

List of packages in reverse topological order:

package and namespace with
autoware_ autoware.universe#6817

build(static_centerline_generator): prefix

tier4_planning_launch

static_centerline_generator

- Fix(autoware_static_centerline_generator):
 remove prefix from topics and node
 names autoware.universe#7028
- behavior_velocity_planner
 - refactor(behavior_velocity_planner)!: prefix
 package and namespace with
 autoware_ autoware.universe#6693
- behavior_velocity_walkway_module
 - refactor(autoware_velocity_walkway_module
 prefix package with autoware_ and move code
 to the autoware
 namespace autoware.universe#7153
- behavior_velocity_run_out_module
 - refactor(autoware_velocity_run_out_module)
 prefix package with autoware_ and move code
 to the autoware
 namespace autoware.universe#7154
- behavior_path_external_request_lane_change_module
 - build(behavior_path_external_request_lane_change_module): prefix package and namespace with autoware_autoware.universe#6636
- behavior_path_avoidance_by_lane_change_module
 - refactor(behavior_path_avoidance_by_lane_change_module): prefix package and namespace with autoware_autoware.universe#6638
 - Duplicate:
 - \$\frac{\text{refactor(behavior_path_avoidance_by_lane_change_module)!: prefix package and namespace with autoware autoware.universe#7309
- tier4_control_launch
- behavior_velocity_virtual_traffic_light_module
 - refactor(autoware_velocity_virtual_traffic_lig ht_module): prefix package with autoware_ and move code to the autoware namespace autoware.universe#7155
- behavior_velocity_traffic_light_module
 - refactor(behavior_velocity_traffic_light_mod ule): prefix package and namespace with autoware autoware.universe#7162
- behavior_velocity_template_module
 - refactor(behavior_velocity_template_module
 prefix package and namespace with
 autoware_ autoware.universe#6639
- behavior_velocity_stop_line_module
 - refactor(behavior_velocity_stop_line_module
 prefix package and namespace with
 autoware_ autoware.universe#7285
- behavior_velocity_speed_bump_module

- refactor(autoware_behavior_velocity_speed_ bump_module): prefix package and namespace with autoware autoware.universe#7467
- behavior_velocity_out_of_lane_module
 - refactor(out_of_lane): remove from behavior_velocity autoware.universe#7359
- behavior_velocity_occlusion_spot_module
 - refactor(occlusion_spot): add autoware prefix autoware.universe#7357
 - fix(occlusion_spot_module): fix dependencies, docs, codeowners autoware.universe#7393
- behavior_velocity_no_stopping_area_module
 - refactor(no_stopping_area)!: add autoware prefix autoware.universe#7425
- behavior_velocity_no_drivable_lane_module
 - refactor(behavior_velocity_no_drivable_lane _module): prefix package and namespace with autoware autoware.universe#7469
- behavior_velocity_intersection_module
 - refactor(behavior velocity intersection)!:
 prefix package and namespace with
 autoware_ autoware.universe#7315
- behavior_velocity_dynamic_obstacle_stop_module
 - ! refactor(behavior_velocity_dynamic_obstacl e_stop_module): prefix package and namespace with autoware autoware.universe#7470
- behavior_velocity_detection_area_module
 - refactor(autoware_behavior_velocity_detection_area_module): prefix package and namespace with autoware autoware.universe#7466
- behavior_velocity_crosswalk_module
 - refactor(crosswalk)!: add autoware_ prefix autoware.universe#7407
- behavior_velocity_blind_spot_module
 - refactor(behavior_velocity_blind_spot_modul
 prefix package and
 nam... autoware.universe#7380
- behavior_path_start_planner_module
 - refactor(behavior_path_start_planner_module)!: prefix package and namespace with autoware autoware.universe#7352
- behavior_path_side_shift_module
 - refactor(behavior_path_side_shift_module)!:
 prefix package and namespace with
 autoware autoware.universe#7326
- behavior_path_lane_change_module
 - refactor(behavior_path_lane_change_module)!: prefix package and namespace with autoware autoware.universe#7370

