

Supplementary Material — Learning to Estimate Two Dense Depths from LiDAR and Event Data^{*}

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1 Linear vs Log Scale

In this article, we use a linear scale for the event sensor in CARLA rather than the default logarithmic scale. We argue here that the logarithmic scale amplifies too much the creation of events in the dark areas of the image, as a very slight change in the intensity results in a large logarithmic intensity change, thus triggering an event. On the contrary, in the clearer areas, little to no events are produced, as a large intensity change is necessary to generate a logarithmic difference sufficient to trigger an event. An illustration of this phenomenon is given in Fig. 1 and Fig. 2.

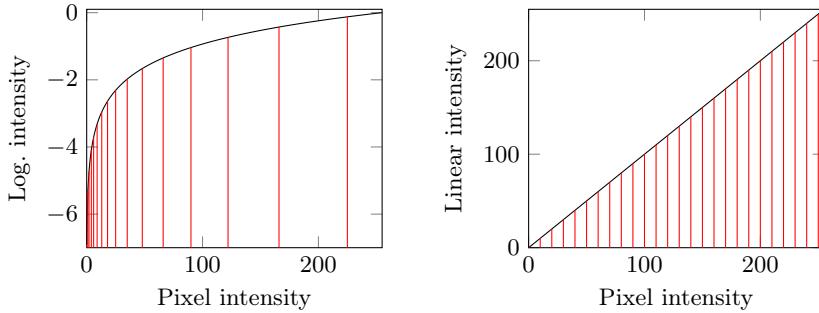


Fig. 1: Comparison of the triggering of events when the logarithmic and the linear scales are used. The logarithmic intensity in CARLA is computed as $\ln(I/255 + 0.001)$, where I is the pixel intensity. Each red vertical line denotes the triggering of an event, with thresholds set to 0.3 for the logarithmic scale, and 10 for the linear scale.

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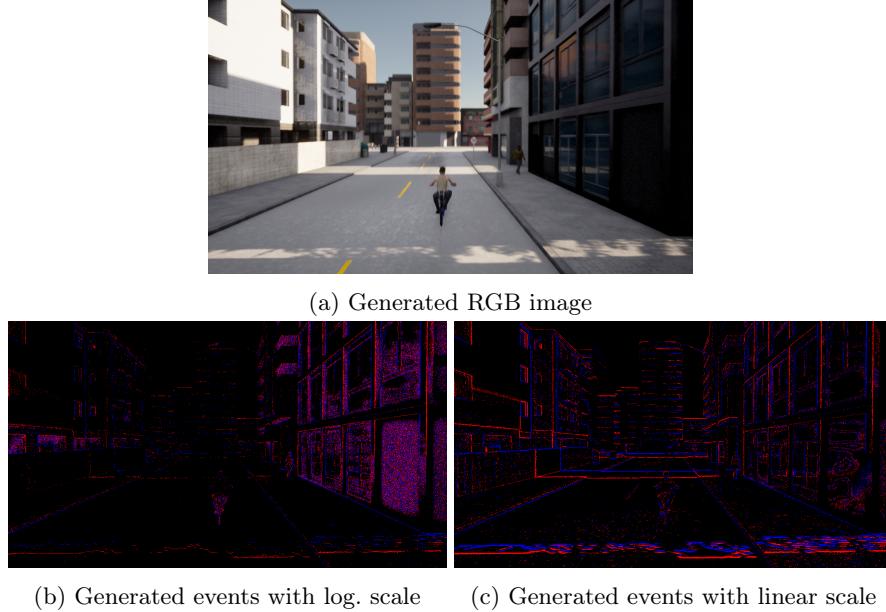


Fig. 2: Visual comparison of the triggering of events when the logarithmic and the linear scales are used for a urban scene in CARLA. With the logarithmic scale, notice how the dark building on the right generates a high amount of events compared to the other buildings, and how details such as road markings or shadows are mostly lost. In comparison, with the linear scale, notice how the events are better distributed in the image.

2 Example Data from our SLED Dataset

We showcase in Fig. 3 some example data from our SLED dataset. In particular, we display here illustrations from two very different recordings: one on *Town01* during daytime, and a second one on *Town07* during nighttime.

3 Detailed Results on our SLED Dataset

As a complement to the summarized results shown in Table 2 of the main article on our SLED dataset, we provide here the full results for every recording on both maps of the testing set, *Town01* and *Town03*. These results are given in Table 1 and 2 respectively.

