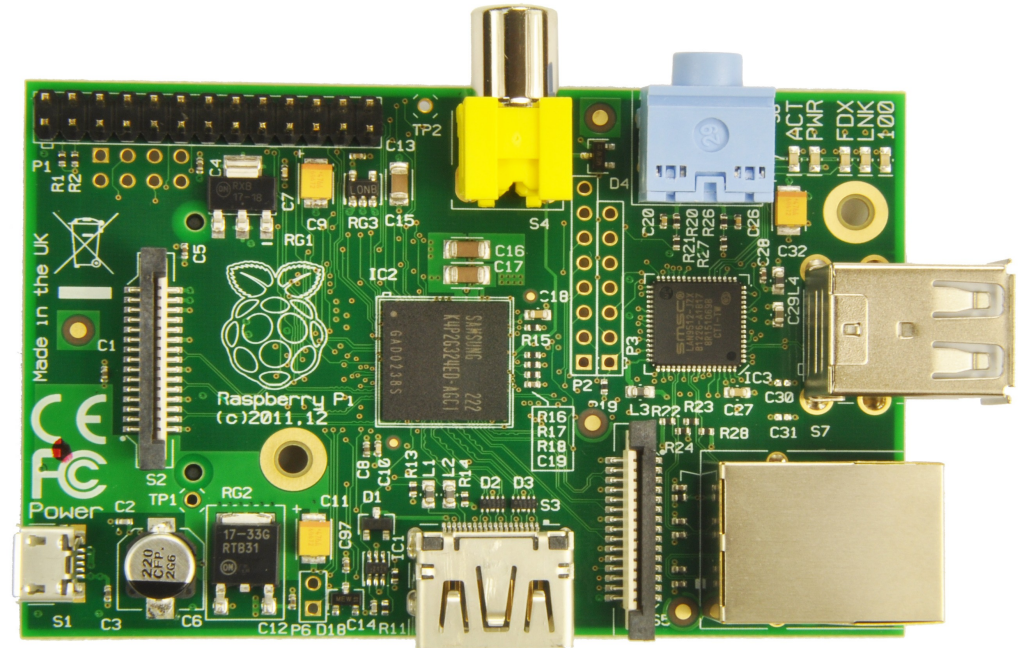
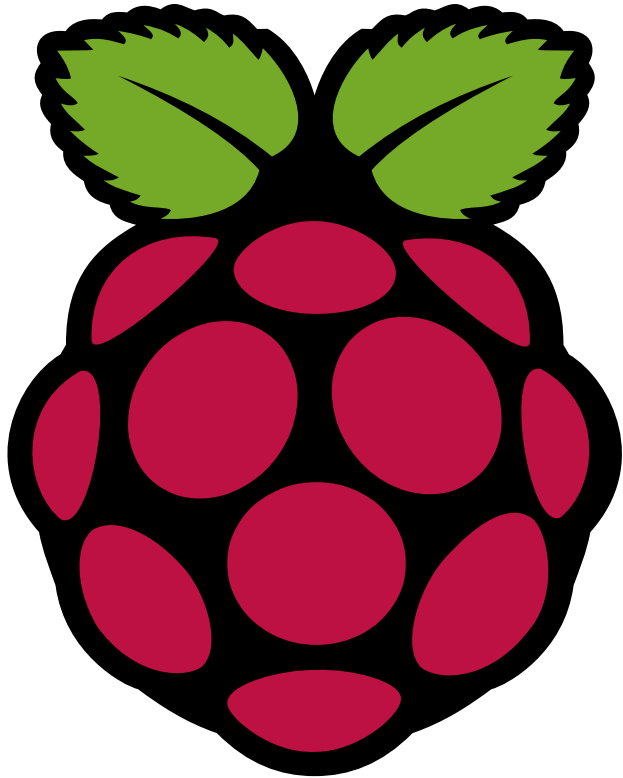


Exploring Raspberry Pi



About Speakers

- Lentin Joseph, Achu Wilson and Aronin Chandu
- Experience in Robotics and Embedded systems for last 3 years
- <http://www.lentinjoseph.com>
- <http://www.sastrarobotics.com>


Questions ???

- Why did you choose this workshop ?
- What are you expecting from this workshop ?
- What do you want to make with RaspberryPi ?

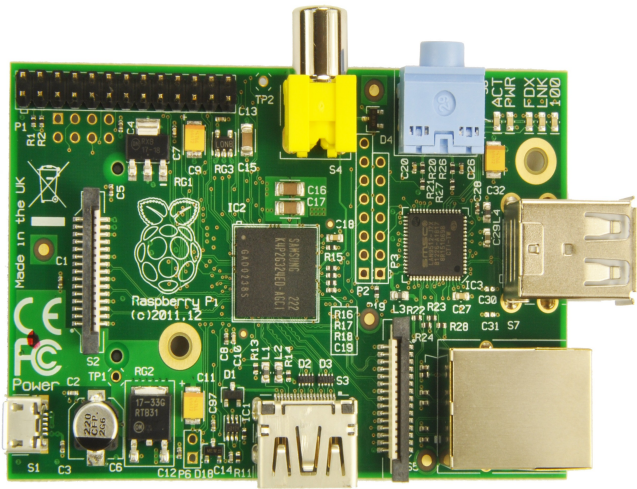
Agenda

- Introduction to Raspberry
- Hardware description
- Installation of OS
- OS Introduction
- Remote Access using SSH,VNC
- Package Management
- GPIO,I2C,SPI

Agenda

- Python & GCC
 - Wiring Pi and Python GPIO
 - Hello_World demo
 - LED Blink, PWM etc
 - Raspberry Pi and Arduino
 - Raspberry Pi and Camera
 - Hackathon
- 

