Atividade Computacional II - Sistemas Nebulosos

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1 Implementação das funções de pertinência

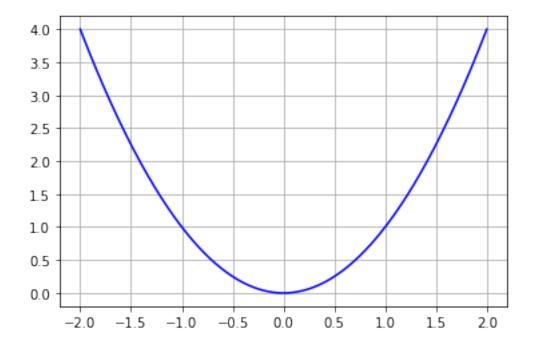
```
[1]: from matplotlib import pyplot as plt
    import numpy as np
    from math import *
    from sklearn.metrics import mean_squared_error
    import skfuzzy as fuzz
    from skfuzzy import control as ctrl
[2]: def trimf(x,a,b,c):
        y = np.zeros(len(x))
        for i in range(len(x)):
            y[i] = \max([\min([(x[i]-a)/(b-a), (c-x[i])/(c-b)]), 0])
        return y
    def gaussmf(x,c,sigma):
        return e^{**(-1/2 * ((x-c)/sigma)**2)}
    def trapmf(x,a,b,c,d):
        y = np.zeros(len(x))
        for i in range(len(x)):
            if x[i] > a and x[i] \le b:
                y[i] = (x[i]-a)/(b-a)
            if x[i] > b and x[i] \le c:
                y[i] = 1
            if x[i] > c and x[i] < d:
                y[i] = (-x[i]+d)/(-c+d)
        return y
    def gbellmf(x, a, b, c):
        return 1/(1+abs(((x-c)/a)**(2*b)))
    def sigmf(x, c, a):
```

```
return 1/(1 + e^{**(-a^{*}(x-c))})
```

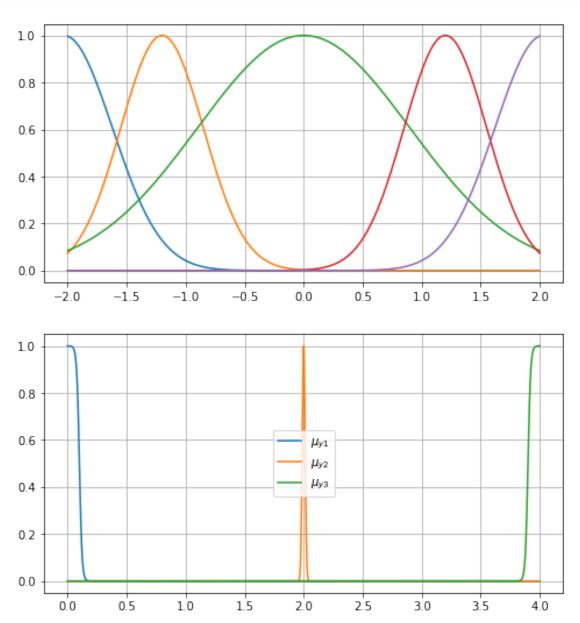
2 Questão 1 - Parábola

Aproximar a função $y = x^2, x \in [0,2]$, empregando os mecanismos de inferência do Mamdani e do Sugeno (linear e constante).

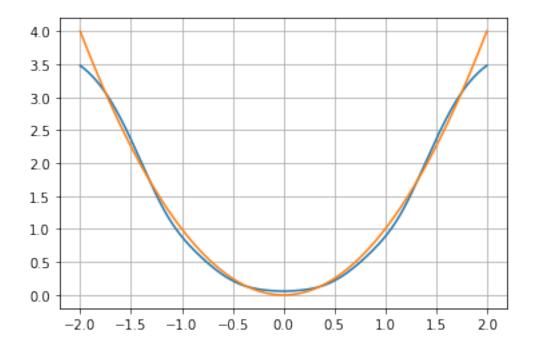
```
[3]: # Universe Variables:
    x = np.linspace(-2, 2, 2000)
    y = np.linspace(0, 4, 5000)
    y_real = x**2
    plt.plot(x, y_real, 'b-')
    plt.grid()
```