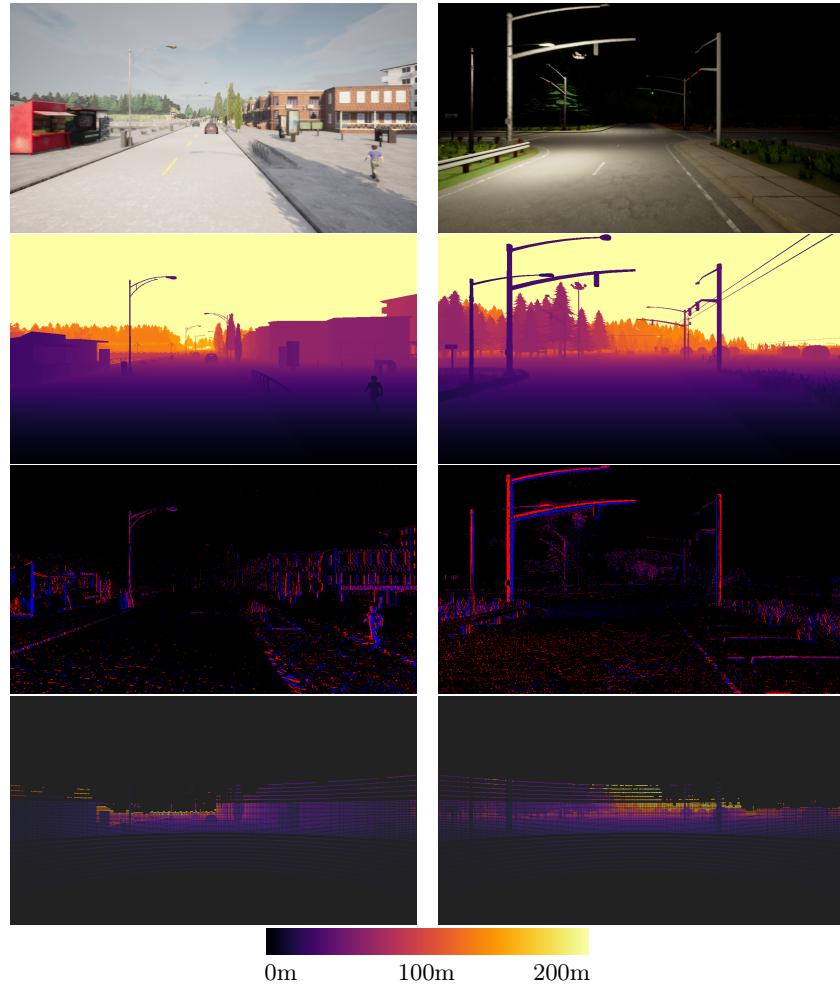


Fig. 3: Example data from the “Town01_04” (left) and “Town07_00” (right) sequences from our SLED dataset. Top to bottom: RGB image; depth image; events; projected LiDAR points; color scale.

Table 1: Detailed results for recordings on *Town01* for the SLED dataset.

