

DTU

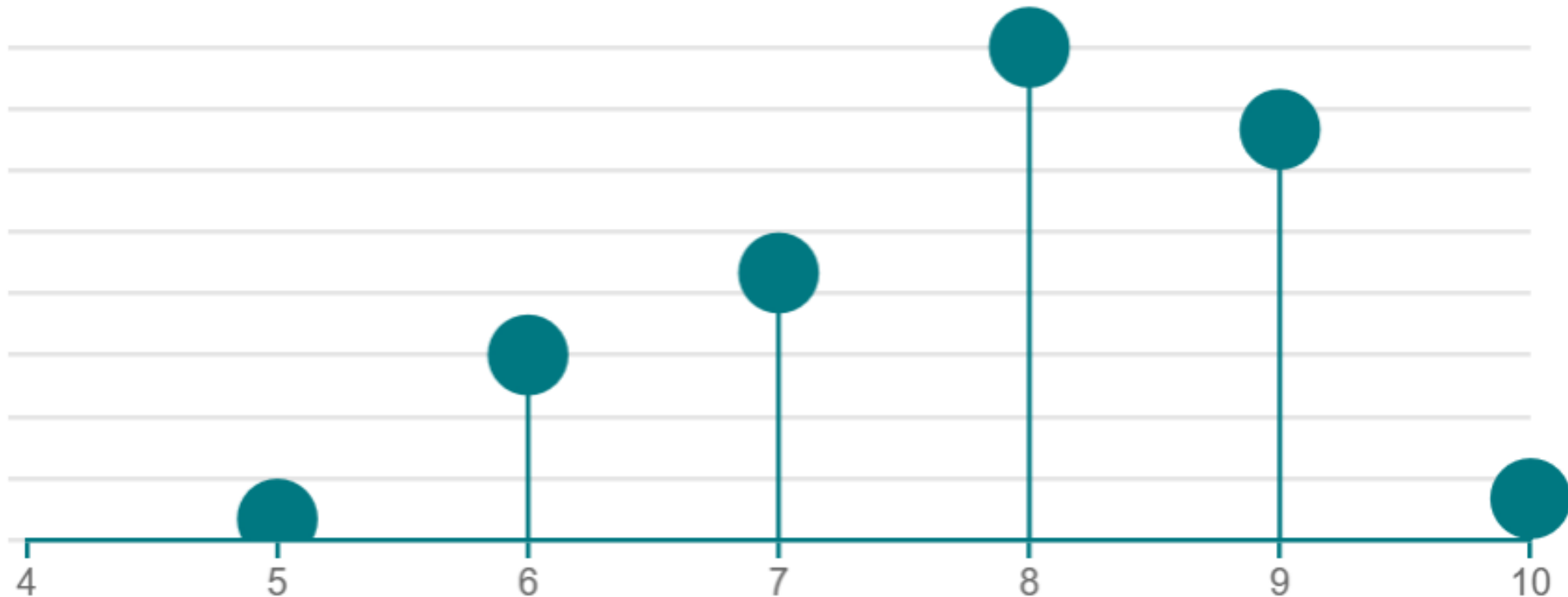


Feedback & Follow-up

1 How good/bad was today? (scale 1-10)

69

Mean average: 7.86



What you liked

Cool quiz

Finally got somewhat of an idea of what a Markov Decision Process is

The fact that the class was interactive , to learn doing games and slide through slide it was really nice

Examples given

Like that we have possibility to be active

The overall structure with slides and excercises

The quizzes helping me realize that I didn't know enough 🤔.

Well structured, clear lecture.

Very great examples. Very great brick by brick explanations.

The thorough explanation of the concepts. A clear example containing all concepts.

Consistency and participation activities

The quiz! Also the lecture was about 1.5 hour and I like short lectures

The quiz

The explanations were clear, good to see examples of code given as well

The game

Relatively quick.

The game at the end was fun The example (of last year's assignment) was informative

Overall it was nice to follow and easily explained

my expectation about the class somewhat fulfilled.

How the content was explained. Super dynamic and structured, good flow.

Not too much information but thorough explanation

The interactive approach

Approaching the theory with a practical example

The catching up on theory

Going through the "old" exam and translating it for us.. Together

I liked the quizzes during the lecture - it was Easier to understand the difference between...

Answer a lot of questions about Markov makes it easier to understand

MDP were new to me, I learnt a new approach to problems

Active learning

The approach to explain with a lead example and the quiz in the end

Everything

The walkthroughs, the highlighted text pieces

The quiz was nice

Seeing an example.

Nice with a walkthrough of last years exercise and a fun quiz to end the lecture with.

The connection with the prev assignment

Explanation about the topic was clear.

All

The quiz

Detailed and good presentation

The game

The quiz

decision approach

The quiz

Examples

Q&A

Made me think with the interactive quiz

The example was good, helps explain a lot of the concept

It's still a fun and interactive class

Interactive class

Your explanations were good

The fast pace, it was clear but concise.

pretty much

Was good.

Active learning method is the best

We are engaged in finding the solution

The game

I like that it is short and concise

Active class in which we could participate.

What you disliked

Nothing much	Can you present the slides as pdf instead of PowerPoint format	Maybe too fast sometimes , the code also was not on the slide so it was difficult to understand	The programming part could have been a bit more detailed	Very little actual information. I think the interactivity is refreshing but it takes up so much time.	Nothing	Maybe a bit more of tying the subject to the subject of last week. To get a more continuous feel	Vevox doesn't work :(I couldnt see the code properly, which i consider an important part, so I didnt get some of the commands...
None	I like the quiz format in the end but not that you may take it into account when grading. Top 3 is only selected on...	The speed of explanations, its hard to keep up from time to time. -> talking too fast	The pace. Perhaps a diagram that shows how the elements are connected	It could be nice if the slides had the symbols on them, and not just blank space:)	Some of the coding seems hard and could be explained in more detail. Fx showing some of the functions.	Not much material based on mdp. Maybe find a better case study to explain it for example battery charge	Stress more and spend more time on the most important parts	Confusing quizz
Not being able to prepare for class	Too easy, too much use og technology.	The terms might have been covered a little too fast.	That the slides we had differed from the one at on the projector	not very informative slides. unclear which are the deadlines for tasks/assignments	Try using a kahoot for the quizz	The bugs on vevox	To many questions in the last quiz	That the example was in Julia and we have to code it in pyomo
The quick walkthrough of the environment simulation code	.	I didn't win the quiz	Maybe you were going to fast	The quiz results	I bit heavy on some areas with only one break. Try dividing into more shorter breaks	hard to follow the code on the slides, maybe upload it next time	A practical numerical simulation of MDP would have been helpful, on top of the qualitative explanation, to better...	Maybe a heads up for a quiz that could enhance your grade beforehand would be nice
Nothing	Having a focus on grading during the lectures (the quiz) feels weird. Takes focus away	Very loose definitions - would not understand eg Markov property if I hadn't seen it before	nothing	Nothing :) Nice with a shorter lecture and a quiz, I feel like you learn a lot from the quiz.	Could you pls upload the slides a little bit earlier as it a bit of hard for me to catch up directly	Not linking slides with presented code	Nothing	the terms are too complicated to set apart easy. needs more training, but it is not as straight forward as...
			NA	Nothing very well formed the whole lecture	Too quick on the code implementation	That I didn't won	I have had a machine learning course before and therefore have done mdp. But today I just got more confused...	n/a
			Maybe there could be a bit more math	Nothing	No reading material	Computer bugged out Not ur fault tho	None	All fine
						nothing	Nothing :) Nice with a shorter lecture and a quiz, I feel like you learn a lot from the quiz.	Could you pls upload the slides a little bit earlier as it a bit of hard for me to catch up directly

Some comments

Some people like the quiz, some don't

Math rendering on the slides fixed

Deadline for Assignment A is April 7th

Some people find the material too hard, others too easy

Also check the Q&A section after each lecture.
Some answers & info can be found there.

- Top 3 in the quiz gets you 1,5 bonus points
- Textbook(s): <https://algorithmsbook.com/>
- Another example on MDP: https://www.youtube.com/watch?v=H_9YQBN45fo

Plan

→ ~~Task 0~~

→ ~~Task 1~~

~~Building an evaluation framework for sequential decision-making methods~~

→ Today: Task 2

Stochastic Programming policy (2-stage)
+ Expected Value policy a.k.a. MPC

→ Next Week: Task 2

Multi-stage Stochastic Programming + caveats

→ Week 5: Assignment Work for Task 2 and Q&A

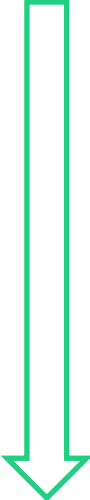
→ Weeks 6-7: Task 3

Approximate Dynamic Programming

→ Week 8: Assignment Work for Task 3 and Q&A

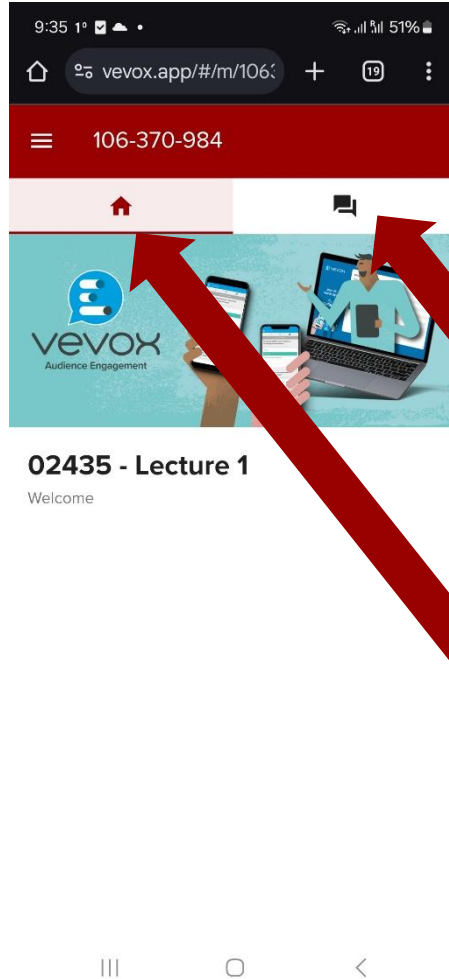
→ Weeks 9-11: Assignment B

Robust Optimization



Task 4 is
about
reporting
the results
from
Tasks 2
and 3

Scan me:

