$$(I_1^2 R_1) + (I_2^2 R_2)$$

primary coil
energy loss secondary coil
energy loss

then
secondary

2) Iron loss \rightarrow flux leakage.

: all losses included in iron losses

B-4 DPP

- 1) D
- 2) B
- 3) B
- 4) A
- 5) C
- 6) A
- 7) D.
- 8) B

- 9) D
- 10) A

AC advantages

\rightarrow more economical

\rightarrow voltage can be stepped up & down.

\rightarrow can be regulated by choke coil with energy loss

\rightarrow can be transmitted to distant places

\rightarrow AC \rightarrow DC converted easily by rectifiers

Disadvantages

\rightarrow more fatal shock.

\rightarrow can't be used in electroplating

\rightarrow skin effect \rightarrow less AC flows on outer

skin of wire

$$\begin{array}{c} 10^6 \times 10^{-1} \\ 1/164 \quad \frac{1}{16} \quad \frac{1}{16} \quad \frac{1}{16} \\ \frac{1}{36} \quad \frac{1}{84} \quad \frac{1}{96} \end{array}$$