



**Sceintific project  
on  
Automated Guided Vehicle(AGV)**

**Supervisors:**  
**Dr.-Ing. Tobias Reggelin**  
**M.Sc. Sebastian Lang**

**Presented by:**  
**Vasu Dev Mukku**

# Agenda

- Introduction
- Motivation
- Conceptual Design
- Implementation
- Design problems and Limitations
- Conclusion
- Demos



# Introduction

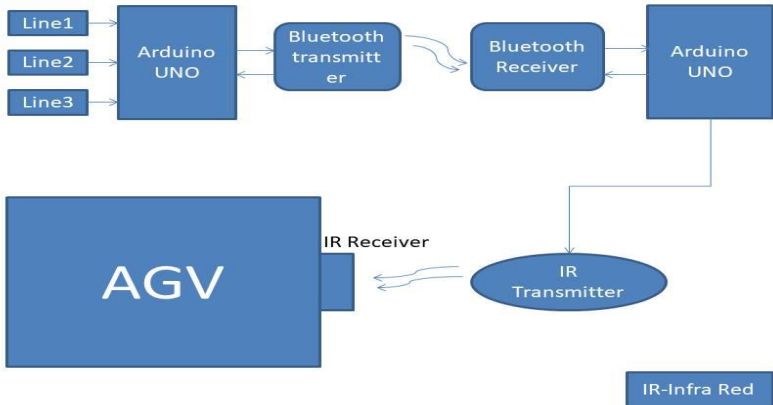
- The central idea of our project is to build an intelligent vehicle in smart industry
- Communication between AGV and conveyor systems
- Bluetooth and IR communication
- Obstacle avoidance



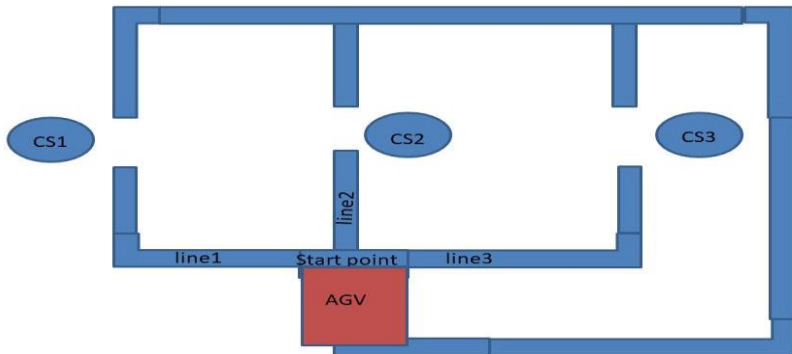
## Motivation

- Implementation of advanced technology in industry
- Decrease of production cost
- Exploring new ideas to improve industry automation

## Conceptual Design of AGV



## Conceptual Design of Path prototype



CS-Conveyor System

# Implementation

- Communication Protocols
- Central Master Transmitter
- Slave Receiver on top of AGV
- Implementation of AGV

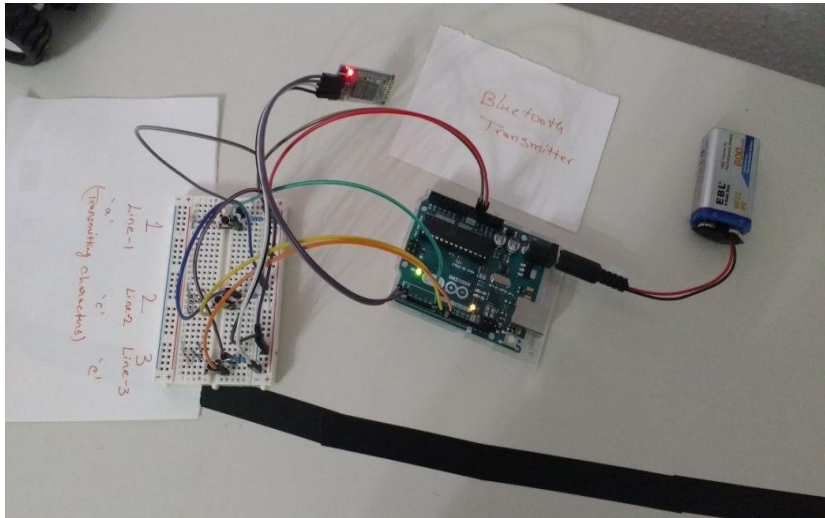


# Communication Protocols

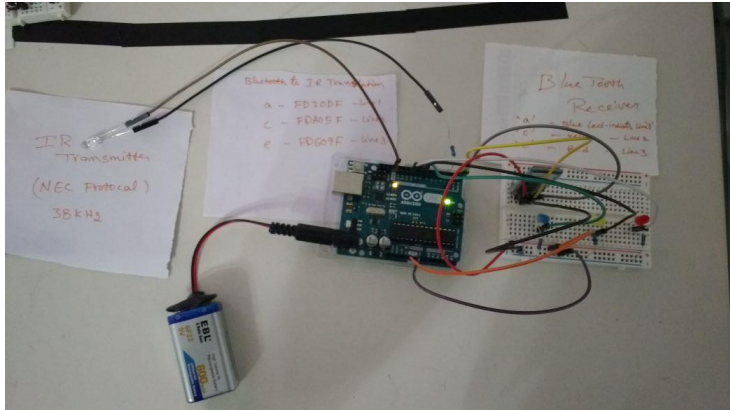
- Bluetooth communication
- IR communication



