

Data Processing Chain for Heterodyne Spectrometer

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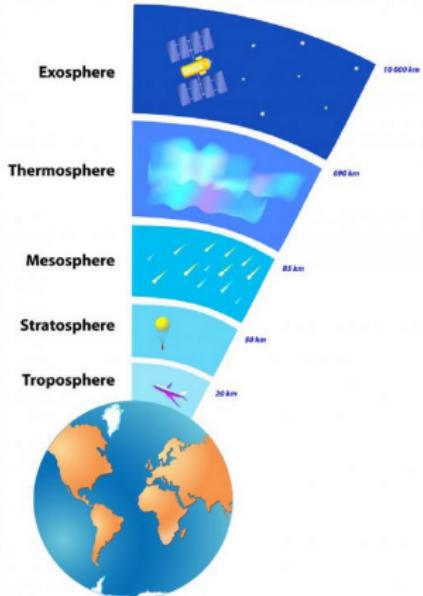
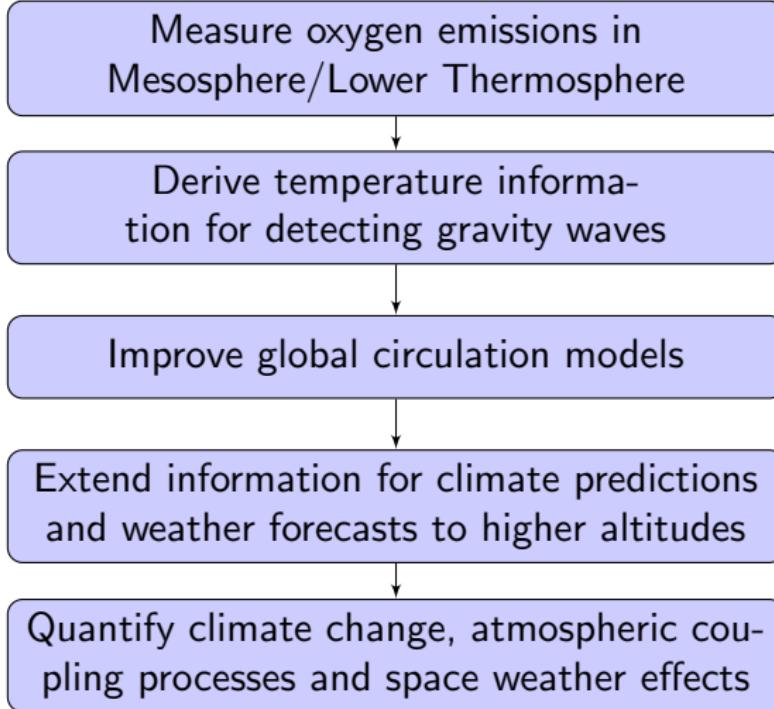
The Spatial Heterodyne Spectrometer

- Instrument developed at Institute of Energy and Climate Research: Stratosphere (IEK-7)
- Used for studying earth atmosphere by nano-satellite
- Prototype deployed on Chinese communication satellite



3D-printed model without solar panels of AtmoCube-1 [Deiml, 2018]

Research Goals



Source: wisegeek.com

Overview

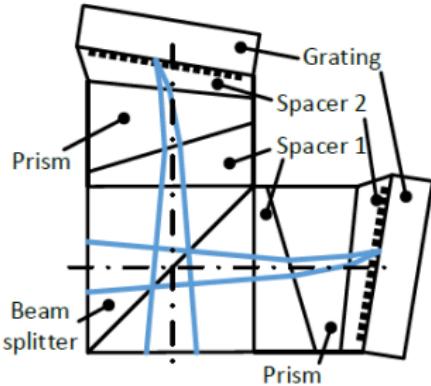
Used Data

- Synthetic
- Real measurements
 - Laser light on earth
 - In the orbit

Considered Image Effects

- Saturation (exceeded sensor sensitivity)
- Tilted vertical lines
- Lower intensities towards edges (vignetting)

Schematic of Spatial Heterodyne Spectrometer



(a) Schematic of the SHS.



(b) Assembled SHS for the precursor mission.