behavior_path_goal_planner_module Prefactor(goal_planner): add autoware prefix autoware.universe#7420 behavior_path_static_obstacle_avoidance h chore(static_obstacle_avoidance, dynamic_obstacle_avoidance): rename avoidance package autoware.universe#7168 behavior_path_dynamic_obstacle_avoidance_module h chore(static_obstacle_avoidance, dynamic_obstacle_avoidance): rename avoidance package autoware.universe#7168 trajectory_follower_node tier4_perception_launch behavior_velocity_planner_common Prefactor(behavior_velocity_planner_common)!: prefix package and namespace with autoware autoware.universe#7314 behavior_path_sampling_planner_module li> refactor(behavior_path_sampling_planner_m odule): add autoware prefix autoware.universe#7392 behavior_path_planner li> refactor(behavior_path_planner): prefix autoware_ to behavior_path_planner package autoware.universe#7433 traffic_light_fine_detector tier4_simulator_launch tier4_localization_launch tier4_autoware_api_launch scenario_selector language
 language< and namespace with autoware_ autoware.universe#7379 sample_sensor_kit_launch pure_pursuit Prefactor(pure_pursuit): prefix package and namespace with autoware_ autoware.universe#7301 planning_validator li> refactor(planning_validator)!: prefix package and namespace with autoware autoware.universe#7320 pid_longitudinal_controller li> refactor(pid_longitudinal_controller)!: prefix package and namespace with autoware autoware.universe#7383 path smoother leading to the property of the propert and namespace with autoware autoware.universe#7381

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path_sampler
obstacle_velocity_limiter
obstacle_stop_planner
                land the property of t
                         prefix package and namespace with
                         autoware autoware.universe#7565
obstacle_cruise_planner
                % refactor(obstacle_cruise_planner)!: add
                          autoware_ prefix autoware.universe#7419
obstacle_avoidance_planner
mpc_lateral_controller

    refactor(mpc_lateral_controller,

                         trajectory_follower_node)!: prefix package and
                         namespace with
                         autoware autoware.universe#7306
motion_velocity_smoother
image_projection_based_fusion
                • % refactor(image_projection_based_fusion)!:
                         add package name prefix of
                         autoware_ autoware.universe#8162
freespace_planner
                land autowarerefactor(freespace_planner)!: add autoware
                         prefix autoware.universe#7376
detection_by_tracker
                leading to the property of the propert
                          namespace and directory
                         structure autoware.universe#7742
behavior_path_planner_common
                here(bpp): add prefix
                           autoware_ autoware.universe#7288
awsim_sensor_kit_launch
vehicle_cmd_gate
                % chore(vehicle_cmd_gate): add prefix
                         autoware_ to
                         vehicle_cmd_gate autoware.universe#7327
trajectory_follower_base
tracking_object_merger
                % refactor(tracking_object_merger)!: fix
                         namespace and directory
                         structure autoware.universe#7663
tier4_planning_rviz_plugin
tensorrt_yolox
surround_obstacle_checker
                li> refactor(surround_obstacle_checker)!: prefix
                         package and namespace with
                         autoware autoware.universe#7298
steer_offset_estimator
                h chore(steer_offset_estimator): add prefix
                          autoware_ to
```

steer_offset_estimator autoware.universe#7342

simple_planning_simulator			
✓ radar_object_tracker			
 refactor(radar_object_tracker)!: fix 			
namespace and directory			
structure autoware.universe#7658			
✓ radar_object_clustering			
 refactor(radar_object_clustering)!: fix 			
namespace and directory structure autoware.universe#7654			
predicted_path_checker			
pose_initializer			
 ∾ refactor(pose_initializer)!: prefix package and namespace with 			
autoware autoware.universe#8701			
planning_topic_converter			
○ % chore(autoware_planning_topic_converter):			
add prefix autoware_ autoware.universe#7296			
