

CS F364 ASSIGNMENT 2

Submitted To

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Design and Analysis of Algorithms : CS F364



BITS Pilani

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Introduction:

This algorithm is used to find the densest subgraphs in the most efficient manner. For a graph Density can be defined as the ratio of the number of edges and the number of vertices.

$$\text{density of a graph } G(v, E) = \frac{\text{number of Edges}}{\text{number of vertices}}$$

This problem in graphs has wide application in many fields including networks , biology , graph databases and system optimization.

The problem has two approaches :

1. Edge-density based DSD
2. h-clique based DSD

The challenges to solve this problem are enormous with the already existing algorithms (These algorithms currently use flow), because these algorithms (edge-density based DSD) are very slow for large graphs and (h-clique based DSD) is even more computationally expensive. To handle this issue the authors of this paper have come up with a solution using k-core

decomposition, where k core is a maximal subgraph where each vertex has a degree at least k . (k, Ψ) -core generalizes k -core for h -cliques. Crucial for efficiently solving DSD based on h -clique-density or pattern-density.

Datasets

Datasets	Vertices	Edges
as20000102	6474	12572
CA-HepTh	9577	25998
Netscience	1589	2742
as-Caida	26475	106762

Algorithm 1 : Exact Algorithm

Algorithm 1: The algorithm: Exact.

Input: $G(V, E), \Psi(V_\Psi, E_\Psi)$;
Output: The CDS $D(V_D, E_D)$;

```

1 initialize  $l \leftarrow 0, u \leftarrow \max_{v \in V} \deg_G(v, \Psi)$ ;
2 initialize  $\Lambda \leftarrow$  all the instances of  $(h-1)$ -clique in  $G, D \leftarrow \emptyset$ ;
3 while  $u - l \geq \frac{1}{n(n-1)}$  do
4    $\alpha \leftarrow \frac{l+u}{2}$ ;
5    $V_{\mathcal{F}} \leftarrow \{s\} \cup V \cup \Lambda \cup \{t\}$ ; // build a flow network
6   for each vertex  $v \in V$  do
7     add an edge  $s \rightarrow v$  with capacity  $\deg_G(v, \Psi)$ ;
8     add an edge  $v \rightarrow t$  with capacity  $\alpha |V_\Psi|$ ;
9   for each  $(h-1)$ -clique  $\psi \in \Lambda$  do
10    for each vertex  $v \in \psi$  do
11      add an edge  $\psi \rightarrow v$  with capacity  $+\infty$ ;
12   for each  $(h-1)$ -clique  $\psi \in \Lambda$  do
13    for each vertex  $v \in V$  do
14      if  $\psi$  and  $v$  form an  $h$ -clique then
15        add an edge  $v \rightarrow \psi$  with capacity 1;
16   find minimum st-cut  $(S, T)$  from the flow network  $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$ ;
17   if  $S = \{s\}$  then  $u \leftarrow \alpha$ ;
18   else  $l \leftarrow \alpha, D \leftarrow$  the subgraph induced by  $S \setminus \{s\}$ ;
19 return  $D$ ;
```

In graph theory, a clique is a subset of vertices in a graph where every two distinct vertices are adjacent. The problem of detecting an h -clique, where each clique contains exactly h vertices, has significant applications in network analysis, social networks, and bioinformatics.

The Exact algorithm aims to efficiently identify h -cliques in a graph $G=(V,E)$ using a flow network approach. The algorithm proceeds through the following key steps:

Exact Algorithm Overview

1. **Input Parameters:** The algorithm operates on a graph $G=(V,E)$ with vertices V and edges E .
A set of potential h -cliques ψ , and a degree function $\mathbf{deg}(v,\psi)$ that determines the number of vertices a node connects to within the clique.
2. **Initialization:** A binary search is set up for the maximum degree within the graph. The lower bound $l=0$ and the upper bound $u=\max_{v \in V} \mathbf{deg}(v,\psi)$ for all vertices v .
A flow network is initialized to store the identified h -cliques.
3. **Building the Flow Network:** A source node is connected to each vertex $v \in V$ with a capacity equal to its degree.
Vertices are connected to a sink with a capacity scaled by a factor α , depending on the graph's properties.
For each identified h -clique (denoted Δ), edges are created to

represent the connections between the vertices forming the clique.

4. **Flow Calculations:** The algorithm calculates maximum flow iteratively, using binary search on the edge capacities.

