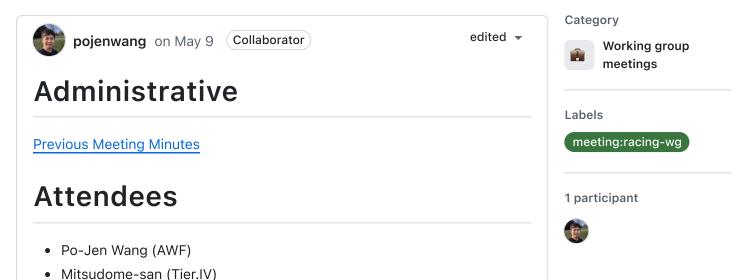


## 2024-05-09 Racing Working Group Meeting #4706

pojenwang started this conversation in Working group meetings



## **Topics**

Autonomous Karting Series (AKS) Competition

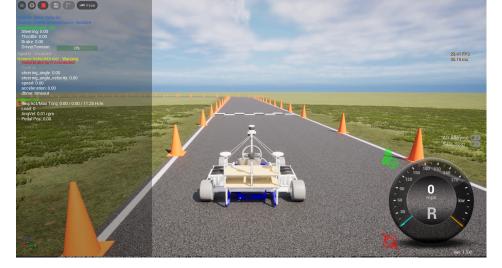
David Walmroth (Open AD Kit / Pix-Moving)

AKS competition website

Jack Silberman (UCSD)

Minutes: Po-Jen Wang

- The competition is coming up in less than two weeks. The team has been working hard preparing for the racing though there's still a list of tasks that need to be completed
- We spent a lot of effort making sure we comply with the safety requirements of the competition:
- 1. Remote Estop that applies max brake and cut power to the drivetrain
- 2. Estop triggered when RC controller disconnect
- 3. Deadman switch requirement was removed, this rule that requires active hold on a switch was not clear in the first place
- For the reactive category, track detection is achieved with vision-based grass and cone detection. It generates 2D Lidar format data that can be fused with Lidar data.
- Upgraded the grass field models in the simulator and now we are using the simulator to test the software pipeline for the reactive race



- Track detection demo on the AV4EV Sim
- We are working on the gap follower planner which shall be completed shortly.
- For the pre-mapped category, our current GNSS setup does not seem very reliable. We are experimenting with a <u>Fix-Position Vision RTK2</u> sensor. This sensor achieves localization with GNSS, IMU, and visual odometry
- Our backup solution is to utilize particle filter on the detected track boundary to achieve localization. Though we are missing the odom message and we are writing a driver for that
- We also plan on experimenting with the Eagleye package for GNSS sensor fusion though launching the package currently gives us an error

## Other topics:

AWF Work Group overview: https://autoware.org/join-a-work-group/



## 0 comments