

# Generating Performance Portable Code using Rewrite Rules

From High-Level Functional Expressions  
to High-Performance OpenCL Code

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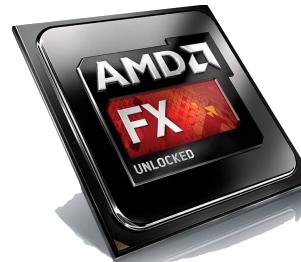


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*of* EDINBURGH



# The Problem(s)

- Parallel processors everywhere
- Many different types: CPUs, GPUs, ...
- Parallel programming is hard
- Optimising is even harder
- **Problem:**  
No portability of performance!



CPU



GPU



FPGA

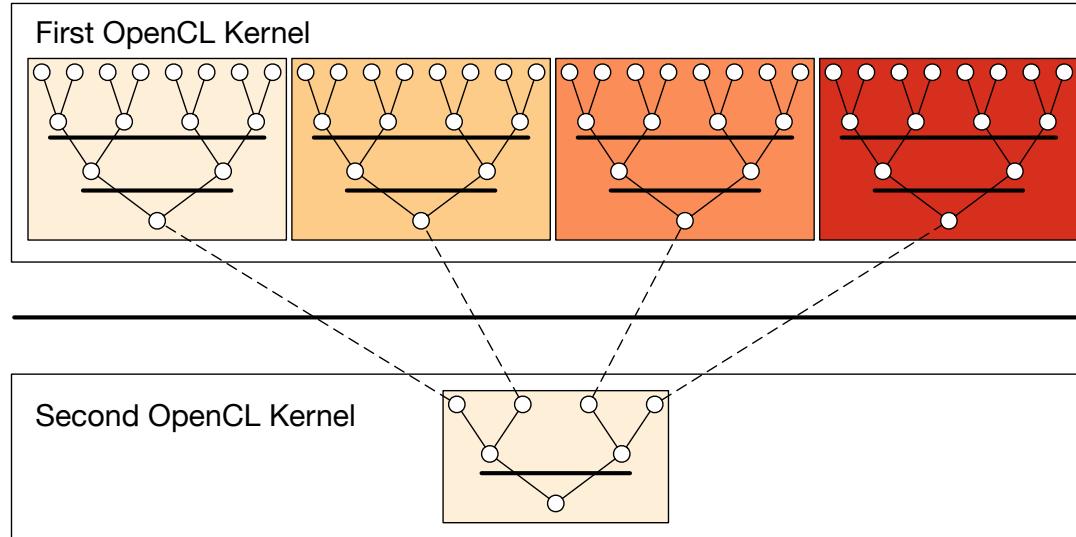


Accelerator



# Case Study: Parallel Reduction in OpenCL

- Summing up all values of an array
- Comparison of 7 implementations by Nvidia
- Investigating complexity and efficiency of optimisations



# Unoptimised Implementation Parallel Reduction

```
kernel void reduce0(global float* g_idata, global float* g_odata,
                    unsigned int n, local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i   = get_global_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    barrier(CLK_LOCAL_MEM_FENCE);
    // do reduction in local memory
    for (unsigned int s=1; s < get_local_size(0); s*= 2) {
        if ((tid % (2*s)) == 0) {
            l_data[tid] += l_data[tid + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    // write result for this work-group to global memory
    if (tid == 0) g_odata[get_group_id(0)] = l_data[0];
}
```



# OpenCL Programming Model

```
kernel void reduce0(global float* g_idata, global float* g_odata,
                    unsigned int n, local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i   = get_global_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    barrier(CLK_LOCAL_MEM_FENCE);
    // do reduction in local memory
    for (unsigned int s=1; s < get_local_size(0); s*= 2) {
        if ((tid % (2*s)) == 0) {
            l_data[tid] += l_data[tid + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    // write result for this work-group to global memory
    if (tid == 0) g_odata[get_group_id(0)] = l_data[0];
}
```

- Multiple *work-items* (threads) execute the same *kernel* function
- *Work-items* are organised for execution in *work-groups*



# Avoid Divergent Branching

```
kernel void reduce1(global float* g_idata, global float* g_odata,
                    unsigned int n, local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i   = get_global_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    barrier(CLK_LOCAL_MEM_FENCE);

    for (unsigned int s=1; s < get_local_size(0); s*= 2) {
        // continuous work-items remain active
        int index = 2 * s * tid;
        if (index < get_local_size(0)) {
            l_data[index] += l_data[index + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid == 0) g_odata[get_group_id(0)] = l_data[0];
}
```



# Avoid Interleaved Addressing

```
kernel void reduce2(global float* g_idata, global float* g_odata,
                    unsigned int n, local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i   = get_global_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    barrier(CLK_LOCAL_MEM_FENCE);

    // process elements in different order
    // requires commutativity
    for (unsigned int s=get_local_size(0)/2; s>0; s>>=1) {
        if (tid < s) {
            l_data[tid] += l_data[tid + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid == 0) g_odata[get_group_id(0)] = l_data[0];
}
```



# Increase Computational Intensity per Work-Item

```
kernel void reduce3(global float* g_idata, global float* g_odata,
                    unsigned int n, local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i = get_group_id(0) * (get_local_size(0)*2)
                    + get_local_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    // performs first addition during loading
    if (i + get_local_size(0) < n)
        l_data[tid] += g_idata[i+get_local_size(0)];
    barrier(CLK_LOCAL_MEM_FENCE);

    for (unsigned int s=get_local_size(0)/2; s>0; s>>=1) {
        if (tid < s) {
            l_data[tid] += l_data[tid + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid == 0) g_odata[get_group_id(0)] = l_data[0];
}
```



# Avoid Synchronisation inside a Warp

```
kernel void reduce4(global float* g_idata, global float* g_odata,
                    unsigned int n, local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i = get_group_id(0) * (get_local_size(0)*2)
                    + get_local_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    if (i + get_local_size(0) < n)
        l_data[tid] += g_idata[i+get_local_size(0)];
    barrier(CLK_LOCAL_MEM_FENCE);

    # pragma unroll 1
    for (unsigned int s=get_local_size(0)/2; s>32; s>>=1) {
        if (tid < s) { l_data[tid] += l_data[tid + s]; }
        barrier(CLK_LOCAL_MEM_FENCE); }

    // this is not portable OpenCL code!
    if (tid < 32) {
        if (WG_SIZE >= 64) { l_data[tid] += l_data[tid+32]; }
        if (WG_SIZE >= 32) { l_data[tid] += l_data[tid+16]; }
        if (WG_SIZE >= 16) { l_data[tid] += l_data[tid+ 8]; }
        if (WG_SIZE >=  8) { l_data[tid] += l_data[tid+ 4]; }
        if (WG_SIZE >=  4) { l_data[tid] += l_data[tid+ 2]; }
        if (WG_SIZE >=  2) { l_data[tid] += l_data[tid+ 1]; } }

    if (tid == 0) g_odata[get_group_id(0)] = l_data[0]; }
```

# Complete Loop Unrolling

```
kernel void reduce5(global float* g_idata, global float* g_odata,
                    unsigned int n, local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i = get_group_id(0) * (get_local_size(0)*2)
                    + get_local_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    if (i + get_local_size(0) < n)
        l_data[tid] += g_idata[i+get_local_size(0)];
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) { l_data[tid] += l_data[tid+128]; }
        barrier(CLK_LOCAL_MEM_FENCE); }

    if (WG_SIZE >= 128) {
        if (tid < 64) { l_data[tid] += l_data[tid+ 64]; }
        barrier(CLK_LOCAL_MEM_FENCE); }

    if (tid < 32) {
        if (WG_SIZE >= 64) { l_data[tid] += l_data[tid+32]; }
        if (WG_SIZE >= 32) { l_data[tid] += l_data[tid+16]; }
        if (WG_SIZE >= 16) { l_data[tid] += l_data[tid+ 8]; }
        if (WG_SIZE >= 8) { l_data[tid] += l_data[tid+ 4]; }
        if (WG_SIZE >= 4) { l_data[tid] += l_data[tid+ 2]; }
        if (WG_SIZE >= 2) { l_data[tid] += l_data[tid+ 1]; } }

    if (tid == 0) g_odata[get_group_id(0)] = l_data[0]; }
```