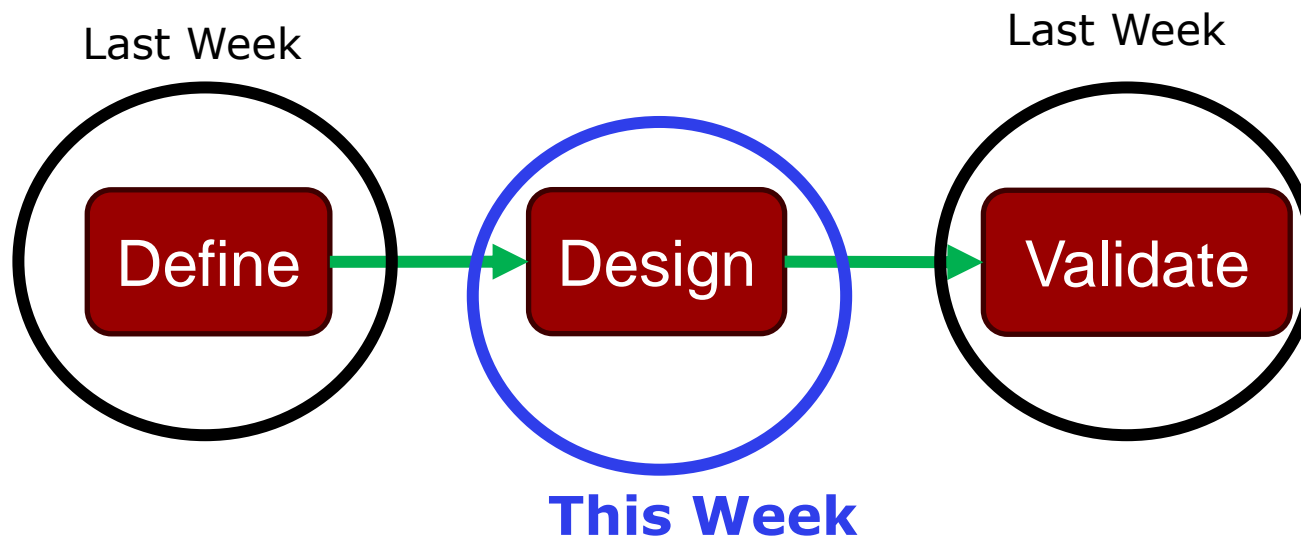
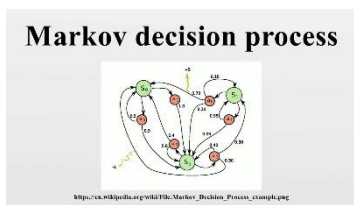


Anonymous Survey (at the end)

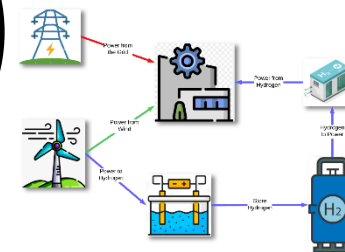
Anonymous Questions
(during or after the lecture)

Quizzes

The process of designing “Decision-making” frameworks



Coding a simulation Environment to evaluate *any* decision-making policy



Agenda for today

1. MDP recap and questions
2. Expected Value Policy
3. Two-stage Stochastic Programming policy

- Stages $t \in \mathcal{T}$
- State $\mathbf{x}_t = \{x_{1,t}, x_{2,t}, \dots\}$
- Decision $\mathbf{u}_t = \{u_{1,t}, u_{2,t}, \dots\}$
- Dynamics $\mathbf{x}_{t+1} = f(\mathbf{x}_t, \mathbf{u}_t)$
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The *State* variables \mathbf{x}_t enclose the necessary and sufficient information to model the system's behavior from stage t onwards.

Markov Decision Process

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Solution Concept:

Policy $\pi: \mathbf{u}_t = \pi(\mathbf{x}_t)$

Optimal Policy:

we cannot solve it when the algorithm is close to optimal we need to approximate

$$\min_{\pi} \left\{ \sum_t E_{\mathbf{x}_t \sim \pi} [c_t] \right\}$$

$$\mathbf{u}_t = \pi(\mathbf{x}_t), \quad \forall t$$

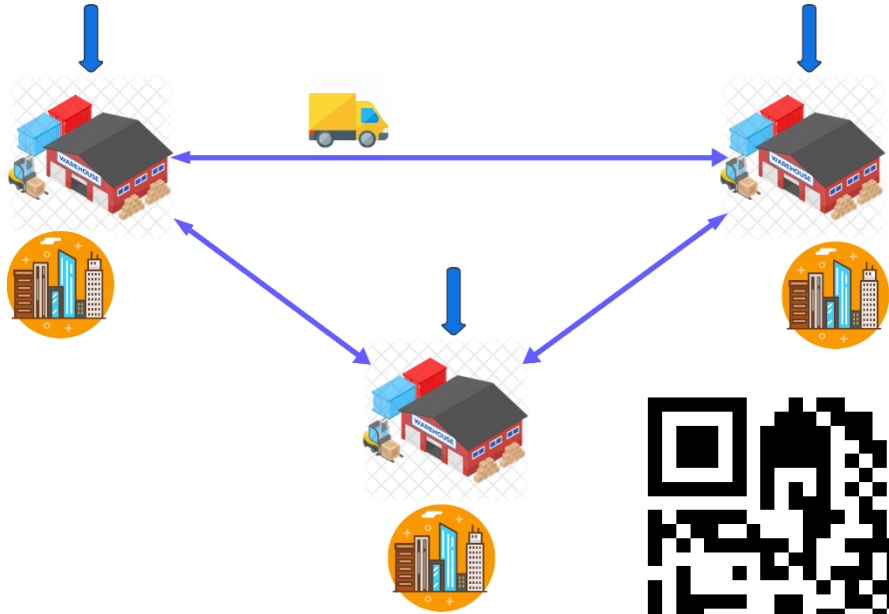
$$c_t = g(\mathbf{x}_t, \mathbf{u}_t), \quad \forall t$$

$$\mathbf{x}_{t+1} = f(\mathbf{x}_t, \mathbf{u}_t), \quad \forall t$$

For problems with discrete (and small) state/action spaces, we can design optimal policies:

Value Iteration, Policy Iteration (not in this course)

The Lead Example



Consider a city divided into three districts.

Each district features a dedicated warehouse $w \in W = \{1, 2, 3\}$ which serves the district's demand $D_{w,t}$ for coffee.

The coffee demand for each warehouse and day is known.

Each warehouse can store coffee up to a capacity limit C^{store} .

Denote the storage level of w at t by $z_{w,t}$.

At stage t , each warehouse w can order an amount $o_{w,t}$ of coffee from external suppliers at price $p_{w,t}$.

The price is different for each warehouse and each day.

Neighboring warehouses can also exchange coffee between them.

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Each exchange comes at a per-unit transportation cost $e_{w,q}$.

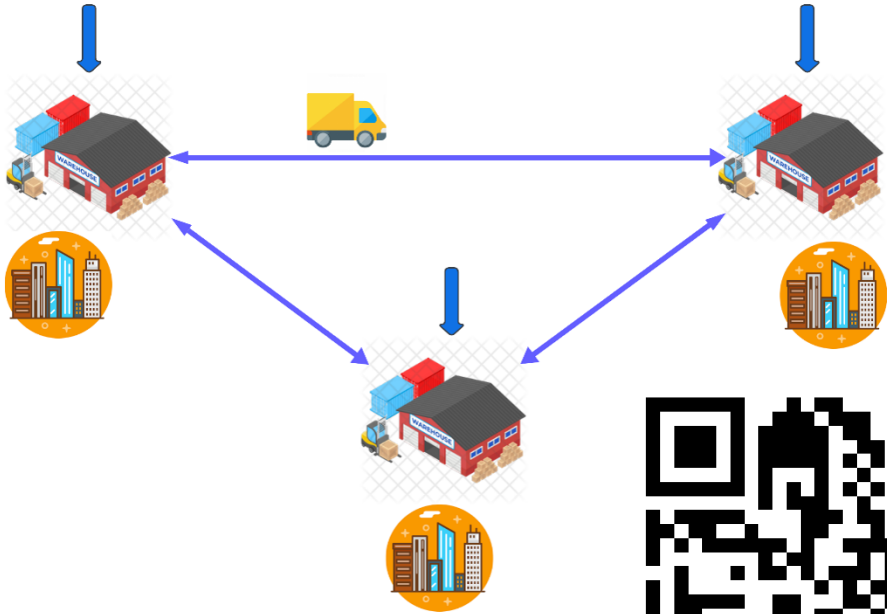
Failing to meet a district's demand at any day comes at a per-unit cost of b_w .

Your job is to build a program that makes the day-by-day decisions for the coffee distribution system of the three warehouses, so that the city's coffee needs are met at the minimum expected cost.