Sequence	Cutoff	Dense depths errors				Sparse depths errors				Depth change map errors				
		On D_{df}	Rel.	Raw	On D_{ds}	Rel.	NN	On D_{df}	ALEDS	On D_{ds}	ALEDS	Absolute error	Correctly classified events (with a threshold of $\pm 1m$)	
Town01_00	10m	1.13m	22.35%	1.23m	24.58%	1.00m	1.02m	1.73m	1.15m	1.35m	1.63m	3.55m	94.84%	
	20m	3.58m	34.06%	3.82m	37.37%	1.80m	1.81m	2.07m	2.07m	2.07m	4.2m	3.55m	87.0%	
	100m	5.37m	34.85%	4.77m	39.39%	4.66m	4.75m	5.08m	5.45m	5.32m	6.34m	5.33m	82.03%	
	200m	6.09m	23.39%	6.59m	25.28%	7.14m	4.17m	9.71m	5.35m	7.08m	7.08m	5.35m	80.31%	
Town01_01	10m	0.85m	12.58%	0.82m	12.27%	1.58m	1.27m	2.45m	1.43m	1.68m	1.63m	3.55m	94.23%	
	20m	2.50m	23.27%	2.74m	24.94%	4.94m	5.82m	6.68m	6.30m	4.69m	4.69m	4.69m	89.96%	
	30m	3.24m	25.24%	3.53m	27.05%	4.73m	6.67m	6.36m	7.45m	5.04m	5.04m	5.04m	88.35%	
	100m	9.87m	34.86%	10.25m	36.56%	4.69m	6.62m	6.34m	7.36m	5.33m	5.33m	5.33m	86.03%	
	200m	8.23m	22.50%	8.55m	23.61%	13.74m	9.88m	16.33m	11.39m	8.00m	8.00m	8.00m	79.91%	
Town01_02	10m	0.51m	9.52%	0.53m	9.69%	0.48m	0.51m	0.72m	0.61m	0.73m	0.73m	0.73m	93.64%	
	20m	1.00m	10.34%	1.04m	10.65%	0.47m	0.65m	0.80m	0.71m	1.48m	1.48m	1.48m	90.29%	
	30m	1.96m	12.73%	2.03m	13.14%	0.57m	0.92m	0.98m	0.99m	2.54m	2.54m	2.54m	85.05%	
	100m	4.23m	15.80%	4.30m	16.14%	1.05m	1.76m	1.61m	1.84m	4.13m	4.13m	4.13m	79.08%	
	200m	5.40m	14.43%	5.47m	14.84%	1.57m	2.09m	2.17m	2.19m	6.11m	6.11m	6.11m	78.12%	
Town01_03	10m	0.66m	10.23%	0.69m	11.09%	0.66m	0.53m	0.98m	0.64m	0.59m	0.59m	0.59m	94.96%	
	20m	1.02m	11.44%	1.02m	12.92%	0.70m	0.60m	1.24m	0.75m	1.42m	1.42m	1.42m	94.12%	
	30m	1.69m	12.10%	1.73m	13.44%	0.86m	1.28m	1.54m	0.89m	2.71m	2.71m	2.71m	87.88%	
	100m	2.70m	12.15%	2.80m	12.73%	1.39m	1.47m	2.51m	1.70m	4.01m	4.01m	4.01m	82.84%	
	200m	2.85m	9.13%	2.93m	9.55%	2.47m	1.90m	3.84m	2.16m	6.05m	6.05m	6.05m	81.50%	
Town01_04	10m	0.95m	17.55%	1.17m	22.00%	0.94m	0.96m	1.85m	1.40m	2.22m	2.22m	2.22m	84.93%	
	20m	1.29m	16.70%	1.56m	20.64%	1.28m	1.35m	2.37m	1.74m	2.80m	2.80m	2.80m	80.03%	
	30m	1.54m	16.58%	1.82m	20.28%	1.44m	1.64m	2.62m	2.03m	2.98m	2.98m	2.98m	78.99%	
	100m	2.14m	16.60%	2.45m	20.07%	2.04m	2.37m	3.45m	2.82m	3.44m	3.44m	3.44m	77.08%	
	200m	2.05m	10.38%	2.25m	12.48%	4.01m	3.15m	6.56m	4.94m	5.44m	5.44m	5.44m	75.44%	
Town01_05	10m	0.42m	7.40%	0.52m	9.83%	0.96m	0.78m	1.93m	1.15m	0.99m	0.99m	0.99m	93.63%	
	20m	0.88m	8.85%	0.96m	10.61%	0.79m	1.13m	1.51m	1.41m	1.41m	1.41m	1.41m	88.30%	
	30m	1.55m	10.45%	1.59m	11.77%	0.84m	1.44m	1.61m	1.60m	2.15m	2.15m	2.15m	80.29%	
	100m	3.41m	12.68%	3.49m	13.74%	1.76m	2.64m	2.94m	2.92m	4.59m	4.59m	4.59m	71.36%	
	200m	3.67m	10.85%	3.87m	11.85%	4.76m	4.02m	6.17m	4.79m	6.35m	6.35m	6.35m	70.24%	
Town01_06	10m	0.63m	8.20%	0.66m	10.26%	0.60m	0.58m	1.04m	1.25m	1.25m	1.25m	1.25m	90.47%	
	20m	1.02m	9.83%	1.17m	12.19%	0.84m	1.28m	1.64m	1.64m	2.94m	2.94m	2.94m	84.81%	
	30m	1.53m	11.33%	1.60m	13.19%	0.98m	1.91m	1.91m	2.36m	3.78m	3.78m	3.78m	80.76%	
	100m	2.02m	18.43%	2.92m	20.17%	1.32m	2.12m	2.06m	2.31m	4.06m	4.06m	4.06m	75.56%	
	200m	3.49m	8.83%	3.79m	10.06%	2.55m	7.46m	13.97m	8.47m	9.00m	9.00m	9.00m	74.50%	
Town01_07	10m	0.99m	16.01%	1.11m	17.89%	0.41m	0.74m	0.76m	0.90m	1.23m	1.23m	1.23m	86.15%	