2.1 Mecanismo de Inferência de Mandani



```
[5]: y_hat = []
    for xi in x:
        # Activation of our fuzzy membership functions at these values.
        x1 = fuzz.interp_membership(x, mu_x_1, xi)
        x2 = fuzz.interp_membership(x, mu_x_2, xi)
        x3 = fuzz.interp_membership(x, mu_x_3, xi)
        x4 = fuzz.interp_membership(x, mu_x_4, xi)
        x5 = fuzz.interp_membership(x, mu_x_5, xi)
        # Rule application
        y_1 = np.fmin(np.fmax(x1, x5), mu_y_3)
        y_2 = np.fmin(np.fmax(x2, x4), mu_y_2)
        y_3 = np.fmin(x3, mu_y_1)
        # Aggregate all three output membership functions together
        aggregated = np.fmax(y_1, np.fmax(y_2, y_3))
        # Calculate defuzzified result
        y_hat.append(fuzz.defuzz(y, aggregated, 'centroid'))
[6]: plt.plot(x, y_hat, x, y_real)
    plt.grid()
```

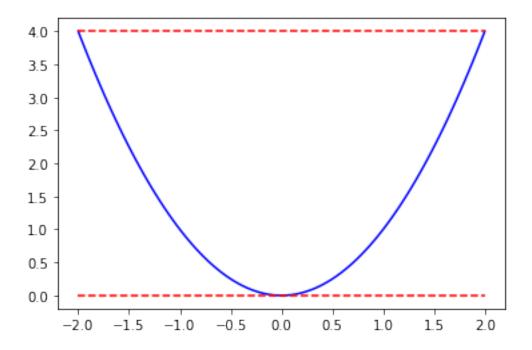


```
[7]: mean_squared_error(y_real, y_hat)
```

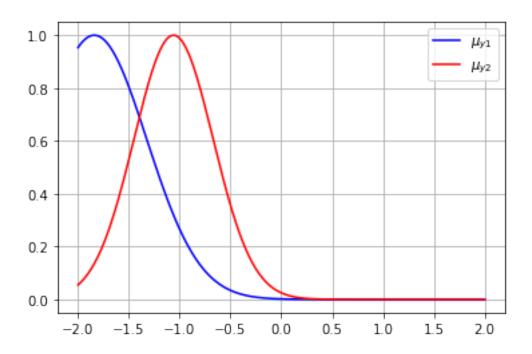
[7]: 0.013967729852900082

2.2 Mecanismo de Inferência de Sugeno (Constante)

```
[8]: x = np.linspace(-2, 2, 100)
y = np.linspace(0, 4, 100)
y_real = x**2
y1 = np.ones(100)*(4)
y2 = np.ones(100)*(0)
plt.plot(x, y_real, 'b-', x, y1,'r--', x, y2, 'r--')
```

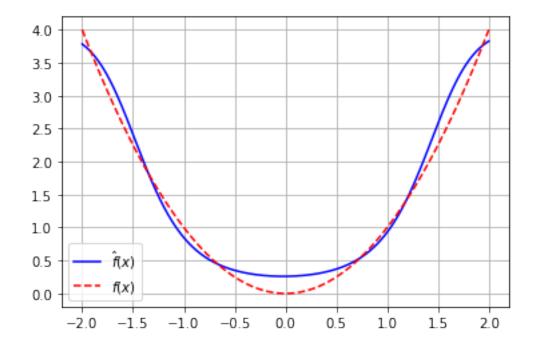


```
[9]: x = np.linspace(-2, 2, 500)
y = x**2
y1 = np.ones(500)*(4)
y2 = np.ones(500)*(0)
mu_y1 = gaussmf(x, -1.84, -0.516)
mu_y2 = gaussmf(x, -1.06, 0.39)
#mu_y3 = gaussmf(x, v[4],v[5])
plt.plot(x,mu_y1,'b-',x,mu_y2,'r-')
legend = plt.legend([r'$\mu_{y1}$', r'$\mu_{y2}$'])
plt.grid()
```



```
[10]: div = mu_y1 + mu_y2
div[div==0] = 0.00001

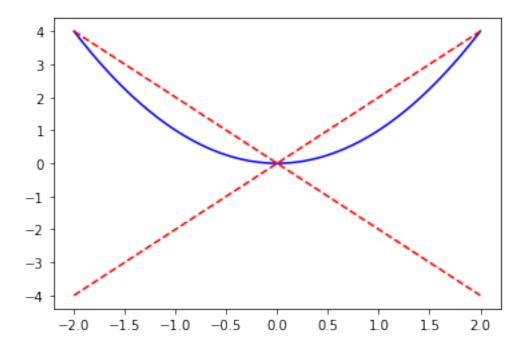
y_hat = np.divide(np.multiply(mu_y1, y1) + np.multiply(mu_y2, y2), div )
plt.plot(x,y_hat,'b-',x,y,'r--')
legend = plt.legend([r'$\hat{f}(x)$', r'$f(x)$'])
plt.grid()
```