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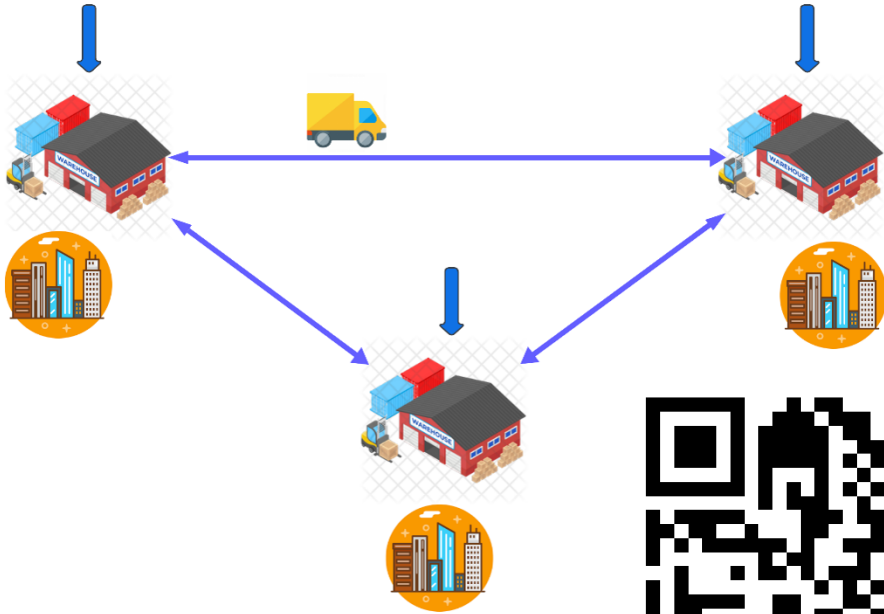
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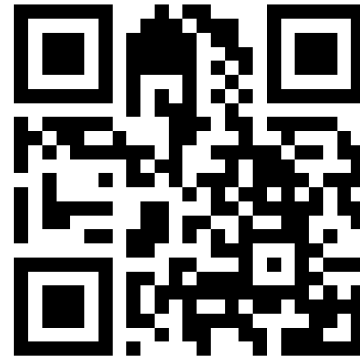
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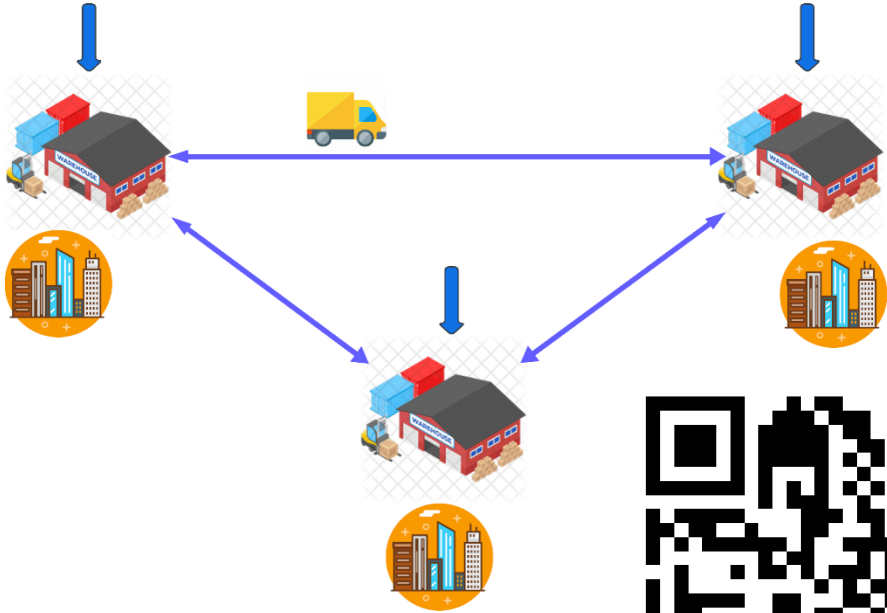
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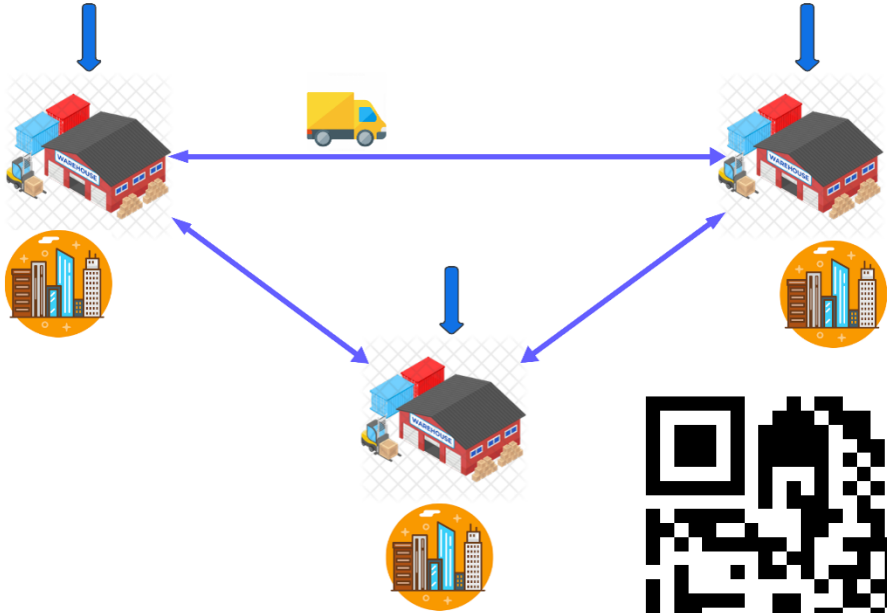
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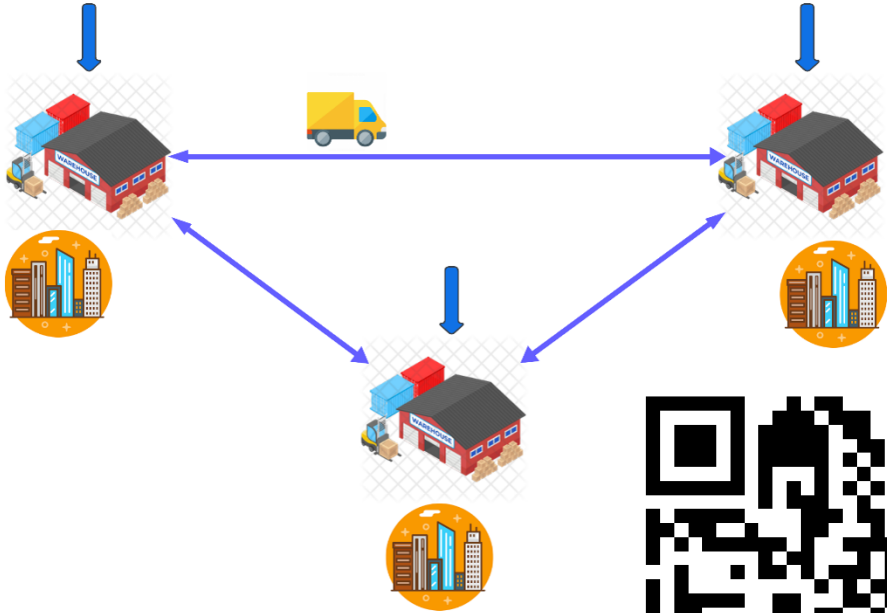
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The Lead Example

$$\cancel{z_{w,t+1}} = \cancel{z_{w,t}} - D_{w,t} + o_{w,t} + y_{w,q,t}^{rcv}$$

$$\cancel{z_{w,t+1}} = \cancel{z_{w,t}} - D_{w,t} + o_{w,t} + \sum_{q \in W} y_{w,q,t}^{rcv}$$

$$z_{w,t+1} = z_{w,t} - d_{w,t} + o_{w,t} + \sum_{q \in W} y_{w,q,t}^{rcv} - \sum_{q \in W} y_{w,q,t}^{send}$$

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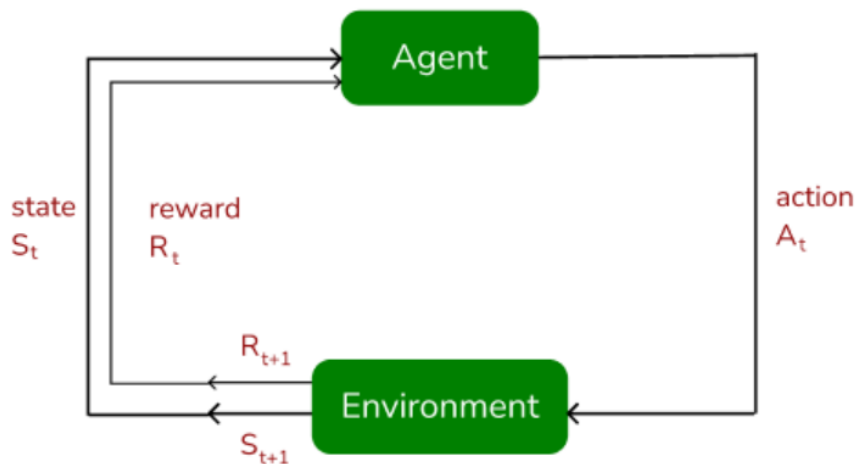
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Simulation Environment



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Simulation Environment

$$c_t = \sum_{w \in W} (p_{w,t} o_{w,t} + e_{w,q} y_{w,q,t}^{send} + b_w (D_{w,t} - d_{w,t}))$$

if $d_{w,t} < 0$:
then $d_{w,t} = 0$

$$Z = z_{w,t} - d_{w,t} + o_{w,t} + \sum_{q \in W} y_{w,q,t}^{rcv} - \sum_{q \in W} y_{w,q,t}^{send} \dots$$

if $Z > C^{store}$:
then $z_{w,t+1} = C^{store}$
if $Z < 0$:
then $z_{w,t+1} = 0$, $d_{w,t} = d_{w,t} - |Z|$
else: $z_{w,t+1} = Z$

if $y_{w,q,t}^{send} > \min\{z_{w,t}, C^{trnsnp}\}$:
then $y_{w,q,t}^{send} = \min\{z_{w,t}, C^{trnsnp}\}$

if $y_{w,q,t}^{rcv} \neq y_{w,q,t}^{send}$:
then $y_{w,q,t}^{rcv} = y_{w,q,t}^{send}$