	20m	1.76m	18.57%	1.93m	20.61%	0.55m	0.93m	1.00m	1.06m	2.61m	2.61m	2.61m	80.28%	
	30m	2.02m	18.45%	2.19m	20.31%	0.77m	1.27m	1.30m	1.40m	3.16m	3.16m	3.16m	78.14%	
	100m	3.12m	18.57%	3.20m	20.17%	1.32m	2.12m	2.06m	2.31m	4.06m	4.06m	4.06m	75.73%	
	200m	2.45m	13.42%	2.64m	14.67%	3.11m	2.67m	4.13m	2.94m	5.28m	5.28m	5.28m	75.12%	
Town01_08	10m	1.06m	17.74%	1.25m	20.76%	0.85m	0.90m	1.84m	1.21m	3.66m	3.66m	3.66m	88.92%	
	20m	1.69m	19.34%	1.90m	22.09%	1.04m	1.45m	2.13m	1.80m	5.79m	5.79m	5.79m	80.47%	
	30m	2.17m	19.47%	2.39m	21.23m	2.01m	2.47m	2.46m	2.41m	6.51m	6.51m	6.51m	75.56%	
	100m	3.12m	19.47%	3.27m	21.92%	2.40m	3.40m	4.00m	3.80m	8.00m	8.00m	8.00m	72.35%	
	200m	4.50m	14.57%	4.74m	16.20%	11.31m	8.22m	13.02m	9.16m	12.81m	12.81m	12.81m	70.12%	
Town01_09	10m	0.58m	11.99%	0.68m	14.03%	0.50m	0.55m	1.50m	1.71m	2.25m	2.25m	2.25m	87.48%	
	20m	1.15m	12.88%	1.30m	14.83%	0.63m	0.45m	4.80m	2.60m	4.80m	4.80m	4.80m	80.01%	
	30m	1.92m	14.83%	2.05m	16.28%	4.99m	3.81m	6.96m	4.22m	6.74m	6.74m	6.74m	70.76%	
	100m	2.69m	14.98%	2.84m	16.72%	6.69m	5.57m	8.88m	6.63m	8.07m	8.07m	8.07m	67.77%	
	200m	4.20m	10.91%	4.38m	12.04%	10.05m	8.53m	12.91m	9.29m	10.19m	10.19m	10.19m	62.17%	
Town01_10	10m	3.24m	47.08%	3.29m	47.53%	0.66m	0.68m	0.98m	0.78m	1.96m	1.96m	1.96m	94.32%	
	20m	6.01m	61.13%	6.14m	7.15m	61.07%	0.83m	1.06m	1.37m	1.19m	4.17m	4.17m	4.17m	92.32%
	30m	9.98m	60.65%	10.09m	71.51m	45.36%	3.93m	2.46m	4.82m	2.70m	6.01m	6.01m	6.01m	88.36%
	100m	11.98m	61.20%	12.18m	62.20%	1.25m	1.83m	2.04m	2.00m	4.58m	4.58m	4.58m	89.85%	
	200m	10.98m	44.63%	11.14m	45.36%	3.93m	3.50m	5.00m	4.50m	6.98m	6.98m	6.98m	81.48%	
Town01_11	10m	0.96m	13.78%	1.07m	15.43%	1.72m	1.31m	1.79m	2.19m	1.64m	1.64m	1.64m	93.85%	
	20m	3.95m	30.55%	4.13m	33.37%	2.07m	2.07m	2.41m	2.41m	2.65m	2.65m	2.65m	89.14%	
	30m	6.20m	37.95%	6.42m	41.31%	4.31m	2.41m	2.65m	3.42m	3.87m	3.87m	3.87m	83.2%	
	100m	7.36m	38.87%	8.05m	41.06%	4.45m	4.45m	5.07m	4.00m	4.41m	4.41m	4.41m	83.09%	
	200m	9.51m	28.98%	10.46m	31.71%	8.61m	1.51m	1.50m	1.29m	6.98m	6.98m	6.98m	78.55%	
Town01_12	10m	2.22m	47.37%	2.58m	47.49%	0.50m	0.98m	0.98m	1.23m	1.62m	1.62m	1.62m	84.09%	
	20m	3.29m	36.77%	3.34m	45.12%	1.56m	2.58m	2.57m	2.50m	2.64m	2.64m	2.64m	81.92%	
	30m	3.48m	39.46%	3.78m	44.69%	2.01m	3.81m	3.28m	4.16m	3.32m	3.32m	3.32m	80.22%	
	100m	3.82m	38.13%	4.11m	42.03%	2.93m	4.40m	3.81m	4.71m	3.74m	3.74m	3.74m	79.38%	
	200m	3.48m	28.85%	3.77m	32.42%	8.63m	5.92m	10.74m	6.56m	5.18m	5.18m	5.18m	78.55%	
Town01_13	10m	1.81m	29.12%	1.99m	32.24%	4.31m	3.96m	6.71m	4.61m	3.00m	3.00m	3.00m	92.10%	
	20m	2.80m	30.46%	3.02m	33.27%	3.59m	3.85m	5.92m	4.41m	4.42m	4.42m	4.42m	82.45%	
	30m	3.50m	30.99%	3.73m	32.91%	3.75m	4.49m	6.22m	4.98m	5.27m	5.27m	5.27m	77.92%	
	100m	4.26m	28.98%	4.56m	31.38%	4.42m	5.55m	7.46m	6.19m	6.54m	6.54m	6.54m	73.83%	
	200m	4.43m	21.75%	4.83m	32.62%	13.17m	7.64m	17.04m	9.09m	8.72m	8.72m	8.72m	72.75%	
Town01_14	10m	1.09m	19.79%	1.28m	21.84%	0.90m	1.09m	1.91m	1.37m	1.92m	1.92m	1.92m	91.74%	
	20m	1.51m	17.72%	1.71m	20.11%	1.25m	1.49m	2.03m	1.68m	2.65m	2.65m	2.65m	88.08%	
	30m	2.15m	17.72%	2.37m	20.31%	2.31m	2.31m	2.65m	2.05m	2.60m	2.60m	2.60m	84.81%	
	100m	2.40m	18.99%	2.51m	22.99%	2.58m	4.03m	4.90m	3.45m	3.79m	3.79m	3.79m	83.32%	
	200m	2.16m	10.10%	2.34m	12.34%	6.32m								