This helps identify a subgraph with a density that satisfies the conditions for an h-clique.

5. **Subgraph Extraction:** If a minimum cut is found in the flow network, and the nodes connected to the sink are reachable under the set capacity, the subgraph is extracted as a valid h-clique.

6. **Termination:** The binary search converges, and the final set of h-cliques or the densest subgraph is returned, based on the flow calculations and capacities.

Algorithm 2 : CodeExact Algorithm

Algorithm 4: The algorithm: CoreExact.

Input: $G(V, E), \Psi(V_\Psi, E_\Psi)$;
Output: The CDS $D(V_D, E_D)$;

- 1 perform core decomposition using Algorithm 3;
- 2 locate the (k'', Ψ) -core using pruning criteria;
- 3 initialize $C \leftarrow \emptyset, D \leftarrow \emptyset, U \leftarrow \emptyset, l \leftarrow \rho'', u \leftarrow k_{\max}$;
- 4 put all the connected components of (k'', Ψ) -core into C ;
- 5 **for** each connected component $C(V_C, E_C) \in C$ **do**
- 6 **if** $l > k''$ **then** $C(V_C, E_C) \leftarrow C \cap ([l], \Psi)$ -core;
- 7 build a flow network $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$ by lines 5-15 of Algorithm 1;
- 8 find minimum st-cut (S, T) from $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$;
- 9 **if** $S = \emptyset$ **then** continue;
- 10 **while** $u - l \geq \frac{1}{|V_C|(|V_C| - 1)}$ **do**
- 11 $\alpha \leftarrow \frac{l+u}{2}$;
- 12 build $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$ by lines 5-15 of Algorithm 1;
- 13 find minimum st-cut (S, T) from $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$;
- 14 **if** $S = \{s\}$ **then**
- 15 $u \leftarrow \alpha$;
- 16 **else**
- 17 **if** $\alpha > [l]$ **then** remove some vertices from C ;
- 18 $l \leftarrow \alpha$;
- 19 $U \leftarrow S \setminus \{s\}$;
- 20 **if** $\rho(G[U], \Psi) > \rho(D, \Psi)$ **then** $D \leftarrow G[U]$;
- 21 **return** D ;

CoreExact is an advanced algorithm used for core decomposition in graph theory, designed to efficiently identify the most connected subgraphs (the "core") within a graph $G=(V,E)$. It builds on the concept of k-core decomposition, where vertices with degree less than k are removed, leaving behind a k-core — a subgraph where each vertex has at least k neighbors.

This algorithm is widely applied in fields such as social network analysis, bioinformatics, and complex systems, where understanding the structure of a graph and identifying its densest, most strongly connected subcomponents is crucial.

CoreExact Algorithm Overview

The CoreExact algorithm processes a graph G through the following steps:

- **Input and Initialization:** The algorithm begins with a graph G consisting of vertices V and edges E , along with a set Ψ of potential core decompositions.

The goal is to identify the core decomposition $D(V_D, E_D)$, where V_D is the set of core vertices and E_D is the set of edges connecting them.

- **Core Decomposition:** The algorithm starts by performing core decomposition (using Algorithm 3), identifying k-core subgraphs within the graph.

It initializes the sets for the k-core, vertices, and other parameters like thresholds α and k_{max} .

- **Identifying Connected Components:** The algorithm iterates over the connected components within the k-core. For each component C , if its size exceeds k' , it proceeds to construct a flow network to calculate the minimum s-cut.
- **Flow Network Construction:** A flow network $\mathcal{F}(V_{\mathcal{F}}, E_{\mathcal{F}})$; is built using the maximum flow algorithm. This network helps identify the strongest parts of the graph by calculating the flow and determining the minimum cut between source SSS and sink T .
- **Refining the Core:** After processing the components and calculating the flow cut, the algorithm updates the core by removing vertices that don't meet the k-core threshold. This refinement continues until the algorithm converges.
- **Termination:** The process concludes when the most stable and connected subgraphs are identified, providing the core decomposition of the graph.

Results :

1. Exact

Datasets	H=2	H=3	H=4
as20000102	8.865	35.910	85.130
CA-HepTh	15.4	155	1123.25
Netscience	9.2	56.5	242.4
as-Caida	17.34	114.44	405.213

2. CoreExact

Datasets	H=2	H=3	H=4
as20000102	8.865	35.910	85.130
CA-HepTh	15.3	154.5	1123.10
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