Source: [Deiml, 2018]

Output: Interferogram which then can be transformed to spectrum by FFT

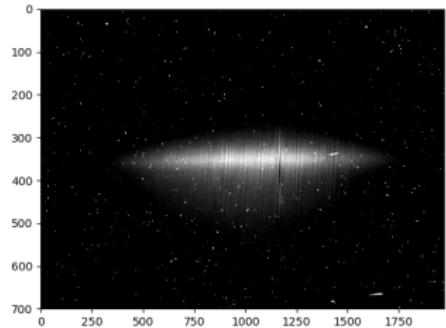
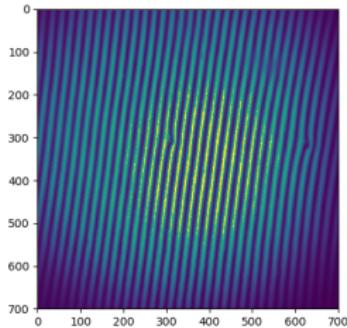
Relation Between Detected Intensities and Incoming Radiation

Relation between $I_g(x)$ and $(\sigma, L(\sigma))$

$$I_g(x) = \int_0^{\infty} 0.5 \cdot L(\sigma) \cdot (1 + \cos(8\pi \tan(\theta_L) \times (\sigma - \sigma_L))) d\sigma$$

- $I_g(x)$ is the intensity of the interference in x
- σ is the wavenumber and $L(\sigma)$ the intensity
- Littrow angle θ_L and Littrow wavenumber σ_L

Laser- and Orbit Data



Emergent Questions

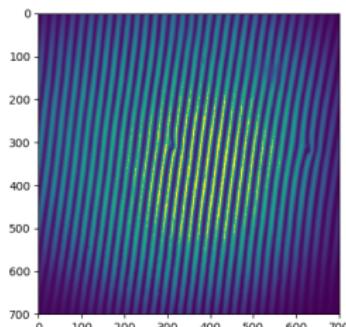
- Why do we have laser data?
- What should we see?

Errors in Laser Data

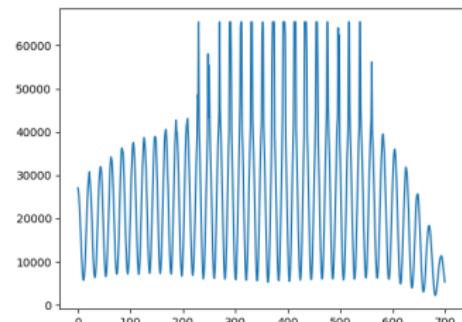
Visible Errors

Decrease of intensity towards edges
(vignette)

exceeded sensitivity



Laser Data



One Row of Laser Data

Generating Synthetic Data

- Simulating the detection image of a laser pointer
- Including errors due to **tilting** and **flattening towards the edges**

$$I_g(x, \sigma) = 0.5L(\sigma) (1 + \cos(8\pi \tan\theta_L \times (\sigma - \sigma_L)))$$

Generating Synthetic Data

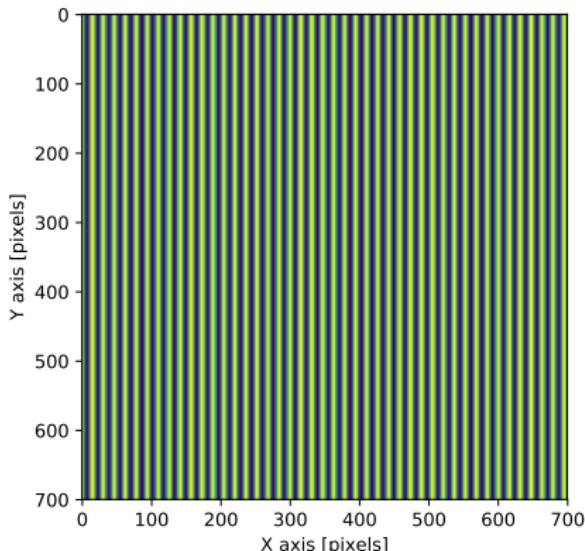
- Simulating the detection image of a laser pointer
- Including errors due to **tilting** and **flattening towards the edges**

$$I_g(x, \textcolor{red}{y}, \sigma) = \textcolor{blue}{f}(x, y) \cdot 0.5L(\sigma) (1 + \cos(8\pi \tan\theta_L \times (\sigma - \sigma_L) \textcolor{red}{+ 2\sigma\varphi y}))$$