planning_test_utils			
planning_evaluator			
perception_online_evaluator			
path_distance_calculator			
Patri_uistance_calculator Prefactor(autoware_path_distance_calculator)			
: prefix package and namespace with			
autoware autoware.universe#8085			
operation_mode_transition_manager			
∘ % refactor(operation_mode_transition_manage			
r): prefix package and namespace with			
autoware_ autoware.universe#7291			
object_merger			
• % refactor(object_merger)!: fix namespace and			
directory structure autoware.universe#7642			
multi_object_tracker			
mission_planner			
• % refactor(mission_planner)!: add autoware			
prefix and namespace autoware.universe#7414			
based prediction autoware.universe#7391			
lidar_centerpoint			
✓ lane_departure_checker			
○ % refactor(lane_departure_checker)!: prefix			
package and namespace with			
autoware autoware.universe#7325			
frenet_planner			
<pre>external_cmd_converter</pre>			
∘ % refactor(external cmd converter)!: add			
autoware_ prefix autoware.universe#7361			
euclidean_cluster			
detected_object_validation			

default_ad_api		
control_validator		
∘ % refactor(control_validator)!: prefix package		
and namespace with		
autoware autoware.universe#7304		
control_performance_analysis		
common_sensor_launch		
cluster_merger		
 ► refactor(cluster_merger)!: fix namespace and directory structure autoware.universe#7738 		
bezier_sampler		
autonomous_emergency_braking		
◦		
prefix package and namespace with		
autoware_ autoware.universe#7294		
ar_tag_based_localizer		
accel_brake_map_calibrator		
• % refactor(accel_brake_map_calibrator)!: add		
autoware_ prefix autoware.universe#7351		
tier4_system_launch		
tier4_sensing_launch		
tier4_perception_rviz_plugin		
tier4_map_launch		
tier4_localization_rviz_plugin		
sampler_common		
<pre>raw_vehicle_cmd_converter</pre>		
package and namespace with		
autoware autoware.universe#7385		
pose_estimator_arbiterrefactor(pose_estimator_arbiter)!: prefix		
package and namespace with		
autoware autoware.universe#8386		
pacmod_interface		
occupancy_grid_map_outlier_filter		
∘		
: fix namespace and directory		
structure autoware.universe#7748		
obstacle_collision_checker		
object_recognition_utils		
◦ refactor(polar_grid): add autoware prefix to		
polar_grid autoware.universe#8945		
nebula_sensor_driver		
ndt_scan_matcher		
motion_utils		
• % refactor(universe_utils/motion_utils)!: add		
autoware namespace autoware.universe#7594		

 № refactor(motion_utils)!: add autoware prefix 		
and include dir autoware.universe#7539		
lidar_apollo_segmentation_tvm_nodes		
landmark_manager		
ground_segmentation		
• 🖁 🖁 refactor(ground_segmentation)!: fix		
namespace and directory		
structure autoware_launch#1044		
namespace and directory		
structure autoware.universe#7744		
global_parameter_loader		
package and namespace with		
autoware autoware.universe#9303		
freespace_planning_algorithms		
 refactor(freespace_planning_algorithms)!: add autoware prefix autoware.universe#7375 		
elevation_map_loader		
compare_map_segmentation? i refactor(autoware_compare_map_segmentat		
ion): prefix package and namespace with		
autoware autoware.universe#7592		
yabloc_pose_initializer		
yabloc_particle_filter		
yabloc_image_processing		
vehicle_info_util		
traffic_light_recognition_marker_publisher		
○ 『↑ refactor(traffic_light_recognition_marker_pu		
blisher): prefix package and namespace with		
autoware autoware.universe#9305		
traffic_light_occlusion_predictor		
traffic_light_map_based_detector		
tier4_vehicle_rviz_plugin		
tier4_system_rviz_plugin		
tier4_control_rviz_plugin		
tier4_automatic_goal_rviz_plugin		
system_monitor		
system_error_monitor		
simple_object_merger		
○		
• № retactor(simple_object_merger)!: tix namespace and directory structure		
autoware.universe#7700		
shape_estimation		
route_handler		
─ radar_tracks_msgs_converter		
○ % refactor(radar_fusion_to_detected_object)!:		
fix namespace and directory		

structure autoware.universe#7650		
✓ radar_static_pointcloud_filter		
 refactor(radar_scan_to_pointcloud2, 		
radar_static_pointcloud_filter,		
radar_threshold_filter)!: add package name		
