

ABSTRACTIVE TEXT SUMMARISATION

RNN (Recurrent Neural Networks)

- ⊛ used in speech recognition, language translation, stock prediction, spam mails, etc.
- ⊛ Also used in image recognition

RNNs are neural networks
↓
that are good at MODELLING SEQUENCE DATA.

uses RNN

Apps

1. Google img search
2. img captioning

Example



pic
(still)

which direction
would it move?

you can only
guess.

If



seems to be a SEQUENCE
i.e. ball is moving towards right.

Sequence Data Forms (Input).

1. Audio → chunks, feed into RNN
2. Text → seq of char/word

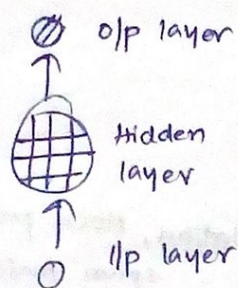
Sequential Memory

ABCD... 2 easy ✓ specific order/sequence

2YXW... BA bit tough.

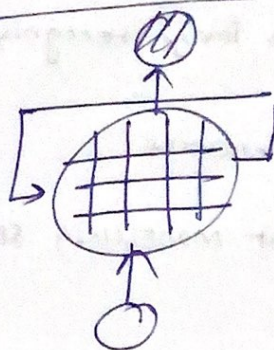
Mechanism that makes it
easier for your brain to
recognize sequence patterns.

Feed Forward Neural Network



In order to use
PREVIOUS INFO TO AFFECT LATER
ONES.

What if we have a loop?



RNN ✓.

Example

CHATBOT.

↓
classify intentions from user's input
↓

step 1

Encode seq. of text using RNN.

step 2

feed RNN's output to feed forward NN.

It'll classify intent

→ perform an action on screen.
used to

- start Activity
- send broadcast rec.
- start services
- send msgs b/w 2 Acti.

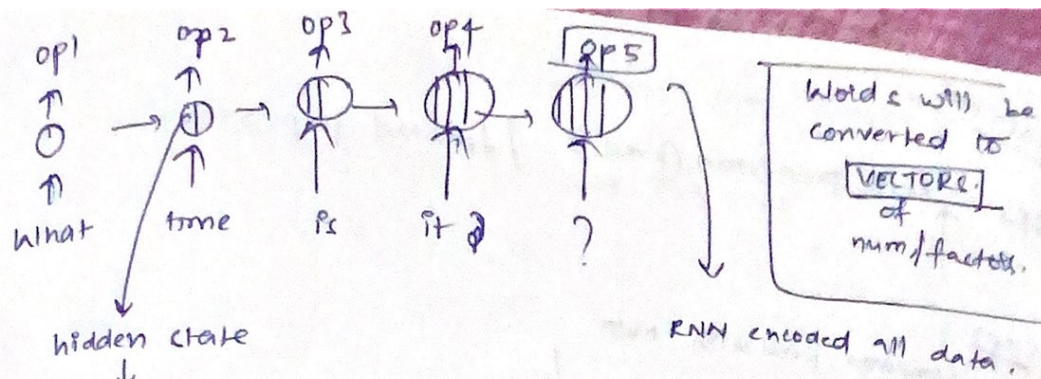
ex what time is it?



what time is it ?



feed one word at a time to RNN sequentially.



hidden state
↓
represents Info
from all prev
states

Asking for time,

↑

○ feed forward NN

↑

op5

code

`mn = RNN()`

`ff = Feed Forward NN()`

`hidden_state = [0.0, 0.0, 0.0, 0.0]` → shape dimensions

for word in input:

`output, hidden_state = mn(word, hidden_state)`

`prediction = ff(output)`

problem

As it goes further, It has trouble retaining Info from prev states

↓

SHORT TERM MEMORY
&
VANISHING GRADIENT

Is due to the nature of
back propagation

Train NN

step 1 → make prediction (pred.) / forward propagation

step 2

compares pred with truth

$$\boxed{\text{loss}(\text{pred}, \text{truth})}$$

↓
outputs ERROR VALUES

↓
estimates how badly network is performing

step 3

back propagation,



calculates Gradients ∇ for each node in network



value used to adjust network's internal weights allowing network to learn.

Bigger ∇ , bigger adj.
vice versa.

prblm

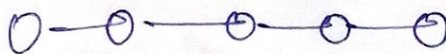
∇ exponentially shrink.

∇ is cal. wrt effects for each node. next node will have even smaller adj. if prev node has smaller adj.

vanishing gradient problem.

same problem.

RNN



← ∇

early words are forgotten.

so, what to do?

2 ways

LSTM (long short term memory)

GRU (Gated recurrent units)

learn to keep only relevant info to make predictions

use GATES

diff tensor operations that can learn what info to add/remove to hidden states.

summary

* RNNs are good for processing sequence data for predictions but suffer from SHORT TERM MEMORY. Thus we also use LSTMs / GRUs.