Generating Synthetic Data

- Simulating the detection image of a laser pointer
- Including errors due to **tilting** and **flattening towards the edges**

$$I_g(x, y, \sigma) = f(x, y) \cdot 0.5L(\sigma) (1 + \cos(8\pi \tan\theta_L \times (\sigma - \sigma_L) + 2\sigma\varphi y))$$

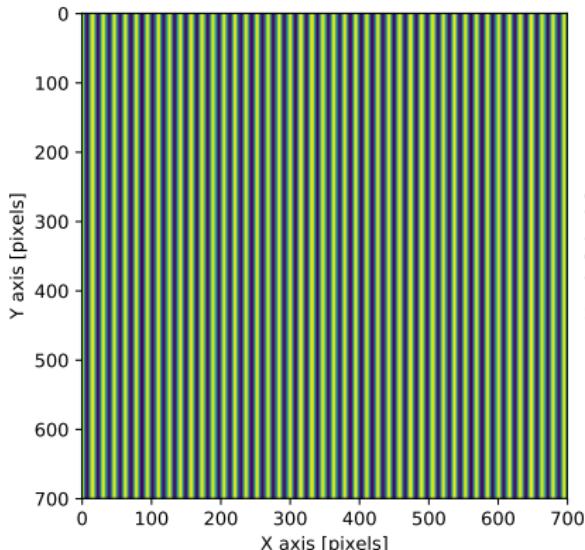


Without effects

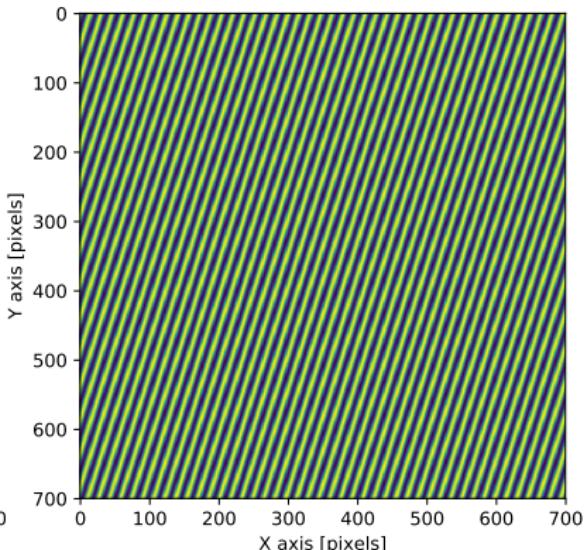
Generating Synthetic Data

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Without effects