# Fully Optimised Implementation

```
kernel void reduce6(global float* g_idata, global float* g_odata,
                    unsigned int n, local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i = get_group_id(0) * (get_local_size(0)*2)
                    + get_local_id(0);
    unsigned int gridSize = WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) { l_data[tid] += g_idata[i];
                      if (i + WG_SIZE < n)
                          l_data[tid] += g_idata[i+WG_SIZE];
                      i += gridSize; }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) { l_data[tid] += l_data[tid+128]; }
        barrier(CLK_LOCAL_MEM_FENCE); }

    if (WG_SIZE >= 128) {
        if (tid < 64) { l_data[tid] += l_data[tid+ 64]; }
        barrier(CLK_LOCAL_MEM_FENCE); }

    if (tid < 32) {
        if (WG_SIZE >= 64) { l_data[tid] += l_data[tid+32]; }
        if (WG_SIZE >= 32) { l_data[tid] += l_data[tid+16]; }
        if (WG_SIZE >= 16) { l_data[tid] += l_data[tid+ 8]; }
        if (WG_SIZE >= 8) { l_data[tid] += l_data[tid+ 4]; }
        if (WG_SIZE >= 4) { l_data[tid] += l_data[tid+ 2]; }
        if (WG_SIZE >= 2) { l_data[tid] += l_data[tid+ 1]; } }

    if (tid == 0) g_odata[get_group_id(0)] = l_data[0]; }
```

# Case Study Conclusions

- Optimising OpenCL is complex
  - Understanding of target hardware required
- Program changes not obvious
- Is it worth it? ...

```
kernel
void reduce0(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i   = get_global_id(0);
    l_data[tid] = (i < n) ? g_idata[i] : 0;
    barrier(CLK_LOCAL_MEM_FENCE);

    for (unsigned int s=1;
         s < get_local_size(0); s*= 2) {
        if ((tid % (2*s)) == 0) {
            l_data[tid] += l_data[tid + s];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```

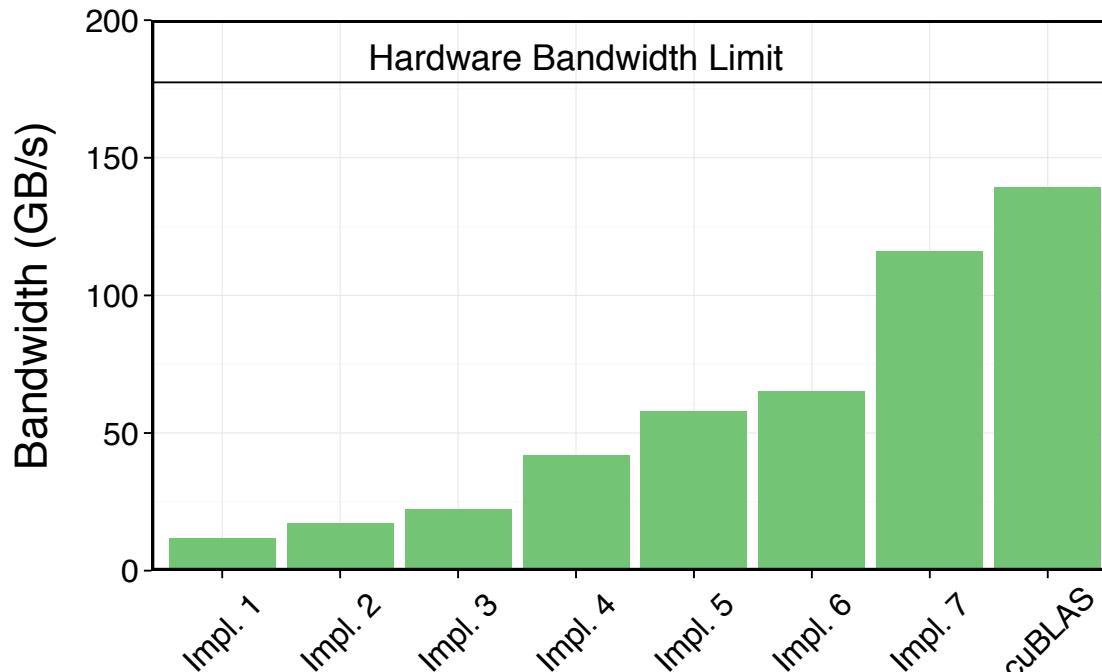
Unoptimized Implementation

```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```

Fully Optimized Implementation

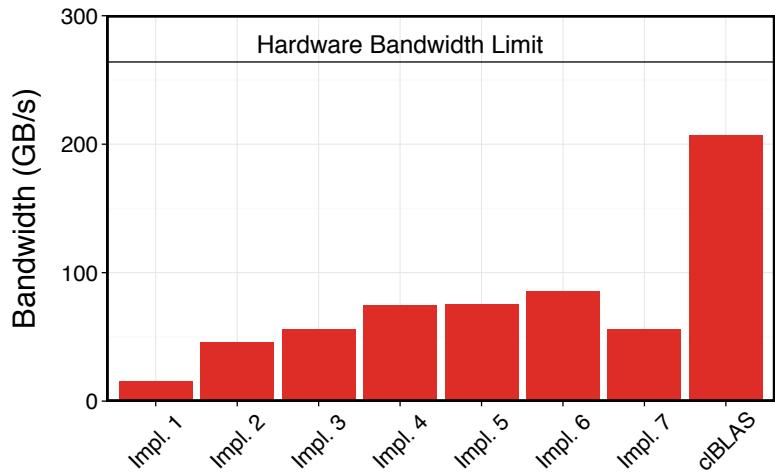
# Performance Results Nvidia



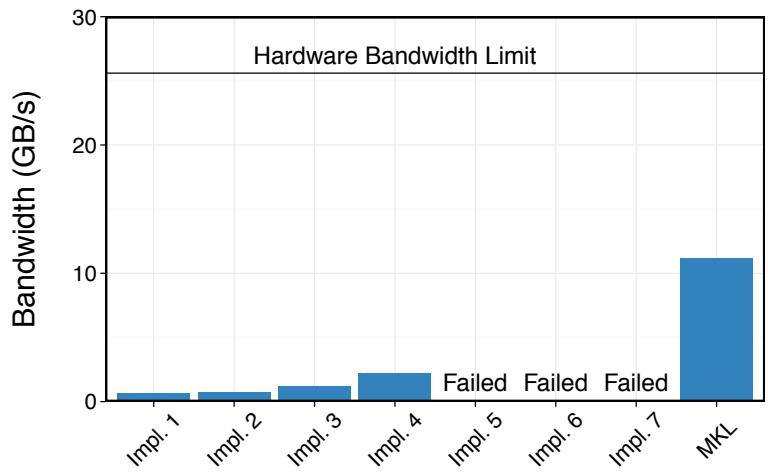
(a) Nvidia's GTX 480 GPU.

- ... Yes! Optimising improves performance by a factor of 10!
- Optimising is important, but ...

