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# Leverage-Based Sketches for Khatri-Rao Products

Redwood Center for Theoretical Neuroscience

November 1, 2024

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# The Berkeley BeBOP and PASSION Groups



I work with two groups at UC Berkeley:

- The **B**erkeley **B**enchmarking and **O**ptimization (BeBOP) group led by James Demmel and Katherine Yelick.
- The **P**arallel **A**lgorithms for **S**calable **S**parsE computations (PASSION) group led by Aydin Buluç, joint with Lawrence Berkeley National Lab.

Our interests include **linear algebraic computations** and **sparse kernels** that can be parallelized and deployed at **supercomputer scale**.



Figure: Frontier, the first exascale supercomputer in the United States. Credit: OLCF, Wikimedia Commons CC2.0.



# Link to Today's Paper

Fast Exact Leverage Score Sampling From Khatri-Rao Products with Applications to Tensor Decomposition [Bha+23]. Link to paper below, more at <https://vivek-bharadwaj.com>.





# Introduction

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# The Khatri-Rao Product

- In this talk, the Khatri-Rao product (KRP, denoted  $\odot$ ) is the column-wise Kronecker product of two matrices:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \odot \begin{bmatrix} w & x \\ y & z \end{bmatrix} = \begin{bmatrix} aw & bx \\ cw & dx \\ ay & bz \\ cy & dz \end{bmatrix}$$

- Output column count is *identical* to inputs. Output row count is the *product* of row counts of inputs.
- Appears in signal processing, compressed sensing, PDE inverse problems. Possible use in hyperdimensional computing where  $\otimes$ , the Kronecker product, used for binding.

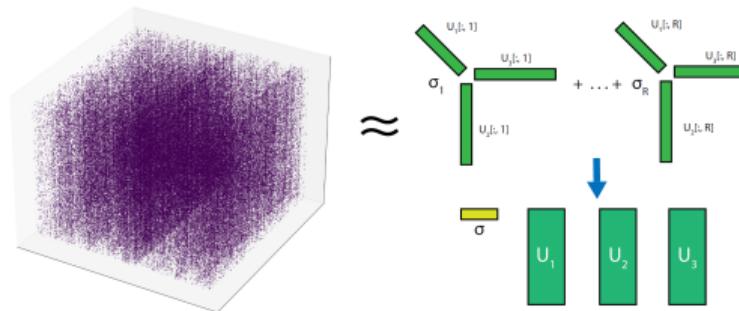


# Motivating Application

- **Our goal:** efficiently solve an overdetermined linear least-squares problem

$$\min_X \|AX - B\|_F$$

where  $A = U_1 \odot \dots \odot U_N$  with  $U_j \in \mathbb{R}^{I \times R}$ .



- Key kernel in alternating least-squares Candecomp / PARAFAC (CP) decomposition [LK22].



# One Step of ALS Illustrated

$$\min_{U_j} \left\| \left[ \bigodot_{k \neq j} U_k \right] \cdot U_j^\top - \text{mat}(\mathcal{T}, j)^\top \right\|_F$$

$$\min_{U_2} \left\| \begin{array}{c} U_3 \\ \odot \\ U_1 \end{array} \cdot \begin{array}{c} U_2^\top \\ - \\ \begin{array}{ccc} \cdot & & \cdot \\ \cdot & & \cdot \end{array} \\ \cdot \\ \text{mat}(\mathcal{T}, 2) \\ \cdot \\ \cdot \end{array} \right\|_F \rightarrow \begin{array}{c} U_2 \\ := \\ \begin{array}{c} \cdot \\ \cdot \end{array} \\ \text{mat}(\mathcal{T}, 2) \\ \cdot \\ \begin{array}{c} \cdot \\ \cdot \end{array} \\ \cdot \end{array} \cdot \begin{array}{c} U_3 \\ \odot \\ U_1 \end{array} \cdot G^+ \underbrace{\phantom{\begin{array}{c} U_3 \\ \odot \\ U_1 \end{array}}}_{\text{MTTKRP}}$$



# Randomized Linear Least-Squares

- **Sketch & Solve:** Apply short-wide sketching matrix  $S$  to both  $A$  and  $B$ , solve reduced problem

$$\min_{\tilde{X}} \left\| S A \tilde{X} - S B \right\|_F$$

- Want an  $(\varepsilon, \delta)$  guarantee on solution quality: with high probability  $(1 - \delta)$ ,

$$\left\| A \tilde{X} - B \right\|_F \leq (1 + \varepsilon) \min_X \| A X - B \|$$

- Could choose  $S$  as:
  - An i.i.d. Gaussian / Rademacher random matrix
  - A Countsketch / Sparse Sign embedding (fixed nnz per column)
  - A composition of random diagonal, FFT-like operator, and uniform sparse sampler



# Subspace Embedding Matrices

i.i.d. Gaussian

$$\begin{bmatrix} -0.01 & -0.39 & 0.37 \\ -0.47 & 0.74 & -0.10 \end{bmatrix}$$

Countsketch

$$\begin{bmatrix} +1 & 0 & +1 \\ 0 & -1 & 0 \end{bmatrix}$$

- Oblivious subspace embeddings: require no prior information about  $A$ ; easy to construct and apply when inputs have no structure, but harder for Khatri-Rao products.
- In this talk: we will just **randomly sample**  $J$  rows of  $A$  and  $B$  to form a pair of much shorter matrices. Preserves structure in both input and output.