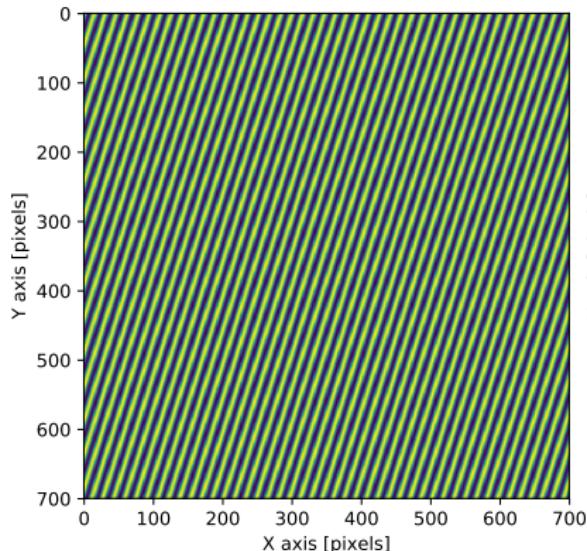


Tilted

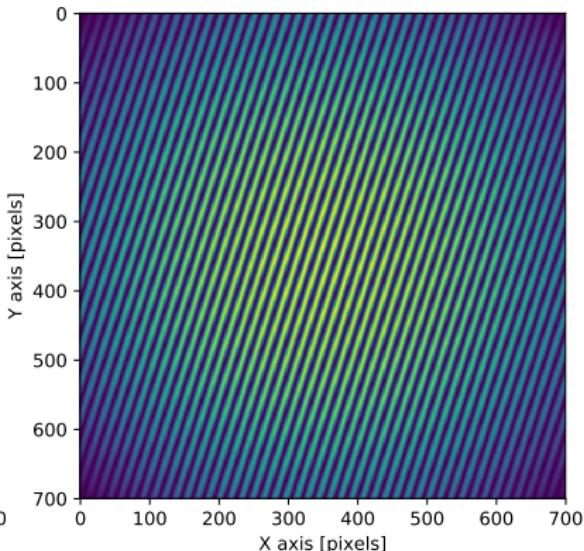
Generating Synthetic Data

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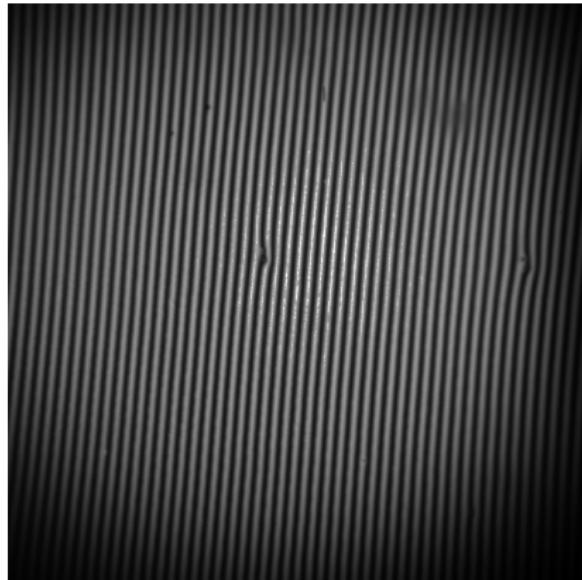


Tilted



Tilted and flattened

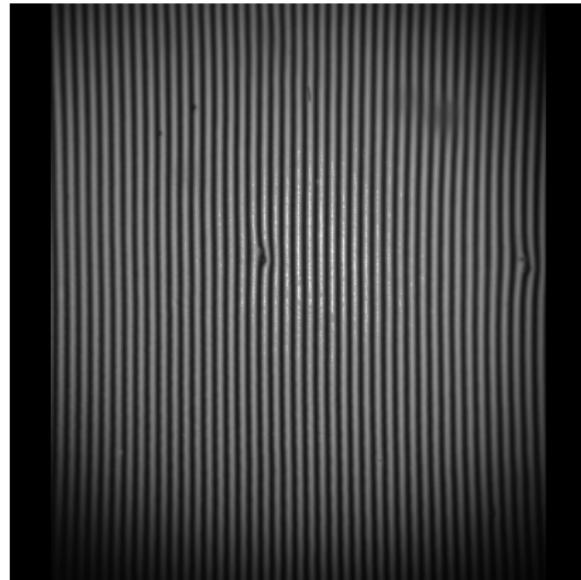
Correction of Tilted Images



- Spectrum is tilted
- Problem: how much is it tilted?
- Idea: find line with maximum intensity
- Angle of this line represents the tilt
- Tilt back by this value