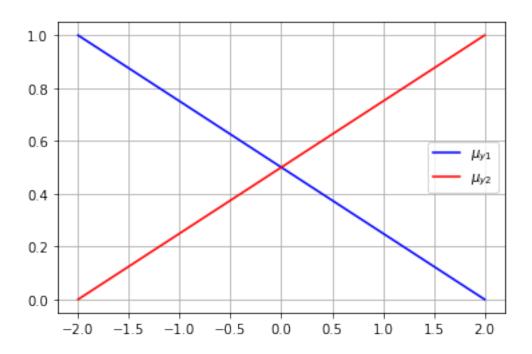
2.3 Mecanismo de Inferência de Sugeno

2.3.1 2 Regras, pertinência do tipo triangular

```
y_{1} = 2x, \quad \mu_{y1} = \operatorname{trimf}(x, -2, -2, 4)
y_{2} = -2x, \quad \mu_{y2} = \operatorname{trimf}(x, -2, 2, 2)
[11]: y_{1} = -2*x
y_{2} = 2*x
y_{1} = -2*x
y_{2} = 2*x
y_{1} = -2*x
y_{2} = 2*x
y_{3} = -2*x
y_{4} = -2*x
y_{5} = -2*x
y_{7} = -2
```

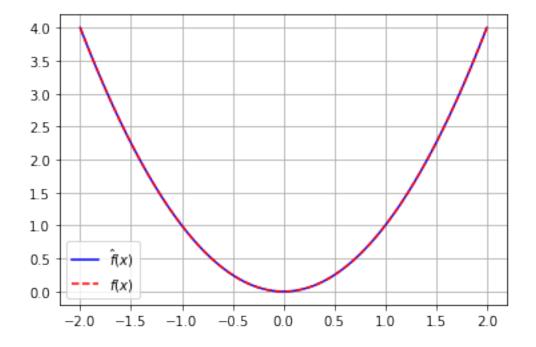


```
[12]: mu_y1 = trimf(x, -3, -2 ,2)
mu_y2 = trimf(x, -2, 2, 3)
plt.plot(x,mu_y1,'b-',x,mu_y2,'r-')
legend = plt.legend([r'$\mu_{y1}$', r'$\mu_{y2}$'])
plt.grid()
```



```
[13]: div = mu_y1 + mu_y2
div[div==0] = 0.001

y_hat = np.divide(np.multiply(mu_y1, y1) + np.multiply(mu_y2, y2), div )
plt.plot(x,y_hat,'b-',x,y,'r--')
legend = plt.legend([r'$\hat{f}(x)$', r'$f(x)$'])
plt.grid()
```



```
[14]: mean_squared_error(list(y), list(y_hat))
```

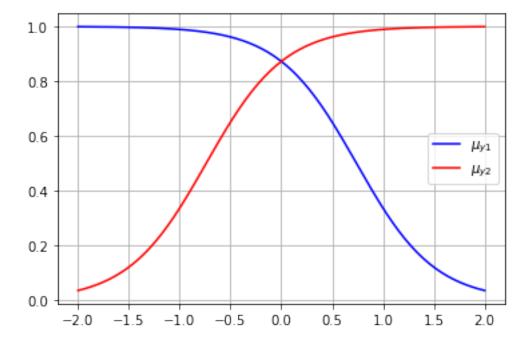
[14]: 3.2985974622557315e-32

2.3.2 2 Regras, pertinência do tipo gaussiana

```
y_1 = 2x, \mu_{y1} = \text{gauss}(x, 0.74, -2.6)

y_2 = -2x, \mu_{y2} = \text{gauss}(x, -0.74, 2.6)
```

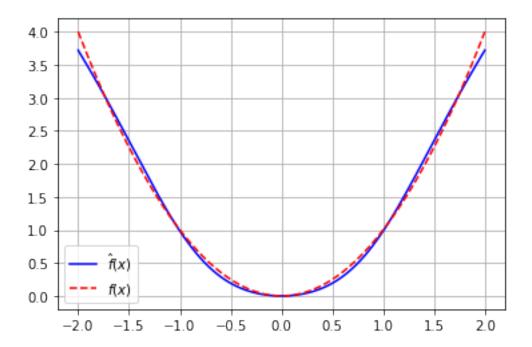
```
[15]: x = np.linspace(-2, 2, 200)
y = x**2
y1 = -2*x
y2 = 2*x
mu_y1 = sigmf(x, 0.74, -2.6)
mu_y2 = sigmf(x, -0.74, 2.6)
#mu_y3 = gaussmf(x, v[4], v[5])
plt.plot(x,mu_y1,'b-',x,mu_y2,'r-')
legend = plt.legend([r'$\mu_{y1}$', r'$\mu_{y2}$'])
plt.grid()
```



```
[16]: div = mu_y1 + mu_y2
div[div==0] = 0.00001

y_hat = np.divide(np.multiply(mu_y1, y1) + np.multiply(mu_y2, y2), div )
plt.plot(x,y_hat,'b-',x,y,'r--')
```