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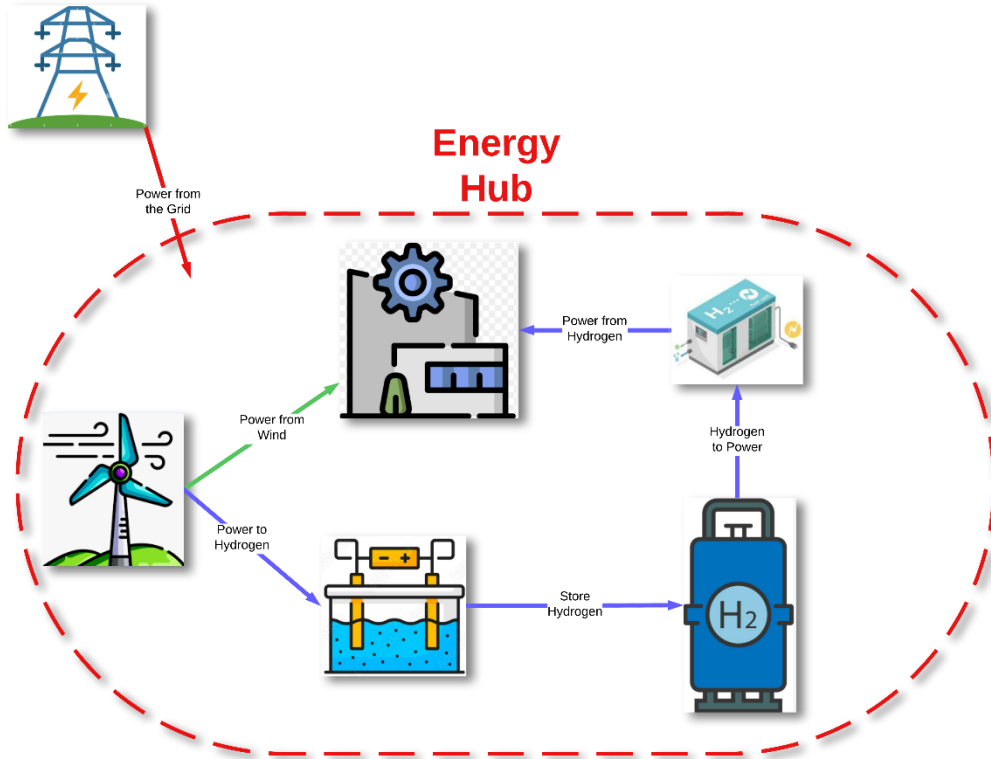
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Failing to meet a district's demand at any day comes at a per-unit cost b_w .

Your job is to build a program that makes the day-by-day decisions for the coffee distribution system of the three warehouses, so that the city's coffee needs are met at the minimum expected cost.

Assignment A, Task 1



Deliverable 1: MDP

State variables $\mathbf{x}_t = \{x_{1,t}, x_{2,t}, \dots\}$

Decision variables $\mathbf{u}_t = \{u_{1,t}, u_{2,t}, \dots\}$

Dynamics $\mathbf{x}_{t+1} = f(\mathbf{x}_t, \mathbf{u}_t)$

Cost function $c_t = g(\mathbf{x}_t, \mathbf{u}_t)$

Deliverable 2: Policy Evaluation Framework

Input: *policy* (python function that returns decisions)

Initialize state variables

For experiment 1 to E:

For stage 1 to H:

decisions = *policy*(state)

check/correct decisions if inconsistent

calculate cost for this stage and experiment

calculate state at next stage

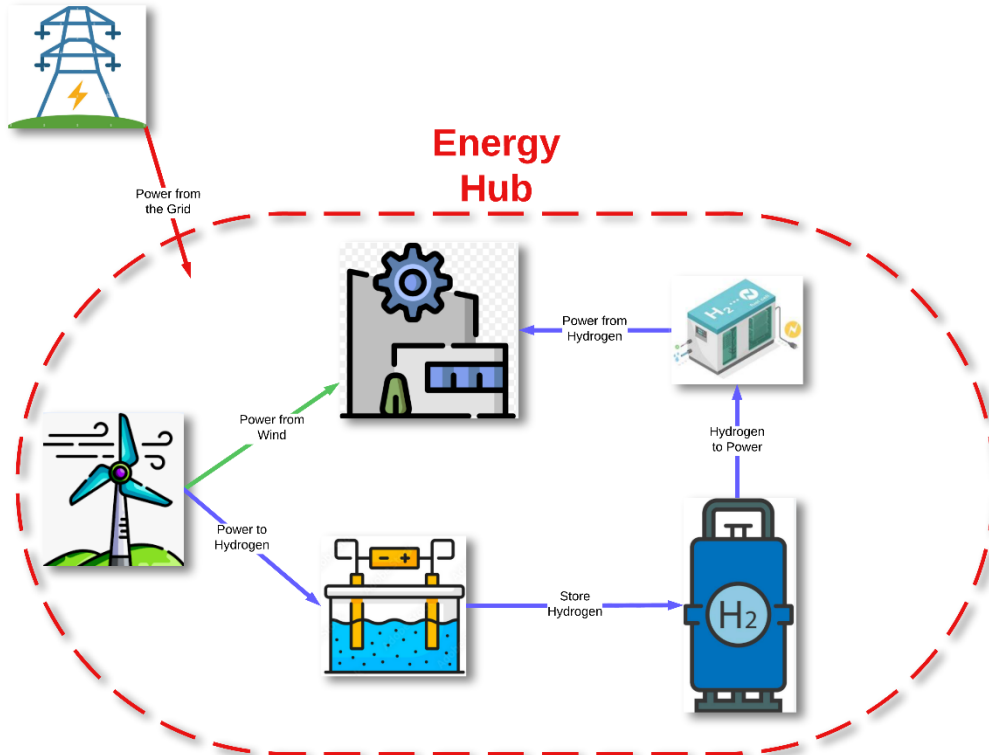
calculate total cost of policy for this experiment

Return: expected policy cost (average over experiments)

the environment need to check if the action are feasible, environment implements this, it calculates the cost and the next state by some random process and it return for the next state

Assignment A, Task 1

Constraints from Task 0



Deliverable 1: MDP

State variables $\mathbf{x}_t = \{x_{1,t}, x_{2,t}, \dots\}$

Decision variables $\mathbf{u}_t = \{u_{1,t}, u_{2,t}, \dots\}$

Dynamics $\mathbf{x}_{t+1} = f(\mathbf{x}_t, \mathbf{u}_t)$

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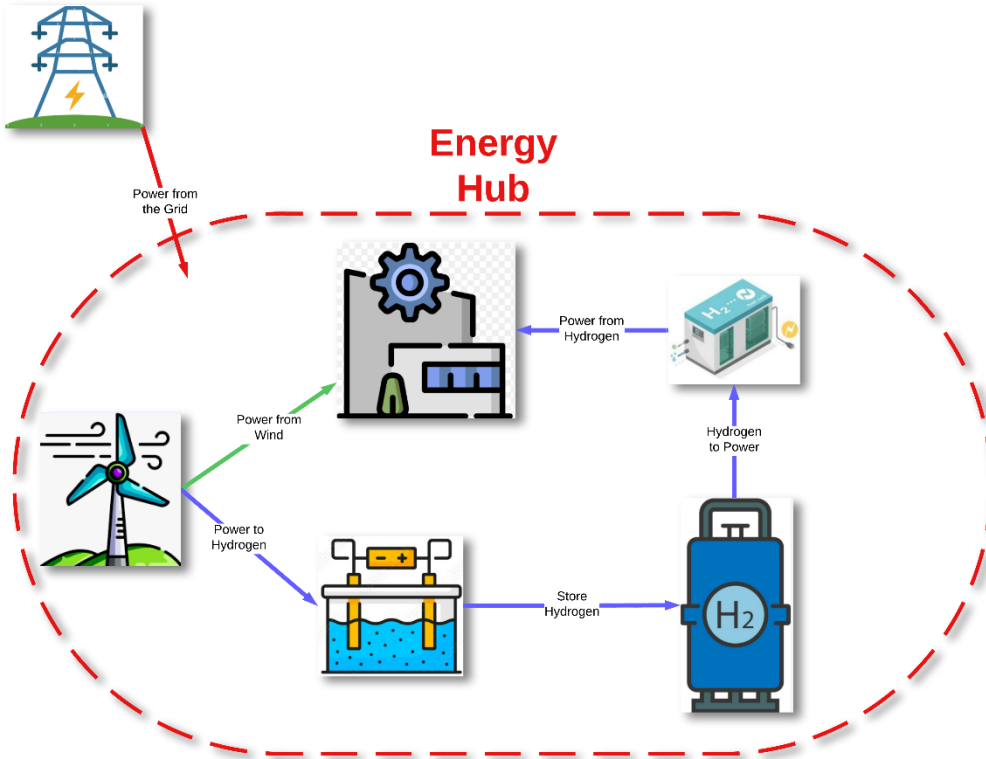
calculate total cost of policy for this experiment

Return: expected policy cost (average over experiments)

this is linked with task 0, implements everything in the constraints, we should find all the conditions that should be complied task 0 server as bench mark to compare with if we new everything before

Assignment A, Task 1

Constraints from Task 0



Deliverable 1: MDP

State variables $\mathbf{x}_t = \{x_{1,t}, x_{2,t}, \dots\}$

Decision variables $\mathbf{u}_t = \{u_{1,t}, u_{2,t}, \dots\}$

Dynamics $\mathbf{x}_{t+1} = f(\mathbf{x}_t, \mathbf{u}_t)$

Cost function $c_t = g(\mathbf{x}_t, \mathbf{u}_t)$

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Input: *policy* (python function that returns decisions)

Initialize state variables

For experiment 1 to E:

For stage 1 to H:

decisions = *policy*(state)

check/correct decisions if inconsistent

calculate cost for this stage and experiment

calculate state at next stage

calculate total cost of policy for this experiment

Return: expected policy cost (average over experiments)

Some Perspective

Not in this course

we had already the forecasting, usually we do not have this stochastic problems that give us the next wind generation, usually we just have historical data