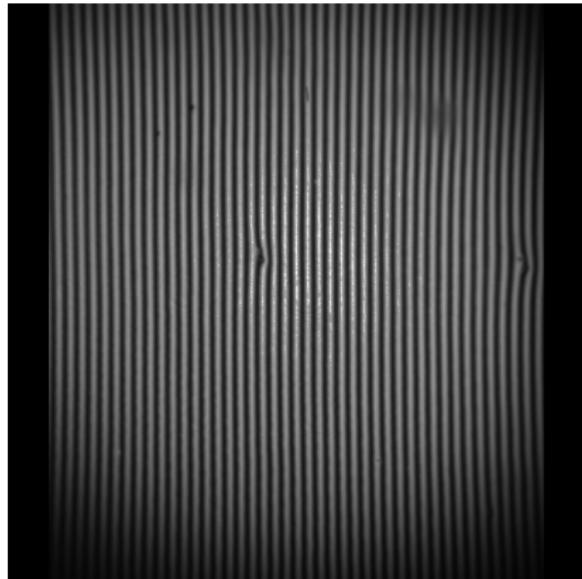
Data from the laser

Pincushion Effect



Pattern after reverse tilt

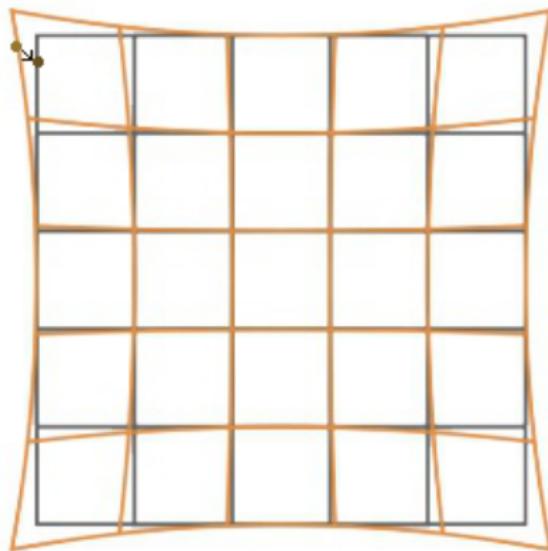
Pincushion Effect



Pattern after reverse tilt

- Remaining problem:
Pincushion distortion
- Image magnification
increases with distance
from optical axis
- Physical reasons:
quadratic distortion
- Get level of distortion
analogously to tilt:
search for parabola

Pincushion Effect

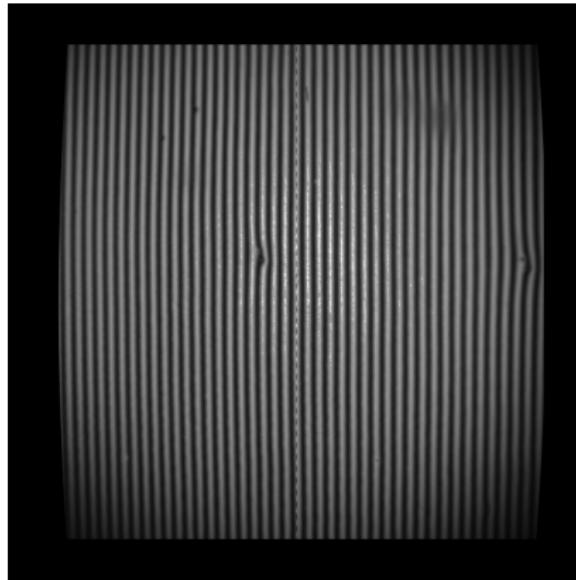


- Calculate the origin of every pixel with the quadratic functions
- Move the pixels to the correct places

Orange: the picture as measured,
gray: picture without pincushion

picture from <http://www.fotokurs-bremen.de>

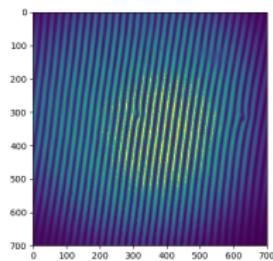
Pincushion Effect



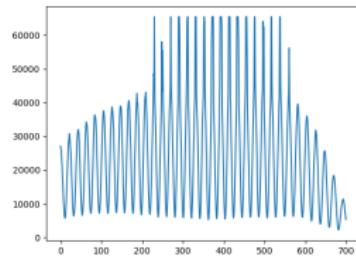
- We get a vertical, straight pattern to work with.

Result after both filters

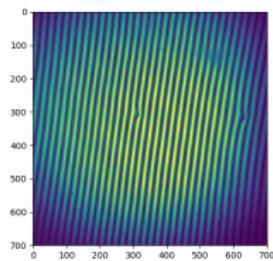
Saturation



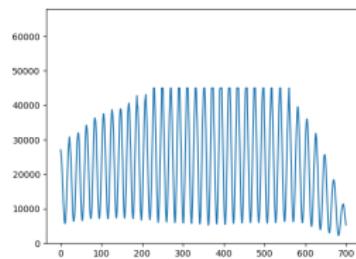
Raw Image



Intensities with
Saturation



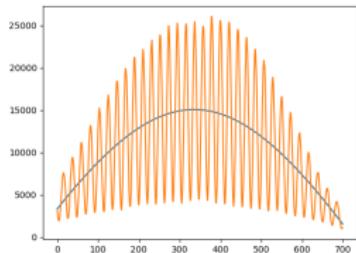
Mitigated Saturation



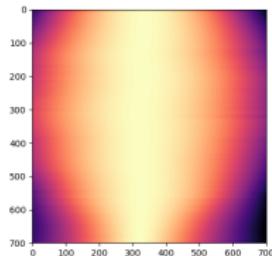
Peaks cut off

Sensitivity Function

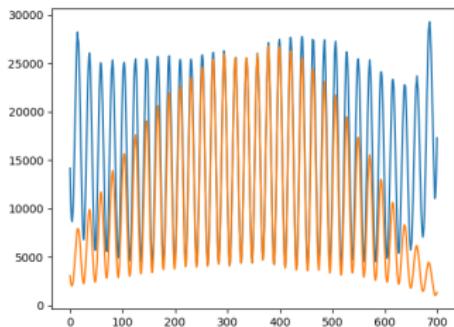
- Counter the vignetting by modeling the flattening as a curve
- Parabolic function: $f(x) = ax^2 + bx + c$
- Hyperbolic function: $g(x) = a\sqrt{1 + \frac{(x + b)^2}{c^2}} + d$
- Sensitivityfunction: $s_p(x) \sim \frac{1}{f(x)}$ and $s_h(x) \sim \frac{1}{g(x)}$



