


Software WG Meeting 2024/07/16 #4994

mitsudome-r started this conversation in Working group meetings



mitsudome-r

on Jul 16

Maintainer

edited ▾

Administrative


- [Past Meeting Minutes](#)

Common Resources

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ONE!

Category




Working group meetings

Labels

meeting:software-wg

1 participant



Attendees

Chaired by Ryohsuke

R	Ryohsuke Mitsudome (Host, me)	 
AE	Ahmed Ebrahim	  
AP	Ata Parlar	 
BK	Berkay Karaman	 
BK	Berkay Karaman / Leo Drive	 
BN	Beyza Nur Kaya	 
BN	Beyza Nur Kaya	 
BN	Beyza Nur Kaya	 
BN	Beyza Nur Kaya	 
B	Bonolo	 
EF	Esteve Fernandez (TierIV)	 
JS	Jun SASAKI / TIER IV	 
KS	Khalil Selyan	 
LL	lucas liu(autocore.ai)	 
LC	Lukasz Chojnacki (Robotec.ai)	 
	M. Alptuğ Cirit	 
	M. Fatih Cirit	 
S	Sujay Amberkar	 
	Youtalk Kondo / TIER IV	 
iA	İsmet Atabay	 

Autware.Universe






- PRs [waiting for review](#) not in the current milestone/high priority.
- Autware.Universe reported [bugs](#) not in the current milestone/high priority.
- Autware [design discussions](#) and [demos](#)

Discussions

Announcements

Updates from developers

- Sujay:
 - [🔗 Add feature to spawn NPC from RVIZ AWSIM-Labs#65](#)
 - Initial implementation is done
 - The spawned object will only collide with ground and not with other objects
 - Berkay: Does it support interactive mode? -> No.
- Ahmed:
 - [🔗 \[Dense-Urban-ODD\] Intersection module is not triggered for low speed NPC autoware.universe#7080](#)
 - Discussed with Berkay and Soblin.
 - [🔗 fix\(min-velocity-map-based-prediction\): reduce min_velocity_for_map_based_prediction autoware_launch#994](#)
 - waiting for approval.
 - [@mitsudome-r](#) to write comment to [@kminoda](#)
 - [@ahmeddesokyebrahim](#) also will add background of the activity in the issue.
 - [🔗 \[Dense-Urban-ODD\] Improve cruise planner safe distance when cruising a front npc autoware.universe#7922](#)
 - We should talk in ODD WG & Planning WG about what would be the best criteria to evaluate the distance to the vehicle driving in front.
 - [🔗 \[Dense-Urban-ODD\] Improve cruise planner slowing down capabilities to overtaking NPC autoware.universe#7877](#)
 - Ahmed retest with updated scenario
- Ata
 - [🔗 Collect Urban Dataset for Autoware and Autoware Labs #4725](#)
 - Leo Drive is going to take another data with the same route.
 - He will continue working on LOAM localization Task 4,5
- Berkay
- [🔗 \[Dense-Urban-ODD\] Enhance Cruise Planner's Responsiveness to Other Road Users autoware.universe#7864](#)
 - Writing up the PR to present in the planning WG.
 - After the modification, is Autoware still able to stop for the vehicle that is decelerating instead of driving in constant velocity.
- Berkay wasn't able to reproduce the slow down issue that Fatih saw last week.
- Beyza
 - [🔗 Dynamic_obstacle_avoidance does not work stable autoware.universe#7689](#)
 - The issue is due to perception module generating predicted path at the centerline of the lane.

- Beyza will create an issue on prediction to generate a better predicted path for detected vehicles that drives with some offsets to the centerline.
- Esteve
 - Continue to work on nodes other than Perception modules
- Jun
 - Continue working on <https://github.com/orgs/autowarefoundation/discussions/4958>
 -  [\[Autoware Labs\] Dense Urban ODD - Reviewing and Tracking Failed Scenarios](#) autoware.universe#7485
- Khalil
 -  [Improve RViz UI - Adding 2D Minimap](#) autoware.universe#6815
 - Adding a fix to support route that goes beyond the visualized minimap tile.
- Lucas
 -  [Implementing BEVDet in Autoware](#) #4635
 - AutoCore will be training against TIER IV dataset and evaluate the performance
 - Investigated CUDA version. Right now they are using 11.6
 - We should test with CUDA 12.x
 - They will consider updating code to 12.3
 - <https://github.com/orgs/autowarefoundation/discussions/4611>
 - Created the repository for simpler sensor configuration
- Lukasz
 -  [feat: enable multi scene setup](#) AWSIM-Labs#96
- Alptug
 - Integrating VPP to AWSIM
 - mitsudome-r: Have you check the license term? -> <https://assetstore.unity.com/packages/tools/physics/vehicle-physics-pro-community-edition-153556>. It uses the standard Unity license so it should be okay with our usage.
 - Made fix on the delay with AWSIM when sensors are toggled.  [fix: lidar simulation timer synchronization](#) AWSIM-Labs#107
- Fatih
 - Continue working on the updates given last week
 - build-and-test-differential (cuda) is back to required again with no-cache.
- Ismet
 - Work on real vehicle testing
 - Ismet will create an issue on Autoware Labs

Distribution of new tasks

Action Items

- Developers to add their discussion items to the agenda for the next meeting
- Developers to share updates on their works in the next meeting

0 comments