<pre>prefix of autoware_ autoware.universe#8132</pre>		
<pre>radar_fusion_to_detected_object</pre>		
◦ refactor(radar_fusion_to_detected_object)!:		
fix namespace and directory		
structure autoware.universe#7650		
<pre>radar_crossing_objects_noise_filter</pre>		
 lefactor(radar_crossing_objects_noise_filter_ 		
)!: fix namespace and directory		
structure autoware.universe#7649		
probabilistic_occupancy_grid_map		
 refactor(probabilistic_occupancy_grid_map, 		
occupancy_grid_map_outlier_filter): add		
autoware_ prefix to package		
name autoware.universe#8183		
pose_instability_detector		
refactor(pose_instability_detector)!: prefix		
package and namespace with		
autoware autoware.universe#8568		
pointcloud_preprocessor		
objects_of_interest_marker_interface		
refactor(objects_of_interest_marker_interfac		
e)!: prefix package and namespace with		
autoware autoware.universe#7413		
object_velocity_splitter		
• % refactor(object_velocity_splitter)!: fix		
namespace and directory structure autoware.universe#7646		
nebula_tests		
nebula_examples		
map_projection_loader		
<pre> map_projection_loader</pre>		
 map_projection_loader refactor(map_projection_loader)!: prefix package and namespace with 		
 map_projection_loader refactor(map_projection_loader)!: prefix package and namespace with 		
 map_projection_loader ∘ № refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader 		
 map_projection_loader refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util 		
 ✓ map_projection_loader ○ № refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util localization_evaluator 		
 map_projection_loader ∘ № refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util localization_evaluator localization_error_monitor 		
 ✓ map_projection_loader ○ % refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util localization_evaluator ✓ localization_error_monitor ○ % refactor(localization_error_monitor)!: prefix 		
 ✓ map_projection_loader refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 □ map_loader □ localization_util □ localization_evaluator ✓ localization_error_monitor refactor(localization_error_monitor)!: prefix package and namespace with 		
 ✓ map_projection_loader ○ % refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util localization_evaluator ✓ localization_error_monitor ○ % refactor(localization_error_monitor)!: prefix package and namespace with autoware autoware.universe#8423 		
 map_projection_loader % refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 map_loader localization_util localization_evaluator localization_error_monitor % refactor(localization_error_monitor)!: prefix package and namespace with autoware autoware.universe#8423 lidar_centerpoint_tvm lidar_apollo_segmentation_tvm 		
<pre>map_projection_loader</pre>		

interpolation		
 ⋄ refactor(autoware_interpolation): prefix 		
package and namespace with		
autoware autoware.universe#8088		
imu_corrector		
image_diagnostics		
◦		
name prefix of		
autoware_ autoware.universe#8130		
gyro_odometer		
 refactor(gyro_odometer)!: prefix package 		
and namespace with		
autoware autoware.universe#8340		
grid_map_utils		
and namespace autoware.universe#7487		
goal_distance_calculator		
package and namespace with		
autoware autoware.universe#9172		
gnss_poser		
 chore(gnss_poser): add autoware prefix to gnss_poser autoware.universe#8323 		
geo_pose_projector		
fault_injection		
<pre>external_cmd_selector</pre>		
 № refactor(external_cmd_selector): prefix 		
package and namespace with		
au autoware.universe#7384		
ekf_localizer		
dummy_perception_publisher		
dummy_diag_publisher		
detected_object_feature_remover		
 refactor(detected_object_feature_remover)!: 		
fix namespace and directory		
structure autoware.universe#7739		
crosswalk_traffic_light_estimator		
○		
add autoware_ prefix autoware.universe#7365		
awapi_awiv_adapter		
ad_api_adaptors		
yabloc_common		
vehicle_velocity_converter		
<pre>traffic_light_visualization</pre>		
 refactor(traffic_light_*)!: add package name 		
prefix of autoware_ autoware.universe#8159		
traffic_light_utils		
 refactor(traffic_light_*)!: add package name 		
<pre>prefix of autoware_ autoware.universe#8159</pre>		