# Performance Results AMD and Intel



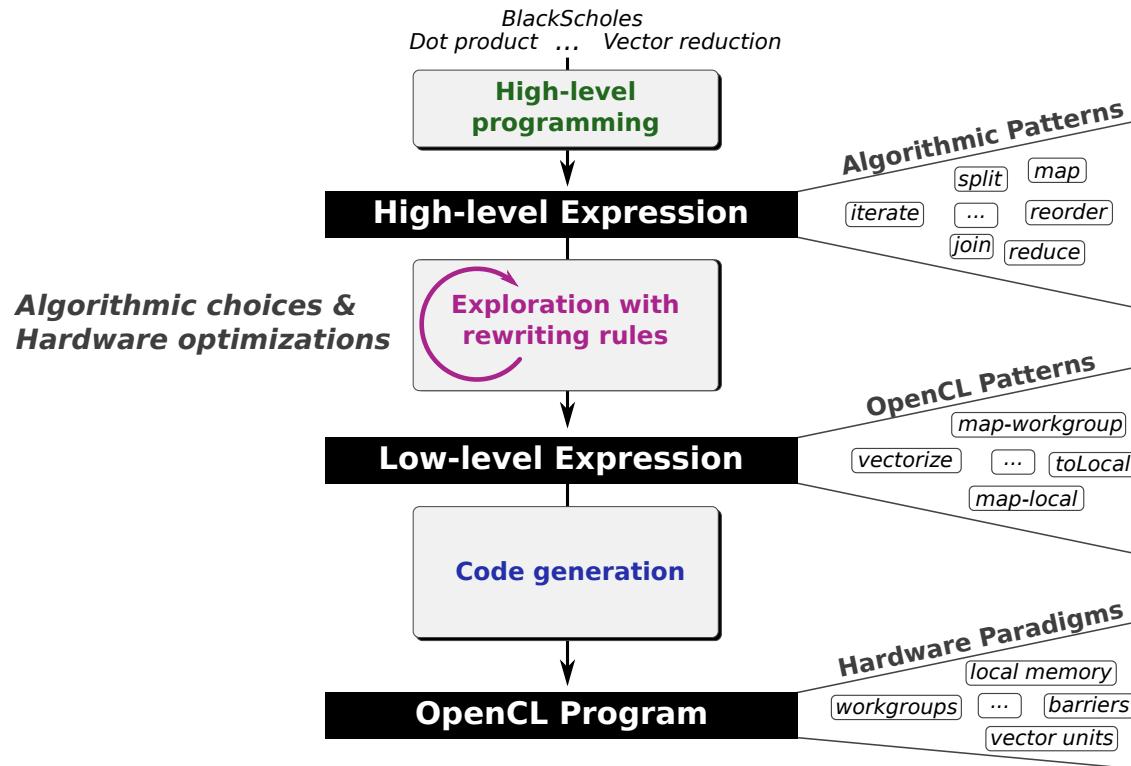
(b) AMD's HD 7970 GPU.



(c) Intel's E5530 dual-socket CPU.

- ... unfortunately, optimisations in OpenCL are not portable!
- **Challenge:** how to achieving portable performance?

# Generating Performance Portable Code using Rewrite Rules



- Goal: automatic generation of *Performance Portable* code

# Example Parallel Reduction ③

①  $\text{vecSum} = \text{reduce } (+) 0$

I  
rewrite rules      code generation

②

```
vecSum = reduce ∘ join ∘ map-workgroup (
    join ∘ toGlobal (map-local (map-seq id)) ∘ split 1 ∘
    join ∘ map-warp (
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 1 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 2 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 4 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 8 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 16 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 32 ∘
    ) ∘ split 64 ∘
    join ∘ map-local (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 64 ∘
    join ∘ toLocal (map-local (reduce-seq (+) 0)) ∘
    split (blockSize/128) ∘ reorder-stride 128 ∘
) ∘ split blockSize
```

```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```



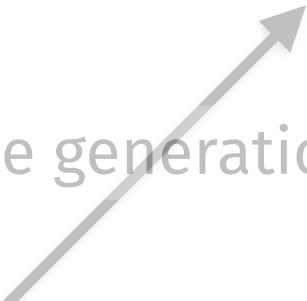
# Example Parallel Reduction

③

①  $\text{vecSum} = \text{reduce } (+) 0$

②

$\text{vecSum} = \text{reduce} \circ \text{join} \circ \text{map-workgroup} ($   
   $\text{join} \circ \text{toGlobal} (\text{map-local} (\text{map-seq id})) \circ \text{split 1} \circ$   
   $\text{join} \circ \text{map-warp} ($   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 1} \circ$   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 2} \circ$   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 4} \circ$   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 8} \circ$   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 16} \circ$   
     $\text{join} \circ \text{map-lane} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 32}$   
   $) \circ \text{split 64} \circ$   
   $\text{join} \circ \text{map-local} (\text{reduce-seq } (+) 0) \circ \text{split 2} \circ \text{reorder-stride 64} \circ$   
   $\text{join} \circ \text{toLocal} (\text{map-local} (\text{reduce-seq } (+) 0)) \circ$   
   $\text{split} (\text{blockSize}/128) \circ \text{reorder-stride 128}$   
 $) \circ \text{split blockSize}$



```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);

    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
            barrier(CLK_LOCAL_MEM_FENCE);
        }
        if (WG_SIZE >= 128) {
            if (tid < 64) {
                l_data[tid] += l_data[tid+ 64];
                barrier(CLK_LOCAL_MEM_FENCE);
            }
            if (tid < 32) {
                if (WG_SIZE >= 64) {
                    l_data[tid] += l_data[tid+32];
                }
                if (WG_SIZE >= 32) {
                    l_data[tid] += l_data[tid+16];
                }
                if (WG_SIZE >= 16) {
                    l_data[tid] += l_data[tid+ 8];
                }
                if (WG_SIZE >= 8) {
                    l_data[tid] += l_data[tid+ 4];
                }
                if (WG_SIZE >= 4) {
                    l_data[tid] += l_data[tid+ 2];
                }
                if (WG_SIZE >= 2) {
                    l_data[tid] += l_data[tid+ 1];
                }
            }
            if (tid == 0)
                g_odata[get_group_id(0)] = l_data[0];
        }
    }
}
```



# ① Algorithmic Primitives

$map_{A,B,I} : (A \rightarrow B) \rightarrow [A]_I \rightarrow [B]_I$

$zip_{A,B,I} : [A]_I \rightarrow [B]_I \rightarrow [A \times B]_I$

$reduce_{A,I} : ((A \times A) \rightarrow A) \rightarrow A \rightarrow [A]_I \rightarrow [A]_1$

$split_{A,I} : (n : \text{size}) \rightarrow [A]_{n \times I} \rightarrow [[A]_n]_I$

$join_{A,I,J} : [[A]_I]_J \rightarrow [A]_{I \times J}$

$iterate_{A,I,J} : (n : \text{size}) \rightarrow ((m : \text{size}) \rightarrow [A]_{I \times m} \rightarrow [A]_m) \rightarrow [A]_{I^n \times J} \rightarrow [A]_J$

$reorder_{A,I} : [A]_I \rightarrow [A]_I$



# ① High-Level Programs

$$scal = \lambda a. map (*a)$$
$$asum = reduce (+) 0 \circ map abs$$
$$dot = \lambda xs ys. (reduce (+) 0 \circ map (*)) (zip xs ys)$$
$$\begin{aligned} gemv = \lambda mat xs ys \alpha \beta. & map (+) ( \\ & zip (map (scal \alpha \circ dot xs) mat) (scal \beta ys) ) \end{aligned}$$


# Example Parallel Reduction ③

①  $\text{vecSum} = \text{reduce } (+) 0$

I  
rewrite rules      code generation

②