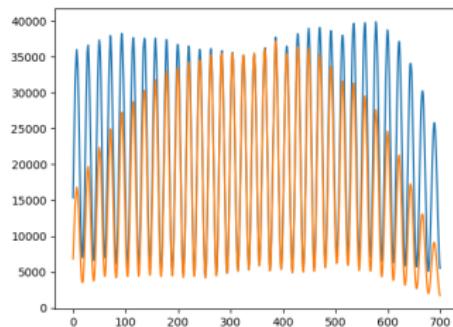
Curvefitting of one row



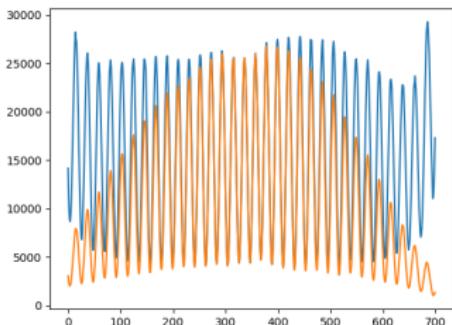
Sensitivity functions
per row of one
interferogram



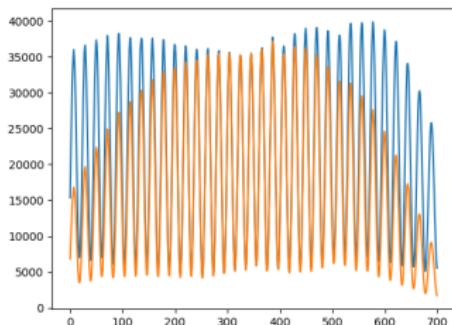
Parabolic Sensitivityfunction



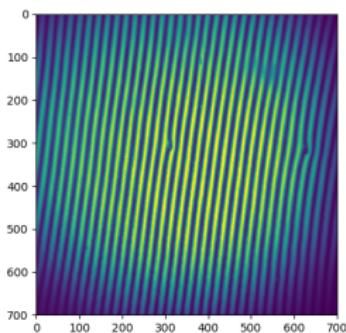
Hyperbolic sensitivity function



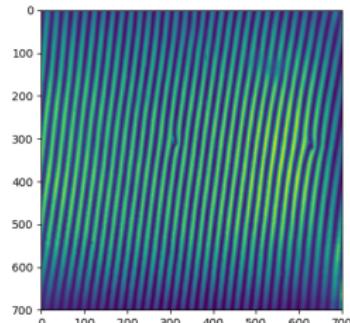
Parabolic Sensitivityfunction



Hyperbolic sensitivity function