Raspberry Pi & PC



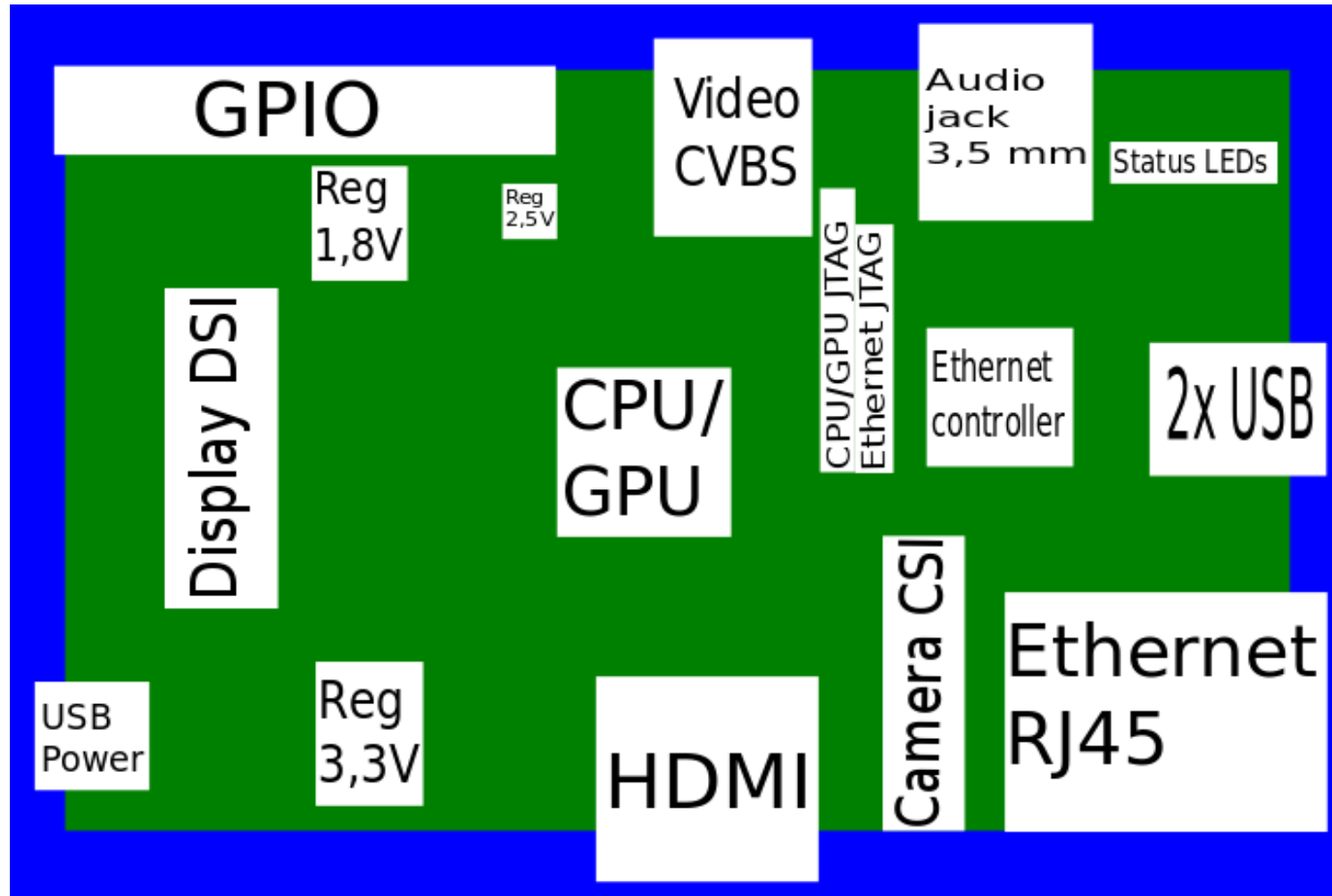
Compare Raspberry Pi and a PC

Components	Laptop or PC	Raspberry Pi Ver B
Processor	Intel 2.2 Ghz,Dual Core	700 Mhz,Single Core Arm 11
RAM	6GB	512 MB
Graphics	Intel HD 3000	Dual core video core IV
Ethernet	Yes	Yes
USB 2.0	Yes	Yes
Video O/P	VGA ,HDMI	Composite RCA HDMI
Audio O/P	Yes	Yes
Storage	500 GB Harddisk	32 GB SD Card
Operating System	Linux/Windows	Only Linux
Dimensions	14 inch laptop	8.6x5.4x1.7 cm

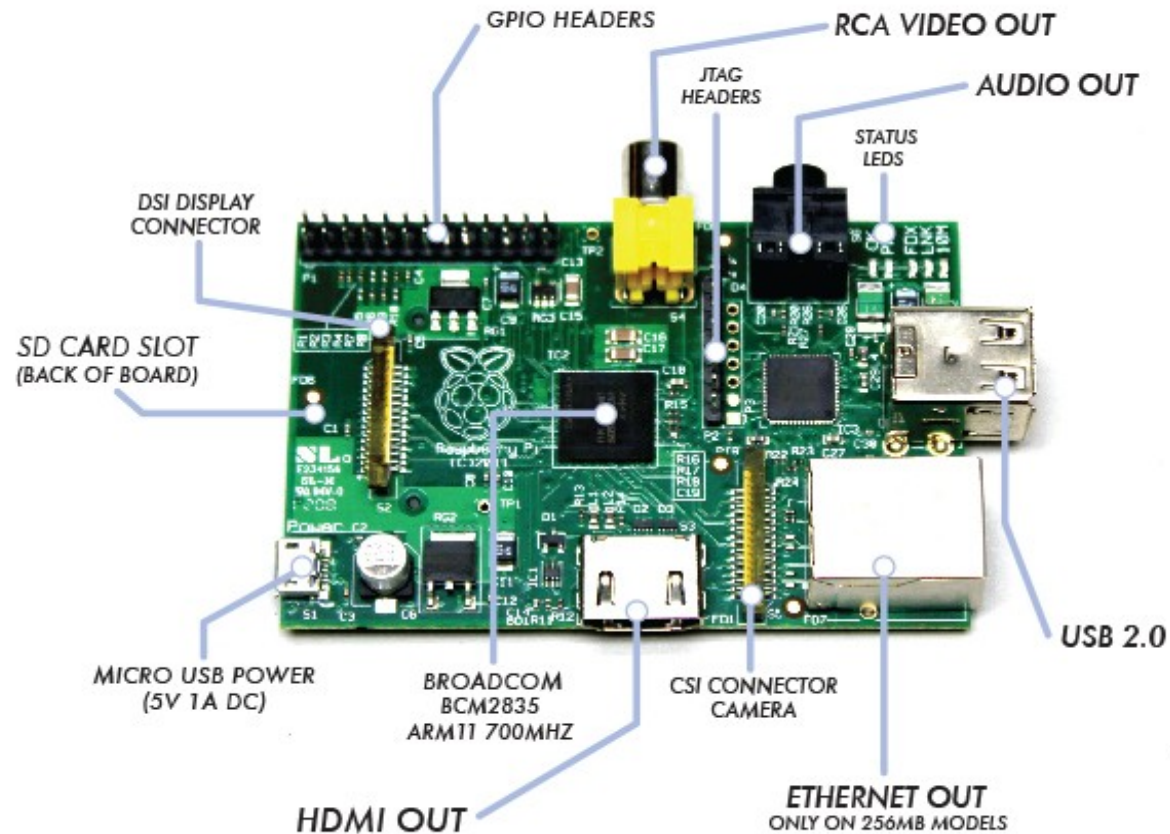
Raspberry Pi Model A&B

	Model A	Model B
RRP	\$25	\$35
System on a Chip	Broadcom BCM2835	
CPU	700 MHz ARM1176JZF-S core	
GPU	Broadcom VideoCore IV, OpenGL ES 2.0. Device capable of MPEG-2 and VC-1, 1080p30 h.264/MPEG-4 AVC decoding and encoding.	
Memory (SDRAM)	256 MB, shared with GPU	512 MB (models build since October 15 th 2012), shared with GPU
USB 2.0	1	2 (integrated USB hub)
Video Out	Composite RCA (PAL and NTSC), HDMI (also Display Serial Interface for LCD panels)	
Audio Out	3.5 mm jack, HDMI	
Storage	SD/MMC/SDIO card slot	
Network	No connector	RJ45 Ethernet through integrated USB hub
Peripheral connectors	8 × GPIO, UART, I ² C bus, SPI bus	
Power rating	300 mA (1.5 W)	700 mA (3.5 W)
Power source	5 volt via MicroUSB or GPIO header	

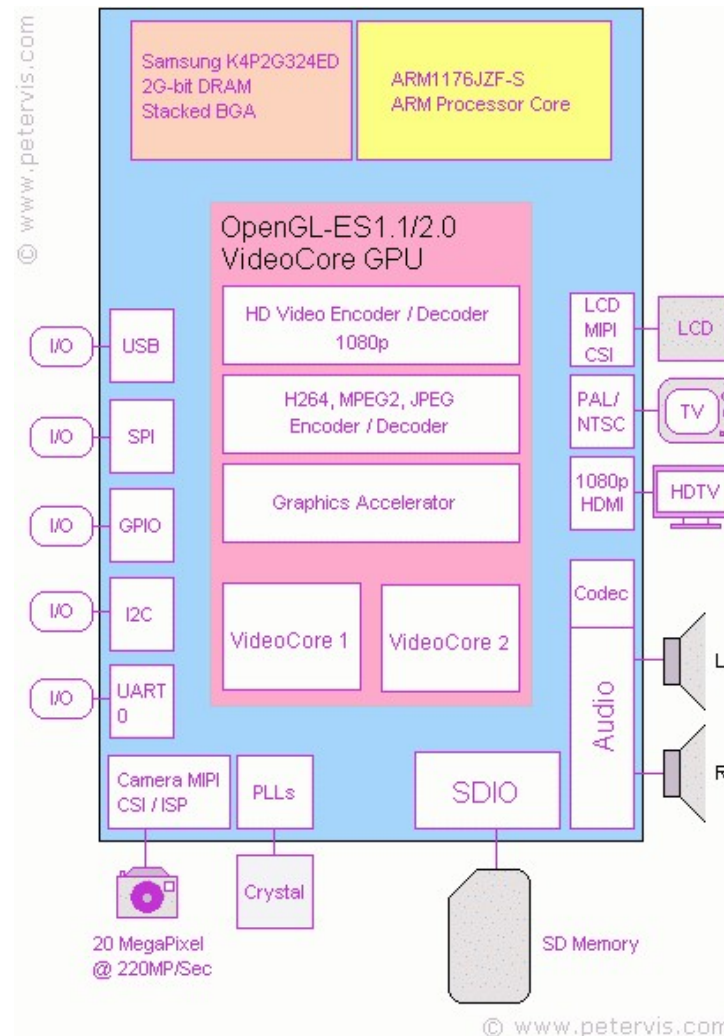
Raspberry Pi Components



Raspberry Pi Components



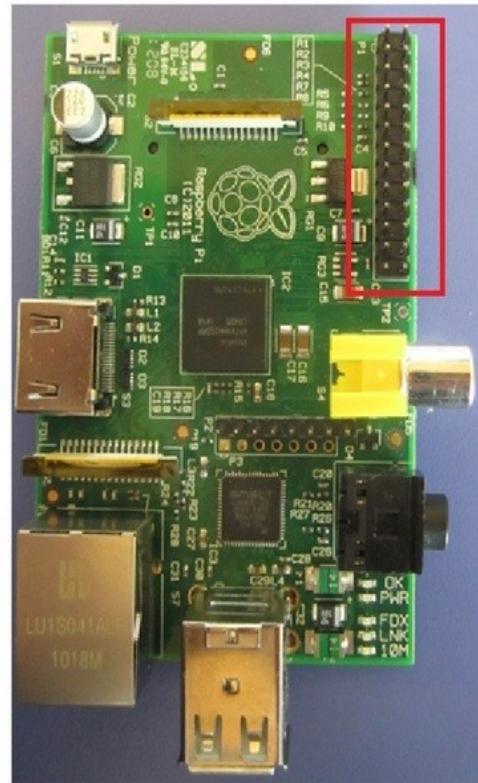
BCM 2835 SoC(System on Chip)