# Our Contributions [Bha+23]

METHOD	SOURCE	ROUND COMPLEXITY ( $\tilde{O}$ NOTATION)
CP-ALS	[KB09]	$N(N + I)I^{N-1}R$
CP-ARLS-LEV	[LK22]	$N(R + I)R^N / (\varepsilon\delta)$
TNS-CP	[MAL22]	$N^3IR^3 / (\varepsilon\delta)$
GTNE	[MS22]	$N^2(N^{1.5}R^{3.5}/\varepsilon^3 + IR^2)/\varepsilon^2$
<b>STS-CP</b>	OURS	$N(NR^3 \log I + IR^2) / (\varepsilon\delta)$

- We build a data structure with runtime **logarithmic** in the height of the KRP and quadratic in  $R$  to sample from *leverage scores* of  $A$ .
- Yields the **STS-CP** algorithm: lower asymptotic runtime for randomized dense CP decomposition than recent SOTA methods (even more advantage for sparse tensors).



# Statistical Leverage Scores

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# Intuition: Do I Need Every Row?

- Consider a univariate regression problem with 100,000  $(x, y)$  points.
- This is a **highly-overdetermined** problem. Can pick a subset of points to perform fitting.

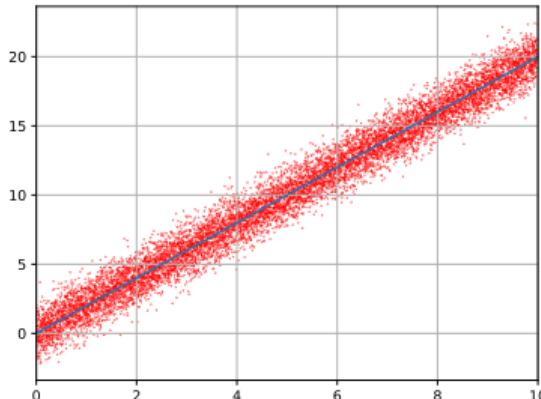


Figure:  $y_i \sim x_i + \mathcal{N}(0, 1)$



# Leverage Score Sampling

We will sample rows i.i.d. from  $A$  according to the *leverage score distribution* on its rows. Given **reduced SVD**  $A = U\Sigma V^\top$ , the leverage score  $\ell_i$  of row  $i$  is

$$\ell_i = \|U[i, :]\|^2.$$

**Theorem (Leverage Score Sampling Guarantees, [Mal22])**

Suppose  $S \in \mathbb{R}^{J \times I}$  is a leverage-score sampling matrix for  $A \in \mathbb{R}^{I \times R}$ , and define

$$\tilde{X} := \arg \min_{\tilde{X}} \|SAX - SB\|_F$$

If  $J \gtrsim R \max(\log(R/\delta), 1/(\varepsilon\delta))$ , then with probability at least  $1 - \delta$ ,

$$\|A\tilde{X} - B\|_F \leq (1 + \varepsilon) \min_X \|AX - B\|_F.$$



# Interpretation of Leverage Scores

When  $A$  has 1 column, leverage scores are proportional to squared distance from origin.

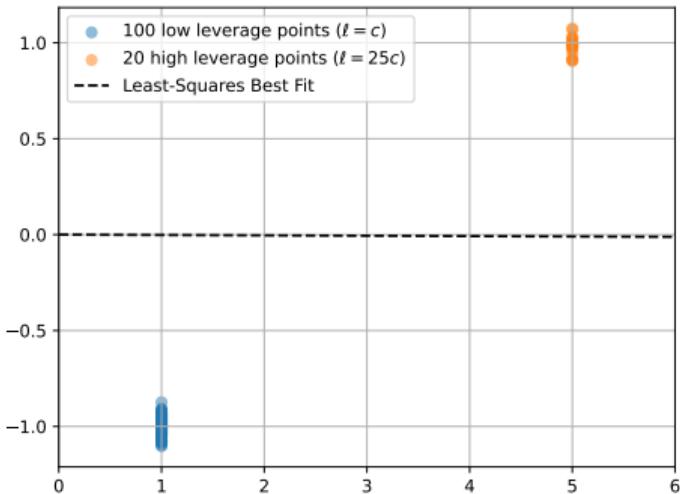
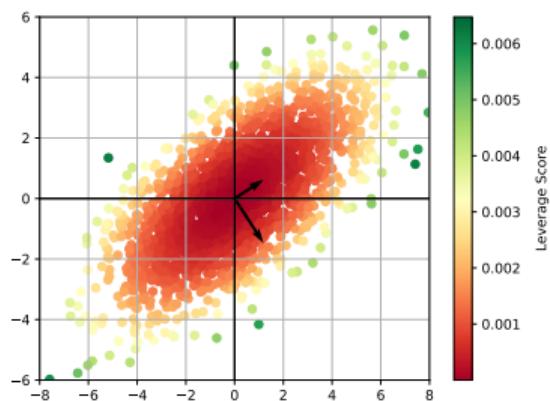


Figure: A univariate regression problem with low and high leverage points (intercept constrained to be 0).

