

## CMake Warning during colcon built #3269



Answered by zulfaqar-azmi-t4

AviBen96 asked this question in Q&A



X AviBen96 on Feb 12, 2023

edited ▼

Good afternoon,

I am switching from autoware.ai to autoware.universe.

I have several CMAKE Warnings during the built, I am unsure if I should consider them or not. Could someone explain me what it is about?

- --- stderr: ndt\_omp && livox\_tag\_filter
- \*\* WARNING \*\* io features related to openni will be disabled
- \*\* WARNING \*\* io features related to openni2 will be disabled
- \*\* WARNING \*\* io features related to pcap will be disabled
- \*\* WARNING \*\* io features related to png will be disabled
- \*\* WARNING \*\* io features related to libusb-1.0 will be disabled
- \*\* WARNING \*\* visualization features related to openni will be disabled
- \*\* WARNING \*\* visualization features related to openni2 will be disabled
- \*\* WARNING \*\* apps features related to openni will be disabled

--- stderr: tvm\_utility

CMake Warning at tvm\_utility-extras.cmake:58 (message):

Skipped download for yolo\_v2\_tiny (enable by setting

DOWNLOAD\_ARTIFACTS)

Call Stack (most recent call first):

CMakeLists.txt:53 (get\_neural\_network)

CMake Warning at CMakeLists.txt:90 (message):

No model is generated for

/home/avner/CARLA\_AUTOWARE\_project/autoware/src/universe/autoware.universe/common/tvm\_utility/test/yolo\_v2\_tiny,

skipping test

Category



Q&A

Labels

None yet

2 participants



- --- stderr: lidar\_apollo\_segmentation\_tvm
- \*\* WARNING \*\* io features related to openni will be disabled
- \*\* WARNING \*\* io features related to openni2 will be disabled
- \*\* WARNING \*\* io features related to pcap will be disabled
- \*\* WARNING \*\* io features related to png will be disabled
- \*\* WARNING \*\* io features related to libusb-1.0 will be disabled
- \*\* WARNING \*\* visualization features related to openni will be disabled
- \*\* WARNING \*\* visualization features related to openni2 will be disabled
- \*\* WARNING \*\* apps features related to openni will be disabled

CMake Warning at

/home/avner/CARLA\_AUTOWARE\_project/autoware/install/tvm\_utility/share/t vm\_utility/cmake/tvm\_utility-extras.cmake:58 (message):

Skipped download for baidu\_cnn (enable by setting

DOWNLOAD\_ARTIFACTS)

Call Stack (most recent call first):

CMakeLists.txt:34 (get\_neural\_network)

CMake Warning at CMakeLists.txt:83 (message):

Neural network not found, skipping package.

--- stderr: lidar\_apollo\_segmentation\_tvm\_nodes

CMake Warning at CMakeLists.txt:50 (message):

lidar\_apollo\_segmentation\_tvm not built, skipping package.

```
--- stderr: tier4_traffic_light_rviz_plugin
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreMemoryAllocatorConfig.h:32,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgrePrerequisites.h:315,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:37,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA AUTOWARE project/autoware
/src/universe/autoware.universe/common/tier4_traf
fic_light_rviz_plugin/src/traffic_light_publish_pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreAlignedAllocator.h:108:73: warning: extra ';'
[-Wpedantic]
108 | AlignedAllocator(const AlignedAllocator<U,
Alignment>& other) {};
| ^
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz common/display cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
```

```
/src/universe/autoware.universe/common/tier4_traf
fic_light_rviz_plugin/src/traffic_light_publish_pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h: In member function 'Ogre::Radian
Ogre::VectorBase<2, float>::angleTo(const
Vector2&) const':
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:770:16: warning: implicitly-declared
'constexpr Ogre::Radian::Radian(const
Ogre::Radian&)' is deprecated [-Wdeprecated-
copy]
770 | return angle;
| ^~~~
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:38,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
/src/universe/autoware.universe/common/tier4_traf
fic light rviz plugin/src/traffic light publish pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreMath.h:70:17: note: because 'Ogre::Radian'
has user-provided 'Ogre::Radian&
Ogre::Radian::operator=(const Ogre::Radian&)'
70 | Radian& operator = (const Radian&r) { mRad =
r.mRad; return *this; }
| ^~~~~
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
```

```
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
/src/universe/autoware.universe/common/tier4_traf
fic_light_rviz_plugin/src/traffic_light_publish_pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h: In member function
'Ogre::Quaternion Ogre::VectorBase<3,
float>::getRotationTo(const Vector3&, const
Vector3&) const':
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:835:32: warning: implicitly-
declared 'constexpr
Ogre::Quaternion::Quaternion(const
Ogre::Quaternion&)' is deprecated [-Wdeprecated-
copy]
835 | return Quaternion::IDENTITY;
| ^~~~~
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:39,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
/src/universe/autoware.universe/common/tier4_traf
fic light rviz plugin/src/traffic light publish pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreQuaternion.h:176:28: note: because
```