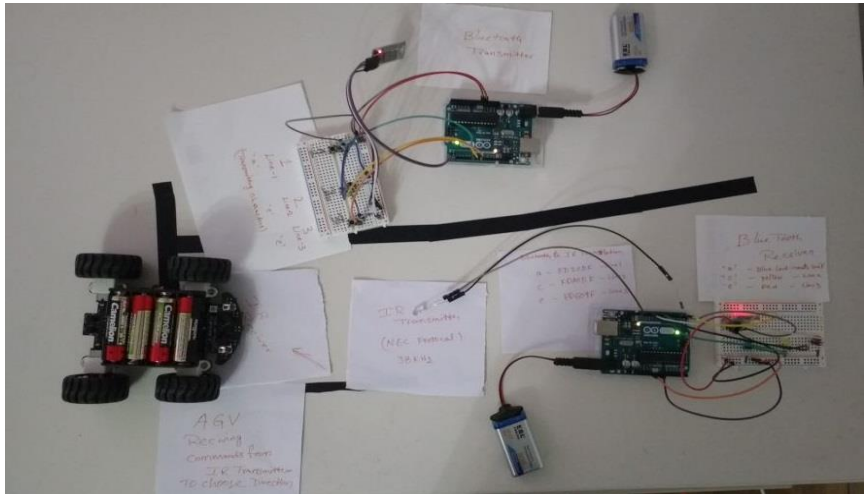
# Central Master Transmitter



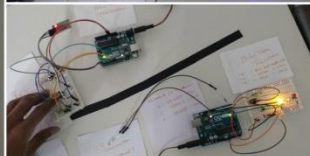
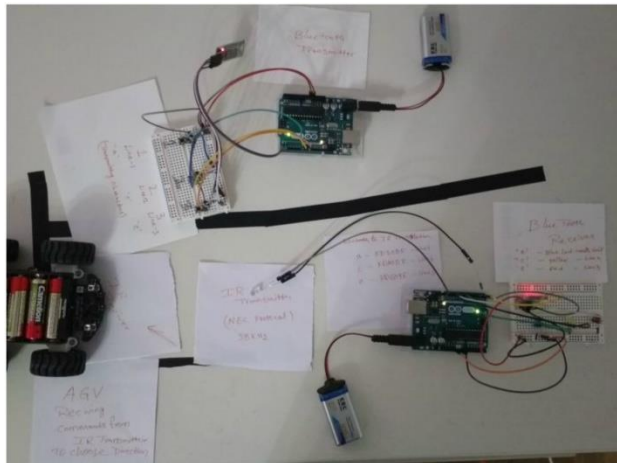
## Slave Receiver on top of AGV



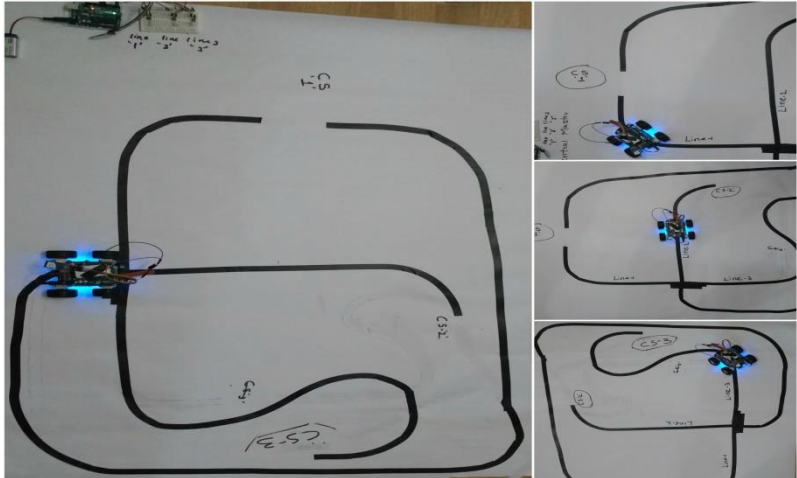
# Implementation of AGV



## Complete setup of AGV



## AGV serving different conveyor systems



## Design Problems and Limitations

- Obstacle Detection
- Battery
- Low range sensors

## Conclusion

- Conveyor systems can communicate with AGV
- AGV responds to Command from Central Master
- Navigate to start point
- Obstacle detection is possible without IR communication

# DEMOS







**Thanks for your attention!**