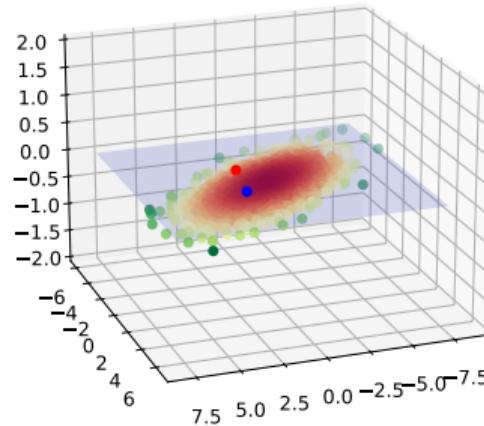


# Interpretation of Leverage Scores

In general, leverage scores of  $A$  quantify *influence* that each row has on the solution, capture correlation of rows of  $A$  with rows of  $\Sigma^{-1}V^\top$ .



(a) Projection onto  $xy$ -plane



(b)  $(x, y, z)$  data

**Figure:** Leverage scores of  $(x, y, 0)$  triples from a multivariate normal distribution. Left: components of  $\Sigma^{-1}V^\top$  shown. Right: the red point has greater influence than the blue point (both equidistant from  $(0, 0, 0)$ ).



# Interpretation of Leverage Scores

- Leverage score sampling captures the geometry of the column space of  $A$ .
- Rigorously: sampling i.i.d. with leverage score probabilities leads to an **optimal** [DM20] sample complexity to construct an  $\ell_2$ -subspace embedding matrix  $S$ .
- **SE Property:** W.h.p simultaneously for ALL vectors  $x \in \mathbb{R}^R$ ,

$$(1 - \tilde{\varepsilon}) \|Ax\|_2 \leq \|SAx\|_2 \leq (1 + \tilde{\varepsilon}) \|Ax\|_2$$

- In turn, an  $\ell_2$ -S.E. guarantees that our sketched solution has close-to-optimal residual with respect to the original problem.



# Prior Work

**Problem:** Cost to compute all leverage scores exactly is identical to runtime of QR decomposition. Defeats the purpose of sampling!

- (SPALS [Che+16]): Sample rows according to *approximate* leverage scores of  $A$ . Worst-case **exponential** in  $N$  to achieve  $(\varepsilon, \delta)$  guarantee.
- (CP-ARLS-LEV [LK22]): Similar approximation, hybrid random-deterministic sampling strategy and practical improvements.
- (TNS-CP [Mal22]): Samples implicitly from exact leverage distribution with **polynomial** complexity to achieve  $(\varepsilon, \delta)$  guarantee, but linear dependence on  $I$  for each sample. **We want to accelerate this algorithm.**



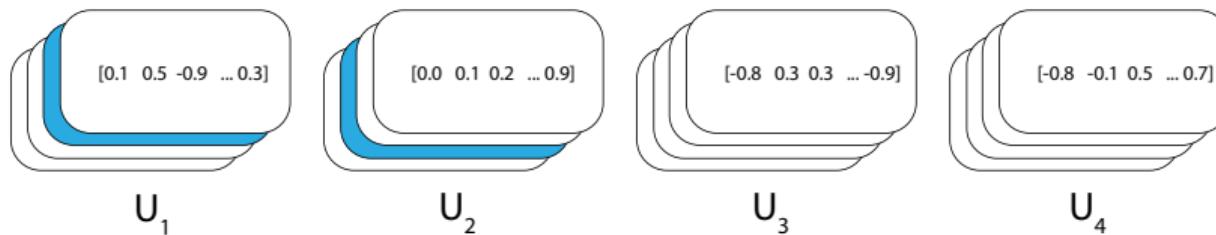
# Efficient Sampling from Khatri-Rao Products

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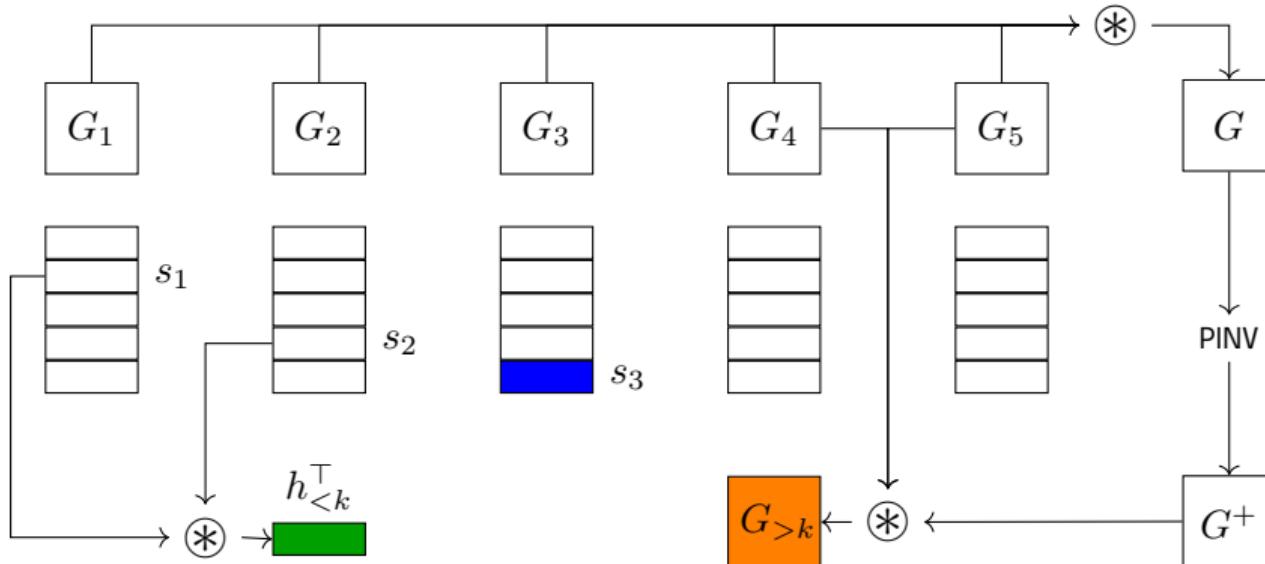
# Implicit Leverage Score Sampling