* RNNs train faster, uses less computational resources.
why? because there are less tensor operations to compute.

The AI hacker - Michael phi

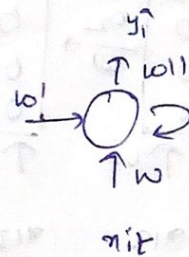
Krish Naik

Tut 29

Why RNN

works well with sequence of data as inp

- Time forecasting
- stock forecasting, etc.
- spam email or not



Ilp data = Text data

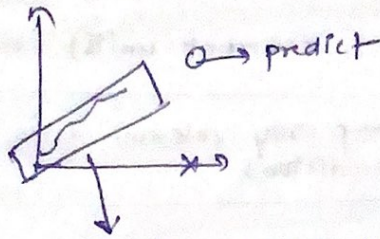
converted to VECTORS

seq. info is imp.

And finds if sentence > 0 or sentence < 0

would1 w2 . . wn
0.75 2

Time series (uses RNN)



considers this entire time block of data

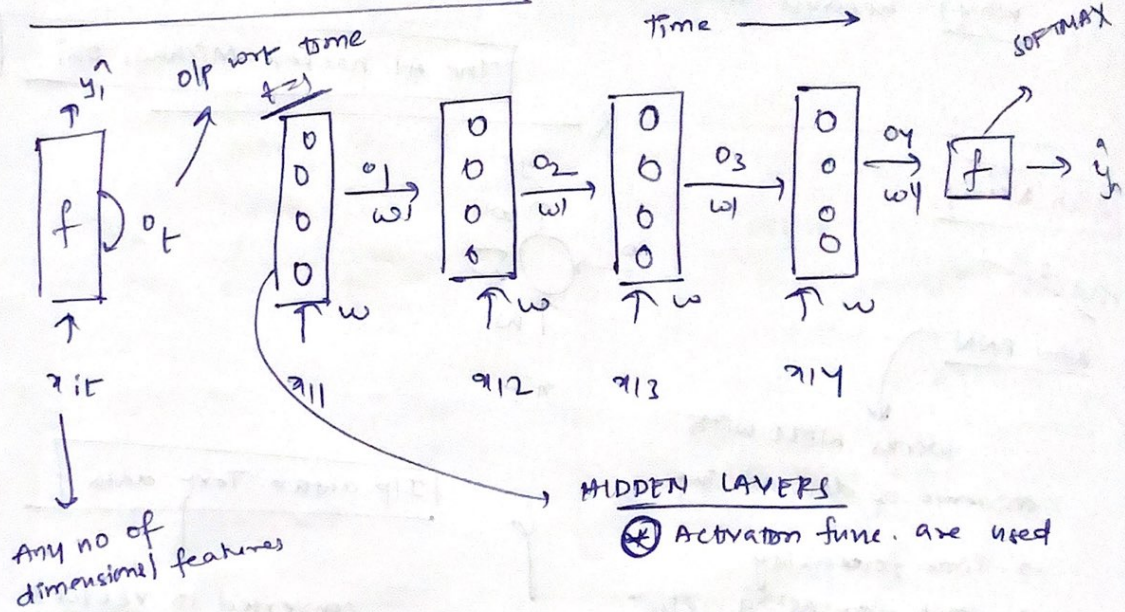
Applications

1. Google Image search
→ text converted to Image
2. Google lens
→ Image to text
3. Google translator
→ many-many RNN.

seq. Info is kept.

Tut-20

Forward Propagation over time



Sentence $x_1 = \langle x_{11}, x_{12}, x_{13}, x_{14} \rangle$

At $t=1$ preprocess this to RNN

y_1, o_1 both sent to next RNN
∴ seq. Info is kept.

$$t=1 \quad o_1 = f(x_{11} \times w) \quad \text{some func. (acts)}$$

$$t=2 \quad o_2 = f(x_{12} \times w + o_1 w_1)$$

$$t=3 \quad o_3 = f(x_{13} \times w + o_2 w_1)$$

$$t=4 \quad o_4 = f(x_{14} \times w + o_3 w_1)$$

$\hat{y}_n \rightarrow$ predicted value.

$$\text{loss} = (\hat{y} - y)$$

AIM: To reduce this

Backward propagation

LSTM (Michael - Phi) → The AI hackel.

⊗ tanh → ensures val b/w -1, 1.

⊗ sigmoid → 0 to 1.

So, problem with RNN = Vanishing Gradient

Rule:

$$\text{new weight} = \text{weight} - \text{learning rate} \times \text{Gradient.}$$

Example

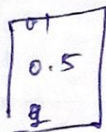
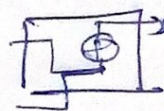
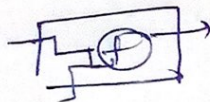
Amazing! The box of cereal gave me a perfectly balanced breakfast, as all things should be. I only ate half of it but will definitely be buying again!

