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TUTORIAL



Using a Character LCD the easy way with the help of the I2C bus.

VIDEO

OVERVIEW

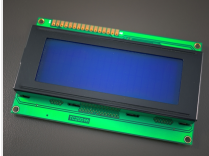
Using a character LCD with an Arduino is nothing new, but let's make it very simple by using the I2C bus.

By using this little I2C LCD board, we can control the LCD using only 2 wires, and not worry about resistors to adjust the contrast since it's all included.

To make this tutorial more interesting, we will use the HC-SR04 ultrasonic range finder that we used before and display the results on the LCD.

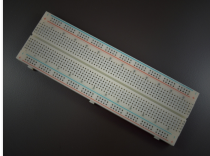
SCHEMATIC

PARTS USED



Character
LCD
Display
20×4
Module

\$11.95



Full size
Breadboard

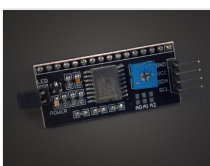
\$6.95



HC-SR04
Ultrasonic
Sensor
module

\$3.50

\$2.95

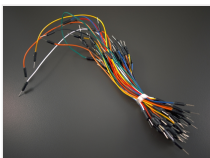


i2c LCD
backpack

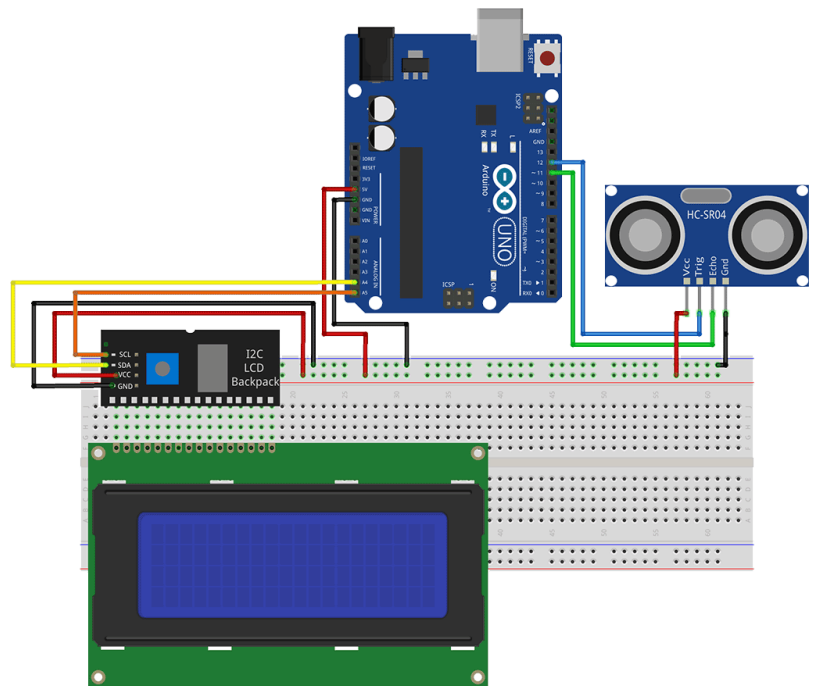
\$2.95



Jumper
Wires
male to
female
20pcs



Jumper
Wires
male to
male –
65pcs



fritzing

We are using a 20×4 Character LCD so we have 4 lines of 20 characters each available.

The I2C LCD module is connected to pin A4-SDA and A5-SCL.

The HC-SR04 is connected to pin 11-echo and 12-trigger.

VCC and Ground from the Arduino are connected to the breadboard rails.

We then connect the VCC and Ground to both the I2C module and the HC-SR04.

THE CODE

Before we can use the I2C module, we need to find out it's HEX address so we can communicate with it.