- For  $I = 10^7, N = 3$ , matrix  $A$  has  $10^{21}$  rows. Can't even index rows with 64-bit integers. Instead: use identity  $\ell_i = A[i, :] (A^\top A)^+ A[i, :]^\top$ .
- Draw a row from each of  $U_1, \dots, U_N$ , return their Hadamard product.



- Let  $\hat{s}_j$  be a random variable for the row index drawn from  $U_j$ . Assume  $(\hat{s}_1, \dots, \hat{s}_N)$  jointly follows the leverage score distribution on  $U_1 \odot \dots \odot U_N$ .

# The Conditional Distribution of $\hat{s}_k$



$$p(\hat{s}_k = s_k \mid \hat{s}_{<k} = s_{<k}) \propto \langle h_{<k} h_{<k}^\top, U_k [s_k, :]^\top U_k [s_k, :], G_{>k} \rangle$$



# A Problem of Variable Dependence

- Each subsequent index depends on the ones that precede it. How to deal with the dependence? Let's look at four approaches:
- Only a finite number of values for  $\hat{s}_1, \hat{s}_2$ . Precompute and store all possible conditional distributions for  $\hat{s}_3$ , and similarly for  $\hat{s}_4, \hat{s}_5\dots$
- Preprocessing time is  $\Omega(I^N)$ , not viable for large  $I$ .

Preprocessing Time	Time for $J$ Samples	# Samples Required
$\Omega(I^N)$	$O(JN)$	$O(R/(\varepsilon\delta))$



## Approach 2: Ignore the Dependence

- Sample **independently** from  $U_1, \dots, U_N$  based on the leverage scores of each factor matrix [Che+16; LK22].
- No longer sampling from the exact leverage score distribution, so require  $O(R^N / (\varepsilon\delta))$  samples to achieve the  $(\varepsilon, \delta)$  guarantee.
- Efficient if  $R, N$  low enough. Can easily update if one matrix  $U_j$  changes.

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Preprocessing Time	Time for $J$ Samples	# Samples Required
$O(NIR^2)$	$O(JN)$	$O(R^N / (\varepsilon\delta))$

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# Approach 3: Form Full Conditional Distribution



- Compute the full conditional distribution  $p(\hat{s}_3 = s_3 \mid \hat{s}_1 = s_1, \hat{s}_2 = s_2)$  for each draw *during* sampling [Mal22].
- Costs  $O(IR^2)$  per matrix  $U_j$  **per sample**.
- Works well if  $I$  is low enough (many dense tensor applications), but performance degrades for  $I \geq 10^3$ .

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Preprocessing Time	Time for $J$ Samples	# Samples Required
$O(NIR^2)$	$O(JNR^2I)$	$O(R/(\varepsilon\delta))$

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## Approach 4: Segment Tree Sampling (Ours)

- Our approach will require only  $O(NR^2 \log I)$  time per sample, after one-time preprocessing costs of  $O(IR^2 + R^3)$  per matrix.
- For  $R \approx 10^2$ , we achieve a sampling time that is practical for sparse tensor decomposition with mode sizes in the tens of millions.

Preprocessing Time	Time for $J$ Samples	# Samples Required
$O(NIR^2)$	$O(NR^3 + JNR^2 \log I)$	$O(R/(\varepsilon\delta))$



# Key Sampling Primitive

$$q[i] := C^{-1} \langle \mathbf{h}_{<k} \mathbf{h}_{<k}^\top, \mathbf{U}_k[i, :]^\top \mathbf{U}_k[i, :], \mathbf{G}_{>k} \rangle$$

- Imagine we magically had all entries of  $q$  - how to sample? Initialize  $I$  bins,  $j$ -th has width  $q[j]$ .
- Choose random real  $r$  in  $[0, 1]$ , find “containing bin”  $i$  such that