```
vecSum = reduce ∘ join ∘ map-workgroup (
    join ∘ toGlobal (map-local (map-seq id)) ∘ split 1 ∘
    join ∘ map-warp (
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 1 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 2 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 4 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 8 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 16 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 32 ∘
    ) ∘ split 64 ∘
    join ∘ map-local (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 64 ∘
    join ∘ toLocal (map-local (reduce-seq (+) 0)) ∘
    split (blockSize/128) ∘ reorder-stride 128 ∘
) ∘ split blockSize
```

```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```



# Example Parallel Reduction

③

①  $\text{vecSum} = \text{reduce } (+) 0$

I  
rewrite rules      code generation



②

```
vecSum = reduce ∘ join ∘ map-workgroup (
    join ∘ toGlobal (map-local (map-seq id)) ∘ split 1 ∘
    join ∘ map-warp (
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 1 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 2 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 4 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 8 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 16 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 32 ∘
    ) ∘ split 64 ∘
    join ∘ map-local (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 64 ∘
    join ∘ toLocal (map-local (reduce-seq (+) 0)) ∘
    split (blockSize/128) ∘ reorder-stride 128 ∘
) ∘ split blockSize
```

```
kernel
void reduce6(global float* g_idata,
            global float* g_odata,
            unsigned int n,
            local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```



## ② Algorithmic Rewrite Rules

- Provably correct rewrite rules
- Express algorithmic implementation choices

Split-join rule:

$$\text{map } f \rightarrow \text{join} \circ \text{map } (\text{map } f) \circ \text{split } n$$

Map fusion rule:

$$\text{map } f \circ \text{map } g \rightarrow \text{map } (f \circ g)$$

Reduce rules:

$$\text{reduce } f z \rightarrow \text{reduce } f z \circ \text{reducePart } f z$$

$$\text{reducePart } f z \rightarrow \text{reducePart } f z \circ \text{reorder}$$

$$\text{reducePart } f z \rightarrow \text{join } \circ \text{map } (\text{reducePart } f z) \circ \text{split } n$$

$$\text{reducePart } f z \rightarrow \text{iterate } n \ (\text{reducePart } f z)$$



## ② OpenCL Primitives

### Primitive

*mapGlobal*

*mapWorkgroup*

*mapLocal*

*mapSeq*

*reduceSeq*

*toLocal* , *toGlobal*

*mapVec*,  
*splitVec*, *joinVec*

### OpenCL concept

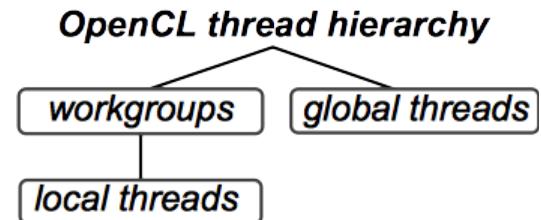
Work-items

Work-groups

Sequential implementations

Memory areas

Vectorization



## ② OpenCL Rewrite Rules

- Express low-level implementation and optimisation choices

Map rules:

$$\text{map } f \rightarrow \text{mapWorkgroup } f \mid \text{mapLocal } f \mid \text{mapGlobal } f \mid \text{mapSeq } f$$

Local/ global memory rules:

$$\text{mapLocal } f \rightarrow \text{toLocal} (\text{mapLocal } f) \quad \text{mapLocal } f \rightarrow \text{toGlobal} (\text{mapLocal } f)$$

Vectorisation rule:

$$\text{map } f \rightarrow \text{joinVec} \circ \text{map} (\text{mapVec } f) \circ \text{splitVec } n$$

Fusion rule:

$$\text{reduceSeq } f \ z \circ \text{mapSeq } g \rightarrow \text{reduceSeq} (\lambda (acc, x). \ f (acc, g \ x)) \ z$$

# Example Parallel Reduction ③

①  $\text{vecSum} = \text{reduce } (+) 0$

I  
rewrite rules      code generation

②

```
vecSum = reduce ∘ join ∘ map-workgroup (
    join ∘ toGlobal (map-local (map-seq id)) ∘ split 1 ∘
    join ∘ map-warp (
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 1 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 2 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 4 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 8 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 16 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 32 ∘
    ) ∘ split 64 ∘
    join ∘ map-local (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 64 ∘
    join ∘ toLocal (map-local (reduce-seq (+) 0)) ∘
    split (blockSize/128) ∘ reorder-stride 128 ∘
) ∘ split blockSize
```

```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```

# Example Parallel Reduction ③

①  $\text{vecSum} = \text{reduce } (+) \ 0$

rewrite rules

code generation

②

```
vecSum = reduce ∘ join ∘ map-workgroup (
    join ∘ toGlobal (map-local (map-seq id)) ∘ split 1 ∘
    join ∘ map-warp (
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 1 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 2 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 4 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 8 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 16 ∘
        join ∘ map-lane (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 32 ∘
    ) ∘ split 64 ∘
    join ∘ map-local (reduce-seq (+) 0) ∘ split 2 ∘ reorder-stride 64 ∘
    join ∘ toLocal (map-local (reduce-seq (+) 0)) ∘
    split (blockSize/128) ∘ reorder-stride 128 ∘
) ∘ split blockSize
```

```
kernel
void reduce6(global float* g_idata,
             global float* g_odata,
             unsigned int n,
             local volatile float* l_data) {
    unsigned int tid = get_local_id(0);
    unsigned int i =
        get_group_id(0) * (get_local_size(0)*2)
        + get_local_id(0);
    unsigned int gridSize =
        WG_SIZE * get_num_groups(0);
    l_data[tid] = 0;
    while (i < n) {
        l_data[tid] += g_idata[i];
        if (i + WG_SIZE < n)
            l_data[tid] += g_idata[i+WG_SIZE];
        i += gridSize;
    }
    barrier(CLK_LOCAL_MEM_FENCE);

    if (WG_SIZE >= 256) {
        if (tid < 128) {
            l_data[tid] += l_data[tid+128];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (WG_SIZE >= 128) {
        if (tid < 64) {
            l_data[tid] += l_data[tid+ 64];
        }
        barrier(CLK_LOCAL_MEM_FENCE);
    }
    if (tid < 32) {
        if (WG_SIZE >= 64) {
            l_data[tid] += l_data[tid+32];
        }
        if (WG_SIZE >= 32) {
            l_data[tid] += l_data[tid+16];
        }
        if (WG_SIZE >= 16) {
            l_data[tid] += l_data[tid+ 8];
        }
        if (WG_SIZE >= 8) {
            l_data[tid] += l_data[tid+ 4];
        }
        if (WG_SIZE >= 4) {
            l_data[tid] += l_data[tid+ 2];
        }
        if (WG_SIZE >= 2) {
            l_data[tid] += l_data[tid+ 1];
        }
    }
    if (tid == 0)
        g_odata[get_group_id(0)] = l_data[0];
}
```

# ③ Pattern based OpenCL Code Generation

- Generate OpenCL code for each OpenCL primitive

*mapGlobal f xs* →

```
for (int g_id = get_global_id(0); g_id < n;  
     g_id += get_global_size(0)) {  
    output[g_id] = f(xs[g_id]);  
}
```

*reduceSeq f z xs* →

```
T acc = z;  
for (int i = 0; i < n; ++i) {  
    acc = f(acc, xs[i]);  
}
```