Raspberry Pi : GPIO

U\$1

3V3	5V0
GPIO3	DNC1
GPIO5	GND
GPIO7	GPIO8
DNC2	GPIO10
GPIO11	GPIO12
GPIO13	DNC3
GPIO15	GPIO16
DNC4	GPIO18
GPIO19	DNC5
GPIO21	GPIO22
GPIO23	GPIO24
DNC6	GPIO26

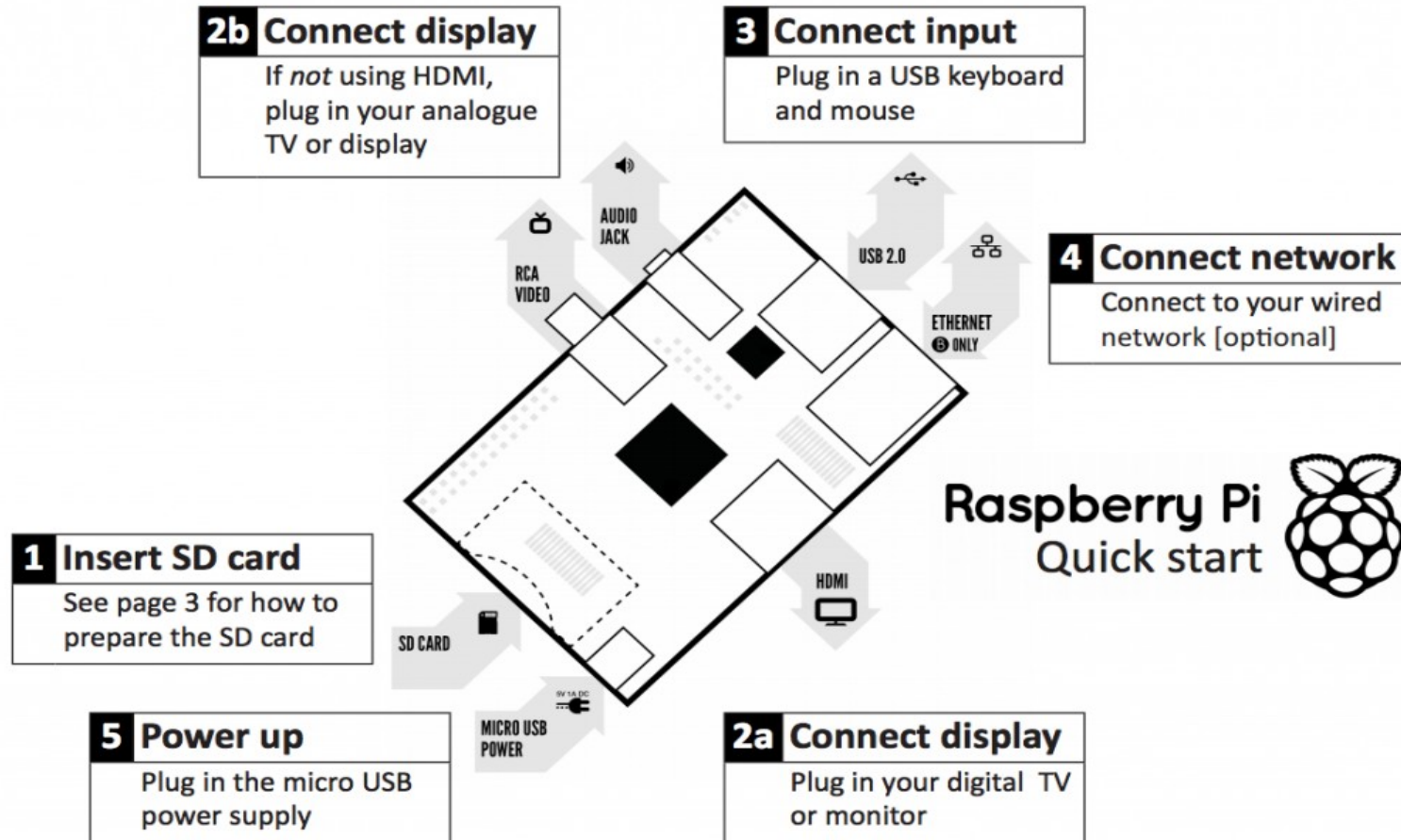


3.3V	1	2	5V
I2C1 SDA	3	4	5V
I2C1 SCL	5	6	GROUND
GPIO4	7	8	UART TXD
GROUND		10	UART RXD
GPIO 17	11	12	GPIO 18
GPIO 27	13	14	GROUND
GPIO 22	15	16	GPIO 23
3.3V	17	18	GPIO 24
SP10 MOSI	19	20	GROUND
SP10 MISO	21	22	GPIO 25
SP10 SCLK	23	24	SP10 CE0 N
GROUND	25	26	SP10 CE1 N

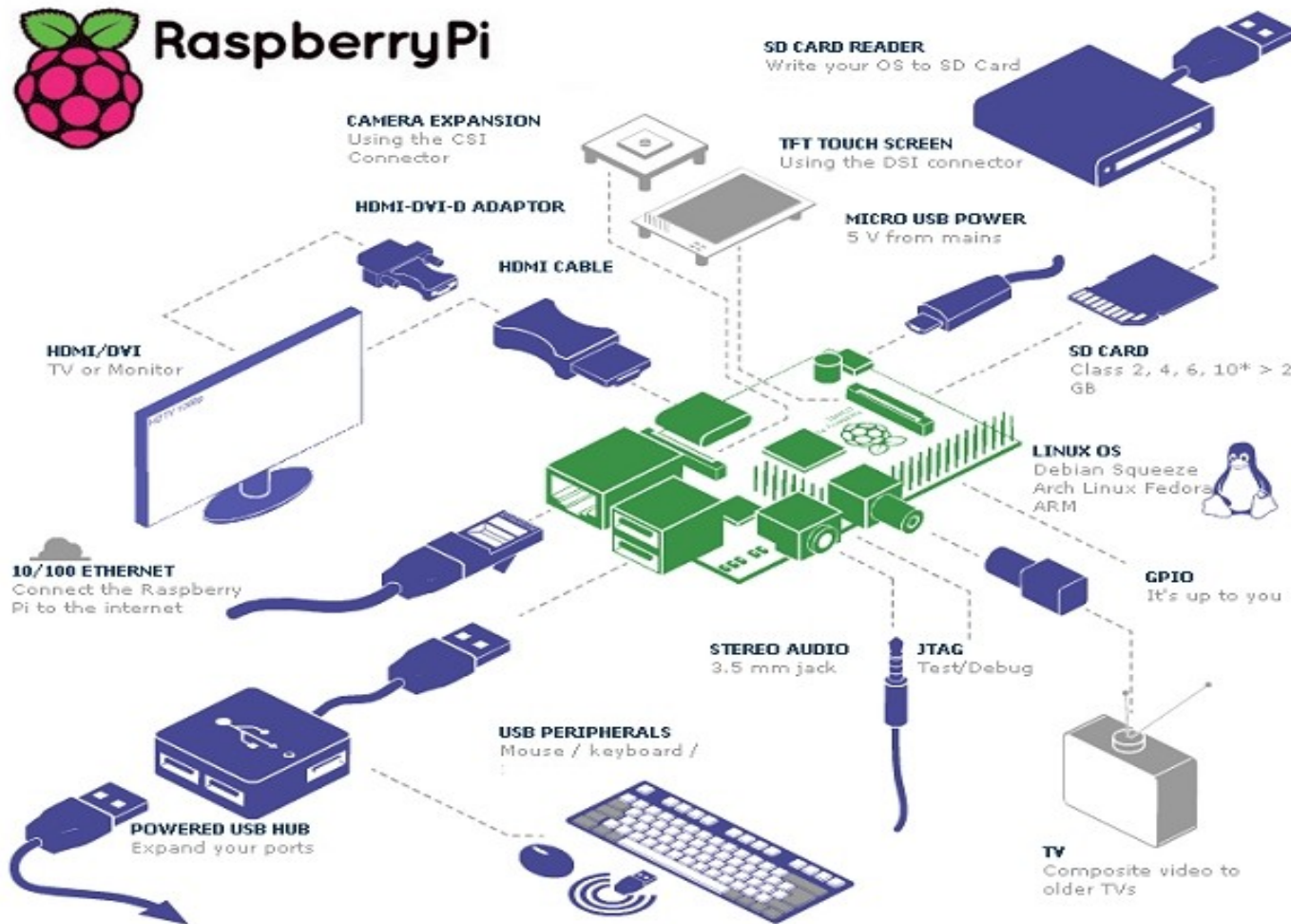
Raspberry Pi : GPIO

- 8x GPIO (General Purpose Input/Output)
- UART ,I2C ,SPI Bus
- 3.3 V and 5 V pins

