

Q1

(a) $G(s) = \frac{50}{s(s^2 + 10s + 50)(s+5)}$; $L_d = \frac{100}{s}$

$$K = L G^{-1} = \frac{100}{s} \times \frac{s(s^2 + 10s + 50)(s+5)}{50}$$

$$= 2(s^2 + 10s + 50)(s+5)$$

Make a proper controller

$$\Rightarrow K = \frac{2(s^2 + 10s + 50)(s+5)}{s^2 \times \left(\frac{s}{10000} + 1\right)}$$

(Adding Integral term & high freq pole)

We know that $G_p = G(1 + \alpha \Delta)$ for $\| \Delta \|_0 < 1$

$$\Rightarrow M = K S G W \quad [W = \alpha]$$

$$= K S G \alpha$$

$$S = \frac{1}{1 + G K} = \frac{1}{1 + \frac{50}{s(s^2 + 10s + 50)(s+5)} \times \frac{2(s^2 + 10s + 50)(s+5)}{s^2 \left(\frac{s}{10000} + 1\right)}}$$

$$= \frac{1}{1 + \frac{100 \times 10^4}{s^3(s+10^4)}} = \frac{s^3(s+10^4)}{s^3(s+10^4) + 10^6}$$

$$M = \frac{2(s^2 + 10s + 50)(s+5) \times 10^4}{s^2(s+10^4)} \times \frac{s^3(s+10^4)}{s^3(s+10^4) + 10^6} \times \frac{50}{s(s^2 + 10s + 50)(s+5)} \propto$$

$$\Rightarrow M = \frac{10^6 \alpha}{s^3(s+10^4)+10^6}$$

$$\therefore \|M\|_{\infty} < 1 \Rightarrow \alpha < \frac{1}{\left\| \frac{10^6}{s^3(s+10^4)+10^6} \right\|_{\infty}} = \frac{1}{\text{Inf}}$$

$$\Rightarrow \boxed{\alpha < 0}$$

Maximum value of α is not positive

\therefore The system cannot be robustly stable
for $\forall \alpha \in \mathbb{R}^+$