⋮

⋮



# Rewrite rules define a space of possible implementations

*reduce (+) 0*



*reduce (+) 0 ○ reducePart (+) 0*

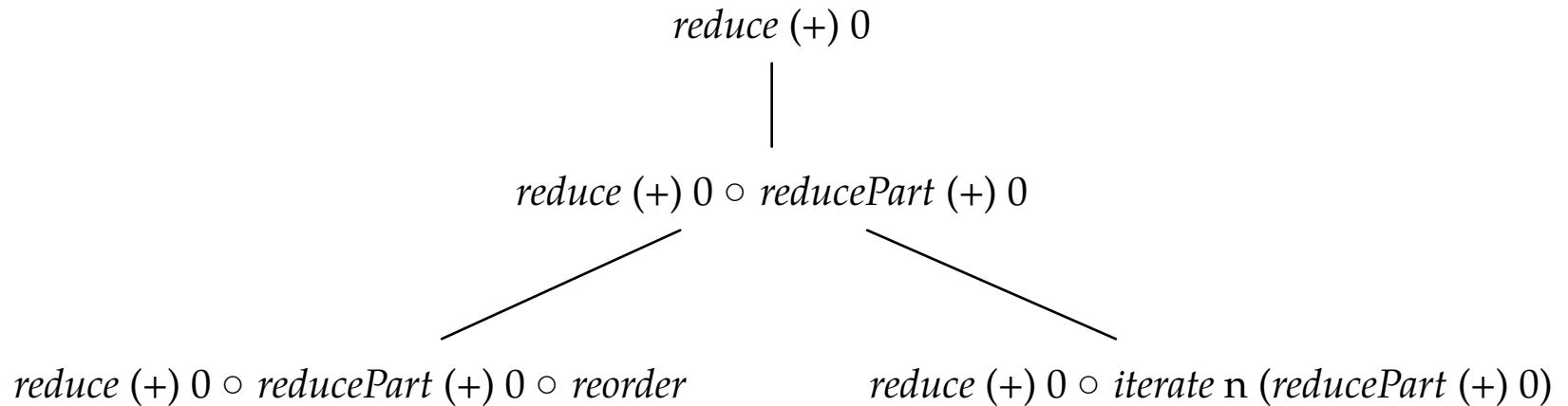


# Rewrite rules define a space of possible implementations

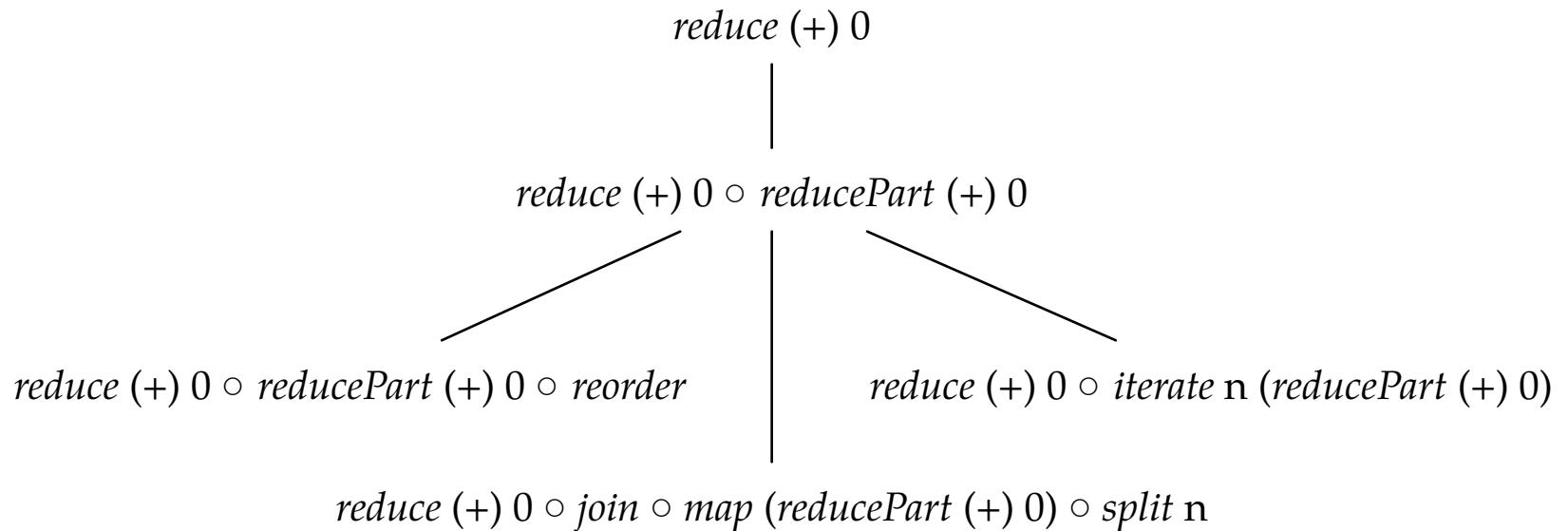
*reduce (+) 0*  
|  
*reduce (+) 0 ○ reducePart (+) 0*  
  
*reduce (+) 0 ○ reducePart (+) 0 ○ reorder*



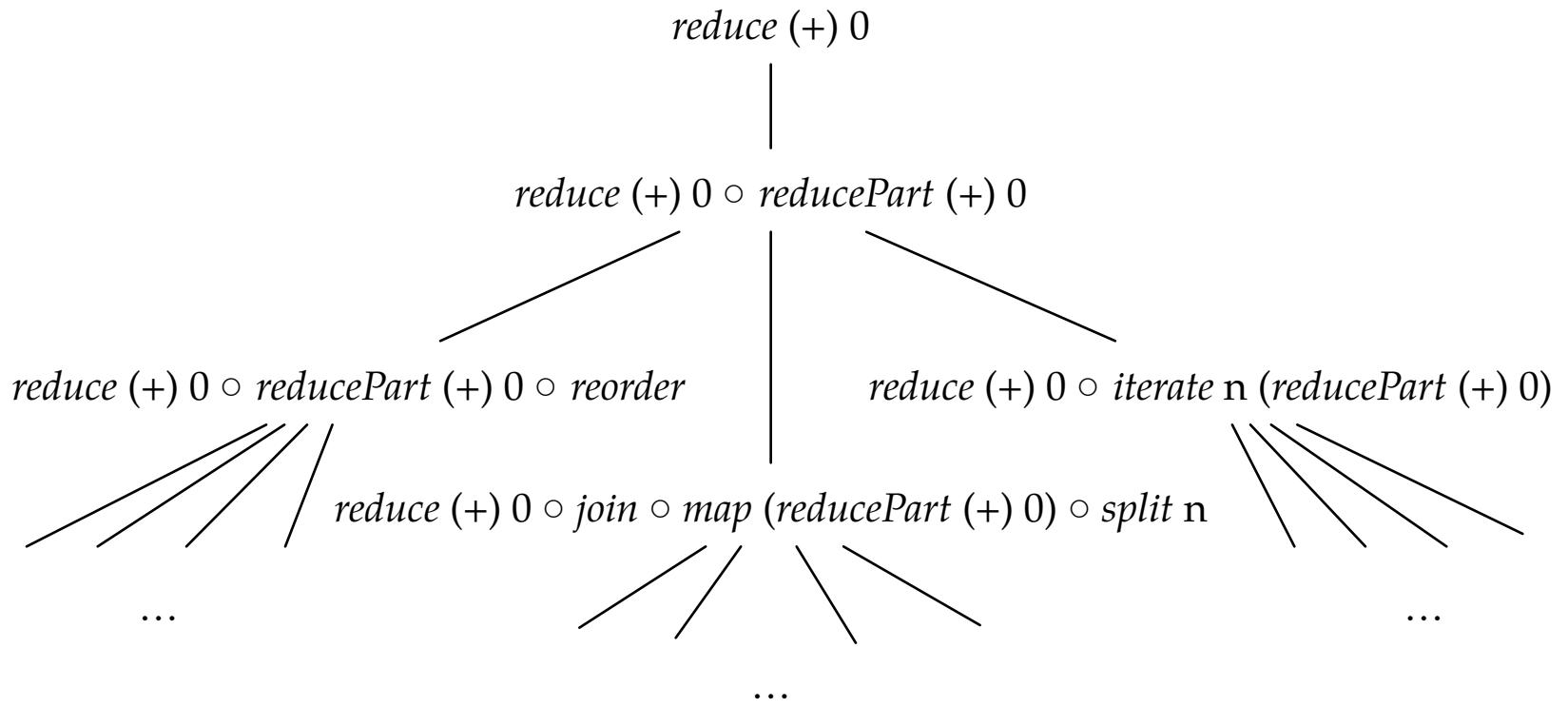
# Rewrite rules define a space of possible implementations