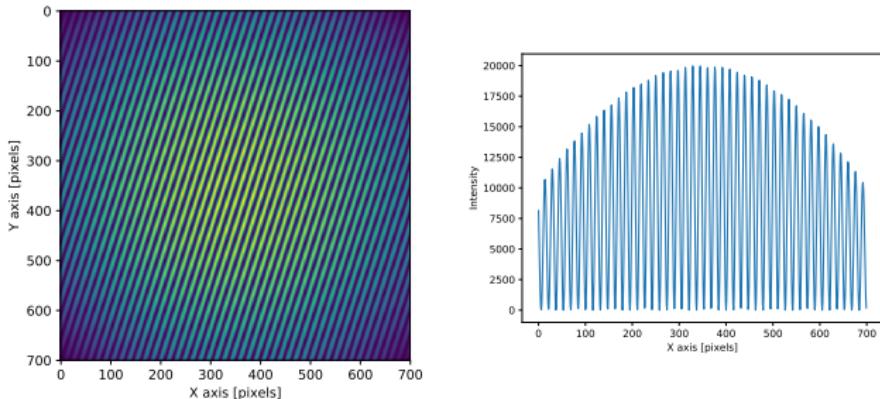


Mitigated saturation

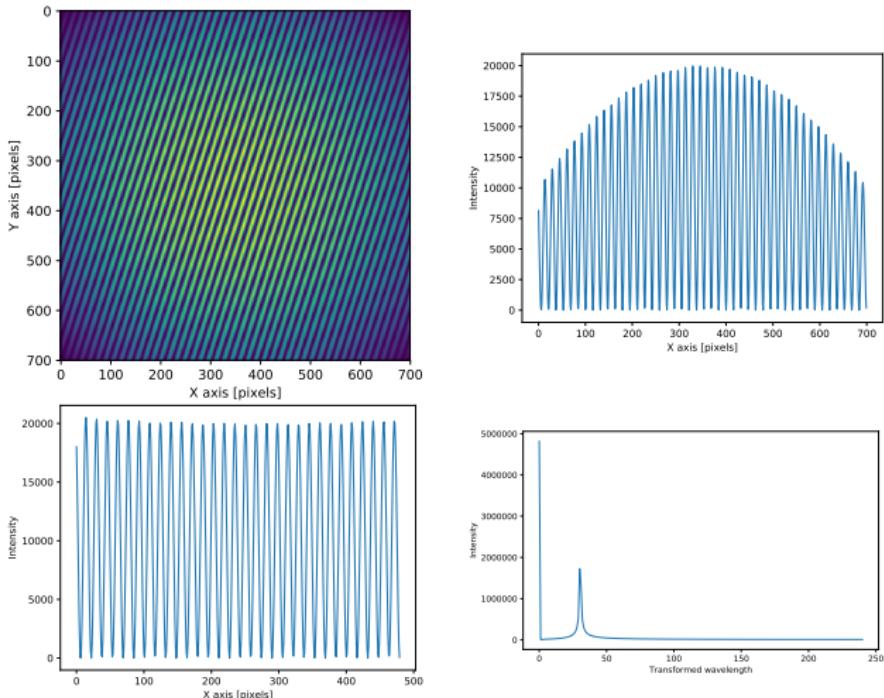


Improved vignetting and
saturation

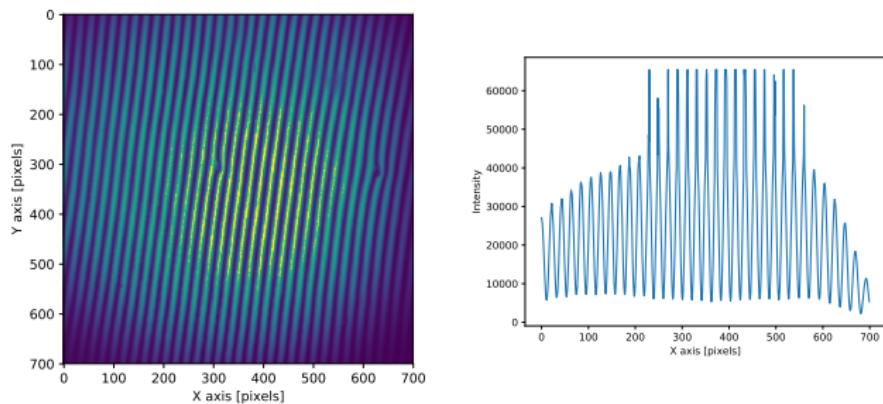
Summary on Synthetic Images



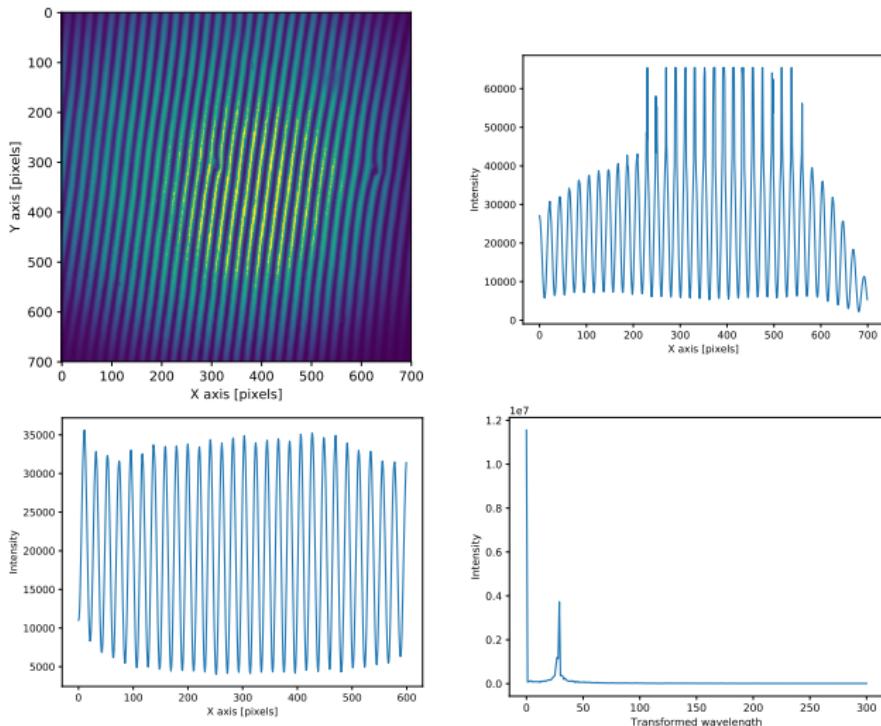
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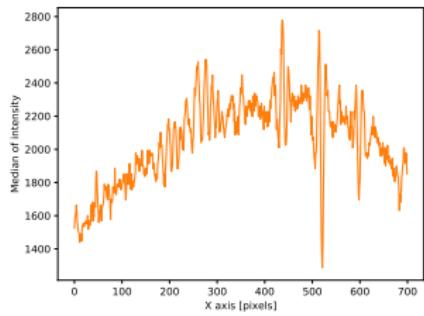
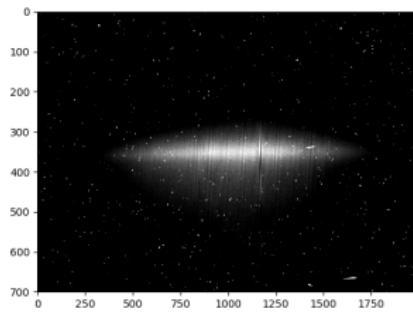
Summary on Real Laser Measurements