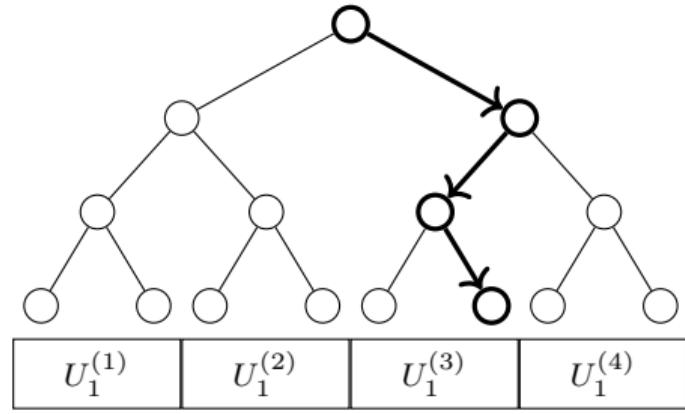
$$\sum_{j=0}^{i-1} q[j] < r < \sum_{j=0}^i q[j]$$



# Binary Tree Inversion Sampling

- Locate bin via binary search (truncated to  $\log(I/R)$  levels)
- Root: branch right iff  $\sum_{j=0}^{I/2} q[j] < r$
- Level 2: branch right iff

$$\sum_{j=0}^{I/2} q[j] + \sum_{j=I/2}^{3I/4} q[j] < r$$



**Key:** Can compute summations quickly if we cache information at each node!



# Caching Partial Gram Matrices

Let an internal node  $v$  correspond to an interval of rows  $[S(v) \dots E(v)]$ .

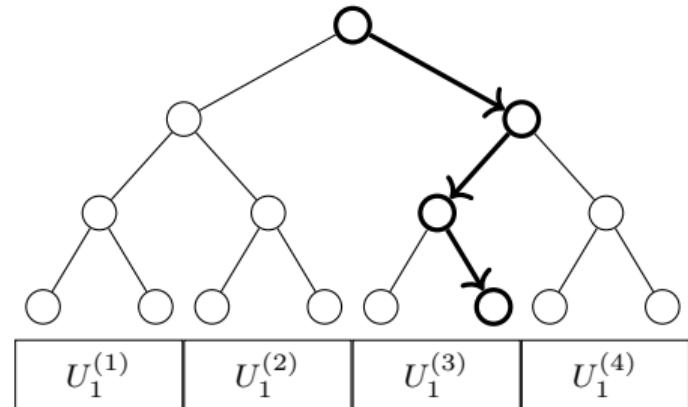
$$\begin{aligned} \sum_{j=S(v)}^{E(v)} q[j] &= \sum_{j=S(v)}^{E(v)} C^{-1} \langle \textcolor{green}{h}_{<k} h_{<k}^\top, \textcolor{blue}{U}_k [j, :]^\top U_k [j, :], \textcolor{orange}{G}_{>k} \rangle \\ &= C^{-1} \langle \textcolor{green}{h}_{<k} h_{<k}^\top, \sum_{j=S(v)}^{E(v)} \textcolor{blue}{U}_k [j, :]^\top U_k [j, :], \textcolor{orange}{G}_{>k} \rangle \tag{1} \\ &= C^{-1} \langle \textcolor{green}{h}_{<k} h_{<k}^\top, \textcolor{blue}{U}_k [S(v) : E(v), :]^\top U_k [S(v) : E(v), :], \textcolor{orange}{G}_{>k} \rangle \\ &:= C^{-1} \langle \textcolor{green}{h}_{<k} h_{<k}^\top, G^v, \textcolor{orange}{G}_{>k} \rangle \end{aligned}$$

Can compute and store  $G^v$  for ALL nodes  $v$  in time  $O(IR^2)$ , storage space  $O(IR)$ . Use BLAS-3 **syrk** calls in parallel to efficiently construct the tree.

# Efficient Sampling after Caching



- At internal nodes, compute  $C^{-1} \langle h_{<k} h_{<k}^T, G^v, G_{>k} \rangle$  in  $O(R^2)$  time (read normalization constant from root)
- At leaves, spend  $O(R^3)$  time to compute remaining values of  $q$ . Can reduce to  $O(R^2 \log R)$ , see paper.
- Complexity per sample:  $O(NR^2 \log I)$  (summed over all tensor modes).