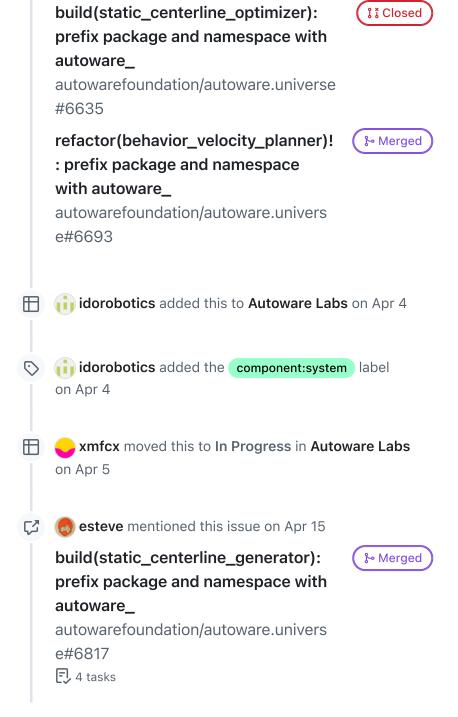
<pre>traffic_light_multi_camera_fusion</pre>			
<pre>prefix of autoware_ autoware.universe#8159</pre>			
traffic_light_classifier			
 refactor(traffic_light_*)!: add package name 			
<pre>prefix of autoware_ autoware.universe#8159</pre>			
<pre>traffic_light_arbiter</pre>			
 refactor(traffic_light_*)!: add package name 			
<pre>prefix of autoware_ autoware.universe#8159</pre>			
tier4_traffic_light_rviz_plugin			
tier4_state_rviz_plugin			
tier4_camera_view_rviz_plugin			
tier4_calibration_rviz_plugin			
tier4_autoware_utils ✓ tier4_autoware_utils			
tier4_autoware_utils autoware.universe#7538			
tier4_auto_msgs_converter			
tier4_adapi_rviz_plugin			
shift_decider			
◦			
namespace with			
autoware_ autoware.universe#7310			
nebula_ros			
mrm_handler			
Thirm_narialer			
man tf generator			
map_tf_generator o % refactor(map_tf_generator)!: prefix package			
 ◦ refactor(map_tf_generator)!: prefix package and namespace with 			
 refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 			
o № refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 map_height_fitter			
o refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 ■ map_height_fitter o refactor(map_projection_loader)!: prefix			
o № refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 map_height_fitter			
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o lanelet2_extension_python o lanelet2_extension_python o lanelet2_extension_python o lanelet2_map_projection_louder)!: prefix package and namespace with python o lanelet2_map_preprocessor o lanelet2_extension_python			
o			
 refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 map_height_fitter refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 lanelet2_map_preprocessor lanelet2_extension_python joy_controller refactor(joy_controller)!: prefix package and namespace with autoware autoware.universe#7382 geography_utils 			
o			
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o			
 refactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 map_height_fitter refactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 lanelet2_map_preprocessor lanelet2_extension_python joy_controller refactor(joy_controller)!: prefix package and namespace with autoware autoware.universe#7382 geography_utils refactor(geography_utils): prefix package and namespace with autoware autoware.universe#7790 emergency_handler 			
o Prefactor(map_tf_generator)!: prefix package and namespace with autoware autoware.universe#8422 map_height_fitter o Prefactor(map_projection_loader)!: prefix package and namespace with autoware autoware.universe#8420 lanelet2_map_preprocessor lanelet2_extension_python joy_controller o Prefactor(joy_controller)!: prefix package and namespace with autoware autoware.universe#7382 geography_utils o Prefactor(geography_utils): prefix package and namespace with autoware autoware.universe#7790 emergency_handler eagleye_rt			
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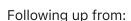
bytetrack		
automatic_pose_initializer		
✓ twist2accel		
 refactor(twist2accel)!: prefix package and 		
namespace with		
autoware autoware.universe#8299		
tier4_vehicle_msgs		
tier4_perception_msgs		
tier4_api_msgs		
tensorrt_classifier		
rtc_manager_rviz_plugin		
object_range_splitter		
• % refactor(object_range_splitter)!: fix		
namespace and directory structure autoware.universe#7644		
nebula_hw_interfaces		
mrm_emergency_stop_operator		
mrm_comfortable_stop_operator		
mission_planner_rviz_plugin		
lanelet2_extension		
hazard_status_converter		
fake_test_node		
external_velocity_limit_selectorchore(autoware_external_velocity_limit_sele		
ctor): add prefix		
autoware_ autoware.universe#7295		
eagleye_navigation		
<pre>eagleye_geo_pose_fusion</pre>		
eagleye_fix2kml		
diagnostic_graph_aggregator		
component_state_monitor		
component_interface_utils		
component_interface_tools		
common_awsim_sensor_launch		
yabloc_monitor		
velodyne_monitor		
vehicle_door_simulator		
tvm_utility		
Refactor(tvm_utility) prefix package and		
namespace with		
autoware autoware.universe#9241		
