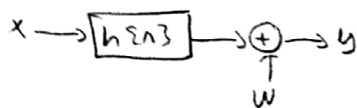


ELEC 462# STATISTICAL SIGNAL PROCESSING
TERM PROJECT

a) Derive the maximum likelihood estimator for X .



(additive white Gaussian channel)

$$y[n] = x[n] \otimes h[n] + w[n] = \sum_{k=-\infty}^{+\infty} x[k] h[n-k] + w[n]$$

(channel equation)

$$\begin{bmatrix} y[0] \\ y[1] \\ y[2] \\ \vdots \\ y[256] \end{bmatrix} = \begin{bmatrix} h[0] & 0 & 0 & \dots & 0 \\ h[1] & h[0] & 0 & \dots & 0 \\ h[2] & h[1] & h[0] & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ h[256] & h[255] & h[254] & \dots & h[0] \end{bmatrix} \cdot \begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ \vdots \\ x[256] \end{bmatrix} + \begin{bmatrix} w[0] \\ w[1] \\ w[2] \\ \vdots \\ w[256] \end{bmatrix}$$

$y = H \cdot x + w$

$x \sim \mathcal{N}(\mu_x, \Sigma_x) : x \sim \mathcal{N}(\mu_x, \Sigma_x)$
 $w \sim \mathcal{N}(0, \sigma^2 I) : w \sim \mathcal{N}(0, 25 \times 10^{-4} I)$
 $y|x \sim \mathcal{N}(Hx, \sigma^2 I)$

$$F_{y|x}(y|x) = P(Y \leq y | X=x) = P(Hx + w \leq y | X=x)$$

$$= P(w \leq y - Hx)$$

$$F_{y|x}(y|x) = F_w(y - Hx)$$

$$\frac{\partial}{\partial y} (F_{y|x}(y|x)) = \frac{\partial}{\partial y} (F_w(y - Hx))$$

$$f_{y|x}(y|x) = f_w(y - Hx) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2} (y - Hx)^T (y - Hx)}$$

likelihood term: $f_{y|x}(y|x) = \frac{1}{(2\pi\sigma^2)^{256/2}} e^{-\frac{1}{2\sigma^2} (y - Hx)^T (y - Hx)}$

Maximum Likelihood: $\hat{x} = \underset{x}{\operatorname{argmax}} (\log(f(y|x)))$

$$\begin{aligned} \hat{J}(x) = \log f(y|x) &= -\frac{L}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} (y - Hx)^T (y - Hx) \\ &= -\frac{1}{2\sigma^2} (y^T y - y^T Hx - (Hx)^T y + (Hx)^T Hx) + \text{constant} \\ &= -\frac{1}{2\sigma^2} (y^T y - y^T Hx - x^T H^T y + x^T H^T Hx) + \text{constant} \\ &= -\frac{1}{2\sigma^2} (y^T y - 2x^T y + x^T H^T Hx) + \text{constant} \end{aligned}$$

$$\hat{J}(x) = \frac{-1}{2\sigma_w^2} (y^T y - 2x^T H^T y + x^T H^T H x) + \text{constant}$$

we want to minimize $\hat{J}(x)$ term. So we'll get derivative and equals it to zero.

$$\frac{\partial \hat{J}(x)}{\partial x} = 0, \quad \frac{-1}{2\sigma_w^2} (-2H^T y + 2H^T H x) = 0$$

$$H^T H x = H^T y$$

$$\hat{x}_{\text{maximum likelihood}} = (H^T H)^{-1} H^T y$$

c) Derive the maximum a-posteriori (MAP) estimator for x

$$\text{likelihood term: } f(y|x) = \frac{1}{(2\pi\sigma_w^2)^{L/2}} \exp \left\{ \frac{-1}{2\sigma_w^2} (y - Hx)^T (y - Hx) \right\}$$

$$\text{prior term: } f(x) = \frac{1}{(2\pi)^{L/2} |\Sigma_x|^{1/2}} \exp \left\{ -\frac{1}{2} (x - \mu_x)^T \Sigma_x^{-1} (x - \mu_x) \right\}$$

$$\hat{x}_{\text{maximum A-Posteriori}} = \arg\max \log f(y|x) f(x)$$

$$\begin{aligned} \text{Let } \hat{J}(x) &= \log[f(y|x) f(x)] \\ &= -\frac{L}{2} \log(2\pi\sigma_w^2) - \frac{1}{2\sigma_w^2} (y - Hx)^T (y - Hx) - \frac{L}{2} \log(2\pi) \\ &\quad - \frac{1}{2} \log |\Sigma_x| - \frac{1}{2} (x - \mu_x)^T \Sigma_x^{-1} (x - \mu_x) \end{aligned}$$

we want to minimize $\hat{J}(x)$ term. So we'll get derivative and equals it to zero.

$$\frac{\partial \hat{J}(x)}{\partial x} = 0$$

$$\frac{1}{\sigma_w^2} H^T (y - Hx) - \Sigma_x^{-1} (x - \mu_x) = 0$$

$$\left(\frac{1}{\sigma_w^2} H^T H + \Sigma_x^{-1} \right) x = \frac{1}{\sigma_w^2} H^T y + \Sigma_x^{-1} \mu_x$$

$$\hat{x}_{\text{maximum A-Posteriori}} = (H^T H + \sigma_w^2 \Sigma_x^{-1})^{-1} (H^T y + \sigma_w^2 \Sigma_x^{-1} \mu_x)$$

$$\begin{aligned} \mu_w &= 0 \\ \mu_x &= 0 \\ \sigma_w^2 &= 25 \times 10^{-4} \\ \Sigma_x &= (\lambda L^T L)^{-1} \end{aligned}$$

$$\hat{x}_{\text{maximum A-Posteriori}} = [H^T H + 25 \times 10^{-4} \cdot (\lambda L^T L)]^{-1} [H^T y + 25 \times 10^{-4} \cdot (\lambda L^T L) \cdot 0]$$

$$\hat{x}_{\text{maximum A-Posteriori}} = [H^T H + 25 \times 10^{-4} \cdot (\lambda L^T L)]^{-1} [H^T y]$$

e) Derive the minimum mean square error (MMSE) Linear estimator for x .