# An Empirical Correctness Check

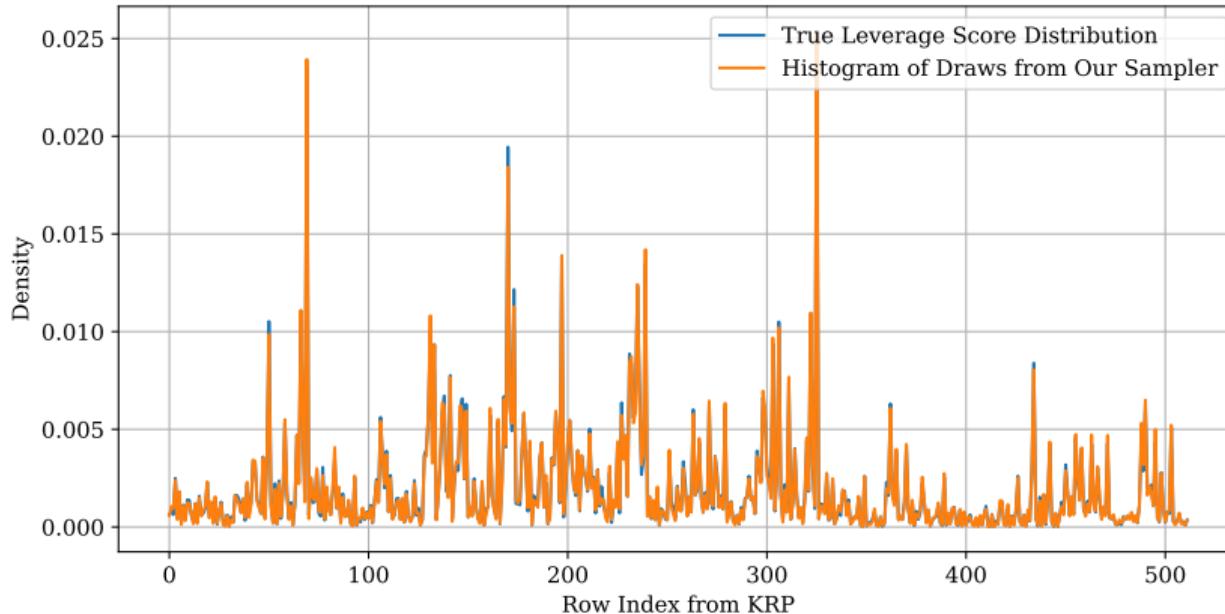


Figure: Distribution Comparison for  $U_1 \odot U_2 \odot U_3$ ,  $U_j \in \mathbb{R}^{8 \times 8}$  initialized i.i.d. Gaussian.



## Remarks and Related Work

- The most comparable results to ours appear in work by Woodruff and Zandieh [WZ22], who construct a leverage-score sampler with **input-sparsity runtime**.
- Their sampler can also be used for low-rank approximation, but has  $O(N^7)$  worst-case scaling in the KRP dimension.
- The best existing **oblivious algorithms** for Khatri-Rao products require either:
  - $\Omega(R^2)$  rows to construct a subspace embedding [Ahl+20].
  - More than input-sparsity runtime.
- **Open Question:** Is LSS **more powerful** than oblivious embedding for Khatri-Rao products, and can we prove a lower bound?



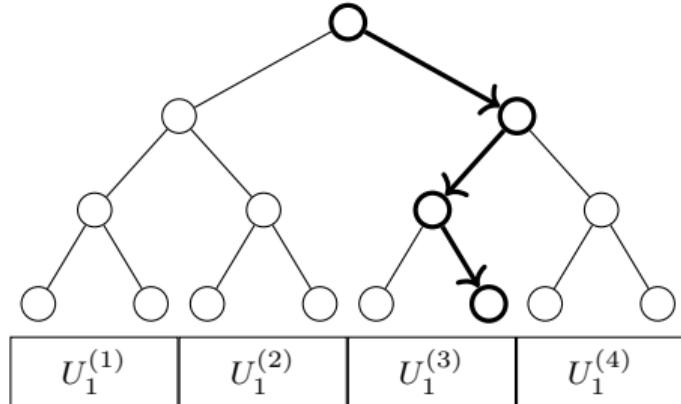
# Performance Measurements

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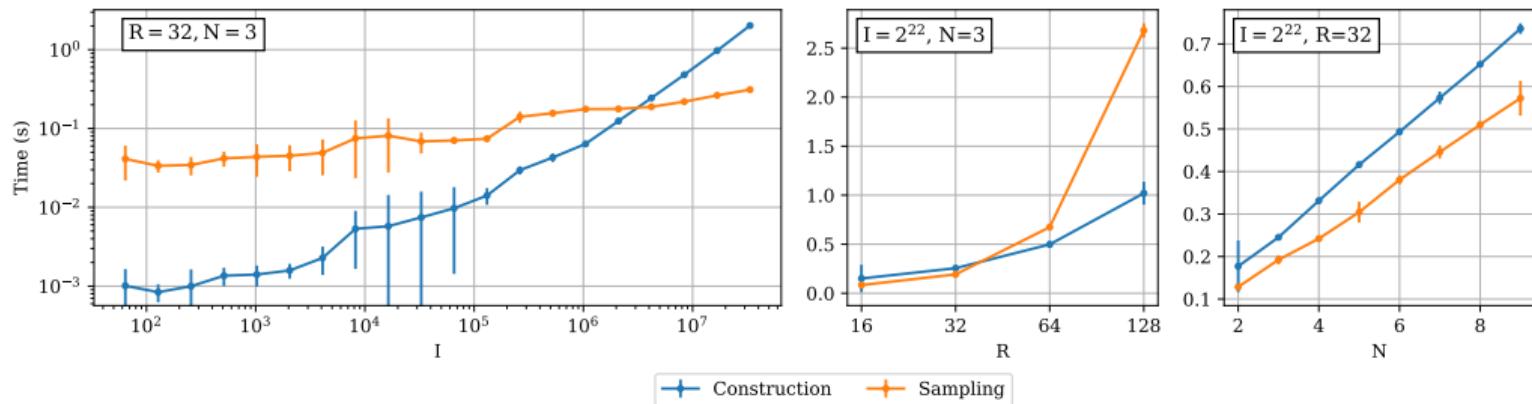
# High-Performance Parallel Sampling



- We want to execute  $J \sim 50,000$  independent random walks down a full, complete tree.
- At each node, execute a matrix-vector multiplication to decide which direction to branch.
- **Solution:** March down the tree one level at a time, computing the branches of ALL random walks using batched GEMV / GEMM.