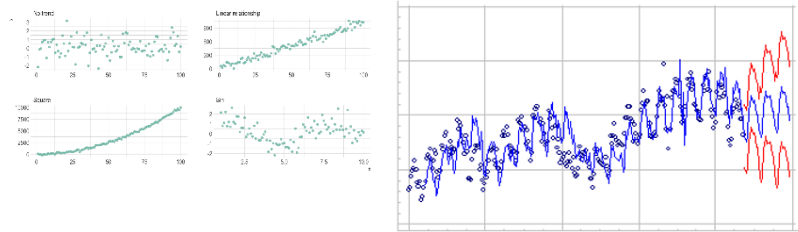
we assume that someone did that for us

we can use samples and we calculate recursively, we fit the current state and we can have the next wind, and so, we can generate all trajectories

easiest policy, meet the demand

we can use linear programming

we can solve optimization problem, we can generate point forecast and plug into the optimization, and we assume this is reality and we solve a linear problem, linear, deterministic

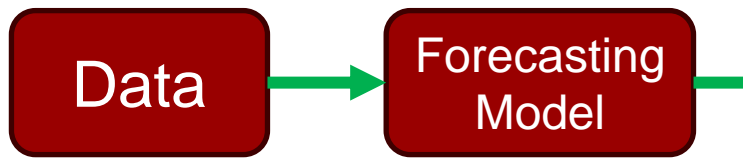


The Expected-Value Policy

Not in this course

At each stage:

1. Forecast uncertainties for a lookahead horizon
2. Solve a deterministic optimization program (similar to the OiH) for the lookahead horizon

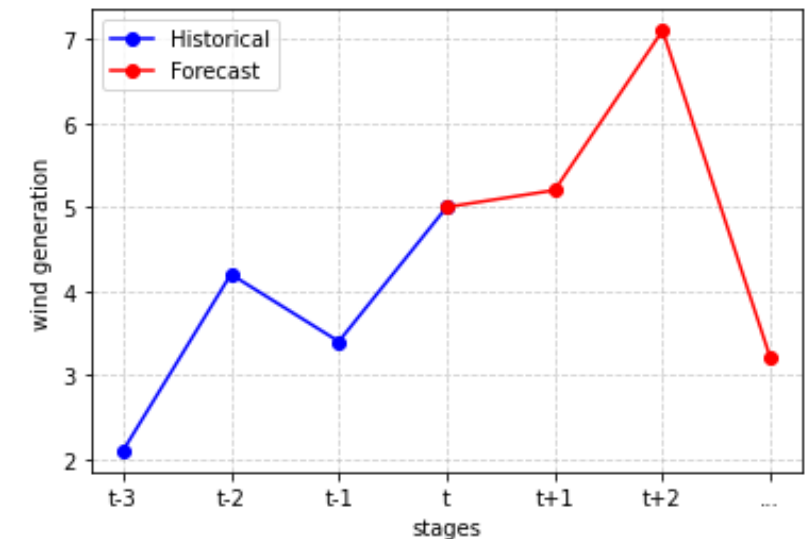
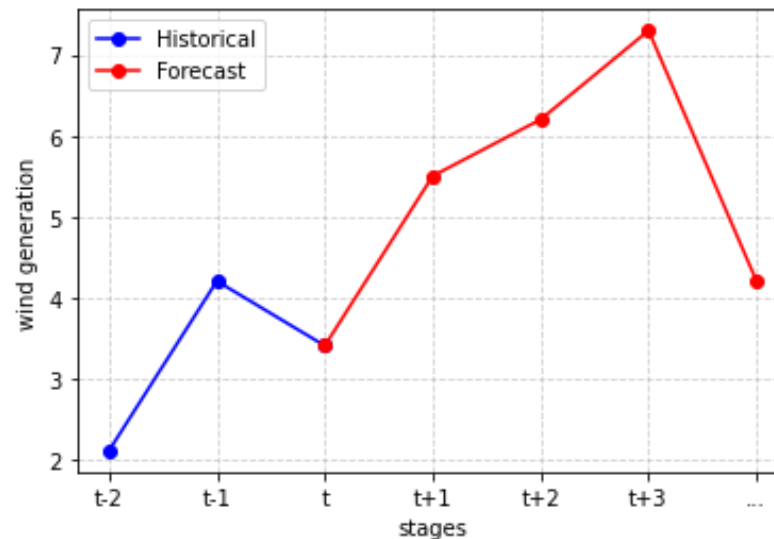
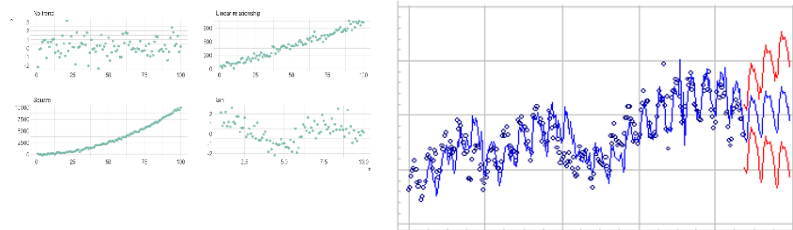


wind_process

i will look 10 days ahead and solve the forecastig, future values

price_process

once i do the decision the policy gave and i am going to the next statge, most proably my forecast will be wrognng, i will have a new wind generation, i take the new uncertainiy that is reavealed, this i my new state, i prodce new forecast, i solve the optimization as every state



The Expected-Value Policy

Input: current state x_0

Set a lookahead horizon length L

Calculate the expected scenario for the exogenous state variables for the horizon, i.e., $\tilde{x}_1 \tilde{x}_2, \dots, \tilde{x}_L$

Solve a deterministic optimization program (similar to the OiH) for the horizon:

$$\min_{u_0, u_1, \dots, u_L} \left\{ \sum_{t \in [0, L]} c_t \right\}$$

s.t. constraints

we go for the horizon, small optimizations

Return: u_0 (and not u_1, \dots, u_L)

only the decision from now, the decisions for all the horizon are just to guide
policy is presented with the state, what will we do,

At each stage:

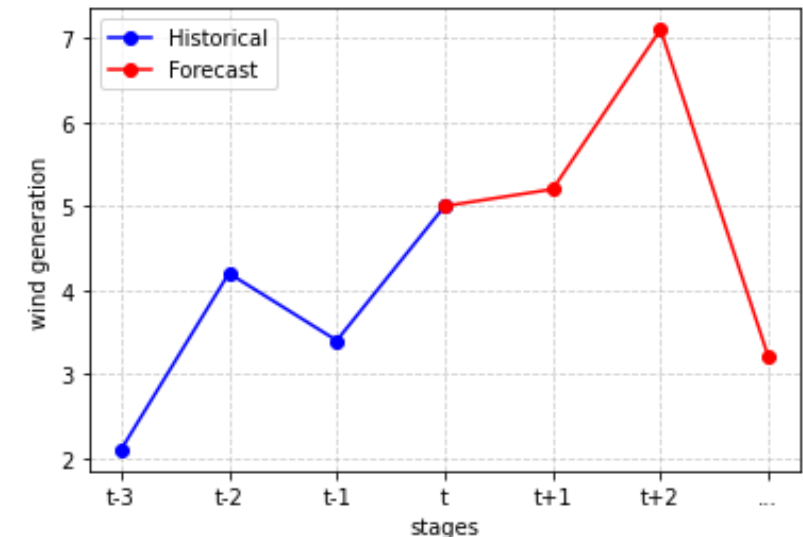
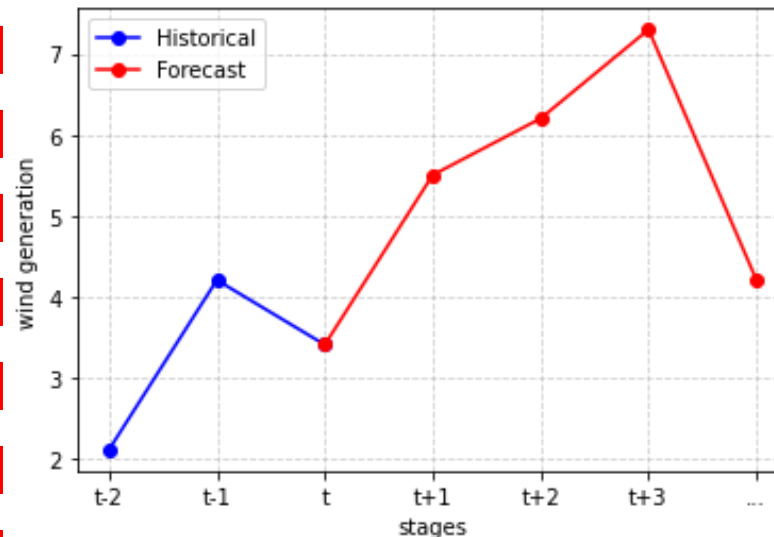
1. Forecast
2. Solve a deterministic optimization program (similar to the OiH) for a lookahead horizon

how long will i look ahead, with this horizon, i will create random samples, random wind, monte carlo for example, we simulate many samples and take the average to take the expected scenario
i can do it when they exogenous when they do not depend of my decisions - like weather, but if it is chess i cannot predict the next 10 plays, it will depend on my moves, it is dependent

wind_process

price_process

Simulate (Monte Carlo) many samples and calculate the average



u_0 effective decision, u_1, u_L are prospective decisions, they are not binding, we do not stick with them

Two-stage Stochastic Programming

Why two-stage?

- a) Easier to understand and sometimes it's a good enough policy
- b) Some problems are just naturally two-stage problems (e.g. investment planning)

investment, in first state i want to build, second, operational, and then investing how much to invest considering now this new inputs

Remember Carl?

Apart from having cows and sheep, Farmer Carl grows wheat, corn and sugar beets on his 500 acres of farmland. He has to decide at the beginning of the season how much space he wants to use for each of the crops. To plant one acre with wheat, corn or sugar beets costs him 150 €, 230 € or 260 €, respectively.

He needs at least 200 tons of wheat and 240 tons of corn to feed his cattle. If he does not produce enough wheat and corn himself, he can buy the missing amount on the market for 238 € and 210 € per ton, respectively. In the case of overproduction, he can sell his potential overproduction at a price of 170 € per ton wheat and 150 € per ton corn.

His sugar beet yield is meant for selling only and brings 36 € per ton.

However, due to a given quota only for a maximal amount of 6000 tons.

Every additional ton can be sold at a price of 10 € per ton only.

The average yield per acre of wheat, corn and sugar beets is 2.5, 3 and 20 tons, respectively.