↓
Brain subconsciously remembers only Imp. keywords like Amazing, not the, gave, etc.

This

box

breakfast

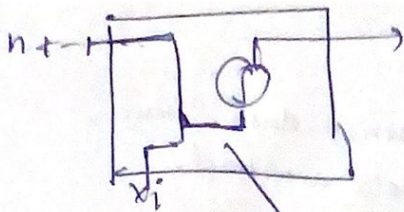


⊗ Words get transformed to machine readable vectors.

⊗ Then, each vector is processed to a RNN in a seq.

⊗ While processing it passes PREV HIDDEN STATE to next seq in HIDDEN STATE

→ holds info on prev data.



$[h_{t-1} + x_i]$ vector \rightarrow has info about curr, prev input

goes to ACTIVATION fun.

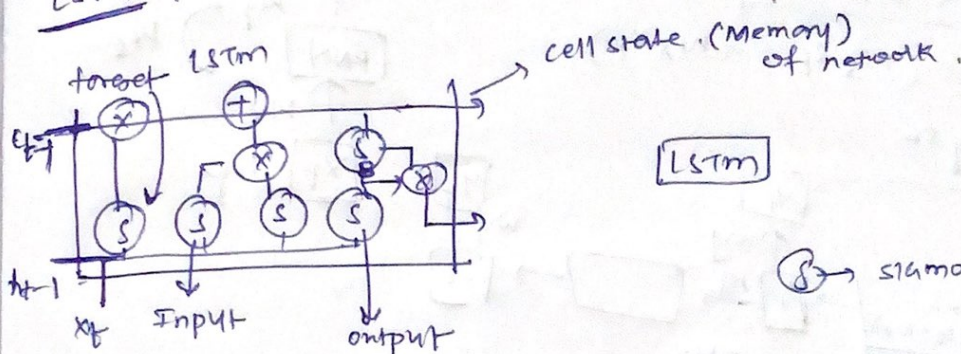
output: h_t hidden state

Here, \tanh is used.

$(-1, 1) \rightarrow$ always.

\swarrow sigmoid is preferable. (0 to 1).
Used \checkmark

LSTM



LSTM

LSTM

$\sigma \rightarrow$ sigmoid.

0 \rightarrow forget
1 \rightarrow keep

$$① \quad f_t * c_{t-1} = B$$

like
find

$$\begin{bmatrix} c_t \checkmark \\ h_t \checkmark \end{bmatrix}$$

for ip in inputs:
 $ch_t = \text{LSTMcell}$
 $(c_{t-1}, h_{t-1}, \text{ip})$

code

```
def LSTMcell (prev-ct, prev-ht, input):
    combine = prev-ht + input
    ft = forget-layer (combine)
    candidate = candidate-layer (combine)  $\rightarrow \in$ 
    it = input-layer (combine)
     $\checkmark$   $c_t = \text{prev-ct} * f_t + \text{candidate} * i_t$ 
    ot = output-layer (combine)
    ht = ot * tanh( $c_t$ )
    return ht, ct.
```


The problem

Problem with Feed Forward NN

- not designed for sequence / time series data. Hence, results with time series / sequential data are bad.
- Does not model memory

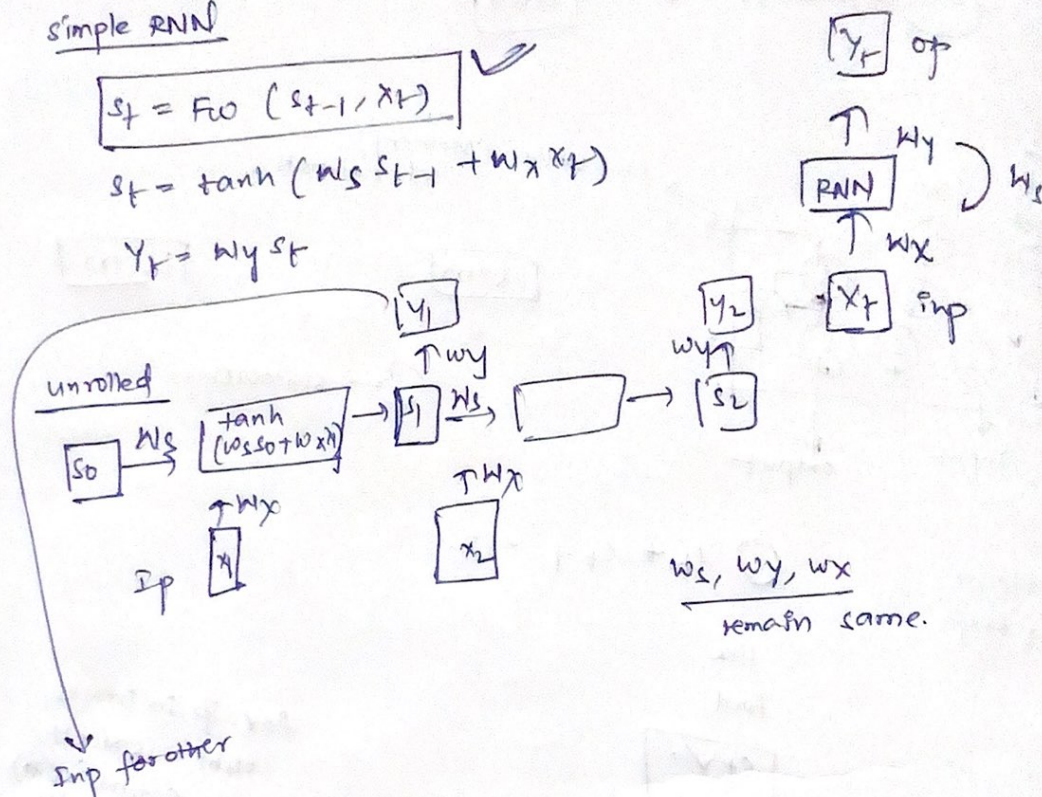
Type of NN designed for capturing Info from sequential time series data.