# Rewrite rules define a space of possible implementations



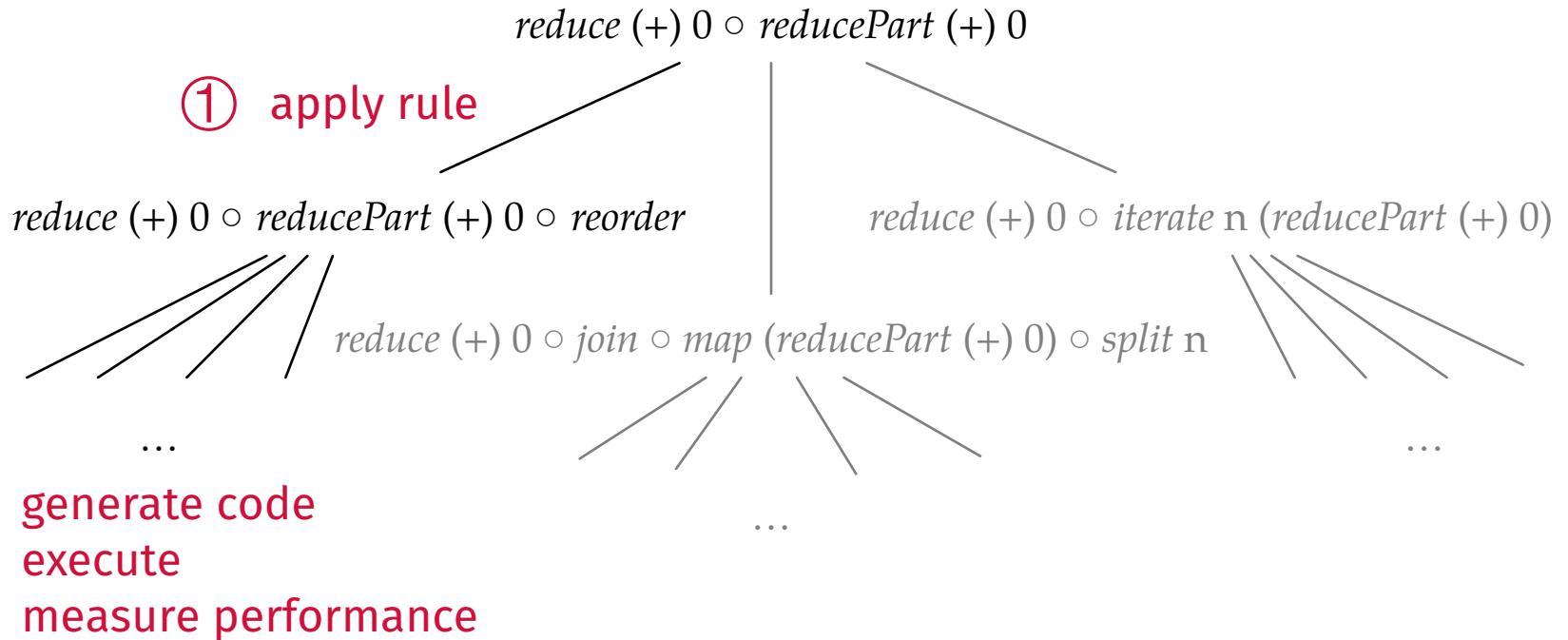
# Rewrite rules define a space of possible implementations



- Fully automated search for good implementations possible

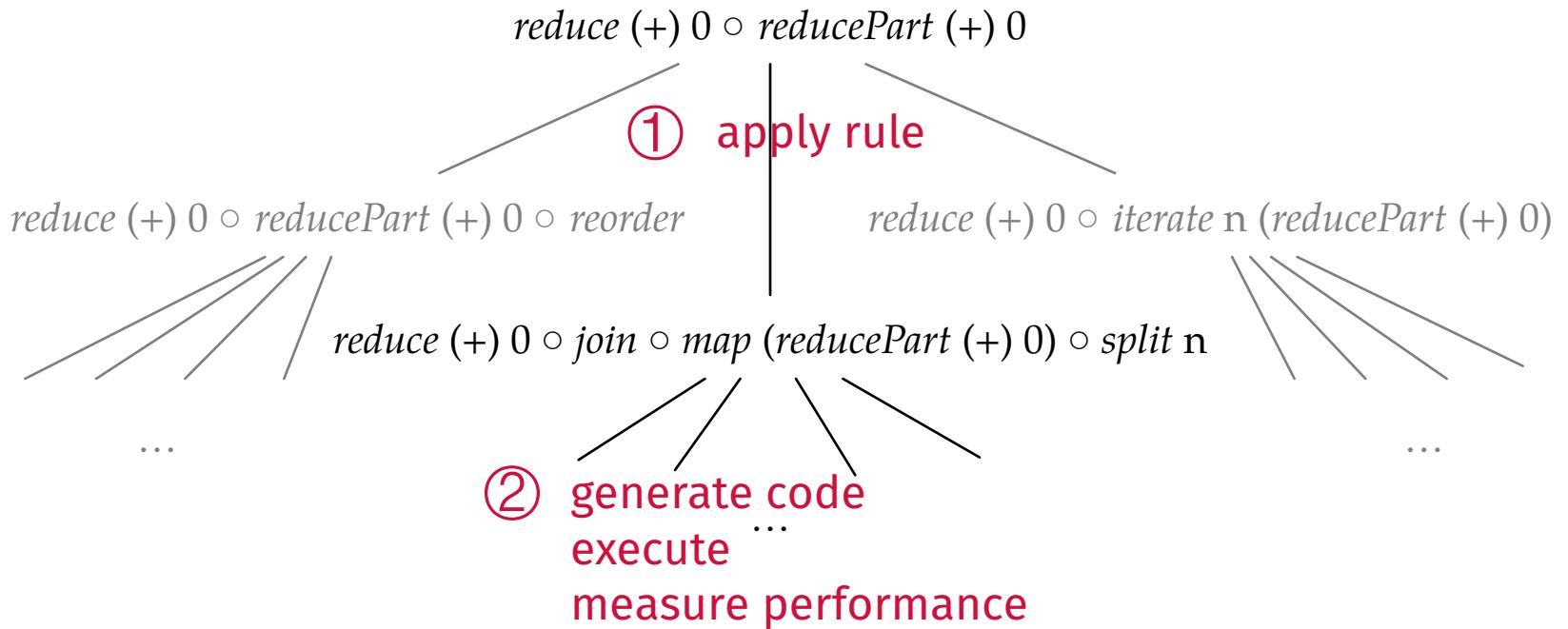
# Search Strategy

- For each node in the tree:
  - Apply one rule and randomly sample subtree
  - Repeat for node with best performing subtree



