

# CMPT 409/981: Optimization for Machine Learning

## Lecture 4

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# Recap

- For  $L$ -smooth functions lower-bounded by  $f^*$ , GD with backtracking Armijo line-search returns an  $\epsilon$  stationary-point in  $O\left(\frac{1}{\epsilon}\right)$  iterations without requiring the knowledge of  $L$ .
- **Convex sets:** Set  $\mathcal{C}$  is convex iff  $\forall x, y \in \mathcal{C}$ , the convex combination  $z_\theta := \theta x + (1 - \theta)y$  for  $\theta \in [0, 1]$  is also in  $\mathcal{C}$ .
  - *Examples:* Half-space:  $\{x | Ax \leq b\}$ , Norm-ball:  $\{x | \|x\|_p \leq r\}$ .
- **Convex functions:** A function  $f$  is convex iff its domain  $\mathcal{D}$  is a convex set, and for all  $x, y \in \mathcal{D}$  and  $\theta \in [0, 1]$ ,  $f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$ .
  - *First-order definition:* If  $f$  is differentiable, it is convex iff its domain  $\mathcal{D}$  is a convex set and for all  $x, y \in \mathcal{D}$ ,  $f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$ .
  - *Second-order definition:* If  $f$  is twice differentiable, it is convex iff its domain  $\mathcal{D}$  is a convex set and for all  $x \in \mathcal{D}$ ,  $\nabla^2 f(x) \succeq 0$ .
  - *Examples:* All norms  $\|x\|_p$ , Negative entropy:  $f(x) = x \log(x)$ , Logistic regression:  $\sum_{i=1}^n \log(1 + \exp(-y_i \langle X_i, w \rangle))$ , Ridge regression:  $\frac{1}{2} \|Xw - y\|^2 + \frac{\lambda}{2} \|w\|^2$ .

# Jensen's Inequality

- Recall the zero-order definition of convexity:  $\forall x, y \in \mathcal{D}$  and  $\theta \in [0, 1]$ ,  
 $f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$ .

This can be generalized to  $n$  points  $\{x_1, x_2, \dots, x_n\}$ , i.e. for  $p_i \geq 0$  and  $\sum_i p_i = 1$ ,

$$f(p_1 x_1 + p_2 x_2 + \dots + p_n x_n) \leq p_1 f(x_1) + p_2 f(x_2) + \dots + p_n f(x_n) \implies f\left(\sum_{i=1}^n p_i x_i\right) \leq \sum_{i=1}^n p_i f(x_i)$$

- If  $X$  is a discrete r.v. that can take value  $x_i$  with probability  $p_i$ , and  $f$  is convex, then,

$$f(\mathbb{E}[X]) \leq \mathbb{E}[f(X)]. \quad (\text{Jensen's inequality})$$

- Jensen's inequality can be used to prove inequalities like the AM-GM inequality:

$$\sqrt{ab} \leq \frac{a+b}{2}.$$

- Proof:* Choose  $f(x) = -\log(x)$  as the convex function, and consider two points  $a$  and  $b$  with  $\theta = 1/2$ . By Jensen's inequality,

$$-\log\left(\frac{a+b}{2}\right) \leq \frac{-\log(a) - \log(b)}{2} \implies \log\left(\frac{a+b}{2}\right) \geq \log(\sqrt{ab}) \implies \frac{a+b}{2} \geq \sqrt{ab}.$$

# Holder's Inequality

**Q:** Prove Holder's inequality, for  $p, q \geq 1$  s.t.  $\frac{1}{p} + \frac{1}{q} = 1$  and  $x, y \in R^n$ ,  $|\langle x, y \rangle| \leq \|x\|_p \|y\|_q$ .

*Proof:* By repeating the AM-GM proof, but for a general  $\theta \in [0, 1]$ , for  $a, b \geq 0$ , we can prove

$$a^\theta b^{1-\theta} \leq \theta a + (1 - \theta)b$$

Use  $a = \frac{|x_i|^p}{\sum_{j=1}^n |x_j|^p}$ ,  $b = \frac{|y_i|^q}{\sum_{j=1}^n |y_j|^q}$ ,  $\theta = 1/p$ , and using the fact that  $1 - \theta = 1 - 1/p = 1/q$

$$\left( \frac{|x_i|^p}{\sum_{j=1}^n |x_j|^p} \right)^{1/p} \left( \frac{|y_i|^q}{\sum_{j=1}^n |y_j|^q} \right)^{1/q} \leq \frac{1}{p} \frac{|x_i|^p}{\sum_{j=1}^n |x_j|^p} + \frac{1}{q} \frac{|y_i|^q}{\sum_{j=1}^n |y_j|^q}$$

Summing both sides from  $i = 1$  to  $n$  and using the fact that  $\frac{1}{p} + \frac{1}{q} = 1$

$$\begin{aligned} \sum_{i=1}^n \frac{|x_i|}{\left( \sum_{j=1}^n |x_j|^p \right)^{1/p}} \frac{|y_i|}{\left( \sum_{j=1}^n |y_j|^q \right)^{1/q}} &\leq 1 \implies \sum_i |x_i y_i| \leq \left( \sum_{i=1}^n |x_i|^p \right)^{1/p} \left( \sum_{i=1}^n |y_i|^q \right)^{1/q} \\ &\implies |\langle x, y \rangle| \leq \|x\|_p \|y\|_q \quad \text{(Triangle inequality)} \end{aligned}$$

# GD for Smooth, Convex Functions

Recall that for convex functions, minimizing the gradient norm results in finding the minimizer. Let us analyze the convergence of GD for smooth, convex problems:  $\min_{w \in \mathbb{R}^d} f(w)$ .