Rpi Connection Diagram



Rpi Connection Diagram



Basic GNU/Linux commands

- `$ls` – List Files
- `$cd` – Change Directory
- `$mkdir` – Create folder
- `$rmdir` – Delete folder
- `$clear` – Clear terminal
- `$nano` – Text editor

Basic GNU/Linux commands

- `$dmesg` – Show kernel messages
- `$lsusb` – List connected usb devices
- `$cp` – Copy Files
- `$ssh` – Secure shell
- `$scp` – Copy files from one pc to other using ssh
- `$vncviewer` – Connect to vnc server

Basic GNU/Linux commands


- `$sudo` – Run in root privilege
- `$ping` – Pinging to ip address
- `$nmap` – Searching tool of IP and Ports

Installation of OS

- OS Name : Raspbian/Linux

- Download link:

<http://www.raspberrypi.org/downloads>

- Based on Debian operating system
 - Desktop Environment : LXDE
 - Light weight OS
- 
- A solid green horizontal bar at the bottom of the slide.

Installation of OS

- Installation tools
- For Windows
 - Win32DiskImager.exe
 - <http://sourceforge.net/projects/win32diskimager/>
- For Linux
 - \$dd
 - <http://sourceforge.net/projects/win32diskimager/>

Installation of OS

- Procedure in Linux
 - Format SD Card in FAT 32/ext2
 - `sudo dd bs=4m if=<name_of_image>.img of=<device name>`
 - Eg: `sudo dd bs=4m if=2013-02-09-wheezy-raspbian.img of=/dev/sdb`

Setting SSH

- SSH – Secure Shell
- http://en.wikipedia.org/wiki/Secure_Shell
- Direct and Remote Login methods in Rpi
- Types of remote connections
 - Rpi and PC connected through router
 - Rpi and PC connected through direct connection
 - Rpi Wifi Hotspot

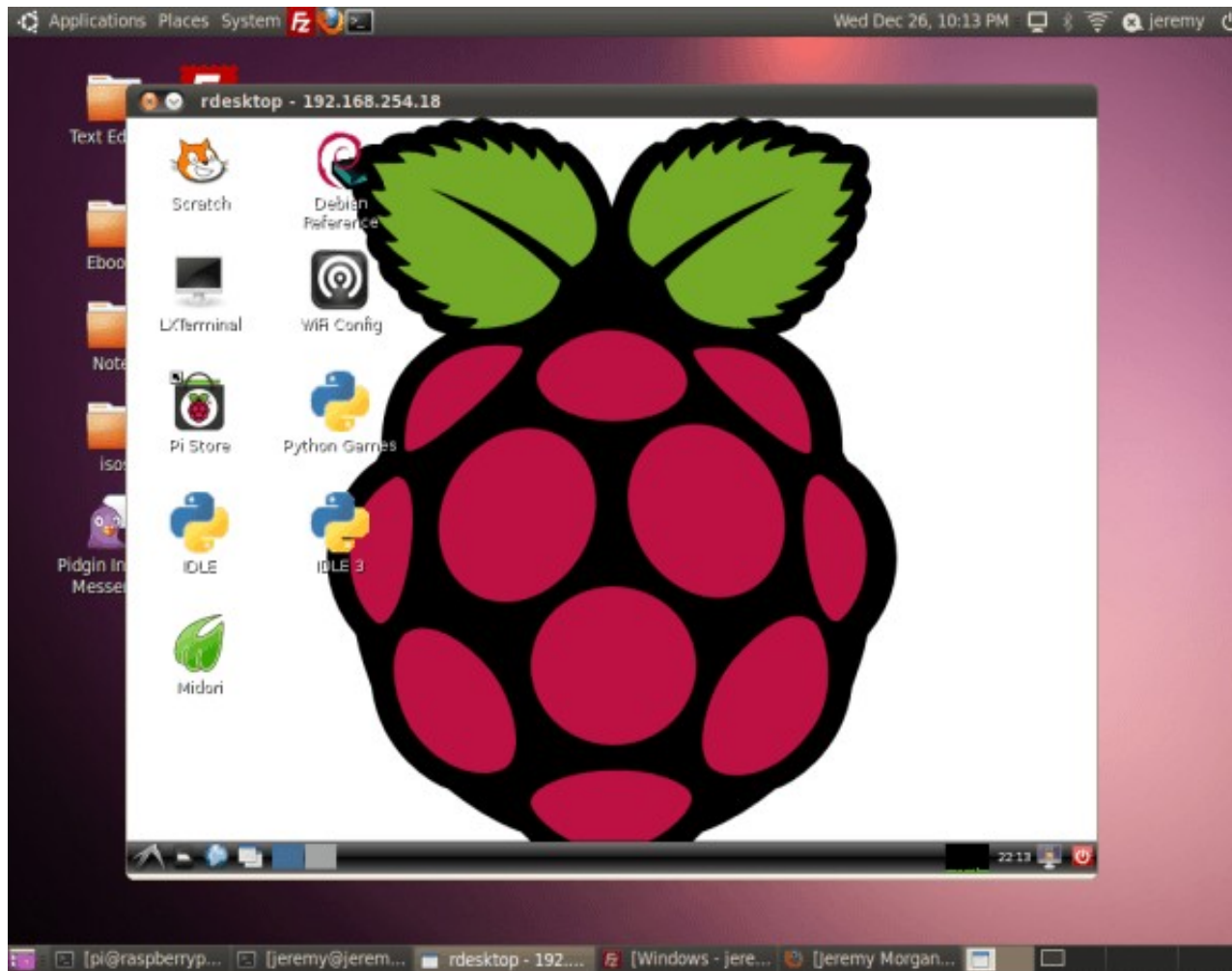
Setting VNC Server

- VNC(Virtual Network Computing)
- http://en.wikipedia.org/wiki/VNC_server
- Graphical desktop sharing system
- Installation
 - `$sudo apt-get install tightvncserver`
- In Raspberry Pi
 - `$ vncserver :1 -geometry 1366x600 -depth 16 -pixelformat rgb565`