Remember Carl?

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He needs **at least 200 tons of wheat and 240 tons of corn** to feed his cattle. If he does not produce enough wheat and corn himself, **he can buy the missing amount on the market** for 238 € and 210 € per ton, respectively. In the case of overproduction, he can sell his potential overproduction at a price of 170 € per ton wheat and 150 € per ton corn.

His sugar beet yield is meant for selling only and brings 36 € per ton. However, due to a given quota **only for a maximal amount of 6000 tons**. **Every additional ton can be sold** at a price of 10 € per ton only.

The average yield per acre of wheat, corn and sugar beets is 2.5, 3 and 20 tons, respectively.

x^W, x^C, x^S	Acres used for wheat, corn, sugar beets
y^W, y^C	Tons of wheat and corn purchased
z^W, z^C	Tons of wheat and corn sold
z^S	Tons of sugar beets sold at price 36 €
v^S	Tons of sugar beets sold at price 10 €

$$\begin{aligned} \text{Max Profit} &= 170z^W + 150z^C + 36z^S + 10v^S \\ &\quad - 150x^W - 230x^C - 260x^S - 238y^W - 210y^C \\ \text{s.t. } &x^W + x^C + x^S \leq 500 \\ &2.5x^W + y^W - z^W \geq 200 \\ &3.0x^C + y^C - z^C \geq 240 \\ &z^S \leq 6000 \\ &z^S + v^S \leq 20x^S \\ &x^W, x^C, x^S, y^W, y^C, z^W, z^C, z^S, v^S \geq 0 \end{aligned}$$

if we short we need to buy, if we have more we need to sell

Linear program formulation

x^W, x^C, x^S	Acres used for wheat, corn, sugar beets
y^W, y^C	Tons of wheat and corn purchased
z^W, z^C	Tons of wheat and corn sold
z^S	Tons of sugar beets sold at price 36 €
v^S	Tons of sugar beets sold at price 10 €

the variables will be the same and
constraints as well

$$\begin{aligned}
 \text{Max } Profit &= 170z^W + 150z^C + 36z^S + 10v^S \\
 &\quad - 150x^W - 230x^C - 260x^S - 238y^W - 210y^C \\
 \text{s.t. } &x^W + x^C + x^S \leq 500 \\
 &\underline{2.5}x^W + y^W - z^W \geq 200 \\
 &\underline{3.0}x^C + y^C - z^C \geq 240 \\
 &z^S \leq 6000 \\
 &z^S + v^S \leq \underline{20x^S} \\
 &x^W, x^C, x^S, y^W, y^C, z^W, z^C, z^S, v^S \geq 0
 \end{aligned}$$

Considering Uncertainty

The average yield per acre of wheat, corn and sugar beets is 2.5, 3 and 20 tons, respectively.

What if, the yield depends on weather and other circumstances in each year. In a good year, the yield can be higher while in a bad year, the yield can be lower. This table gives the yields in the different situations.

Yield	Wheat	Corn	Sugar beets	Probability
High (+20%)	3.0	3.6	24.0	0.2
Average	2.5	3.0	20.0	0.5
Low (-20%)	2.0	2.4	16.0	0.3

We solve the optimization model also for a year with high yield and for a year with low yield.

Stochastic Program Formulation

$$\text{s.t. } x^W + x^C + x^S \leq 500 \quad x^W, x^C, x^S \geq 0$$

Stochastic Program Formulation

$$\text{s.t. } x^W + x^C + x^S \leq 500 \quad x^W, x^C, x^S \geq 0$$

for each scenario we change the yield, we have 3 version, good, bad and average year

we need to include all the constraints we don't know each will be real

Scenario 1

$$3.0x^W + y_1^W - z_1^W \geq 200$$

$$3.6x^C + y_1^C - z_1^C \geq 240$$

$$z_1^S \leq 6000$$

$$z_1^S + v_1^S \leq 24x^S$$

$$y_1^W, y_1^C, z_1^W, z_1^C, z_1^S, v_1^S \geq 0$$

Scenario 2

$$2.5x^W + y_2^W - z_2^W \geq 200$$

$$3.0x^C + y_2^C - z_2^C \geq 240$$

$$z_2^S \leq 6000$$

$$z_2^S + v_2^S \leq 20x^S$$

$$y_2^W, y_2^C, z_2^W, z_2^C, z_2^S, v_2^S \geq 0$$

Scenario 3

$$2.0x^W + y_3^W - z_3^W \geq 200$$

$$2.4x^C + y_3^C - z_3^C \geq 240$$

$$z_3^S \leq 6000$$

$$z_3^S + v_3^S \leq 16x^S$$

$$y_3^W, y_3^C, z_3^W, z_3^C, z_3^S, v_3^S \geq 0$$

Stochastic Program Formulation

We optimize for the expected value over all scenarios

$$\begin{aligned} \text{Max Profit} = & -150x^W - 230x^C - 260x^S \\ & + 0.2(170z_1^W + 150z_1^C + 36z_1^S + 10v_1^S - 238y_1^W - 210y_1^C) \\ & + 0.5(170z_2^W + 150z_2^C + 36z_2^S + 10v_2^S - 238y_2^W - 210y_2^C) \\ & + 0.3(170z_3^W + 150z_3^C + 36z_3^S + 10v_3^S - 238y_3^W - 210y_3^C) \\ \text{s.t. } & x^W + x^C + x^S \leq 500 \quad x^W, x^C, x^S \geq 0 \end{aligned}$$

they look the same but have a probability
we have variables defined for each state, if we have a good state we will sell thus mych z_1^W , if we dont see that much z_3^S ...

what changes is the availability i
ahve to see or buy

Scenario 1

$$\begin{aligned} 3.0x^W + y_1^W - z_1^W & \geq 200 \\ 3.6x^C + y_1^C - z_1^C & \geq 240 \\ z_1^S & \leq 6000 \\ z_1^S + v_1^S & \leq 24x^S \\ y_1^W, y_1^C, z_1^W, z_1^C, z_1^S, v_1^S & \geq 0 \end{aligned}$$

Scenario 2

they are indexed by scenario

$$\begin{aligned} 2.5x^W + y_2^W - z_2^W & \geq 200 \\ 3.0x^C + y_2^C - z_2^C & \geq 240 \\ z_2^S & \leq 6000 \\ z_2^S + v_2^S & \leq 20x^S \\ y_2^W, y_2^C, z_2^W, z_2^C, z_2^S, v_2^S & \geq 0 \end{aligned}$$

Scenario 3

$$\begin{aligned} 2.0x^W + y_3^W - z_3^W & \geq 200 \\ 2.4x^C + y_3^C - z_3^C & \geq 240 \\ z_3^S & \leq 6000 \\ z_3^S + v_3^S & \leq 16x^S \\ y_3^W, y_3^C, z_3^W, z_3^C, z_3^S, v_3^S & \geq 0 \end{aligned}$$

General Formulation

x first-stage decision variables

y second-stage decision variables

Let $\omega \in \Omega$ be the **finite set of scenarios** of uncertainty and $\pi(\omega)$ the probability of scenario ω .

Extensive form / deterministic equivalent linear program:

$$\begin{aligned}
 \min \quad & c^T x + \overbrace{\sum_{\omega \in \Omega} \pi(\omega) q(\omega)^T y(\omega)}^{\text{Expected value} \quad \text{cost to go}} \\
 \text{s.t.} \quad & Ax = b \\
 & T(\omega)x + W(\omega)y(\omega) = h(\omega) \quad \forall \omega \in \Omega \\
 & x \geq 0 \\
 & y(\omega) \geq 0 \quad \forall \omega \in \Omega
 \end{aligned}$$

expected cost to go we will talk later, coefficients, for the corn it was the prices to buy seed, $q(\omega)$

each constraint need to be stated to each scenario

Stochastic Program Solution

Expected profit = 105436 €

Stage	Scenario	Variable	Wheat	Corn	Sugar beets	Profit
1st	all	Acres	120	80	300	
2nd	High yield	Purchase	0	0	-	148000
		Sale	160	48	6000 (36 €)	
					1200 (10 €)	
	Average yield	Purchase	0	0	-	118600
		Sale	100	0	6000 (36 €)	
					0 (10 €)	
	Low yield	Purchase	0	48	-	55120
		Sale	40	0	4800 (36 €)	
					0 (10 €)	

sum them with the given probabilities we have the provability if we dont know if it will be good or bad year

Stochastic Program vs Expected Value Program

Expected profit = 105436 €

$$\begin{aligned} \text{Max Profit} = & -150x^W - 230x^C - 260x^S \\ & + 0.2(170z_1^W + 150z_1^C + 36z_1^S + 10v_1^S - 238y_1^W - 210y_1^C) \\ & + 0.5(170z_2^W + 150z_2^C + 36z_2^S + 10v_2^S - 238y_2^W - 210y_2^C) \\ & + 0.3(170z_3^W + 150z_3^C + 36z_3^S + 10v_3^S - 238y_3^W - 210y_3^C) \\ \text{s.t. } & x^W + x^C + x^S \leq 500 \quad x^W, x^C, x^S \geq 0 \end{aligned}$$

Scenario 1

$$3.0x^W + y_1^W - z_1^W \geq 200$$

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$$z_1^S \leq 6000$$

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Scenario 2

$$2.5x^W + y_2^W - z_2^W \geq 200$$

$$3.0x^C + y_2^C - z_2^C \geq 240$$

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Scenario 3

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$$y_3^W, y_3^C, z_3^W, z_3^C, z_3^S, v_3^S \geq 0$$

Yield	Wheat	Corn	Sugar beets	Probability
High (+20%)	3.0	3.6	24.0	0.2
Average	2.5	3.0	20.0	0.5
Low (-20%)	2.0	2.4	16.0	0.3
Expected	2.45	2.94	19.6	