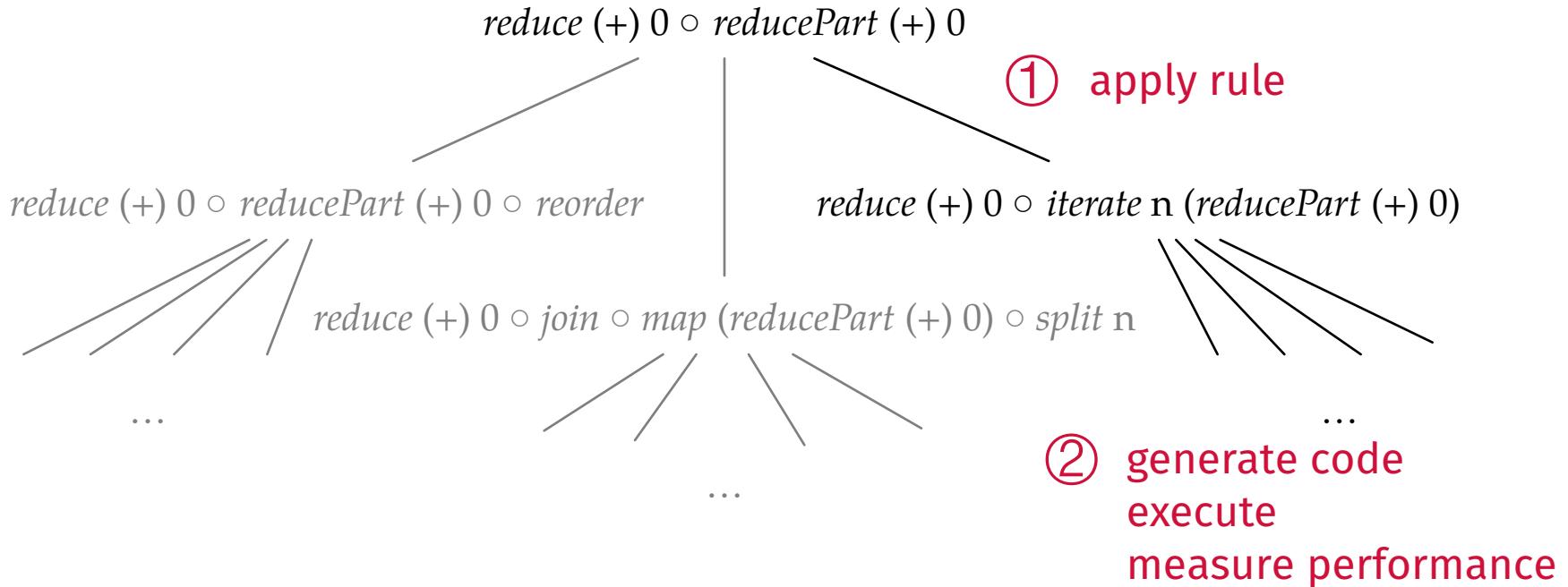
# Search Strategy

- For each node in the tree:
  - Apply one rule and randomly sample subtree
  - Repeat for node with best performing subtree



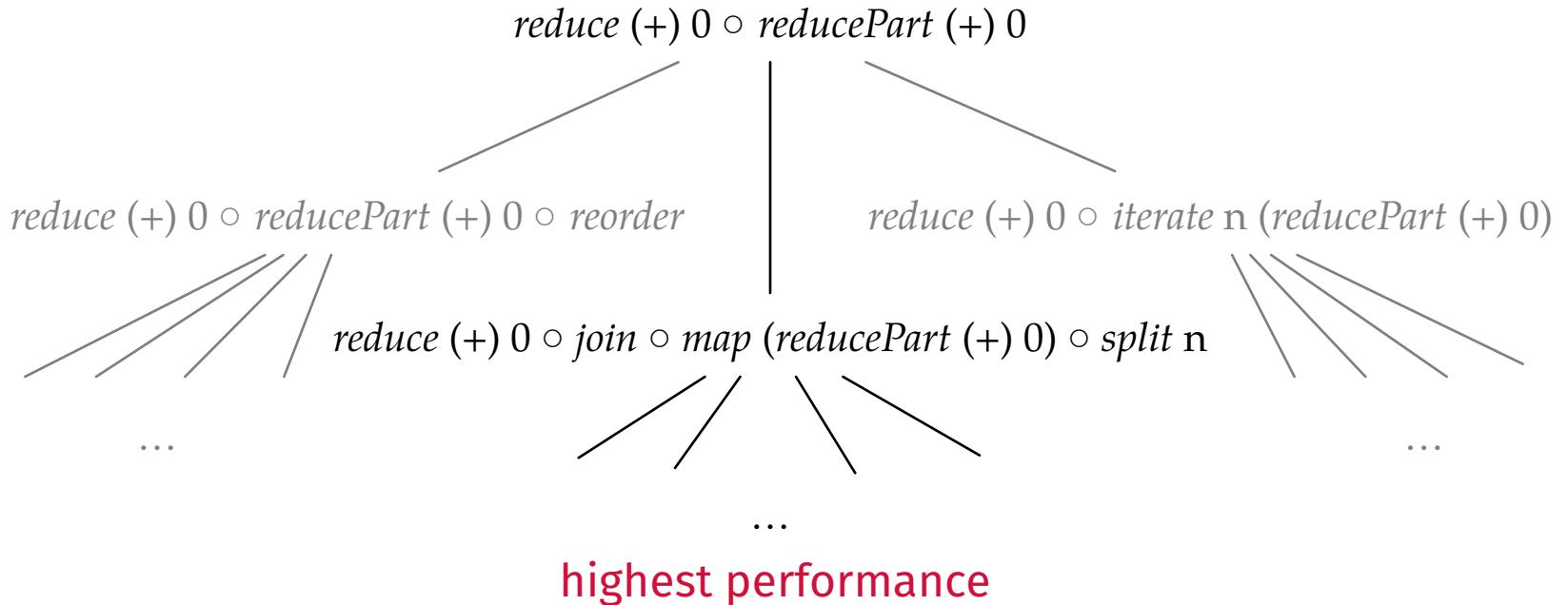
# Search Strategy

- For each node in the tree:
  - Apply one rule and randomly sample subtree
  - Repeat for node with best performing subtree



# Search Strategy

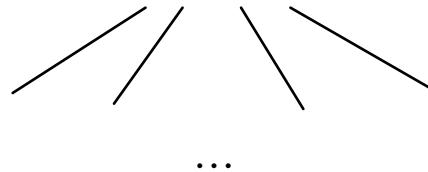
- For each node in the tree:
  - Apply one rule and randomly sample subtree
  - Repeat for node with best performing subtree



# Search Strategy

- For each node in the tree:
  - Apply one rule and randomly sample subtree
  - Repeat for node with best performing subtree

*reduce (+) 0 ○ join ○ map (reducePart (+) 0) ○ split n*



③ repeat process



# Search Results

## Automatically Found Expressions

$$asum = reduce (+) 0 \circ map abs$$


Nvidia  
GPU

$$\lambda x. (reduceSeq \circ join \circ join \circ mapWorkgroup (\\ toGlobal (mapLocal (reduceSeq (\lambda(a, b). a + (abs b)) 0)) \circ reorderStride 2048 \\ ) \circ split 128 \circ split 2048) x$$

AMD  
GPU

$$\lambda x. (reduceSeq \circ join \circ joinVec \circ join \circ mapWorkgroup (\\ mapLocal (reduceSeq (mapVec 2 (\lambda(a, b). a + (abs b))) 0 \circ reorderStride 2048 \\ ) \circ split 128 \circ splitVec 2 \circ split 4096) x$$