Simple RNN

$$s_t = F(s_{t-1}, x_t)$$

$$s_t = \tanh(w_s s_{t-1} + w_x x_t)$$

$$y_t = w_y s_t$$



- ⊗ loss cal. in backward.
- ⊗ RNN learn in backward.

Say, each state has $gr = 10^{-2}$.
100 states

$$1st \text{ state, } = (10^{-2})^{100} \approx 0.$$

update in states = 0

∴ neural network won't learn at all

Vanishing Gradient problem.

LSTM

= 3 Gates + 1 cell state

$$f_t = \sigma(W_f s_{t-1} + W_{f'} x_t) \longrightarrow \text{forget Gate}$$

$$i_t = \sigma(W_i s_{t-1} + W_{i'} x_t) \longrightarrow \text{Input Gate}$$

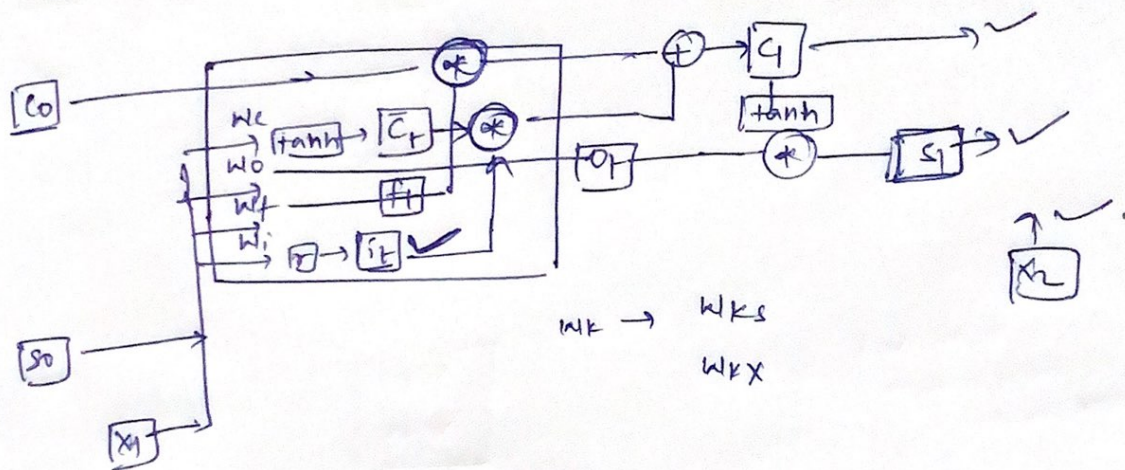
$$o_t = \sigma(W_o s_{t-1} + W_{o'} x_t) \longrightarrow \text{Output Gate}$$

⊛ Each gate has DIFFERENT WEIGHTS.

$$\bar{c}_t = \tanh(W_c s_{t-1} + W_{c'} x_t)$$

$$c_t = (i_t * \bar{c}_t) + (f_t * c_{t-1}) \longrightarrow \text{cell state,}$$

$$h_t = o_t * \tanh(c_t) \longrightarrow \text{new state,}$$



operations

1. calculate i_t
2. calculate \bar{c}_t
3. $i_t * \bar{c}_t = \alpha$
4. calculate f_t
5. $f_t * c_{t-1} = \beta$
6. calculate o_t

$$\alpha + \beta = c_t \quad \checkmark$$

$$o_t * \tanh(c_t) = \boxed{\text{new state} = h_t} \quad \checkmark$$