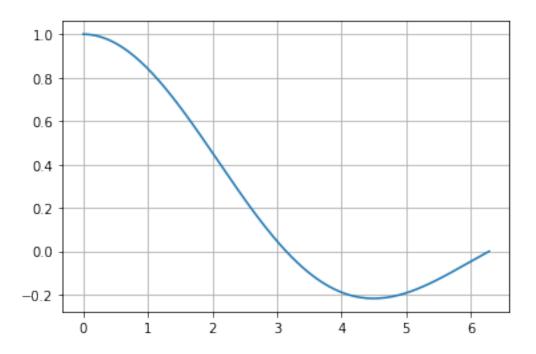
```
legend = plt.legend([r'$\hat{f}(x)$', r'$f(x)$'])
plt.grid()
```



```
[17]: mean_squared_error(list(y), list(y_hat))
```

[17]: 0.0060465477165923195

3 Questão 1 - Função Sinc



3.1 Mecanismo de Inferência de Mandani

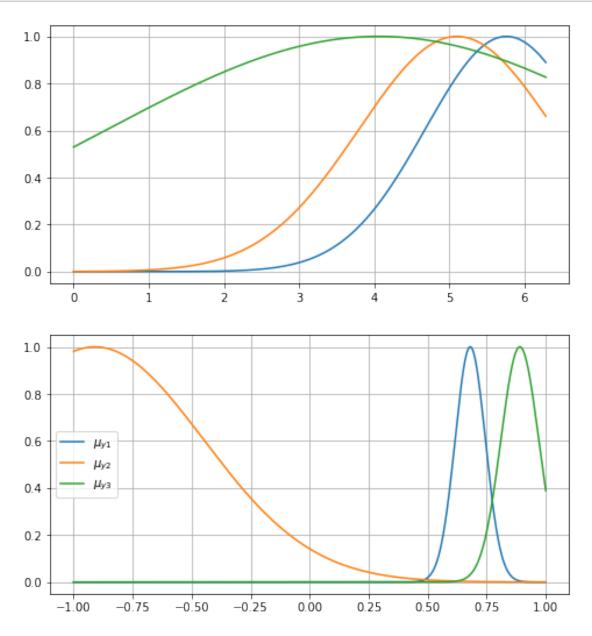
```
[19]: fig, (ax0, ax1) = plt.subplots(nrows=2, figsize=(8, 9))
     x = np.linspace(0.000001, 2*pi, 1000)
     y = np.linspace(-1, 1, 1000)
     y_real = np.sin(x)/x
     mu_x_1 = gaussmf(x, 5.76, 1.08)
     mu_x_2 = gaussmf(x, 5.1, 1.3)
     mu_x_3 = gaussmf(x, 4.06, 3.6)
     ax0.plot(x, mu_x_1,'-', x, mu_x_2,'-', x, mu_x_3,'-')
     legend = plt.legend([r'$\mu_{x1}$', r'$\mu_{x2}$', r'$\mu_{x3}$',__
     r'\mu_{x4}$', r'$\mu_{x5}$'])
     ax0.grid()
    mu_y_1 = gaussmf(y, 0.68, 0.064)
     mu_y_2 = gaussmf(y, -0.91, 0.46)
     mu_y_3 = gaussmf(y, 0.89, 0.08)
     ax1.plot(y, mu_y_1,'-', y, mu_y_2,'-', y, mu_y_3,'-')
     legend = plt.legend([r'$\mu_{y1}$', r'$\mu_{y2}$', r'$\mu_{y3}$'])
     ax1.grid()
     y_hat = []
     for xi in x:
         # Activation of our fuzzy membership functions at these values.
         x1 = fuzz.interp_membership(x, mu_x_1, xi)
```

```
x2 = fuzz.interp_membership(x, mu_x_2, xi)
x3 = fuzz.interp_membership(x, mu_x_3, xi)

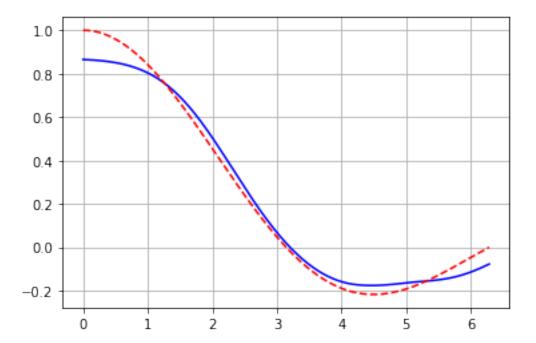
# Rule application
y_1 = np.fmin(x1, mu_y_1)
y_2 = np.fmin(x2, mu_y_2)
y_3 = np.fmin(x3, mu_y_3)

# Aggregate all three output membership functions together
aggregated = np.fmax(y_1, np.fmax(y_2, y_3))

# Calculate defuzzified result
y_hat.append(fuzz.defuzz(y, aggregated, 'centroid'))
```



```
[20]: plt.plot(x, y_hat, 'b', x, y_real, 'r--') plt.grid()
```