Intel  
CPU

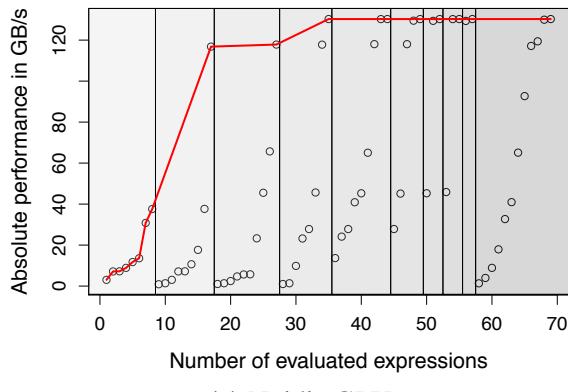
$$\lambda x. (reduceSeq \circ join \circ mapWorkgroup (join \circ joinVec \circ mapLocal (\\ reduceSeq (mapVec 4 (\lambda(a, b). a + (abs b))) 0 \\ ) \circ splitVec 4 \circ split 32768) \circ split 32768) x$$

- Search on: **Nvidia GTX 480 GPU, AMD Radeon HD 7970 GPU, Intel Xeon E5530 CPU**

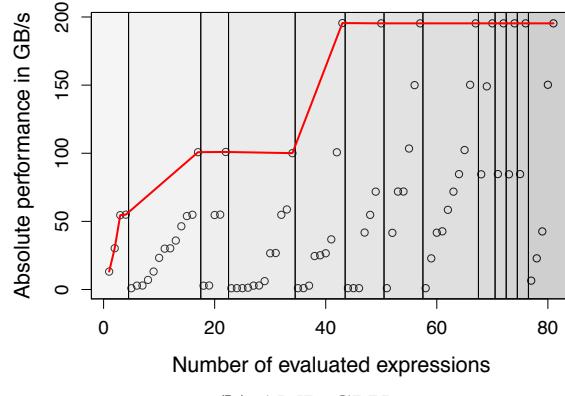


# Search Results

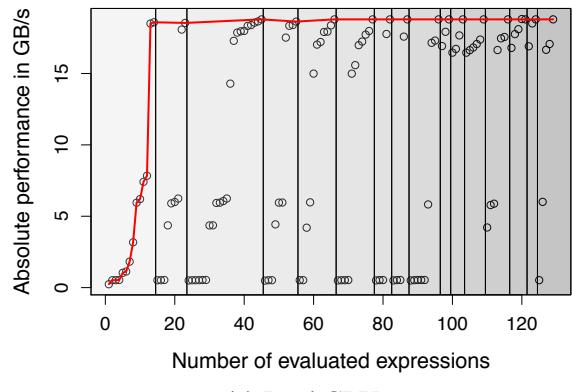
## Search Efficiency



(a) Nvidia GPU



(b) AMD GPU



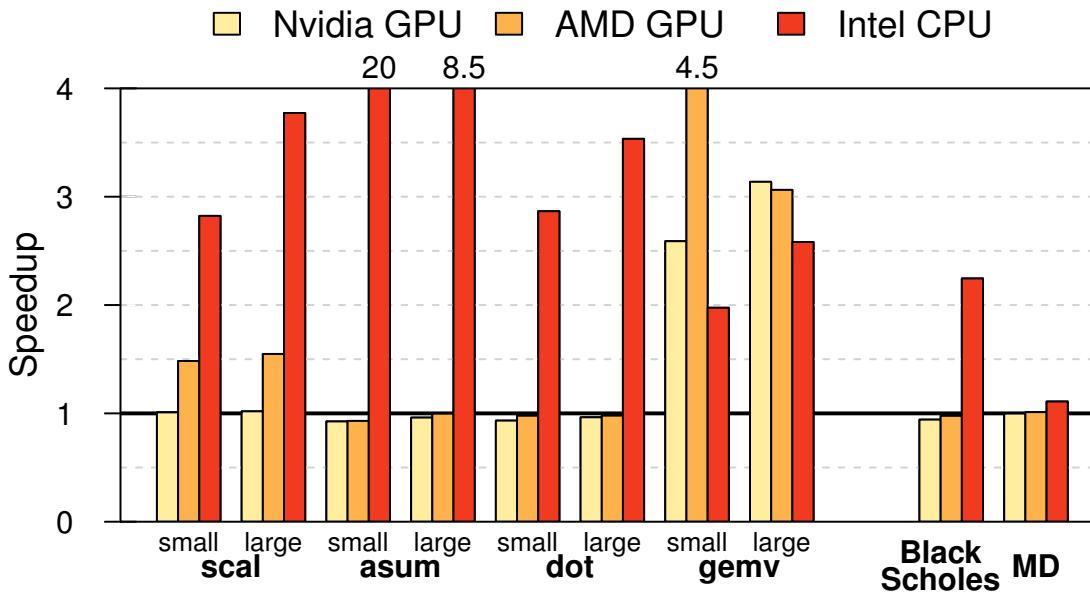
(c) Intel CPU

- Overall search on each platform took < 1 hour
- Average execution time per tested expression < 1/2 second



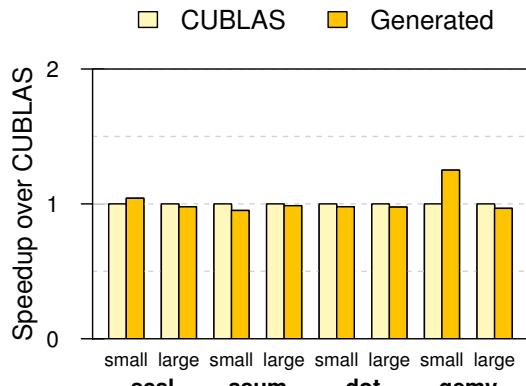
# Performance Results

## vs. Portable Implementation

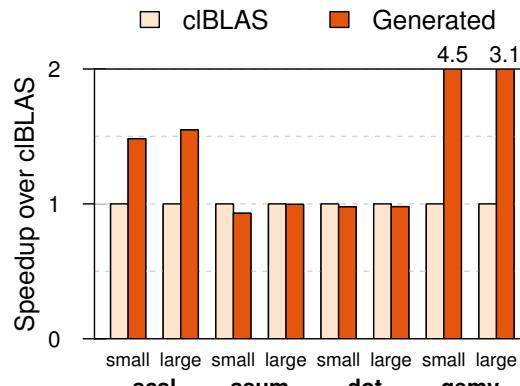


- Up to 20x speedup on fairly simple benchmarks vs. portable clBLAS implementation

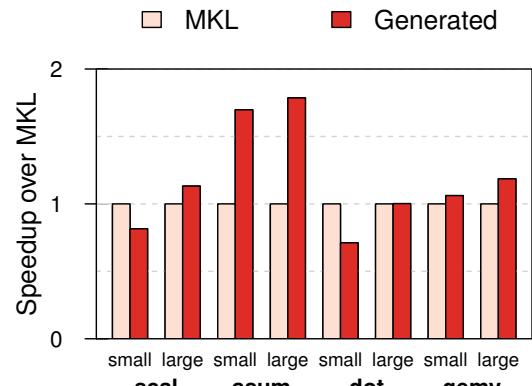
# Performance Results vs. Hardware-Specific Implementations



(a) Nvidia GPU



(b) AMD GPU



(c) Intel CPU

- Automatically generated code vs. expert written code
- Competitive performance vs. highly optimised implementations
- Up to **4.5x** speedup for *gemv* on AMD

# Summary

- OpenCL code is not *performance portable*
- Our approach uses
  - functional **high-level primitives**,
  - **OpenCL-specific low-level primitives**, and
  - **rewrite-rules** to generate *performance portable* code.
- Rewrite-rules define a space of possible implementations
- Performance on par with specialised, highly-tuned code

Michel Steuwer — [michel.steuwer@ed.ac.uk](mailto:michel.steuwer@ed.ac.uk)