Table 2: Detailed results for recordings on *Town03* for the SLED dataset.

Sequence	Cutoff	Dense depths errors				Sparse depths errors				Depth change map errors			
		On D_{hf}		On D_{sf}		On D_{hf}		On D_{sf}		On D_{hf}		On D_{sf}	
		Raw	Rel.	Raw	Rel.	NN	ALEDs	NN	ALEDs	NNAbsolute error	ALEDsAbsolute error	Correctly classified events (with a threshold of $\pm 1m$)	
Town03_01	10m	0.63m	11.61%	0.71m	13.23%	0.45m	0.25m	0.45m	0.30m	0.14m	0.10m	99.93%	
	20m	3.27m	26.39%	3.31m	27.51%	0.45m	0.32m	0.49m	0.40m	0.22m	0.26m	99.76%	
	30m	4.87m	31.92%	4.91m	32.29%	0.48m	0.36m	0.54m	0.44m	0.30m	0.36m	99.62%	
	100m	8.39m	35.65%	8.53m	36.67%	0.87m	0.89m	1.01m	0.99m	0.73m	0.81m	98.06%	
	200m	10.28m	25.56%	10.29m	26.17%	3.90m	2.51m	4.14m	2.66m	1.32m	1.32m	92.96%	
Town03_02	10m	0.59m	11.69%	0.63m	12.29%	0.44m	0.43m	0.45m	0.49m	0.14m	0.10m	99.65%	
	20m	3.14m	13.44%	3.18m	13.52%	0.47m	0.37m	0.50m	0.42m	0.21m	0.24m	97.13%	
	30m	3.19m	15.96%	3.34m	22.05%	0.88m	1.02m	1.20m	1.07m	2.94m	3.03m	94.33%	
	100m	5.29m	22.74%	5.67m	24.01%	1.87m	2.46m	2.96m	2.81m	4.71m	5.11m	88.91%	
	200m	7.08m	16.06%	7.41m	16.92%	5.15m	3.91m	6.91m	4.82m	7.17m	8.52m	85.20%	
Town03_03	10m	0.29m	4.45%	0.33m	4.99%	0.43m	0.41m	1.17m	0.50m	1.03m	1.03m	96.81%	
	20m	0.65m	6.10%	0.73m	6.81%	1.06m	0.65m	2.08m	0.88m	2.80m	1.90m	91.20%	
	30m	0.95m	6.95%	1.09m	7.86%	1.74m	1.10m	3.26m	1.43m	3.61m	3.61m	87.28%	
	100m	1.83m	7.45%	2.07m	8.37%	2.93m	2.72m	5.36m	3.48m	4.97m	5.75m	75.93%	
	200m	1.75m	5.37%	2.00m	6.05%	4.62m	3.47m	7.31m	4.49m	6.40m	7.56m	75.65%	
Town03_04	10m	0.31m	4.41%	0.38m	5.46%	0.63m	0.38m	0.95m	0.46m	1.12m	1.12m	96.29%	
	20m	1.88m	13.42%	2.08m	15.21%	0.70m	0.63m	1.05m	0.79m	3.83m	3.83m	79.65%	
	30m	2.62m	14.96%	2.79m	16.40%	0.82m	1.03m	1.58m	1.17m	3.83m	3.82m	76.22%	
	100m	3.54m	15.83%	3.71m	16.76%	1.65m	2.05m	2.75m	2.53m	4.03m	5.35m	75.98%	
	200m	4.35m	14.82%	4.52m	16.90%	2.45m	3.89m	3.83m	3.10m	5.17m	7.37m	75.47%	
Town03_05	10m	0.22m	3.57%	0.43m	6.19%	0.50m	0.60m	0.66m	0.54m	1.22m	1.22m	93.65%	
	20m	1.01m	9.11%	1.06m	9.67%	0.87m	0.75m	1.43m	0.83m	4.22m	4.22m	83.49%	
	30m	1.56m	10.42%	1.62m	10.97%	1.12m	1.27m	1.88m	1.35m	5.44m	5.44m	79.60%	
	100m	2.59m	12.15%	3.05m	12.70%	1.98m	2.67m	3.14m	2.78m	7.64m	7.66m	76.06%	
	200m	4.18m	10.13%	4.28m	10.56%	4.91m	4.23m	6.30m	4.44m	10.73m	10.73m	74.61%	
Town03_06	10m	7.05m	87.16%	7.20m	88.34%	0.34m	0.55m	0.43m	0.65m	1.82m	1.82m	93.50%	
	20m	10.02m	99.82%	10.32m	101.69%	0.35m	0.83m	0.67m	1.01m	3.30m	3.30m	88.19%	
	30m	11.15m	83.69%	11.36m	85.20%	1.75m	2.87m	3.06m	3.32m	4.94m	5.74m	75.94%	
	100m	12.16m	74.37%	12.37m	75.77%	2.10m	3.41m	3.65m	4.00m	5.99m	7.43m	74.93%	
	200m	12.22m	35.99%	12.42m	37.20%	3.15m	8.74m	4.67m	7.66m	4.92m	6.17m	75.07%	
Town03_07	10m	0.22m	3.59%	0.22m	3.62%	0.57m	0.30m	0.70m	0.39m	0.34m	0.34m	97.94%	
	20m	0.53m	4.60%	0.57m	5.07%	0.72m	0.57m	0.79m	0.79m	1.62m	1.62m	89.30%	
	30m	0.80m	8.07%	1.02m	1.20%	1.20m	1.06m	1.77m	1.22m	2.48m	2.48m	83.88%	
	100m	3.34m	10.69%	3.41m	10.97%	1.95m	3.20m	3.40m	3.57m	4.64m	7.50m	75.50%	
	200m	3.07m	8.31%	3.15m	8.74m	4.76m	4.67m	7.66m	4.92m	6.17m	7.23m	75.07%	
Town03_08	10m	0.30m	4.01%	0.33m	5.10%	0.73m	0.47m	1.27m	0.56m	0.97m	0.97m	94.49%	
	20m	0.69m	6.37%	0.80m	7.29%	1.27m	0.73m	2.69m	0.95m	2.47m	2.47m	86.80%	
	30m	1.42m	8.72%	1.57m	9.77%	1.94m	1.18m	3.87m	1.51m	3.84m	77.83%		
	100m	3.14m	10.72%	3.49m	11.91%	3.57m	3.51m	6.50m	4.56m	5.40m	68.94%		
	200m	3.07m	8.42%	3.46m	9.39%	3.58m	4.37m	8.57m	5.60m	6.86m	68.81%		
Town03_09	10m	0.85m	12.67%	1.15m	16.72%	0.17m	0.57m	0.57m	0.07m	0.55m	0.55m	74.88%	
	20m	1.19m	13.53%	1.50m	17.21%	0.17m	0.66m	0.33m	0.67m	2.11m	2.11m	74.90%	
	30m	1.32m	13.41%	1.61m	16.87%	0.22m	0.57m	0.52m	0.85m	0.95m	2.38m	75.08%	
	100m	1.86m	13.22%	2.10m	16.93%	1.57m	2.15m	2.32m	2.31m	3.05m	73.89%		
	200m	2.07m	9.82%	2.32m	12.05%	3.02m	3.20m	3.20m	3.73m	3.96m	72.83%		
Town03_10	10m	3.27m	94.35%	3.64m	64.63%	0.17m	0.47m	0.54m	1.82m	1.82m	1.82m	86.20%	
	20m	4.57m	43.57%	5.20m	58.14%	0.16m	1.22m	0.26m	1.57m	1.57m	1.57m	83.47%	
	30m	5.18m	42.73%	5.29m	45.01%	0.27m	1.52m	0.71m	1.68m	1.63m	1.63m	83.39%	
	100m	3.50m	40.82%	3.62m	42.98%	0.38m	1.93m	0.85m	2.09m	2.00m	2.00m	82.62%	
	200m	3.23m	35.29%	3.32m	37.20%	0.53m	1.96m	0.93m	2.12m	2.44m	2.44m	82.49%	
Town03_11	10m	2.56m	30.96%	2.60m	32.49%	0.65m	0.66m	0.85m	0.77m	1.16m	1.16m	91.32%	
	20m	2.71m	27.29%	2.80m	28.47%	0.49m	0.68m	0.73m	0.77m	1.41m	1.41m	91.30%	
	30m	3.63m	29.05%	3.73m	31.07%	0.60m	1.00m	1.02m	1.11m	2.02m	2.02m	89.91%	
	100m	7.85m	33.13%	7.99m	34.18%	1.44m	2.67m	2.51m	2.92m	3.87m	3.87m	84.03%	
	200m	7.38m	26.17%	7.52m	27.03%	4.35m	4.35m	5.85m	5.96m	5.33m	5.33m	81.81%	
Town03_12	10m	0.43m	6.06%	0.47m	6.62%	0.67m	0.43m	0.89m	0.45m	0.99m	0.99m	98.51%	
	20m	2.24m	15.59%	2.38m	16.64%	0.98m	0.66m	1.51m	0.68m	3.07m	3.07m	89.26%	
	30m	4.15m	22.42%	4.24m	23.01%	1.06m	0.98m	1.90m	1.04m	3.43m	3.43m	81.02%	
	100m	8.18m	15.95%	5.01m	16.46%	2.45m	2.64m	2.63m	2.82m	4.99m	76.75%		
	200m	3.86m	15.19%	4.03m	15.98%	5.02m	3.41m	6.61m	3.75m	5.43m	75.71%		
Town03_13	10m	0.20m	4.44%	0.32m	4.92%	0.61m	0.26m	0.67m	0.26m	0.65m	0.65m	98.45%	
	20m	0.60m	5.64%	0.60m	6.40%	0.65m	0.53m	1.00m	0.65m	1.67m	1.67m	89.75%	
	30m	1.00m	6.72%	1.07m	7.40%	1.14m	0.85m	1.91m	1.03m	2.50m	2.50m	85.92%	
	100m	2.02m	7.93%	2.14m	8.58%	2.75m	2.55m	4.05m	2.81m	3.42m	79.38%		
	200m	1.97m	5.65%	2.10m	6.12%	4.65m	3.40m	6.22m	3.78m	4.48m	78.09%		
Town03_14	10m	0.30m	4.86%	0.36m	5.71%	0.56m	0.35m	0.82m	0.51m	0.86m	0.86m	95.75%	
	20m	1.68m	12.08%	1.87m	13.72%	0.61m	0.56m	1.21m	0.77m	3.00m	3.00m	80.50%	
	30m	2.54m	14.42%	2.71m	15.75%	0.75m	0.95m	1.49m	1.13m	3.67m	3.67m	75.82%	
	100m	3.43m	15.21%	3.58m	16.36%	1.58m	2.44m	2.50m	2.61m	4.41m	74.22%		
	200m	4.02m	14.06%	4.14m	15.08%	3.05m	2.94m	4.05m	3.13m	6.02m	73.78%		
Town03_15	10m	0.65m	12.46%	0.64m	11.99%	0.80m	0.57m	1.00m	0.62m	0.87m	0.87m	98.33%	
	20m	1.94m	22.17%	2.13m	23.34%	0.92m	0.77m	2.06m	0.93m	2.90m	2.90m	90.03%	
	30m	2.32m	22.17%	2.55m	23.36%	1.26m	1.04m	2.60m	1.28m	3.62m	3.62m	85.86%	
	100m	3.89m	18.38%	4.00m	18.47%	2.85m	3.90m	4.68m	4.33m	8.77m	76.20%		
	200m	5.40m	14.13%	5.62m	14.26%	8.66m	6.74m	10.78m	7.58m	14.13m	74.72%		
Town03_16	10m	0.42m	6.33%	0.50m	7.64%	0.86m	0.68m	1.46m	0.92m	1.81m	1.81m	91.42%	
	20m	1.02m	9.35%	1.13m	10.61%	1.06m	0.92m	1.90m	1.12m	4.97m	4.97m	80.90%	
	30m	1.45m	10.34%	1.54m	11.43%	1.39m	1.20m	2.43m	1.39m	6.16m	6.16m	78.03%	
	100m	2.47m	10.59%	2.61m	11.70%	2.16m	2.08m	3.4					