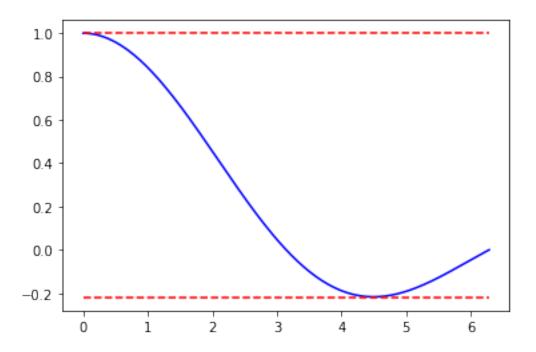


```
[21]: mean_squared_error(y_real, y_hat)
```

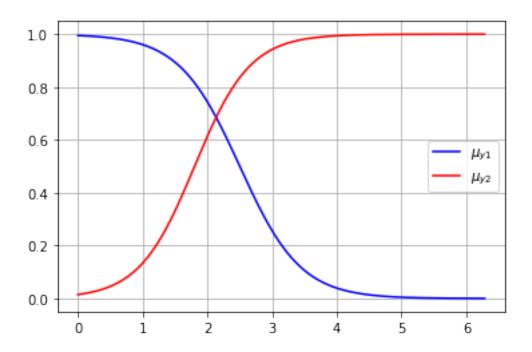
[21]: 0.0029259400791651355

3.2 Mecanismo de Inferência de Sugeno (Constante)

```
[22]: x = np.linspace(0.0001,2*pi,200)
y = np.linspace(-1, 1, 200)
y_real = np.sin(x)/x
y1 = np.ones(len(x))*1
y2 = np.ones(len(x))*(-0.22)
plt.plot(x,y_real,'b-',x,y1,'r--', x, y2, 'r--')
```

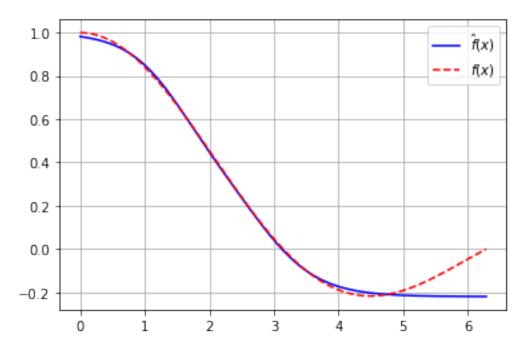


```
[23]: x = np.linspace(0.0001,2*pi,500)
y = np.sin(x)/x
y1 = np.ones(500)*(1)
y2 = np.ones(500)*(-0.22)
mu_y1 = sigmf(x, 2.5, -2.13)
mu_y2 = sigmf(x, 1.8, 2.33)
#mu_y3 = gaussmf(x, v[4],v[5])
plt.plot(x,mu_y1,'b-',x,mu_y2,'r-')
legend = plt.legend([r'$\mu_{y1}\$', r'$\mu_{y2}\$'])
plt.grid()
```



```
[24]: div = mu_y1 + mu_y2
div[div==0] = 0.00001

y_hat = np.divide(np.multiply(mu_y1, y1) + np.multiply(mu_y2, y2), div )
plt.plot(x,y_hat,'b-',x,y,'r--')
legend = plt.legend([r'$\hat{f}(x)$', r'$f(x)$'])
plt.grid()
```



```
[25]: mean_squared_error(y, y_hat)
```