tree_structured_parzen_estimator		
topic_state_monitor		
time_utils		
◦ refactor(time_utils): prefix package and		
namespace with autoware autoware.universe#9173		

tier4_vehicle_launch
tier4_target_object_type_rviz_plugin
tier4_system_msgs
tier4_simulated_clock_rviz_plugin
tier4_screen_capture_rviz_plugin
tier4_planning_msgs
tier4_pcl_extensions
tier4_metrics_rviz_plugin
tier4_logging_level_configure_rviz_plugin
tier4_hmi_msgs
tier4_nm_msgs tier4_debug_rviz_plugin
tier4_datetime_rviz_plugin
tier4_control_msgs
tier4_api_utils
stop_filter
 refactor(stop_filter): prefix package and namespace with
autoware autoware.universe#7789
signal_processing
 ◇ 🏲 refactor(signal_processing): prefix package
and namespace with
autoware autoware.universe#8541
rtklib_bridge
✓ rtc_replayer
 refactor(rtc_replayer): prefix rtc
replayer autoware_tools#37
✓ rtc_interface
 refactor(rtc_interface)!: prefix package and
namespace with autoware autoware.universe#7321
✓ radar_tracks_noise_filter refactor(radar_tracks_msgs_converter,
simple_object_merger,
radar_tracks_noise_filter)!: add package name
prefix of autoware_ autoware.universe#8173
<pre>radar_threshold_filter</pre>
 refactor(radar_scan_to_pointcloud2,
radar_static_pointcloud_filter,
radar_threshold_filter)!: add package name
<pre>prefix of autoware_ autoware.universe#8132</pre>
✓ radar_scan_to_pointcloud2
 refactor(radar_scan_to_pointcloud2, radar_static_pointcloud_filter,
radar_static_pointeloud_intel, radar_threshold_filter)!: add package name
prefix of autoware_ autoware.universe#8132
 refactor(qp_interface): prefix package and
namespace with
autoware autoware.universe#9236

pose2twist		
◦ refactor(pose2twist)!: prefix package and		
namespace with		
autoware autoware.universe#8347		
polar_grid		
 refactor(polar_grid): add autoware prefix to polar_grid autoware.universe#8945 		
perception_utils		
osqp_interfacerefactor(osqp_interface): added autoware		
prefix to osqp_interface autoware.universe#8958		
nebula_decoders		
☑ livox_tag_filter		
** refactor(livox_tag_filter): prefix package and		
namespace with		
autoware autoware.universe#7788		
kalman_filter		
◦ refactor(kalman_filter): prefix package and		
namespace with		
autoware autoware.universe#7787		
✓ image_transport_decompressor○		
decompressor/autoware		
prefix autoware.universe#8197		
glog_component		
and namespace with		
autoware autoware.universe#9302		
agleye_msgs		
duplicated_node_checker		
dummy_infrastructure		
diagnostic_converter		
cuda_utils		
◦		
namespace with		
autoware autoware.universe#9171		
boost_udp_driver		
boost_serial_driver		
bluetooth_monitor		
bag_time_manager_rviz_plugin		
ad_api_visualizers		
vls_description		
tier4_v2x_msgs		
tier4_simulation_msgs		
tier4_rtc_msgs		
tier4_map_msgs		
tier4_localization_msgs		
tier4_external_api_msgs		

tier4_debug_msgs	
☐ tamagawa_imu_driver	
sample_vehicle_launch	
sample_vehicle_description	
sample_sensor_kit_description	
rtklib_msgs	
☐ robosense_msgs	
☐ radar_description	
pointcloud_to_laserscan	
pandar_msgs	
pandar_description	
nebula_common	
ndt_omp	
o : refactor(ndt_omp): prefix with	
autoware_ tier4/ndt_omp#68	
☐ mussp	
☐ Ilh_converter	
☐ livox_description	
individual_params imu_description eagleye_tf eagleye_coordinate eagleye_can_velocity_converter camera_description boost_tcp_driver boost_io_context awsim_sensor_kit_description	
velodyne_description	
tensorrt_common	
morai_msgs	
heaphook	
R esteve self-assigned this on Mar 27	
This was referenced on Mar 27	
C++ code should be in the autoware	
namespace #4117	
build(behavior_path_external_reque st_lane_change_module): prefix package and namespace with autoware_ autowarefoundation/autoware.univers	% Merged
e#6636	





- https://github.com/orgs/autowarefoundation/discussion s/4097#discussioncomment-8384169
 - autoware_package_name/include/autoware/packag e_name
- build(static_centerline_generator): prefix package and namespace with autoware_ autoware.universe#6817 (comment)

We should prefix the package folder names with autoware_ too.

The package name in the package.xml file should match its parent folder.

I might have missed something too, open to discussion.