Expected profit = 113545.92 €

i dont bother myself wit texoected scenarios, i summe them up and i get the expected scneario
i only have one scnerio i o the average witht the probability

$$\begin{aligned} \text{Max Profit} = & 170z^W + 150z^C + 36z^S + 10v^S \\ & - 150x^W - 230x^C - 260x^S - 238y^W - 210y^C \end{aligned}$$

$$\text{s.t. } x^W + x^C + x^S \leq 500$$

$$2.45x^W + y^W - z^W \geq 200$$

$$2.94x^C + y^C - z^C \geq 240$$

$$z^S \leq 6000$$

$$z^S + v^S \leq 19.6x^S$$

$$x^W, x^C, x^S, y^W, y^C, z^W, z^C, z^S, v^S \geq 0$$

we need to validate we need to
simulate, first we apply and then
reallity kicks in and after the
uncertainty is revealed i need to
decide,

Stochastic Program vs Expected Value Program

Expected profit = 105436 €

$$\begin{aligned} \text{Max Profit} = & -150x^W - 230x^C - 260x^S \\ & + 0.2(170z_1^W + 150z_1^C + 36z_1^S + 10v_1^S - 238y_1^W - 210y_1^C) \\ & + 0.5(170z_2^W + 150z_2^C + 36z_2^S + 10v_2^S - 238y_2^W - 210y_2^C) \\ & + 0.3(170z_3^W + 150z_3^C + 36z_3^S + 10v_3^S - 238y_3^W - 210y_3^C) \\ \text{s.t. } & x^W + x^C + x^S \leq 500 \quad x^W, x^C, x^S \geq 0 \end{aligned}$$

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$$z_3^S \leq 6000$$

$$z_3^S + v_3^S \leq 16x^S$$

$$y_3^W, y_3^C, z_3^W, z_3^C, z_3^S, v_3^S \geq 0$$

Simulate second stage uncertainty realization (experiments) and evaluate the "actual" profit...

Expected profit = 104156.7 € So, actually less than the SP

~~Expected profit = 113545.92 €~~

$$\begin{aligned} \text{Max Profit} = & 170z^W + 150z^C + 36z^S + 10v^S \\ & - 150x^W - 230x^C - 260x^S - 238y^W - 210y^C \end{aligned}$$

$$\text{s.t. } x^W + x^C + x^S \leq 500$$

$$2.45x^W + y^W - z^W \geq 200$$

$$2.94x^C + y^C - z^C \geq 240$$

$$z^S \leq 6000$$

$$z^S + v^S \leq 19.6x^S$$

$$x^W, x^C, x^S, y^W, y^C, z^W, z^C, z^S, v^S \geq 0$$

we don't stick what solvers predicts, we need to only take first decisions and then after observing reality, only then we decide what we will actually sell in the market, the recall decisions, and we simulate with the environment then

Connection to the Assignment

1. Optimal in Hindsight solution (Task 0)
2. Expected Value policy (Task 2)
3. 2-stage Stochastic Programming policy (Task 2)

we can use the code to simulate one scenario

Develop a simulation environment to evaluate a policy (Task 1)

Evaluate each of the above over the same experiments to evaluate each one's expected cost (Task 4)

stochastic performs better than expected

Which of the three will have the highest, and which the lowest average cost?

Ruszczynski A, Shapiro A (2003): *Chapter 1 - Stochastic Programming Models*, Handbooks in Operations Research and Management Science, Vol. 10

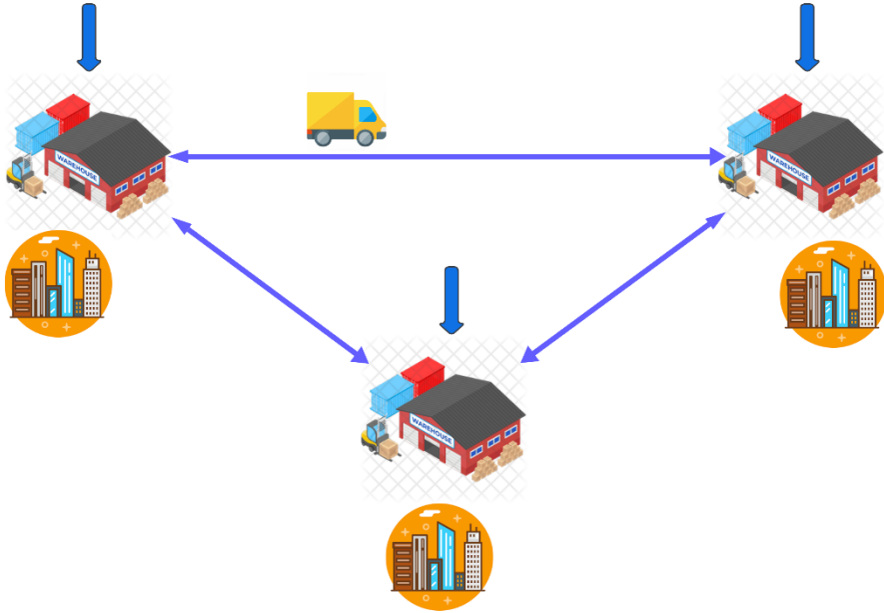
Relevant pages: 1-22

The farmer example is based on:

Birge J R, Louveaux F (1997): *Introduction to Stochastic Programming*, Springer

Relevant pages: 4-10

Back to Coffee



Consider a city divided into three districts.

Each district features a dedicated warehouse $w \in W = \{1,2,3\}$ which serves the district's demand $D_{w,t}$ for coffee.

The coffee demand for each warehouse and day is known.

Each warehouse can store coffee up to a capacity limit C^{store} .

Denote the storage level of w at t by $z_{w,t}$.

At stage t , each warehouse w can order an amount $o_{w,t}$ of coffee from external suppliers at price $p_{w,t}$.

The price is different for each warehouse and each day.

Neighboring warehouses can also exchange coffee between them.

Let $y_{w,q,t}^{rcv}$ denote the amount received by w from a neighboring warehouse q , at t .

Similarly, $y_{w,q,t}^{send}$ is the amount sent by w to q .

To send an amount $y_{w,q,t}^{send}$, warehouse w must already have this amount previously stored.

The amount sent in one stage is restricted by a transportation limit C^{trnsp} .

Each exchange comes at a per-unit transportation cost $e_{w,q}$.

Failing to meet a district's demand at any day comes at a per-unit cost of b_w .

Your job is to build a program that makes the day-by-day decisions for the coffee distribution system of the three warehouses, so that the city's coffee needs are met at the minimum expected cost.

Coffee Problem Nomenclature

Sets

- $w, q \in W$: set of warehouses, where w and q belong to $\{1, 2, 3\}$
- $t \in T$: set of timeslots (daily), in $\{1, 2, \dots\}$

Parameters

- $D_{w,t}$: coffee demand for warehouse w in period t , being constant at 4 units per day
- $C_w^{storage}$: storage capacity limit for warehouse w
- $C_{w,q}^{transp}$: daily transportation capacity limit for what warehouse w can send to warehouse q , where if $w = q$ then the capacity is zero
- $p_{w,t}$: external coffee price for warehouse w at time t , continuous in $[0, 10]$
- $e_{w,q}$: transportation per-unit cost between warehouse w and q , where if $w = q$ then the cost is zero
- b_w : per-unit cost of missing daily demand for warehouse w

Variables

- $x_{w,t}$: continuous, amount of coffee ordered in timeslot t by warehouse w
- $z_{w,t}$: continuous, amount of coffee stored by the end of timeslot t in warehouse w
- $m_{w,t}$: continuous, amount of coffee missing when daily demand is not met in warehouse w in t
- $y_{w,q,t}^{send}$: continuous, amount of coffee sent by warehouse w to q in timeslot t
- $y_{w,q,t}^{receive}$: continuous, amount of coffee received by warehouse w from q in timeslot t

Coffee Problem OiH formulation

Minimize the total cost of the coffee distribution system (orders, transfers and missed) so that the demands are met. The objective function includes all 3 costs: orders placed, transport between warehouses and failing to meet the demand.

$$\min \sum_{w \in W} \sum_{t \in T} x_{w,t} \cdot p_{w,t} + \sum_{w \in W} \sum_{q \in W} \sum_{t \in T} y_{w,q,t}^{send} \cdot e_{w,q} + \sum_{w \in W} \sum_{t \in T} m_{w,t} \cdot b_w \quad (1)$$

Constraints

- To always respect the truck (transport) capacity between the warehouses

$$y_{w,q,t}^{send} \leq C_{w,q}^{transp} \quad \forall w, q \in W, t \in T \quad (2)$$

- To have the same quantity being received and sent between two warehouses in a specific period

$$y_{w,q,t}^{send} = y_{q,w,t}^{receive} \quad \forall w, q \in W, t \in T \quad (3)$$

- To always respect the storage capacity in all warehouses

$$z_{w,t} \leq C_w^{storage} \quad \forall w \in W, t \in T \quad (4)$$

- To ensure demand fulfillment in all warehouses in $t \in T$

$$x_{w,t} + m_{w,t} + z_{w,t-1} + \sum_{q \in W} y_{w,q,t}^{receive} = D_{w,t} + z_{w,t} + \sum_{q \in W} y_{w,q,t}^{send} \quad \forall w \in W, t \in T \quad (5)$$

- The amount sent between warehouses can only be determined by the amount stored in the previous time slot

$$\sum_{q \in W} y_{w,q,t}^{send} \leq z_{w,t-1} \quad \forall w \in W, t \in T \quad (6)$$

- Non-negativity for all variables

$$\begin{aligned} x_{w,t} &\geq 0, z_{w,t} \geq 0, m_{w,t} \geq 0 & \forall w \in W, t \in T \\ y_{w,q,t}^{send} &\geq 0, y_{w,q,t}^{receive} \geq 0 & \forall w \in W, t \in T \end{aligned} \quad (7)$$

Coffee Problem 2-stage Stochastic Program

Sets

- $s \in S$: set of scenarios, in $\{1, 2, \dots\}$

Parameters

- $p1_w$: external coffee price for warehouse w on day 1, continuous in $[0, 10]$
- $p2_{w,s}$: external coffee price for warehouse w on day 2 in scenario s , continuous in $[0, 10]$
- $prob_s$: probability of occurrence of scenario s .
- $z0_w$: initial stock for each warehouse in $t = 1$.