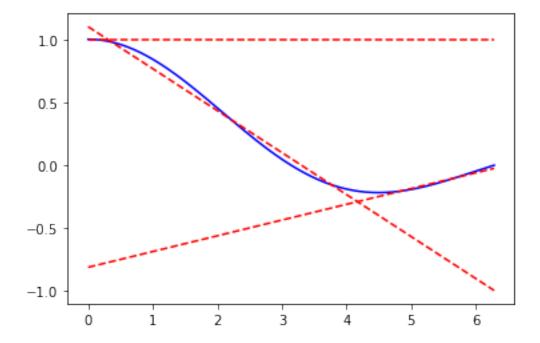
[25]: 0.003543258598444329

3.3 Mecanismo de Inferência de Sugeno (Linear)

3.3.1 3 Regras, pertinência tipo gaussiana:

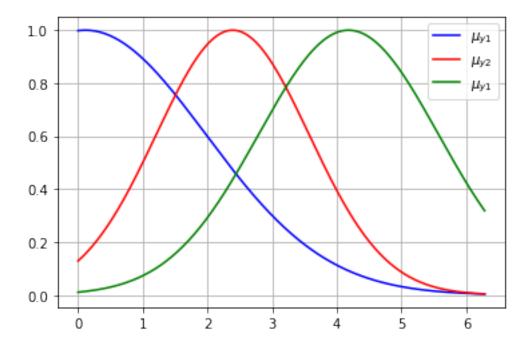
$$y_1 = 1,$$
 $\mu_{y1} = \operatorname{trimf}(x, -\pi, 0, \pi)$
 $y_2 = -\frac{x}{3} + 1.1,$ $\mu_{y2} = \operatorname{trimf}(x, 0, \pi, 2\pi)$
 $y_3 = \frac{x}{8} - 0.8,$ $\mu_{y3} = \operatorname{trimf}(x, \pi, 2\pi, 3\pi)$

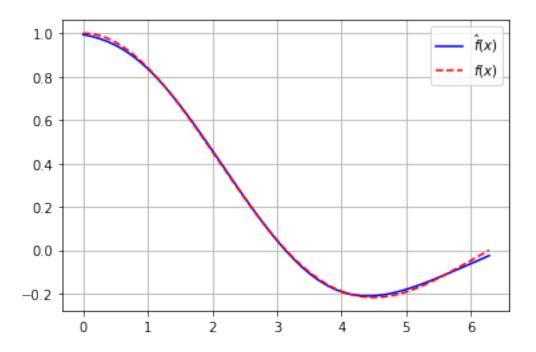
```
[26]: y1 = np.ones(len(x))
y2 = -x/3 + 1.1
y3 = x/8-0.81
plt.plot(x,y,'b-',x,y1,'r--', x, y2, 'r--', x, y3, 'r--')
```



```
[27]: mu_y1 = gaussmf(x, 0.115, 1.86)
mu_y2 = gaussmf(x, 2.39, 1.18)
mu_y3 = gaussmf(x, 4.18, 1.39)
```

```
plt.plot(x,mu_y1,'b-',x,mu_y2,'r-',x, mu_y3,'g-')
legend = plt.legend([r'$\mu_{y1}$', r'$\mu_{y2}$', r'$\mu_{y1}$'])
plt.grid()
```





```
[29]: mean_squared_error(list(y), list(y_hat))
```

[29]: 6.8602488937589e-05

4 Questão 2 - Classificação de Padrões

```
[30]: from sklearn.datasets import make_blobs

# centers of the blobs

centers = [(0,0), (-1,1), (1,1), (1,-1), (-1,-1)]

# create the sample

X, y = make_blobs(n_samples=500, n_features=2, cluster_std=0.2,___

-centers=centers, shuffle=False)

y[np.where(y==4)] = 5

y[np.where(y==3)] = 4

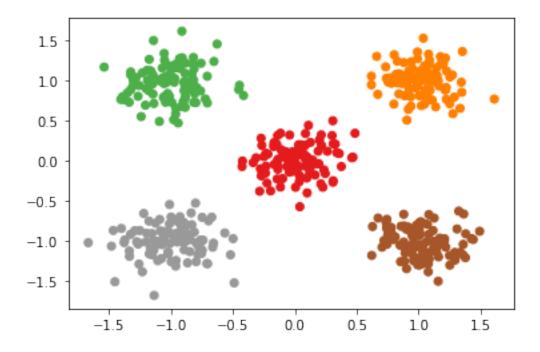
y[np.where(y==2)] = 3

y[np.where(y==1)] = 2

y[np.where(y==0)] = 1

plt.scatter(X[:,0], X[:,1], c=y-1, cmap="Set1")
```

