


Split the planning/control packages into a separate container #5081

New issue

Closed

3 tasks

youtalk opened this issue on Aug 13 · 0 comments · Fixed by #5194



youtalk commented on Aug 13

Member

☐

Build only RViz plugin packages and split them into a separate container #5076

☐

Reorganize the autoware.universe/common packages #5077


☐

Reorganize the autoware.universe/evaluator packages #5078

Create a build stage that includes only the [autoware.universe/planning](#) and [autoware.universe/control](#) packages. This is part of the second step in the Discussions post. Since separating planning and control into different containers might introduce performance issues, they will temporarily remain in the same container.

<https://github.com/orgs/autowarefoundation/discussions/4661#discussioncomment-9995806>

Assignees

 youtalk

Labels

component:openadkit

type:containers

Projects

None yet

Milestone


No milestone


Development

Successfully merging a pull request may close this issue.

feat(docker): separation from universe...

autowarefoundation/autoware




 youtalk added


type:containers


component:openadkit

labels on Aug 13



 youtalk self-assigned this on Sep 6



 youtalk mentioned this issue on Sep 7

feat(docker): separation from universe-devel stage to universe-planning-control-devel stage #5194

Merged

5 tasks



 youtalk closed this as completed in #5194 on Sep 9

1 participant