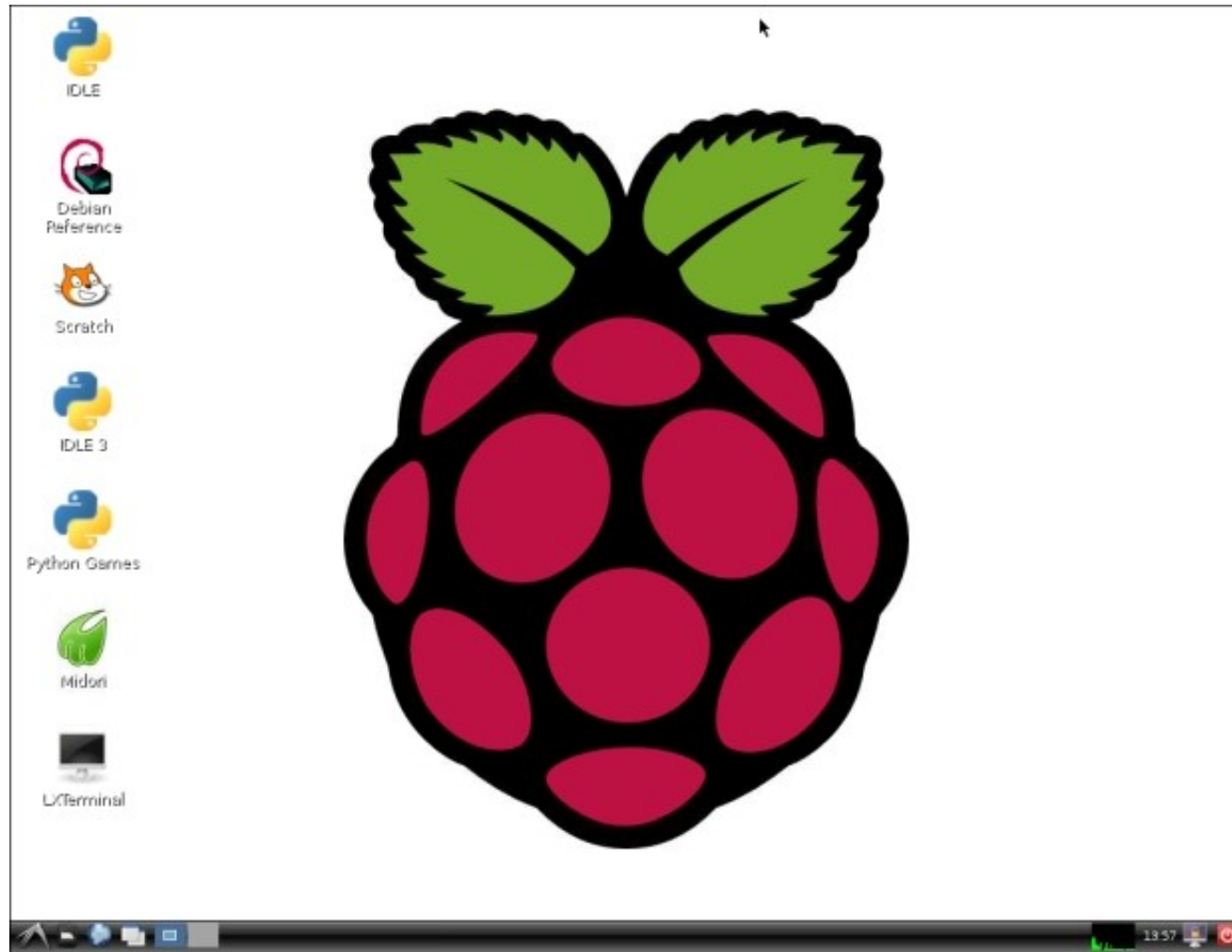
Setting VNC Server

- In PC
 - Install tightvncviewer
 - \$ vncviewer ip:5901
 - \$ vncviewer 192.168.1.3:5901

Remote Desktop



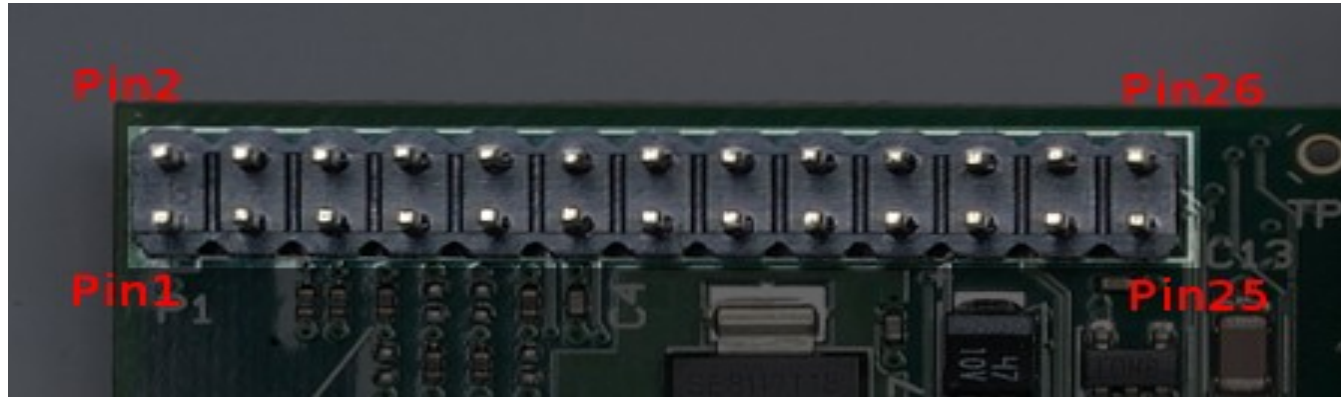
Introduction to Raspbian



Package Management

- `$apt-get install`
- Synaptic Package Manager : GUI of `apt-get`
- `$dpkg`

GPIO ,I2C,&SPI



R-Pi GPIO		left		right	
		bottom	top	bottom	top
		P1-01	P1-02	P1-25	P1-26
3V3 Power					
R1: GPIO 0 (SDA)					
R2: GPIO 2 (SDA)					
R1: GPIO 1 (SCL)					
R2: GPIO 3 (SCL)					
GPIO 4 (GPCLK0)					
Ground					
GPIO 17					
R1: GPIO 21					
R2: GPIO 27					
GPIO 22					
3V3 Power					
GPIO 10 (MOSI)					
GPIO 9 (MISO)					
GPIO 11 (SCLK)					
Ground					

R1: Revision 1
R2: Revision 2

GPIO ,I2C,&SPI

- GPIO Libraries
 - Rpi.GPIO
 - Wiring Pi

Rpi.GPIO Installation

- GPIO Library Installation
 - `$ sudo apt-get update`
 - `$ sudo apt-get install python-dev`
 - `$ sudo apt-get install python-rpi.gpio`

WiringPi Installation

- Wiring Pi Library Installation
 - `$ sudo apt-get install git-core`
 - `sudo apt-get update`
 - `sudo apt-get upgrade`
 - `git clone git://git.drogon.net/wiringPi`
 - `cd wiringPi`
 - `git pull origin`
 - `cd wiringPi`
 - `./build`

Python & GCC

- Introduction to Python ?
- Sample codes
- Introduction to GCC(Gnu C compiler)
- Sample Codes

Rpi.GPIO Basics

```
> import RPi.GPIO as GPIO #Importing GPIO Module
> import time # Importing Time module
>
> GPIO.setmode(GPIO.BOARD) # Taking Pin number from the board
> GPIO.setup(12, GPIO.OUT) # Setting 12th pin as OUTPUT
>
> try:
>     while True:
>         GPIO.output(12, GPIO.HIGH) #Setting 12th pin high
>         time.sleep(1) # 1 sec delay
>         GPIO.output(12, GPIO.LOW) #Setting 12th pin low
>         time.sleep(1)
> finally:
>     GPIO.cleanup() #Cleaning the configurations
```

WiringPi Basics

- `$ man gpio`
- `$ gpio -g #` Taking BCM GPIO Number
- `$gpio [-g] mode <pin> in/out/pwm/up/down/tri`
- `$ gpio [-g] write <pin> <value>`
- `$gpio [-g] pwm <pin> <value>(0-1023)`
- `$ gpio [-g] read < pin>`
- `$ gpio readall`

WiringPi Pinout

P1: The Main GPIO connector

WiringPi Pin	BCM GPIO	Name	Header		Name	BCM GPIO	WiringPi Pin
		3.3v	1	2	5v		
8	Rv1:0 - Rv2:2	SDA	3	4	5v		
9	Rv1:1 - Rv2:3	SCL	5	6	0v		
7	4	GPIO7	7	8	TxD	14	15
		0v	9	10	RxD	15	16
0	17	GPIO0	11	12	GPIO1	18	1
2	Rv1:21 - Rv2:27	GPIO2	13	14	0v		
3	22	GPIO3	15	16	GPIO4	23	4
		3.3v	17	18	GPIO5	24	5
12	10	MOSI	19	20	0v		
13	9	MISO	21	22	GPIO6	25	6
14	11	SCLK	23	24	CE0	8	10
		0v	25	26	CE1	7	11
WiringPi Pin	BCM GPIO	Name	Header		Name	BCM GPIO	WiringPi Pin