1:
 X_stage_1
 X_stage_2

2:
 $X_{w,s,t}$
 $X_{w,s,1} = X_{w,s',1}$ for all $s, s' \in S$

The previously defined variables had to be separated into 1st stage (equal for all scenarios) and 2nd stage (different for each scenario) in the following way:

Variables : First ($t = 1$) and Second ($t = 2$) Stage Decision

- $x1_w$: continuous, amount of coffee ordered in timeslot 1 by warehouse w .
- $x2_{w,s}$: continuous, amount of coffee ordered in timeslot 2 by warehouse w in scenario s .
- $z1_w$: continuous, amount of coffee stored by the end of timeslot 1 in warehouse w .
- $z2_{w,s}$: continuous, amount of coffee stored by the end of timeslot 2 in warehouse w in scenario s .
- $m1_w$: continuous, amount of coffee missing when daily demand is not met in warehouse w in timeslot 1.
- $m2_{w,s}$: continuous, amount of coffee missing when daily demand is not met in warehouse w in timeslot 2 in scenario s .
- $y1_{w,q}^{send}$: continuous, amount of coffee sent by warehouse w to q in timeslot 1.
- $y2_{w,q,s}^{send}$: continuous, amount of coffee sent by warehouse w to q in timeslot 2 in scenario s .
- $y1_{w,q}^{receive}$: continuous, amount of coffee received by warehouse w from q in timeslot 1.
- $y2_{w,q,s}^{receive}$: continuous, amount of coffee received by warehouse w from q in timeslot 2 in scenario s .

Why do they define different variables for stage 1 and stage 2?

first decisions there are no scenarios, we know the here and now process, we just need for the future

we need to make sure we are just choosing one scenario on the first stage, not several scenarios

if we have 2 stage policy we can go with the first problem and if we have different variables, when it is a multi stage program, how much coffee to order, quickly become not easy to handle, but it is more practically to define it as second ways

Coffee Problem 2-stage SP Objective Function

$$\begin{aligned}
 \min \quad & \sum_{w \in W} x1_w \cdot p1_w + \sum_{w \in W} \sum_{s \in S} x2_{w,s} \cdot p2_{w,s} \cdot prob_s \\
 & + \sum_{w \in W} \sum_{q \in W} ys1_{w,q} \cdot e_{w,q} + \sum_{w \in W} \sum_{q \in W} \sum_{s \in S} ys2_{w,q,s} \cdot e_{w,q} \cdot prob_s \\
 & + \sum_{w \in W} m1_w \cdot b_w + \sum_{w \in W} \sum_{s \in S} m2_{w,s} \cdot b_w \cdot prob_s \quad (8)
 \end{aligned}$$

Coffee Problem 2-stage SP Constraints

Constraints

- To always respect the truck (transport) capacity between the warehouses

$$y1_{w,q}^{send} \leq C_{w,q}^{transp} \quad \forall w, q \in W \quad (9)$$

$$y2_{w,q,s}^{send} \leq C_{w,q}^{transp} \quad \forall w, q \in W, s \in S \quad (10)$$

- To have the same quantity being received and sent between two warehouses in a specific period

$$y1_{w,q}^{send} = y1_{q,w}^{receive} \quad \forall w, q \in W \quad (11)$$

$$y2_{w,q,s}^{send} = y2_{q,w,s}^{receive} \quad \forall w, q \in W, s \in S \quad (12)$$

- To always respect the storage capacity in all warehouses

$$z1_w \leq C_w^{storage} \quad \forall w \in W \quad (13)$$

$$z2_{w,s} \leq C_w^{storage} \quad \forall w \in W, s \in S \quad (14)$$

- To ensure demand fulfillment in all warehouses in $t \in T$

$$x1_w + m1_w + z0_w + \sum_{q \in W} y1_{w,q}^{receive} = D_{w,1} + z1_w + \sum_{q \in W} y1_{w,q}^{send} \quad \forall w \in W \quad (15)$$

$$x2_{w,s} + m2_{w,s} + z1_w + \sum_{q \in W} y2_{w,q,s}^{receive} = D_{w,2} + z2_{w,s} + \sum_{q \in W} y2_{w,q,s}^{send} \quad \forall w \in W, s \in S \quad (16)$$

- The amount sent between warehouses can only be determined by the amount stored in the previous time slot

$$\sum_{q \in W} y1_{w,q}^{send} \leq z0_w \quad \forall w \in W \quad (17)$$

$$\sum_{q \in W} y2_{w,q,s}^{send} \leq z1_w \quad \forall w \in W, s \in S \quad (18)$$

- Non-negativity for all variables

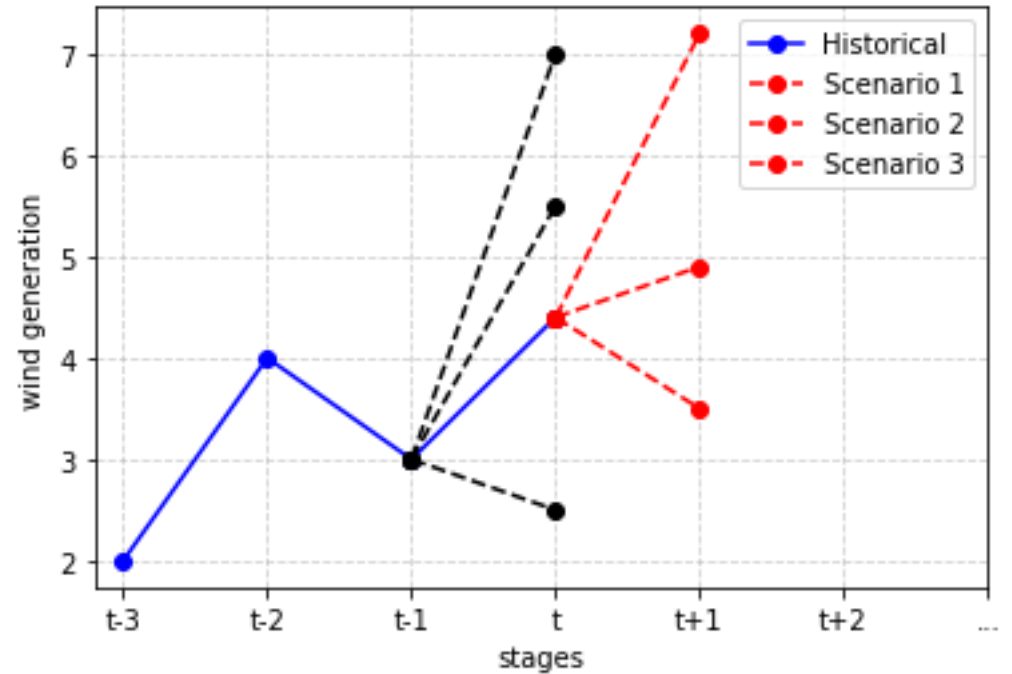
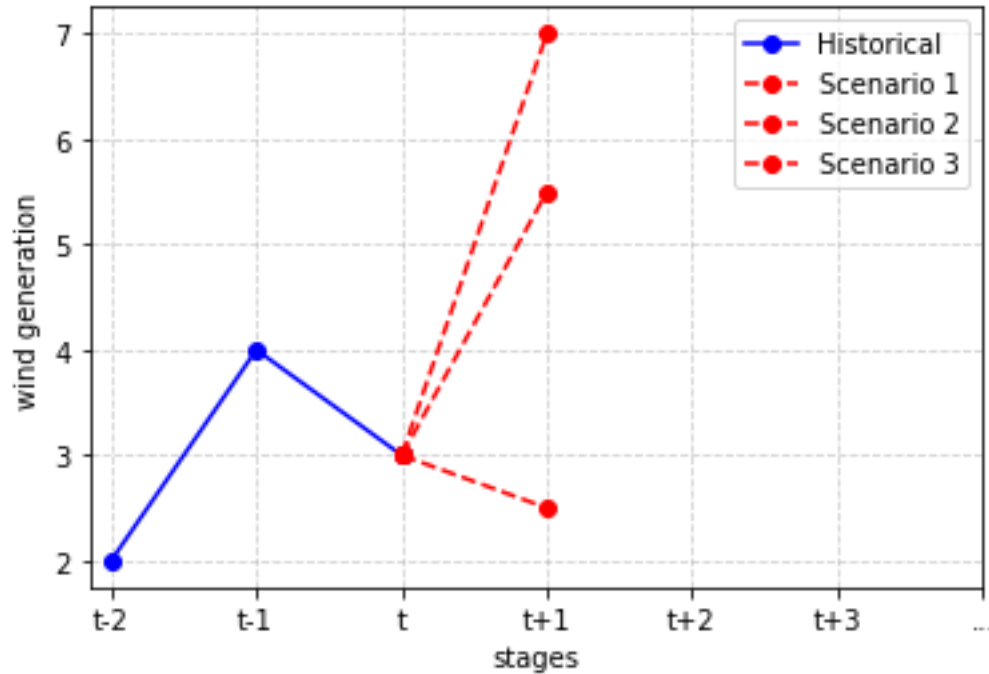
$$x1_w \geq 0, z1_w \geq 0, m1_w \geq 0 \quad \forall w \in W$$

$$y1_{w,q}^{send} \geq 0, y1_{w,q}^{receive} \geq 0 \quad \forall w, q \in W \quad (19)$$

$$x2_{w,s} \geq 0, z2_{w,s} \geq 0, m2_{w,s} \geq 0 \quad \forall w \in W, s \in S$$

$$y2_{w,q,s}^{send} \geq 0, y2_{w,q,s}^{receive} \geq 0 \quad \forall w, q \in W, s \in S \quad (20)$$

One Last Thing



this is the uncertainty, we create scenarios for the next stage, one ahead. and we input, we do a decision to the output, we return to the environment, it evaluates our decisions and gives a cost, the next realization, the new can be something that is none of our scenarios. this is way, 2 stages, 1st two decisions are here and now, and then the others are prospective take new state, generate new scenario,....

Questions and Survey

input- takes state gives decision