4 Additional Dense Depths Results on our SLED Dataset

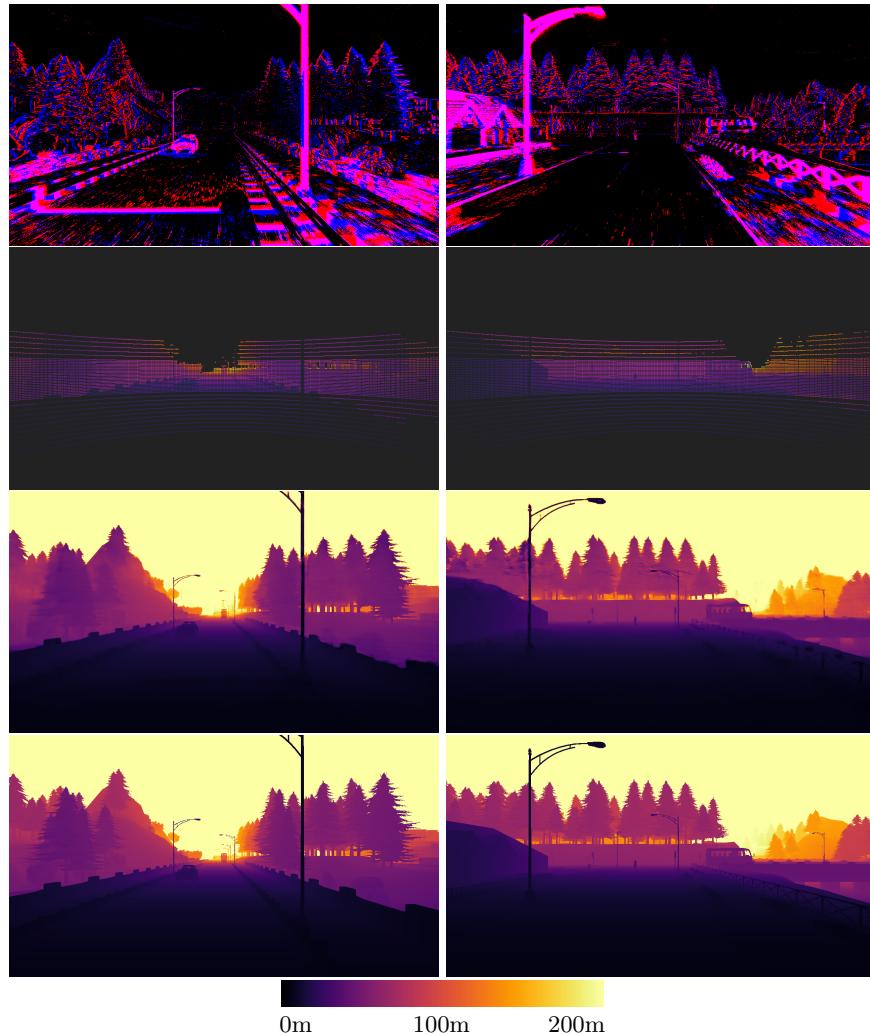


Fig. 4: Additional dense depths results on the SLED dataset.

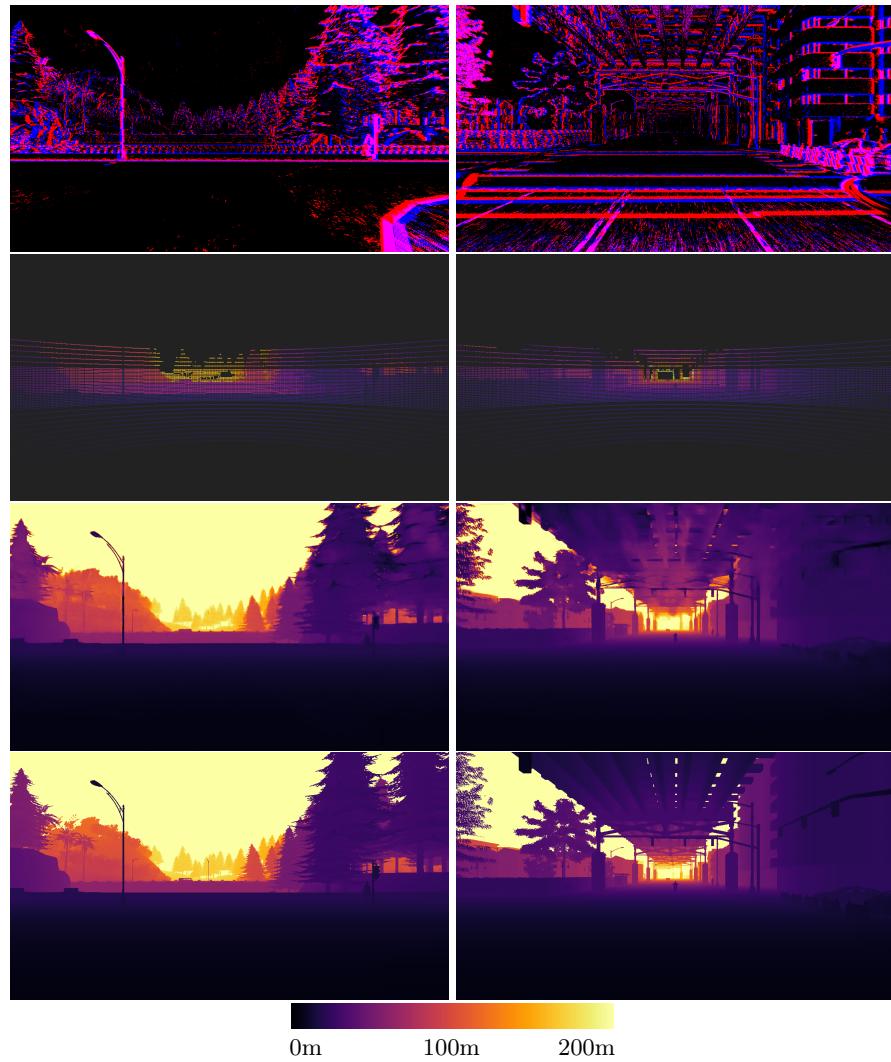


Fig. 5: Additional dense depths results on the SLED dataset.