WiringPi Examples

- Setting wiring pin to HIGH

- `$gpio mode 1 out`
- `$gpio write 1 1`

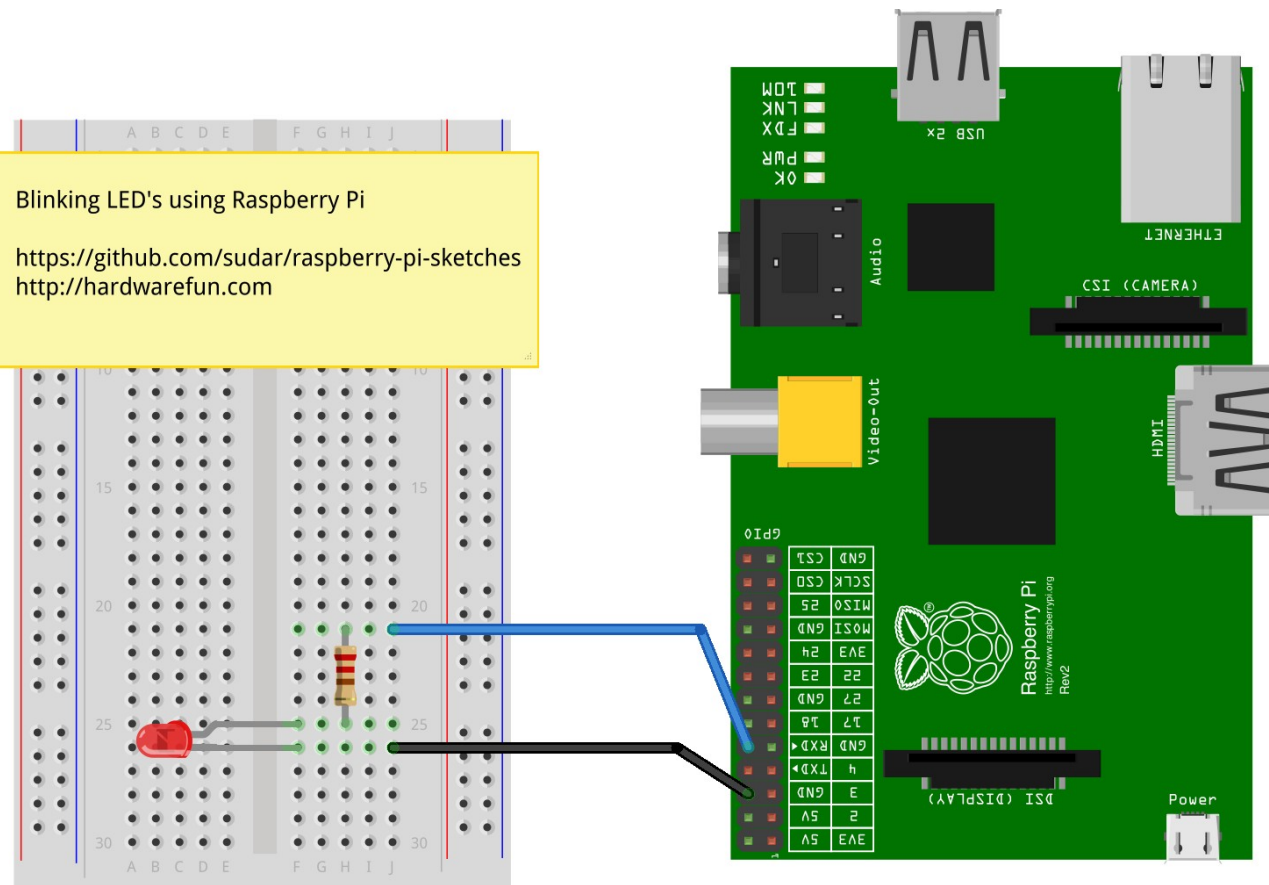
- Setting PWM

- `$gpio mode 1 pwm`
- `$gpio pwm 1 200`

Demo_1:Blink Led

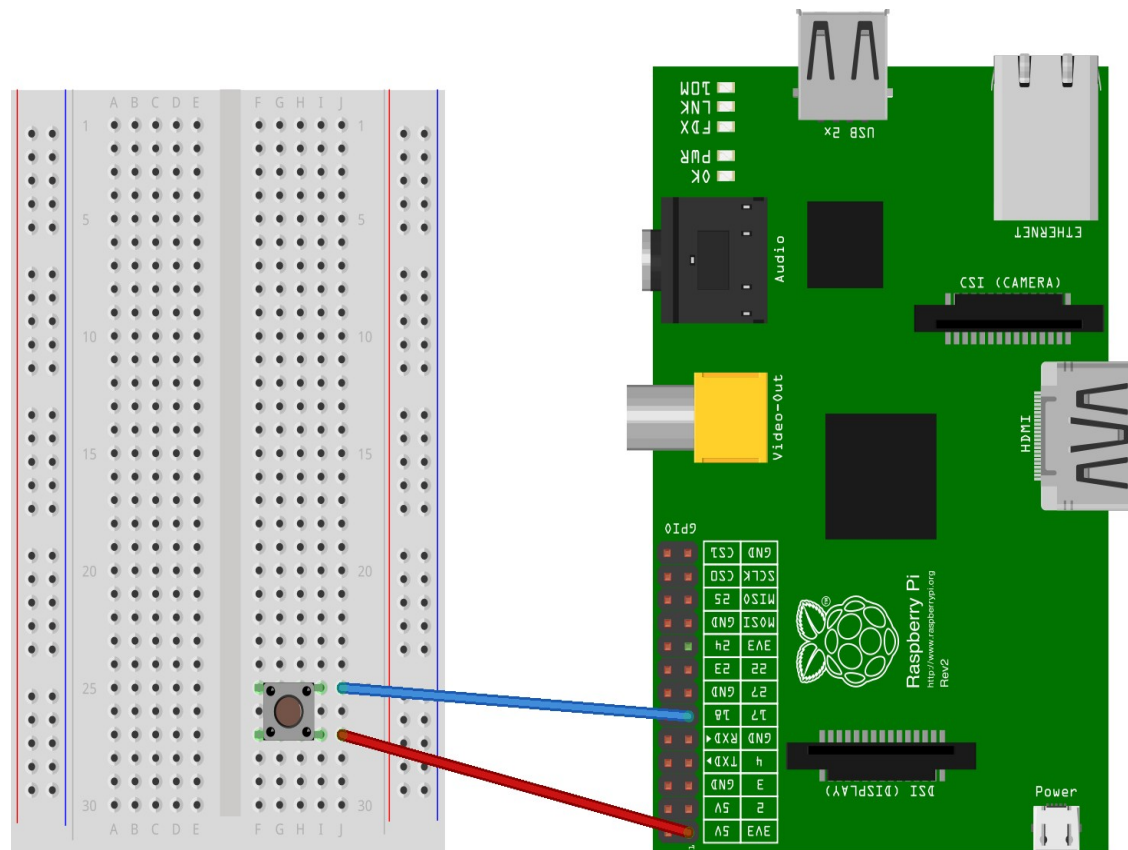
Blinking LED's using Raspberry Pi

<https://github.com/sudar/raspberry-pi-sketches>
<http://hardwarefun.com>