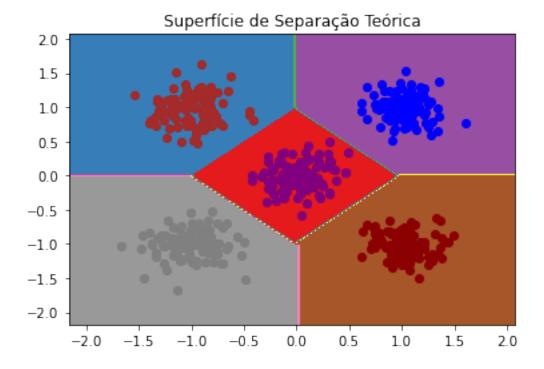
[30]: <matplotlib.collections.PathCollection at 0x7f64b32bf240>



```
[31]: import math
     def kgaussian(x, center, h):
         u = math.sqrt(sum((x - center)**2))/h
         K = 1/(math.sqrt(2*np.pi)*h) * math.exp(-0.5*(u**2))
         return K
[32]: fig = plt.figure()
     # decision surface for logistic regression on a binary classification dataset
     min1, max1 = X[:, 0].min()-0.5, X[:, 0].max()+0.5
     min2, max2 = X[:, 1].min()-0.5, X[:, 1].max()+0.5
     # define the x and y scale
     x1grid = np.arange(min1, max1, 0.05)
     x2grid = np.arange(min2, max2, 0.05)
     # create all of the lines and rows of the grid
     xx, yy = np.meshgrid(x1grid, x2grid)
     # flatten each grid to a vector
     r1, r2 = xx.flatten(), yy.flatten()
     r1, r2 = r1.reshape((len(r1), 1)), r2.reshape((len(r2), 1))
     # horizontal stack vectors to create x1,x2 input for the model
     grid = np.hstack((r1,r2))
     # make predictions for the grid
     y_hat = []
     centers = [[0,0], [-1,1], [1,1], [1,-1], [-1,-1]]
     for x in grid:
         gaussian = []
         for center in centers:
             gaussian.append(kgaussian(x, center, 0.2))
```

```
y_hat.append(np.argmax(gaussian))
y_hat=np.array(y_hat)
# reshape the predictions back into a grid
zz = y_hat.reshape(xx.shape)
# plot the grid of x, y and z values as a surface
plt.contourf(xx, yy, zz, cmap='Set1')
# create scatter plot for samples from each class
colors=['purple', "brown", 'blue', 'darkred', 'gray']
for class_value in [1, 2, 3, 4, 5]:
    # get row indexes for samples with this class
    row_ix = np.where(y == class_value)
    # create scatter of these samples
    plt.scatter(X[row_ix, 0], X[row_ix, 1], c=colors[class_value-1])
plt.title("Superfície de Separação Teórica")
```

[32]: Text(0.5, 1.0, 'Superfície de Separação Teórica')

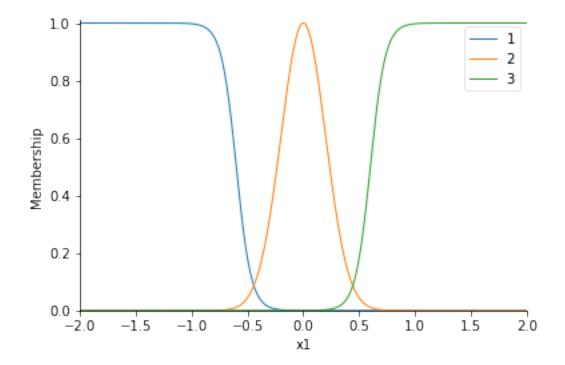


```
[33]: # inputs (Antecedents): x1, x2
# output (Consequents): y
x1 = ctrl.Antecedent(np.linspace(-2, 2, 600), 'x1')
x2 = ctrl.Antecedent(np.linspace(-2, 2, 600), 'x2')
y = ctrl.Consequent(np.linspace(1, 5, 600), 'y')
[34]: # Membership Functions
x1['1'] = fuzz.sigmf(x1.universe, -0.6, -15)
x1['2'] = fuzz.gaussmf(x1.universe, 0, 0.2)
```

```
x1['3'] = fuzz.sigmf(x1.universe, 0.6, 15)
x1.view()
```

/home/vitor/-/.virtualenvs/k36/lib/python3.6/site-packages/skfuzzy/control/fuzzyvariable.py:122: UserWarning: Matplotlib is currently using module://ipykernel.pylab.backend_inline, which is a non-GUI backend, so cannot show the figure.