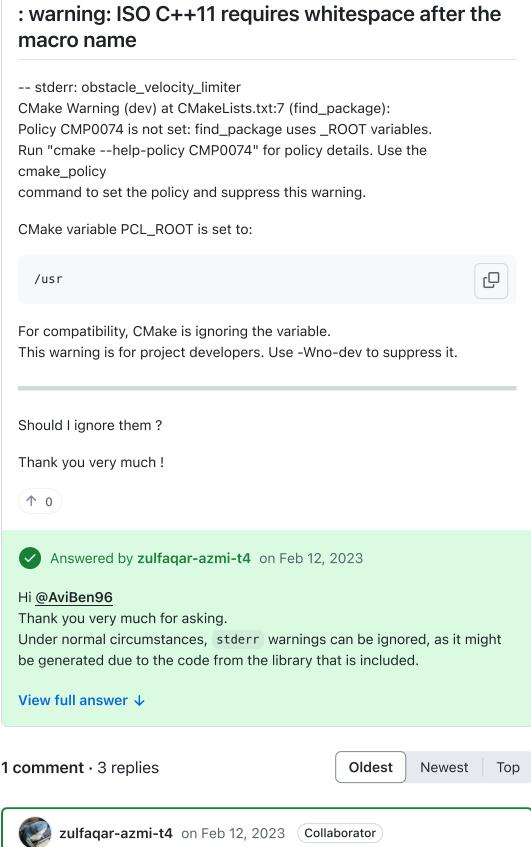
```
'Ogre::Quaternion' has user-provided
'Ogre::Quaternion& Ogre::Quaternion::operator=
(const Ogre::Quaternion&)'
176 | inline Quaternion& operator= (const
Quaternion& rkQ)
| ^~~~~~
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
/src/universe/autoware.universe/common/tier4_traf
fic_light_rviz_plugin/src/traffic_light_publish_pane
I.cpp:28:
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:853:16: warning: implicitly-declared
'constexpr Ogre::Quaternion::Quaternion(const
Ogre::Quaternion&)' is deprecated [-Wdeprecated-
copy]
853 | return q;
In file included from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector.h:39,
from
/opt/ros/galactic/opt/rviz_ogre_vendor/include/OGR
E/OgreVector3.h:1,
from
/opt/ros/galactic/include/rviz_common/frame_mana
ger_iface.hpp:45,
from
/opt/ros/galactic/include/rviz_common/display_cont
ext.hpp:42,
from
/home/avner/CARLA_AUTOWARE_project/autoware
/src/universe/autoware.universe/common/tier4_traf
```

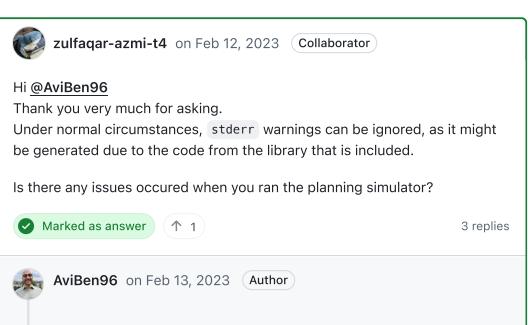
fic\_light\_rviz\_plugin/src/traffic\_light\_publish\_pane l.cpp:28:
/opt/ros/galactic/opt/rviz\_ogre\_vendor/include/OGR E/OgreQuaternion.h:176:28: note: because 'Ogre::Quaternion' has user-provided 'Ogre::Quaternion& Ogre::Quaternion::operator= (const Ogre::Quaternion&)'
176 | inline Quaternion& operator= (const Quaternion& rkQ)
|^~~~~~~

- --- stderr: elevation\_map\_loader
- \*\* WARNING \*\* io features related to openni will be disabled
- \*\* WARNING \*\* io features related to openni2 will be disabled
- \*\* WARNING \*\* io features related to pcap will be disabled
- \*\* WARNING \*\* io features related to png will be disabled
- \*\* WARNING \*\* io features related to libusb-1.0 will be disabled

Finished <<< elevation map loader [2min 40s] [Processing: accel\_brake\_map\_calibrator, behavior\_path\_planner, behavior\_velocity\_planner, control performance analysis, detection by tracker, image\_projection\_based\_fusion, obstacle\_velocity\_limiter, operation\_mode\_transition\_manager, planning\_debug\_tools, planning\_evaluator, tier4 debug tools, tier4 planning rviz plugin, trajectory\_follower\_nodes] --- stderr: image\_projection\_based\_fusion : warning: ISO C++11 requires whitespace after the macro name : warning: ISO C++11 requires whitespace after the macro name : warning: ISO C++11 requires whitespace after the

macro name





Thank you very much for your quick answer! So I should be able to safely ignore those 22 packages warning?

I am still on very basing uses but everything seems to build and work fine for the moment! Thank you:)



zulfaqar-azmi-t4 on Feb 14, 2023 (Collaborator)

So I should be able to safely ignore those 22 packages warning

Yes. It is safe to ignore them for normal use cases.

A few of these are compiler related warnings which warns about code quality etc.

We tried to reduced them on Autoware side by performing clang-tidy check etc.



AviBen96 on Feb 14, 2023 (Author)

Great thank you very much!

Answer selected by **zulfaqar-azmi-t4**