Made with  Fritzing.org

Demo_2: Button & Input

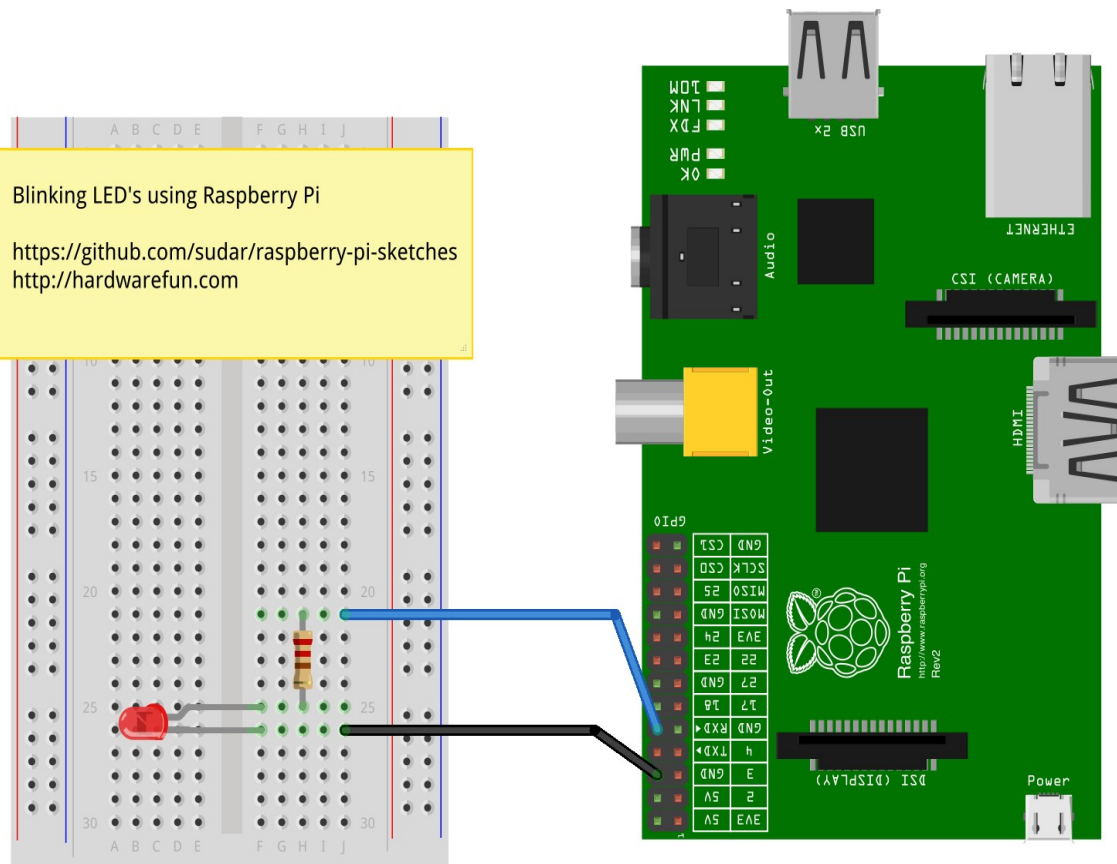


Made with  Fritzing.org

Demo_3:PWM

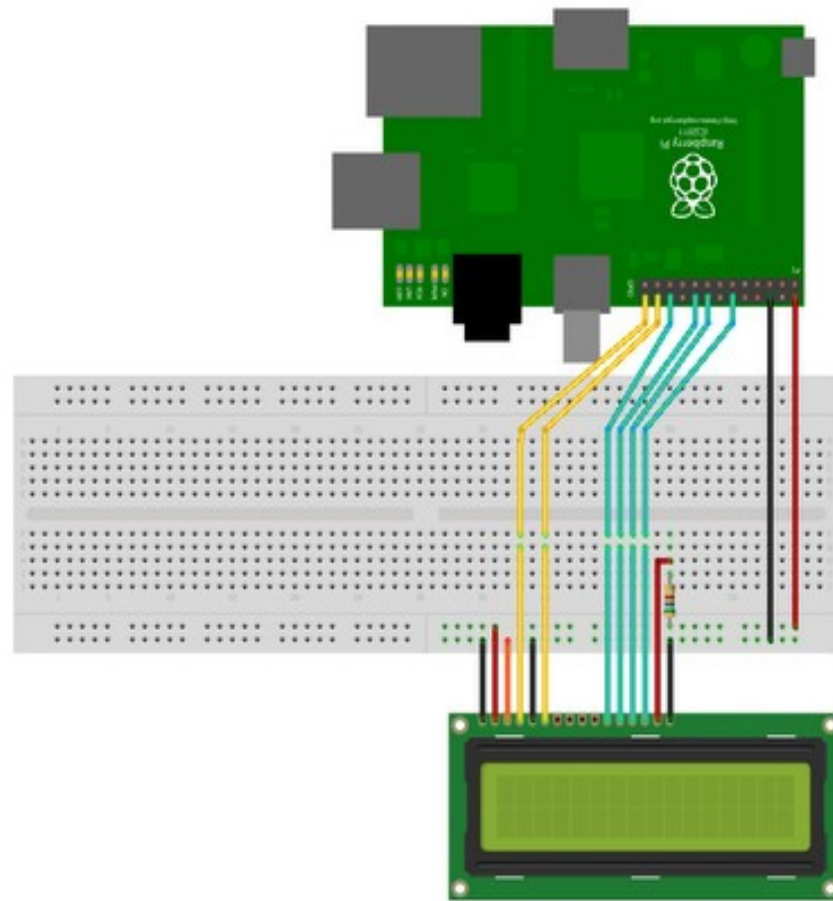
Blinking LED's using Raspberry Pi

<https://github.com/sudar/raspberry-pi-sketches>
<http://hardwarefun.com>

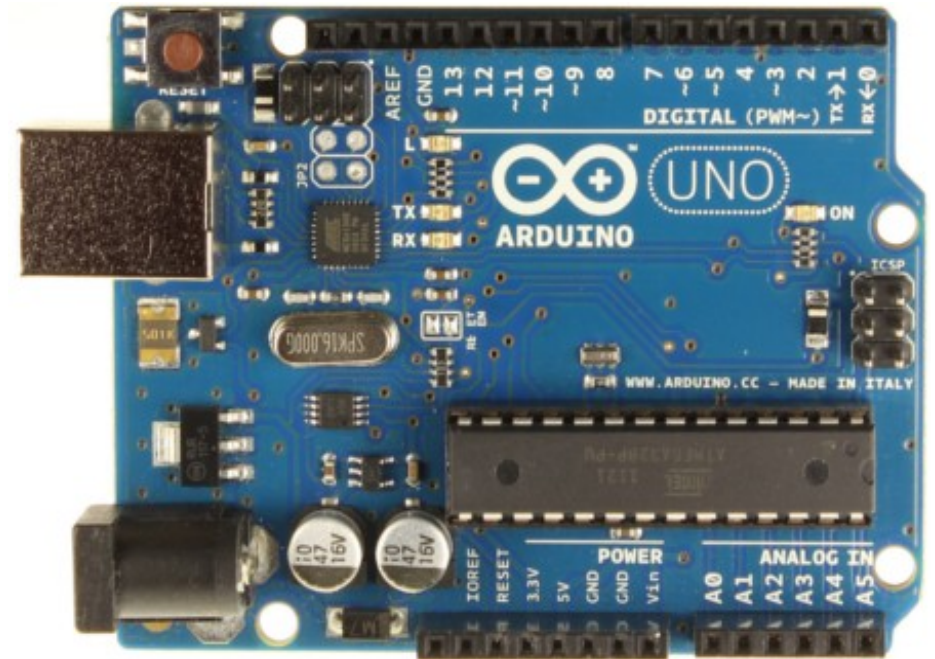
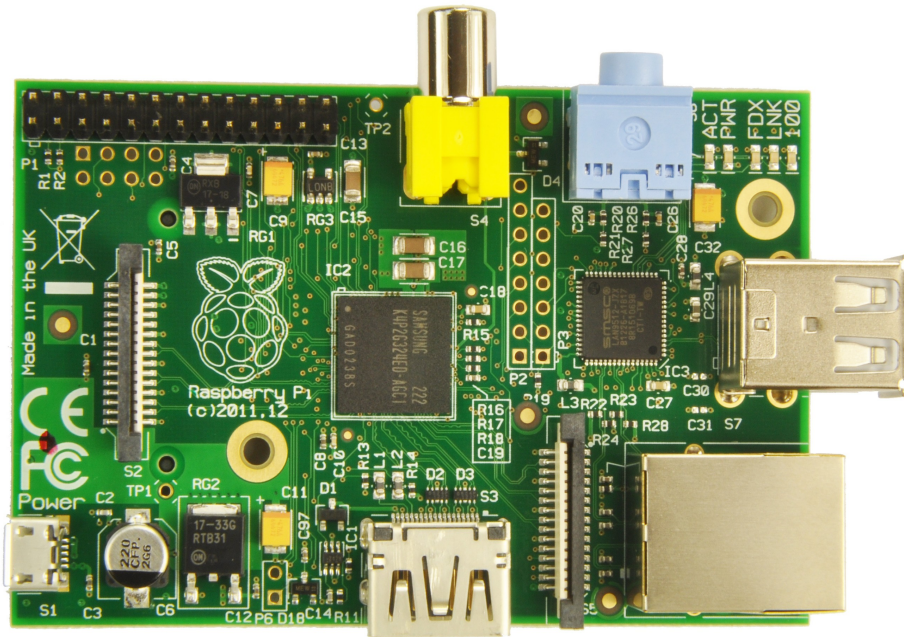