For Gaussian case, the Linear MMSE estimator is the same as MMSE estimator. So, I'll calculate the MMSE estimator, because it is more easy for me and I'll find the same result with Linear MMSE (orthogonal principle theorem).

$$\hat{x}_{\text{MMSE}} = E\{x|y=y\} \text{ (expected value of } x \text{ given } Y=y)$$

$$\text{Bayesian rule: } f(x|y) = \frac{f(y|x)f(x)}{\int_{-\infty}^{+\infty} f(y|x')f(x')dx'} = \frac{\text{likelihood } x \text{ prior}}{\text{normalization term.}}$$

likelihood (we know observation is Gaussian)

$$f(y|x) = \frac{1}{(\sqrt{2\pi}\sqrt{\sigma_w^2})^{1/2}} \exp\left\{-\frac{1}{2\sigma_w^2} (y-Hx)^T (y-Hx)\right\}$$

prior

$$f(x) = \frac{1}{(2\pi)^{\frac{L}{2}} \cdot |\Sigma_x|^{1/2}} \exp\left\{-\frac{1}{2} (x-\mu_x)^T \Sigma_x^{-1} (x-\mu_x)\right\}$$

we'll calculate the $f(x|y)$ posterior.

$f(x)$: Gaussian, $f(y|x)$ Gaussian: and w and x are independent.

Joint pdf of x, w :

$$\begin{bmatrix} x \\ w \end{bmatrix} \sim \mathcal{N}\left(\begin{bmatrix} \mu_x \\ 0 \end{bmatrix}, \begin{bmatrix} \Sigma_x & 0 \\ 0 & \sigma_w^2 \mathbf{I} \end{bmatrix}\right)$$

μ_x : mean of x .
 μ_w : mean of w .
 Σ_x : covariance matrix of x ,
 and crosses terms are zero because of w and x are independent.

Joint pdf of y, x :

$$\begin{bmatrix} y \\ x \end{bmatrix} \sim \mathcal{N}(d, e) \text{ , } d: \text{mean, } e: \text{variance.}$$

$$d = \begin{bmatrix} H & \mathbf{I} \\ \mathbf{I} & 0 \end{bmatrix} \begin{bmatrix} \mu_x \\ 0 \end{bmatrix} = \begin{bmatrix} H\mu_x \\ \mu_x \end{bmatrix}$$

$$e = \begin{bmatrix} H & \mathbf{I} \\ \mathbf{I} & 0 \end{bmatrix} \begin{bmatrix} \Sigma_x & 0 \\ 0 & \sigma_w^2 \mathbf{I} \end{bmatrix} \begin{bmatrix} H^T & \mathbf{I} \\ \mathbf{I} & 0 \end{bmatrix} = \begin{bmatrix} H^T & \mathbf{I} \\ \mathbf{I} & 0 \end{bmatrix} \begin{bmatrix} \Sigma_x H^T & \Sigma_x \\ \sigma_w^2 \mathbf{I} & 0 \end{bmatrix} = \begin{bmatrix} H \Sigma_x H^T + \sigma_w^2 \mathbf{I} & H \Sigma_x \\ \Sigma_x H^T & \Sigma_x \end{bmatrix}$$

$$\begin{bmatrix} y \\ x \end{bmatrix} \sim \mathcal{N}\left(\begin{bmatrix} H\mu_x \\ \mu_x \end{bmatrix}, \begin{bmatrix} H \Sigma_x H^T + \sigma_w^2 \mathbf{I} & H \Sigma_x \\ \Sigma_x H^T & \Sigma_x \end{bmatrix}\right)$$

conditional pdf:

$$x|y=y \sim \mathcal{N}\left(\underbrace{\Sigma_x H^T (H \Sigma_x H^T + \sigma_w^2 \mathbf{I})^{-1} (y - H\mu_x) + \mu_x}_{\text{mean}}, \underbrace{\Sigma_x - \Sigma_x H^T (H \Sigma_x H^T + \sigma_w^2 \mathbf{I})^{-1} (H \Sigma_x)}_{\text{variance}}\right)$$

$$\hat{x}_{\text{Linear MMSE}} = \hat{x}_{\text{MMSE}} = \Sigma_x H^T (H \Sigma_x H^T + \sigma_w^2 \mathbf{I})^{-1} (y - H\mu_x) + \mu_x$$

9) Calculate the peak signal-to-noise ratio PSNR of each estimate such that

$$PSNR = 20 \log_{10} \left(\frac{\max(x) \sqrt{255}}{\|x - \hat{x}\|} \right)$$

	ML	MAP ($\lambda = 100$)	NMSE ($\lambda = 1000$)
PSNR (dB)	-31,252 dB	-9,584 dB	-11,180 dB

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