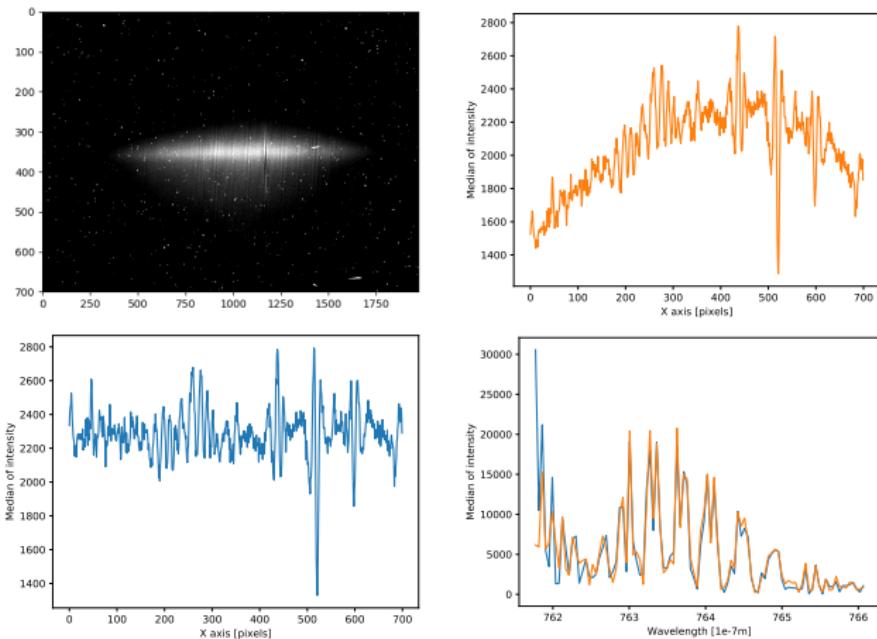
Summary on Real Laser Measurements



Summary on Orbit Data



Summary on Orbit Data



Thank you for your attention!



Deiml, M. (2018).

Development of a Small Satellite Remote Sensing Payload for Passive Limb Sounding of the Atmospheric Oxygen Emission.

PhD thesis, Bergische Universität Wuppertal.

<http://elpub.bib.uni-wuppertal.de/servlets/DocumentServlet?id=7530>.