Made with  Fritzing.org

Demo_4:LCD Interfacing



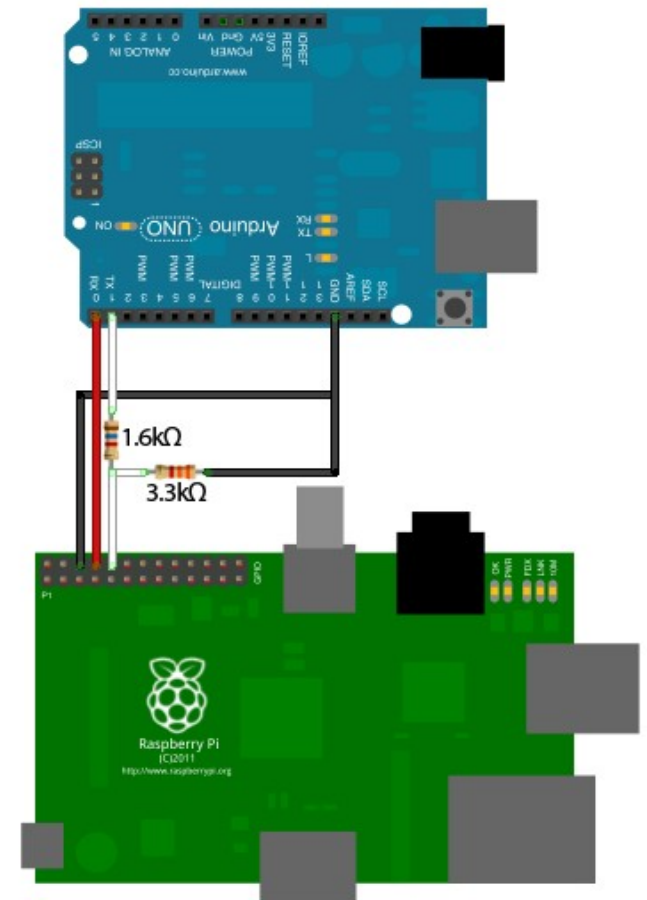
Raspberry Pi & Arduino



<http://blog.oscarliang.net/raspberry-pi-and-arduino-connected-serial-gpio/>

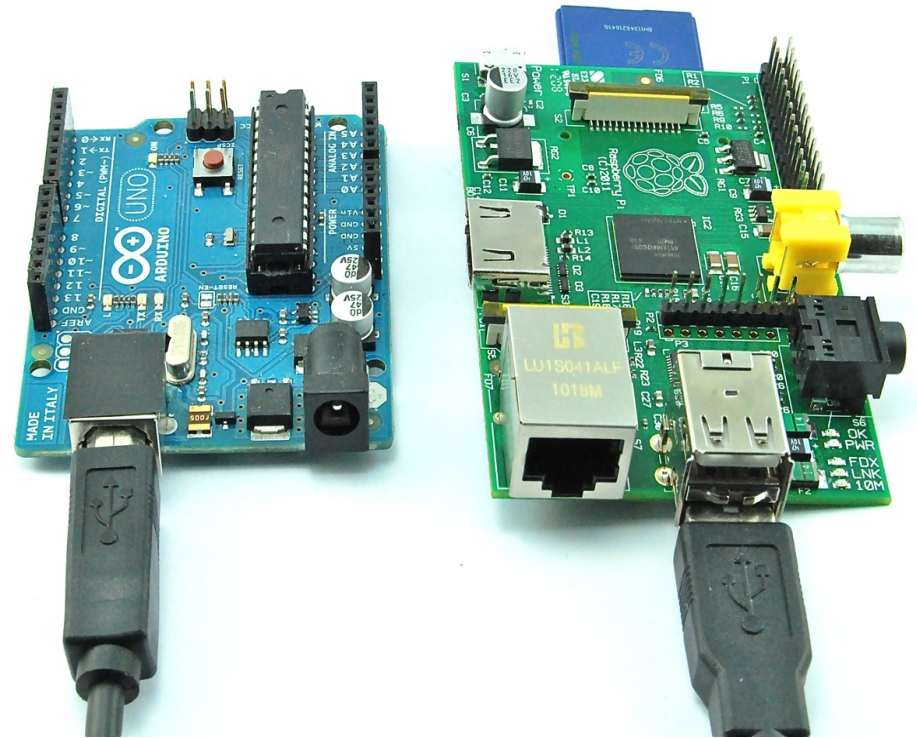
Raspberry Pi & Arduino

- Direct Serial Connection



Raspberry Pi & Arduino

- USB Connection



Raspberry Pi & Arduino

```
// Arduino Code
int serIn;
void setup() {
    Serial.begin(9600);
}
void loop () {

    if(Serial.available()) {

        while (Serial.available()>0){
            serIn = Serial.read();
            Serial.print(serIn, BYTE);
        }
        Serial.println();
    }
    delay(1000);
}
```

```
// Python Code in Raspberry Pi

import serial
import time
ser=serial.Serial('/dev/ttyACM0',9600)

while True:
    ser.write('A')
    Time.sleep(1)
```


Raspberry Pi & Camera



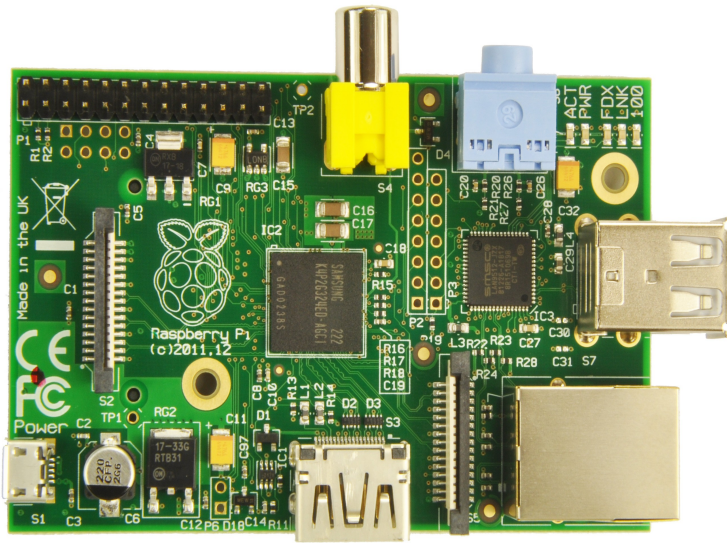
Raspberry Pi & Camera

- Connection: Camera Serial Interconnect (CSI)
- Maximum Still Resolution: 2,592×1,944 (currently limited to 1,920×1,080)
- Maximum Video Resolution: 1,920×1,080 (1080p) 30fps



Raspberry Pi & Camera

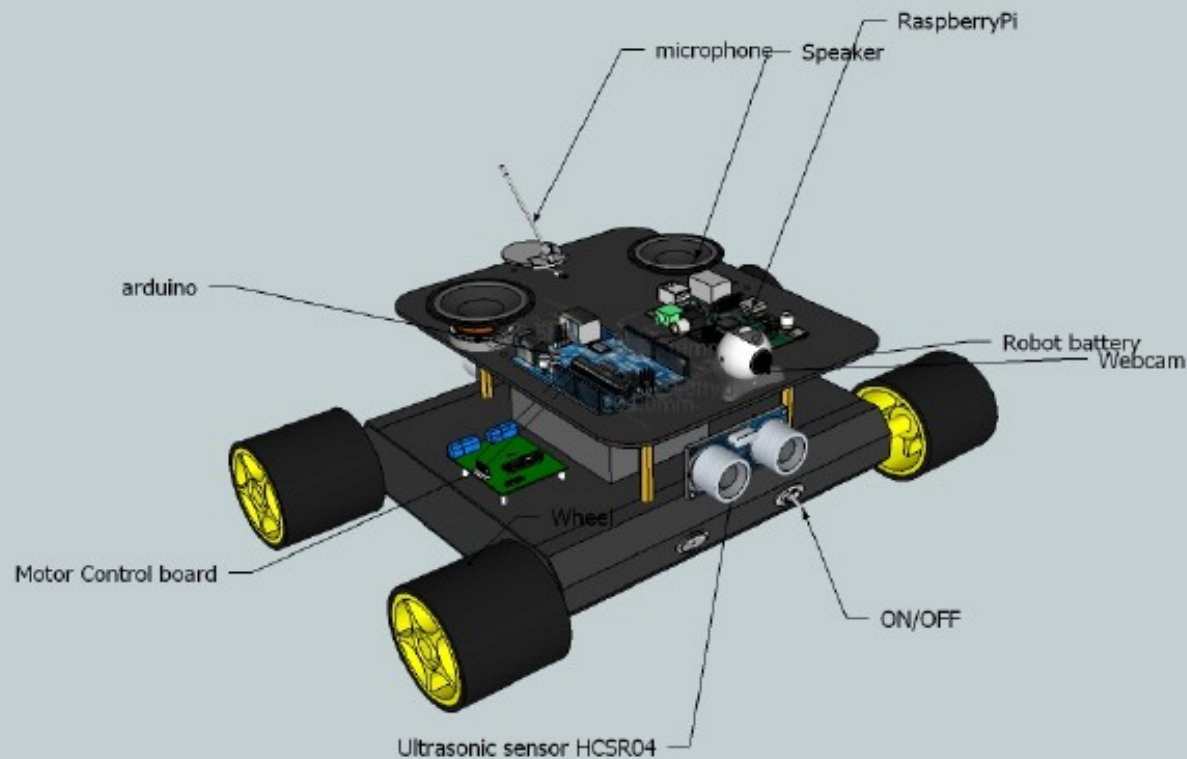
\$ sudo apt-get install guvcview



Raspberry Pi & Sound

- `$ sudo apt-get install mplayer`

Raspberry Pi Robot demo



Questions ??



Hackathon

- Will select best 3 projects
- Duration : 2 hrs