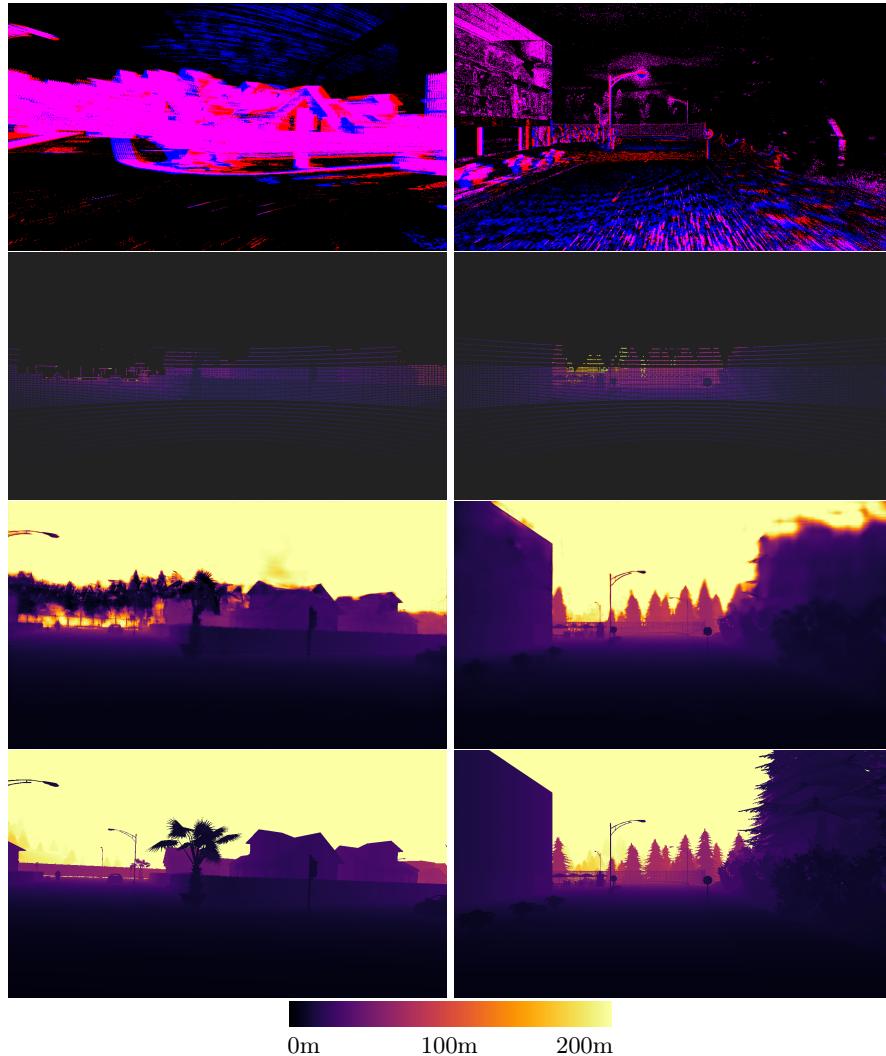


Fig. 6: Additional dense depths results on the SLED dataset. Illustrated here are two failure cases. Left: due to a sharp turn at high speed, accumulated events become too blurry, resulting in an incorrect prediction for distant objects. Right: night scene, where the trees on the right side are too dark to be seen even by the event camera, resulting in a partially blurry prediction.

5 Additional Dense Depths Results on the MVSEC Dataset

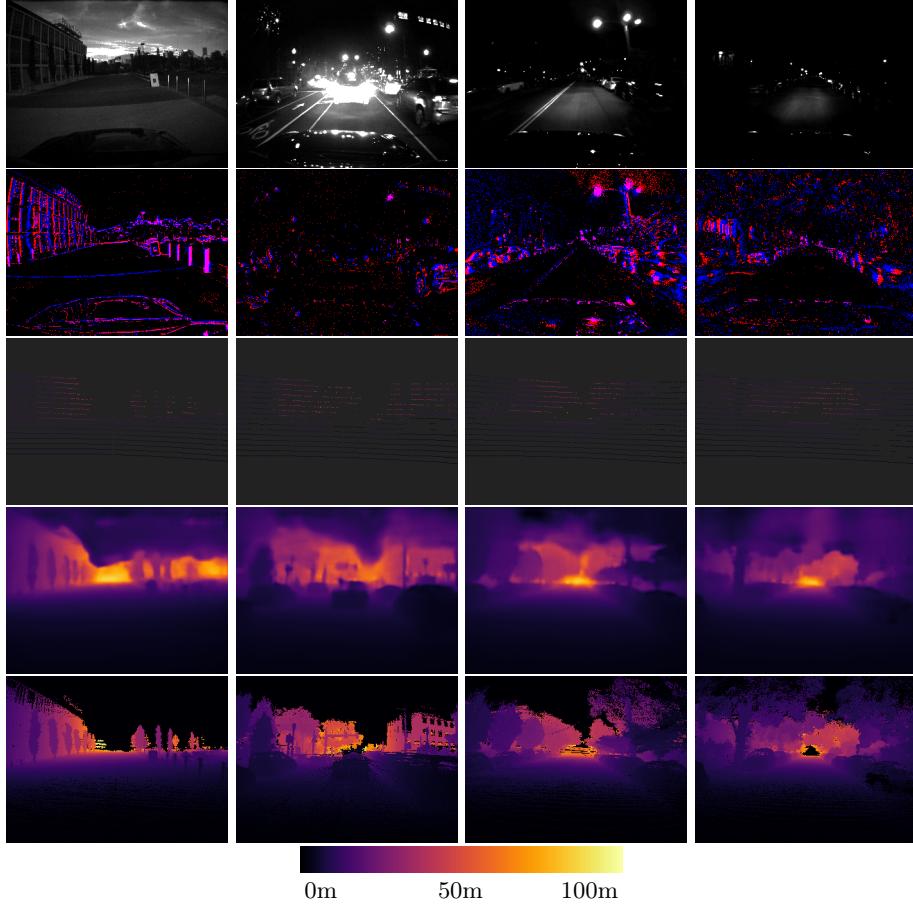


Fig. 7: Additional dense depths results on the MVSEC dataset. From left to right: “Outdoor day 1”, “Outdoor night 1”, “Outdoor night 2”, “Outdoor night 3”. From top to bottom: grayscale reference, events, LiDAR, prediction (ALED_{S→R}), ground truth, color scale.