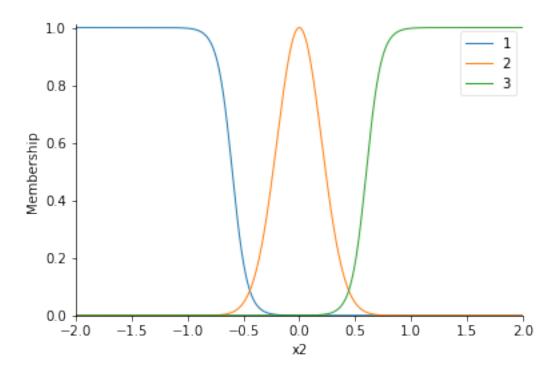
fig.show()



```
[35]: # Membership Functions
x2['1'] = fuzz.sigmf(x2.universe, -0.6, -15)
x2['2'] = fuzz.gaussmf(x2.universe, 0, 0.2)
x2['3'] = fuzz.sigmf(x2.universe, 0.6, 15)
x2.view()
```

/home/vitor/-/.virtualenvs/k36/lib/python3.6/site-packages/skfuzzy/control/fuzzyvariable.py:122: UserWarning: Matplotlib is currently using module://ipykernel.pylab.backend_inline, which is a non-GUI backend, so cannot show the figure.

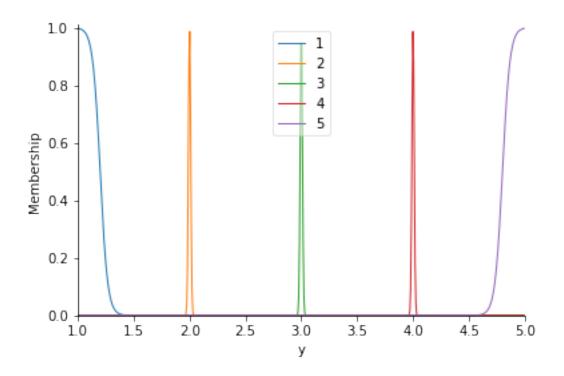
fig.show()



```
[36]: # Membership Functions
y['1'] = fuzz.sigmf(y.universe, 1.2, -30)
y['2'] = fuzz.gaussmf(y.universe, 2, 0.01)
y['3'] = fuzz.gaussmf(y.universe, 3, 0.01)
y['4'] = fuzz.gaussmf(y.universe, 4, 0.01)
y['5'] = fuzz.sigmf(y.universe, 4.8, 30)
y.view()
```

/home/vitor/-/.virtualenvs/k36/lib/python3.6/site-packages/skfuzzy/control/fuzzyvariable.py:122: UserWarning: Matplotlib is currently using module://ipykernel.pylab.backend_inline, which is a non-GUI backend, so cannot show the figure.

fig.show()



```
[37]: rule_1 = ctrl.Rule(x1['2'] & x2['2'], y['1'])
     rule_2 = ctrl.Rule(x1['1'] & x2['3'], y['2'])
     rule_3 = ctrl.Rule(x1['3'] & x2['3'], y['3'])
     rule_4 = ctrl.Rule(x1['3'] & x2['1'], y['4'])
     rule_5 = ctrl.Rule(x1['1'] & x2['1'], y['5'])
[38]: ctrl_ = ctrl.ControlSystem([rule_1, rule_2, rule_3, rule_4, rule_5])
     inf = ctrl.ControlSystemSimulation(ctrl_)
[39]: x_1 = np.linspace(-2, 2, 100)
     x_2 = np.linspace(-2, 2, 100)
[40]: def fun(X, Y):
         Z = []
         for x in X:
             for y in Y:
                 inf.input['x1'] = x
                 inf.input['x2'] = y
                 inf.compute()
                 Z.append(inf.output['y'])
         return Z
[41]: X, Y = np.meshgrid(x_1, x_2)
     zs = np.array(fun(x_1, x_2))
     zs = np.around(zs, 0)
     Z = zs.reshape(X.shape)
     fig = plt.figure()
```

```
ax = fig.add_subplot(111)
plt.contourf(X, Y, Z, cmap='Set1')
```

[41]: <matplotlib.contour.QuadContourSet at 0x7f64b41b6940>