# Runtime Benchmarks (LBNL Perlmutter CPU)



**Figure:** Time to construct sampler and draw  $J = 65,536$  samples. C++ Implementation Linked to OpenBLAS. 1 Node, 128 OpenMP Threads, BLAS3 Construction, BLAS2 Sampling.



# Distortion, Ours vs. Approximate Sampling

We define the distortion  $D(S, A)$  of sketch  $S$  with respect to matrix  $A$  by

$$D(S, A) = \kappa(SQ) - 1$$

where  $Q$  is any orthonormal basis for the column space of  $A$  [Mur+23]. Distortion quantifies the distance preservation property of a sketch.

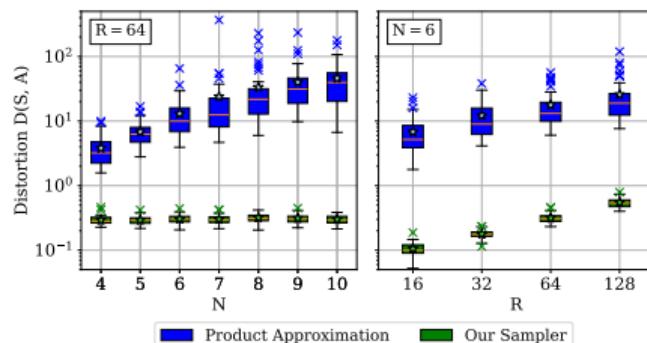


Figure: Sketch distortion as a function of KRP matrix count  $N$  and column count  $R$ ,  $J = 65,536$ . Green: our sampler. Blue: product approximation by [LK22].



# Sparse Tensors from FROSTT

Tensor	Dimensions	NNZ
Uber	$183 \times 24 \times 1.1K \times 1.7K$	$3.3M$
Enron	$6.0K \times 5.6K \times 240K \times 1.2K$	$54M$
NELL-2	$12K \times 9.1K \times 29K$	$77M$
Amazon	$4.8M \times 1.8M \times 1.8M$	$1.7B$
Reddit	$8.2M \times 177K \times 8.1M$	$4.7B$

$$\text{fit}(\tilde{\mathcal{T}}, \mathcal{T}) = 1 - \frac{\|\tilde{\mathcal{T}} - \mathcal{T}\|_F}{\|\mathcal{T}\|_F}$$

# Accuracy Comparison for Fixed Sample Count

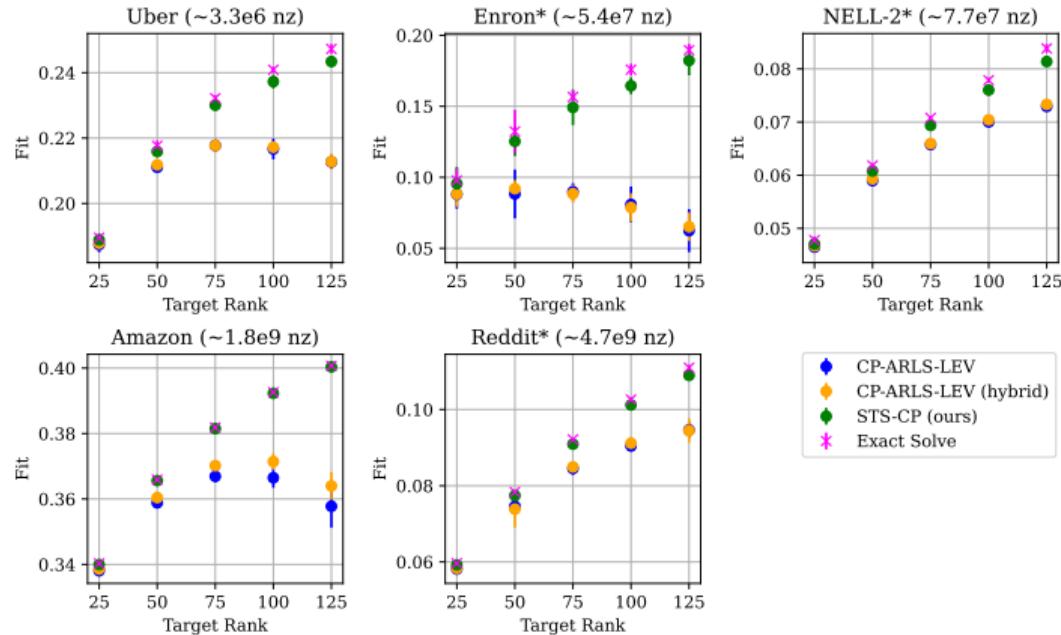


Figure: Sparse tensor ALS accuracy comparison for  $J = 2^{16}$  samples, varied target ranks.