**Claim:** For  $L$ -smooth, convex functions s.t. for any  $w^* \in \arg \min f(w)$ , GD with  $\eta = \frac{1}{L}$  requires  $T \geq \frac{2L \|w_0 - w^*\|^2}{\epsilon}$  iterations to obtain point  $w_T$  that is  $\epsilon$ -suboptimal meaning that  $f(w_T) \leq f(w^*) + \epsilon$ .

**Proof:** For  $L$ -smooth functions,  $\forall x, y \in \mathcal{D}$ ,  $f(y) \leq f(x) + \langle \nabla f(x), y - x \rangle + \frac{L}{2} \|y - x\|^2$ . Similar to Lecture 2, using GD:  $w_{k+1} = w_k - \frac{1}{L} \nabla f(w_k)$  yields

$$f(w_{k+1}) - f(w^*) \leq f(w_k) - f(w^*) - \frac{1}{2L} \|\nabla f(w_k)\|^2 \quad (1)$$

Using  $y = w^*$ ,  $x = w_k$  in the first-order condition for convexity:  $f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$ ,

$$\begin{aligned} f(w_k) - f(w^*) &\leq \langle \nabla f(w_k), w_k - w^* \rangle \leq \|\nabla f(w_k)\| \|w_k - w^*\| && \text{(Cauchy Schwarz)} \\ \implies \|\nabla f(w_k)\| &\geq \frac{f(w_k) - f(w^*)}{\|w_k - w^*\|} && (2) \end{aligned}$$

# GD for Smooth, Convex Functions

In addition to descent on the function, when minimizing smooth, convex functions, GD decreases the distance to a minimizer  $w^*$ .

**Claim:** For GD with  $\eta = \frac{1}{L}$ ,  $\|w_{k+1} - w^*\|^2 \leq \|w_k - w^*\|^2 \leq \|w_0 - w^*\|^2$ .

**Proof:**

$$\|w_{k+1} - w^*\|^2 = \|w_k - \eta \nabla f(w_k) - w^*\|^2 = \|w_k - w^*\|^2 - 2\eta \langle \nabla f(w_k), w_k - w^* \rangle + \eta^2 \|\nabla f(w_k)\|^2$$

Using  $y = w^*$ ,  $x = w_k$  in the first-order condition for convexity:  $f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle$ ,

$$\|w_{k+1} - w^*\|^2 \leq \|w_k - w^*\|^2 - 2\eta[f(w_k) - f(w^*)] + \eta^2 \|\nabla f(w_k)\|^2$$

For convex functions,  $L$ -smoothness is equivalent to

$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{1}{2L} \|\nabla f(x) - \nabla f(y)\|^2$ . Using  $x = w^*$ ,  $y = w_k$  in this equation,

$$\begin{aligned} &\leq \|w_k - w^*\|^2 - 2\eta[f(w_k) - f(w^*)] + 2L\eta^2[f(w_k) - f(w^*)] \\ \implies \|w_{k+1} - w^*\|^2 &\leq \|w_k - w^*\|^2 \quad (\text{By setting } \eta = \frac{1}{L}) \end{aligned}$$

# GD for Smooth, Convex Functions

Combining Eq. 2 with the result of the previous claim,

$$\|\nabla f(w_k)\| \geq \frac{f(w_k) - f(w^*)}{\|w_k - w^*\|} \geq \frac{f(w_k) - f(w^*)}{\|w_0 - w^*\|}$$

Combining the above inequality with Eq. 1,

$$f(w_{k+1}) - f(w^*) \leq f(w_k) - f(w^*) - \frac{1}{2L} \|\nabla f(w_k)\|^2 \leq f(w_k) - f(w^*) - \frac{1}{2L} \frac{[f(w_k) - f(w^*)]^2}{\|w_0 - w^*\|^2}$$

Dividing by  $[f(w_k) - f(w^*)][f(w_{k+1}) - f(w^*)]$

$$\begin{aligned} \frac{1}{f(w_k) - f(w^*)} &\leq \frac{1}{f(w_{k+1}) - f(w^*)} - \frac{1}{2L} \frac{f(w_k) - f(w^*)}{\|w_0 - w^*\|^2} \frac{1}{f(w_{k+1}) - f(w^*)} \\ \Rightarrow \frac{1}{2L \|w_0 - w^*\|^2} \underbrace{\frac{f(w_k) - f(w^*)}{f(w_{k+1}) - f(w^*)}}_{\geq 1} &\leq \left[ \frac{1}{f(w_{k+1}) - f(w^*)} - \frac{1}{f(w_k) - f(w^*)} \right] \end{aligned} \quad (3)$$