6 Thresholded Depth Change Maps Illustrations on our SLED Dataset

We present in Fig. 8 and 9 qualitative results for the thresholded depth change maps. These results visually corroborate the numerical analysis presented in the

main article, i.e., the overall accurate classification of the events. Some errors can still be seen, especially for the lower parts of the objects: as they are closer to the ground, the depth difference is less significant, and errors on the depth change map become therefore more critical.

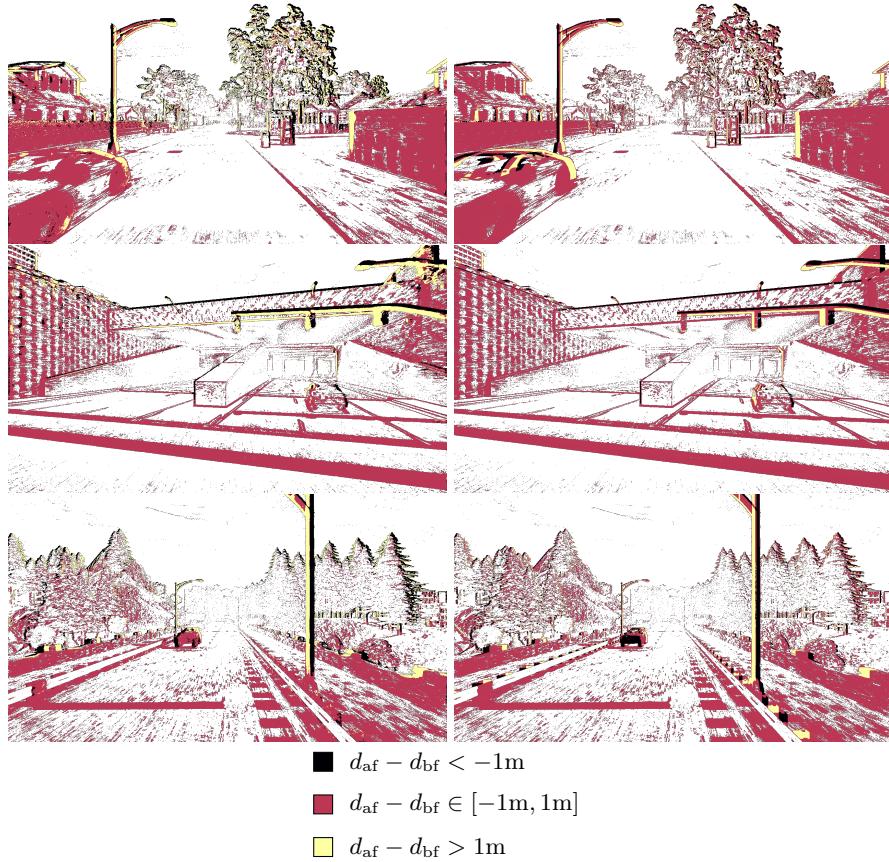


Fig. 8: Thresholded depth change map results, using the events as a mask. Left: prediction (ALED_S). Right: ground truth.

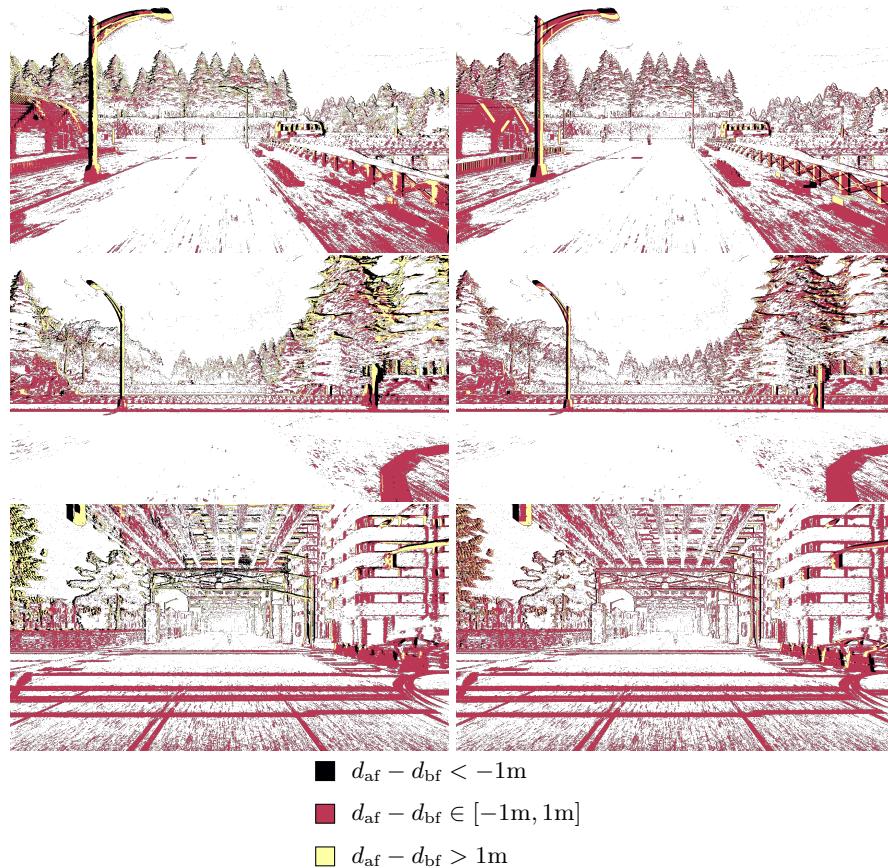


Fig. 9: Additional thresholded depth change map results, using the events as a mask. Left: prediction (ALEDs). Right: ground truth.