# STS-CP Makes Faster Progress to Solution

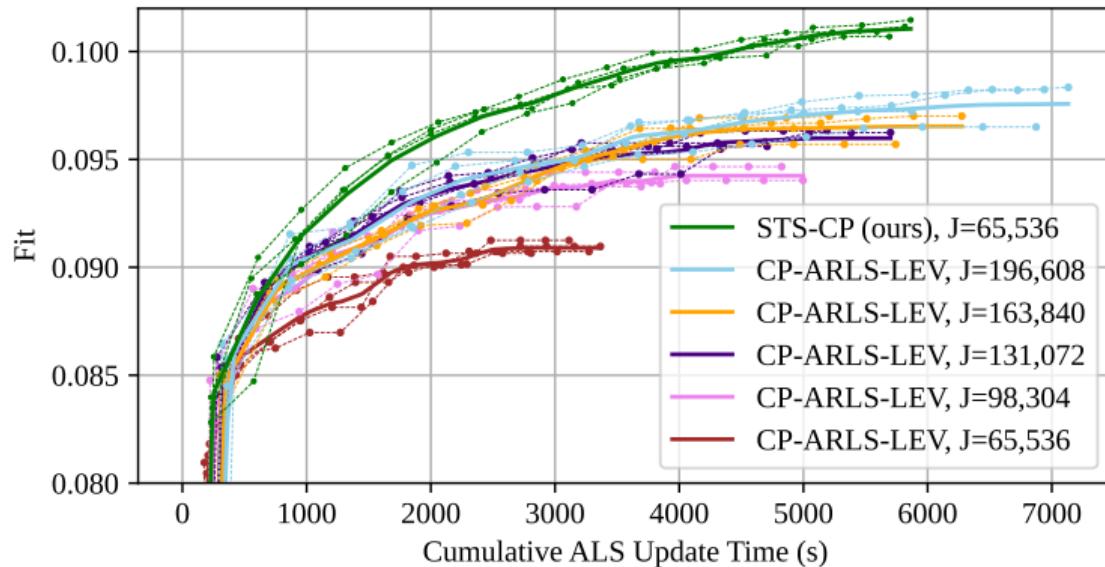


Figure: Fit vs. ALS update time, Reddit tensor,  $R = 100$ .

# Performance at Scale [Bha+24a]

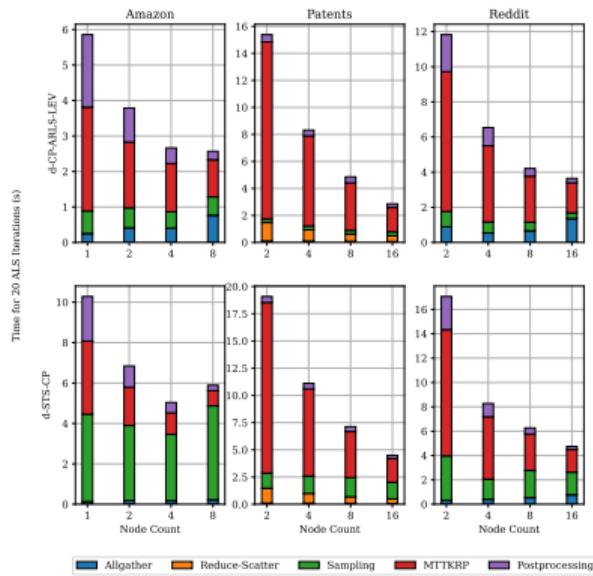
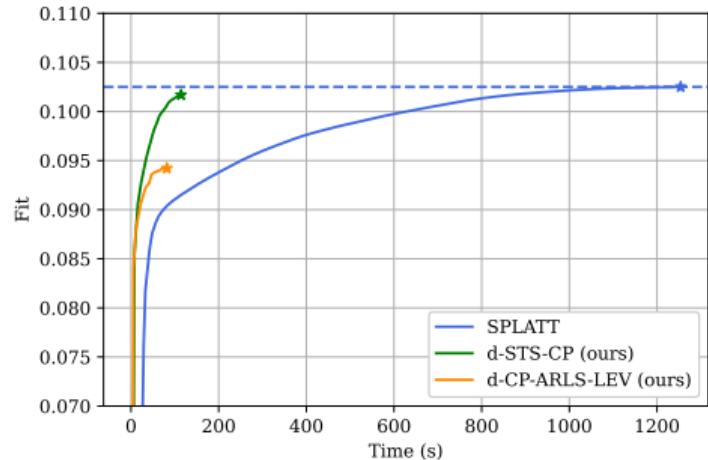


Figure: Fit vs. time, Reddit ( $R = 100$ ) and strong scaling ( $R = 25$ ) for our randomized algorithms.



## Conclusions and References

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# Summary

- We exploited structure in the Khatri-Rao Product to build a leverage score sampler with low polynomial complexity.
- Our implementation relies on well-optimized dense linear algebra primitives, exhibiting strong practical performance in addition to our theoretical guarantees.
- This year, we extended our results to **tensor-train** core chains (find our poster at NeurIPS 2024!) by making key adaptations to our conditional-sampling procedure [Bha+24b].
- Try our code online: [https://github.com/vbharadwaj-bk/fast\\_tensor\\_leverage](https://github.com/vbharadwaj-bk/fast_tensor_leverage).

# Questions?





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