# GD for Smooth, Convex Functions

Summing Eq. 3 from  $k = 0$  to  $T - 1$ ,

$$\begin{aligned} \sum_{k=0}^{T-1} \left[ \frac{1}{2L \|w_0 - w^*\|^2} \right] &\leq \sum_{k=0}^{T-1} \left[ \frac{1}{f(w_{k+1}) - f(w^*)} - \frac{1}{f(w_k) - f(w^*)} \right] \\ \frac{T}{2L \|w_0 - w^*\|^2} &\leq \frac{1}{f(w_T) - f(w^*)} - \frac{1}{f(w_0) - f(w^*)} \leq \frac{1}{f(w_T) - f(w^*)} \\ \implies f(w_T) - f(w^*) &\leq \frac{2L \|w_0 - w^*\|^2}{T} \end{aligned}$$

The suboptimality  $f(w_T) - f(w^*)$  decreases at an  $O\left(\frac{1}{T}\right)$  rate, i.e. the function value at iterate  $w_T$  approaches the minimum function value  $f(w^*)$ .

In order to obtain a function value at least  $\epsilon$ -close to the optimal function value, GD requires  $T \geq \frac{2L \|w_0 - w^*\|^2}{\epsilon}$  iterations.



# Minimizing Smooth, Convex Functions

Recall that GD was optimal (amongst first-order methods with no dependence on the dimension) when minimizing smooth (possibly non-convex) functions.

Is GD also optimal when minimizing smooth, convex functions, or can we do better?

**Lower Bound:** For any initialization, there exists a smooth, convex function such that any first-order method requires  $\Omega\left(\frac{1}{\sqrt{\epsilon}}\right)$  iterations.

Possible reasons for the discrepancy between the  $O(1/\epsilon)$  upper-bound for GD, and the  $\Omega(1/\sqrt{\epsilon})$  lower-bound:

- (1) Our upper-bound analysis of GD is loose, and GD actually matches the lower-bound.
- (2) The lower-bound is loose, and there is a function that requires  $\Omega(1/\epsilon)$  iterations to optimize.
- (3) Both the upper and lower-bounds are tight, and GD is sub-optimal. There exists another algorithm that has an  $O(1/\sqrt{\epsilon})$  upper-bound and is hence optimal.

Option (3) is correct – GD is sub-optimal for minimizing smooth, convex functions. Using Nesterov acceleration is optimal and requires  $\Theta(1/\sqrt{\epsilon})$  iterations.

Questions?

# Strongly convex functions

**First-order definition:** If  $f$  is differentiable, it is  $\mu$ -strongly convex iff its domain  $\mathcal{D}$  is a convex set and for all  $x, y \in \mathcal{D}$  and  $\mu > 0$ ,

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle + \frac{\mu}{2} \|y - x\|^2$$

i.e. for all  $y$ , the function is lower-bounded by the quadratic defined in the RHS.

**Second-order definition:** If  $f$  is twice differentiable, it is strongly-convex iff its domain  $\mathcal{D}$  is a convex set and for all  $x \in \mathcal{D}$ ,

$$\nabla^2 f(x) \succeq \mu I_d$$

i.e. for all  $x$ , the eigenvalues of the Hessian are lower-bounded by  $\mu$ .

**Alternative condition:** Function  $g(x) = f(x) - \frac{\mu}{2} \|x\|^2$  is convex, i.e. if we “remove” a quadratic (curvature) from  $f$ , it still remains convex.

*Examples:* Quadratics  $f(x) = x^T A x + b x + c$  are  $\mu$ -strongly convex if  $A \succeq \mu I_d$ . If  $f$  is a convex loss function, then  $g(x) := f(x) + \frac{\lambda}{2} \|x\|^2$  (the  $\ell_2$ -regularized loss) is  $\lambda$ -strongly convex.

# Strongly-convex functions

**Strict-convexity:** If  $f$  is differentiable, it is strictly-convex iff its domain  $\mathcal{D}$  is a convex set and for all  $x, y \in \mathcal{D}$ ,

$$f(y) > f(x) + \langle \nabla f(x), y - x \rangle$$

If  $f$  is  $\mu$  strongly-convex, then it is also strictly convex.

**Q:** For a strictly-convex  $f$ , if  $\nabla f(w^*) = 0$ , then is  $w^*$  a unique minimizer of  $f$ ?

**Q:** Prove that the ridge regression loss function:  $f(w) = \frac{1}{2} \|Xw - y\|^2 + \frac{\lambda}{2} \|w\|^2$  is strongly-convex. Compute  $\mu$ .

**Q:** Is  $f(w) = \frac{1}{2} \|Xw - y\|^2$  strongly-convex?

# Strongly-convex functions

Q: Is negative entropy function  $f(x) = x \ln(x)$  strictly-convex on  $(0, 1)$ ?

Q: Is logistic regression:  $f(w) = \sum_{i=1}^n \log(1 + \exp(-y_i \langle X_i, w \rangle))$  strongly-convex?

Questions?