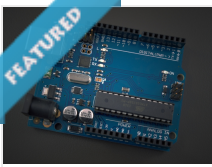
We find the I2C module address by running this "I2C Scanner" sketch on our Arduino :

**note: Watch the tutorial video to see the code in action and the results.*

```
1 #include <Wire.h>
2
3
4 void setup()
5 {
6   Wire.begin();
7
8   Serial.begin(9600);
9   Serial.println("\nI2C Scanner");
10 }
11
12
```

\$2.75

\$3.50



UNO R3

\$16.75-\$17.95

```

13 void loop()
14 {
15     byte error, address;
16     int nDevices;
17
18     Serial.println("Scanning...");
19
20     nDevices = 0;
21     for(address = 1; address < 127; address++ )
22     {
23         // The i2c_scanner uses the return value of
24         // the Write.endTransmission to see if
25         // a device did acknowledge to the address.
26         Wire.beginTransmission(address);
27         error = Wire.endTransmission();
28
29         if (error == 0)
30         {
31             Serial.print("I2C device found at address 0x");
32             if (address<16)
33                 Serial.print("0");
34             Serial.print(address,HEX);
35             Serial.println(" !");
36
37             nDevices++;
38         }
39         else if (error==4)
40         {
41             Serial.print("Unknow error at address 0x");
42             if (address<16)
43                 Serial.print("0");
44             Serial.println(address,HEX);
45         }
46     }
47     if (nDevices == 0)
48         Serial.println("No I2C devices found\n");
49     else
50         Serial.println("done\n");
51
52     delay(5000);           // wait 5 seconds for next
53 }

```

As you can see in the tutorial video, the address for our I2C module is 0X27, so we will use that value in our Sketch to communicate with it.

We will use the “NewPing” library to communicate with the HC-SR04 ultrasonic range sensor.

We are also using the “NewLiquidCrystal” library in our Sketch, this library unlike the one included with the Arduino IDE is more recent, faster and can use the I2C bus, so might as well use it.

You can download the libraries at the bottom of this tutorial page.

**Rename the original LiquidCrystal folder in the Arduino/Libraries to something like LiquidCrystal_Old before extracting the*

NewLiquidCrystal library, since the folders have the same name, and the original library will conflict with this new one.

As always, please watch the tutorial video for more

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Here's is the sketch to display the HC-Sr04 result on the LCD using I2C :

```

HC-SR04 results on LCD using I2C bus
2  #include <LCD.h>
3  #include <LiquidCrystal_I2C.h>
4  #include <NewPing.h>
5
6  #define I2C_ADDR 0x27 // <<- Add your address here.
7  #define Rs_pin 0
8  #define Rw_pin 1
9  #define En_pin 2
10 #define BACKLIGHT_PIN 3
11 #define D4_pin 4
12 #define D5_pin 5
13 #define D6_pin 6
14 #define D7_pin 7
15
16 #define ECHO_PIN 11 // Arduino pin tied to echo pin
17 #define TRIGGER_PIN 12 // Arduino pin tied to trigger
18 #define MAX_DISTANCE 500 // Maximum distance we want
19
20 NewPing sonar(TRIGGER_PIN, ECHO_PIN, MAX_DISTANCE);
21
22 LiquidCrystal_I2C lcd(I2C_ADDR,En_pin,Rw_pin,Rs_pin,
23
24 void setup()
25 {
26   lcd.begin (20,4); // <<-- our LCD is a 20x4, change
27
28   // LCD Backlight ON
29   lcd.setBacklightPin(BACKLIGHT_PIN,POSITIVE);
30   lcd.setBacklight(HIGH);
31
32   lcd.home (); // go home on LCD
33   lcd.print("Range Finder HC-SR04");
34 }
35
36 void loop()
37 {
38   unsigned int uS = sonar.ping(); // Send ping, get p
39   unsigned int cm = sonar.convert_cm(uS); // Convert
40
41   lcd.setCursor (0,1); // go to start of 2nd line
42   lcd.print("Current Distance:");
43   lcd.setCursor (0,3); // go to start of 4th line
44   lcd.print("Ping: ");
45   lcd.print(cm);
46   lcd.print(" cm ");
47
48   delay(500);
49 }

```

Translate »

DOWNLOAD

Download the NewLiquidCrystal library here:

[New LiquidCrystal Library.zip](#)

Download the HC-SR04 library here: [HC-SR04 Library.zip](#)

Download the I2C_Scanner here: [I2C Scanner.zip](#)

Download the Tutorial Sketch here: [I2C LCD Tutorial.zip](#)

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"The real problem is not whether machines think but whether men do."

– B.F. Skinner

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