esteve commented on May 2

Contributor (Author)

@xmfcx I've been waiting for feedback from the TierIV engineers regarding renaming the folders. @mitsudome-r do you have any updates? Thanks.



xmfcx commented on May 2 • edited ▼

Contributor

I would like to change it and see the response in this case. And solve the issues after they arise.

main branch is a development branch and this is expected.



mitsudome-r commented on May 7

Member

I think we can move on with changing the package folder name as well.

However, we did have some concerns about the changing the package names & include folder structure for the packages in autoware_common repository and also the packages with tier4_ prefix.

https://github.com/autowarefoundation/autoware_common



This was referenced on May 7

refactor(behavior_velocity_template _module): prefix package and



namespace with autoware_

autowarefoundation/autoware.univers e#6639

refactor(behavior_path_avoidance_ by_lane_change_module): prefix package and namespace with autoware_

№ Merged

autowarefoundation/autoware.univers e#6638





xmfcx mentioned this issue on May 8

feat: update the naming rules for directories and classes

autowarefoundation/autowaredocumentation#547 4 tasks

Merged

This was referenced on May 28

refactor(autoware_velocity_walkway _module): prefix package with autoware_ and move code to the autoware namespace

autowarefoundation/autoware.univers e#7153

refactor(autoware_velocity_run_out _module): prefix package with autoware_ and move code to the autoware namespace

autowarefoundation/autoware.univers e#7154

refactor(autoware_velocity_virtual_t raffic_light_module): prefix package with autoware_ and move code to the autoware namespace

autowarefoundation/autoware.univers e#7155

refactor(behavior_velocity_traffic_li ght_module): prefix package and namespace with autoware autowarefoundation/autoware.univers

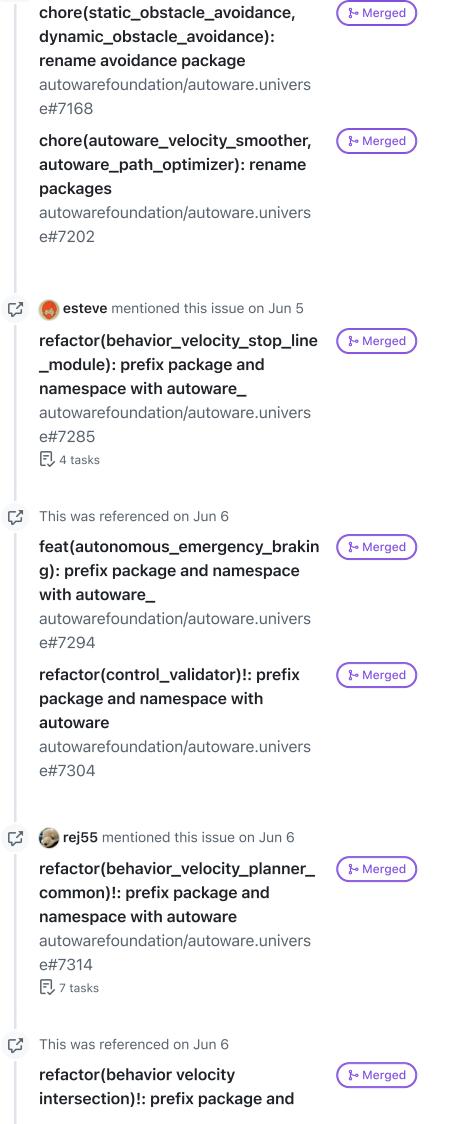
Merged

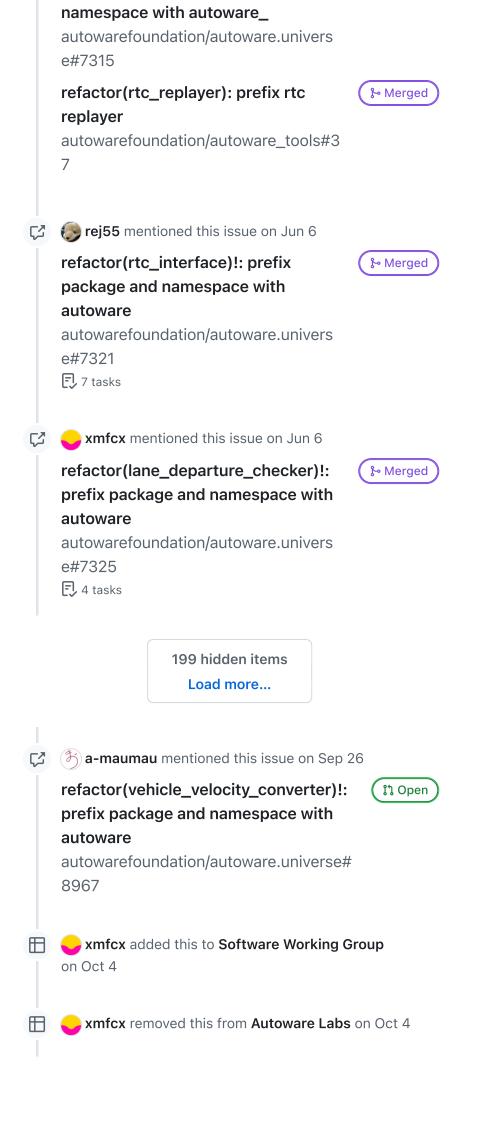
№ Merged

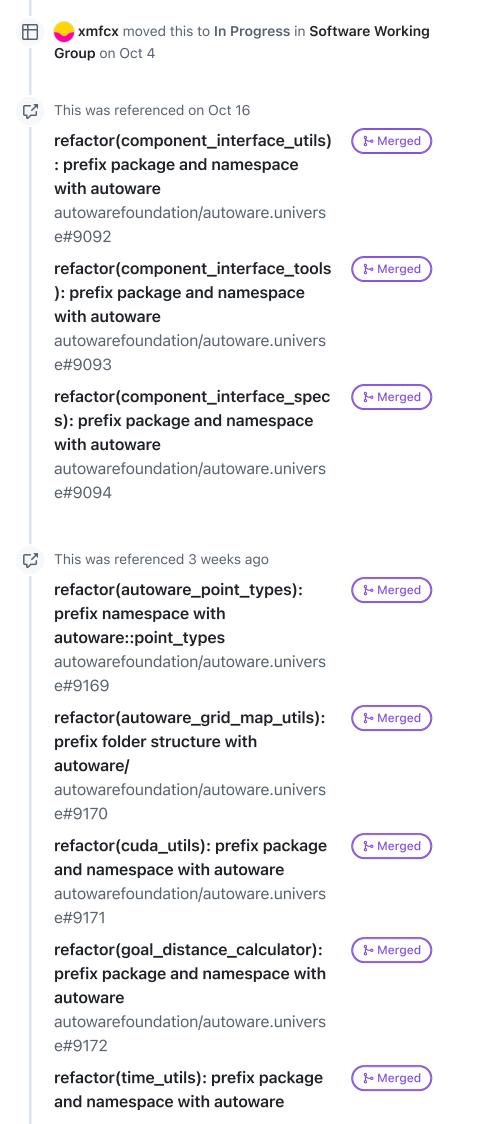
Merged

№ Merged

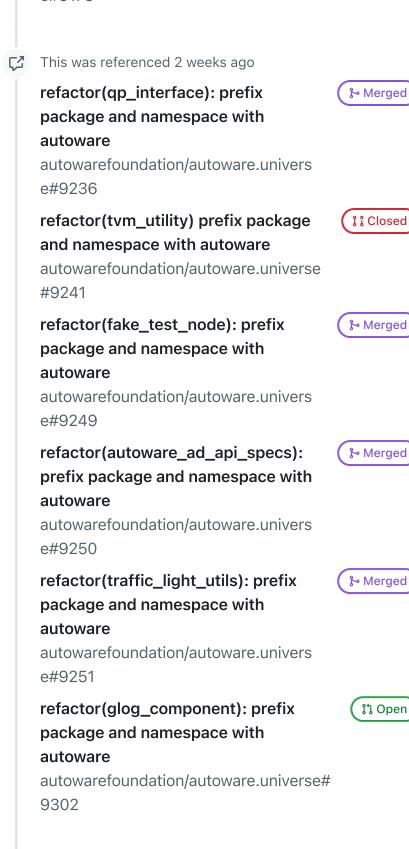
e#7162







autowarefoundation/autoware.univers e#9173



This was referenced last week

refactor(global_parameter_loader): prefix package and namespace with autoware

[] Draft

autowarefoundation/autoware.universe# 9303

refactor(traffic_light_recognition_mar ker_publisher): prefix package and

្សែ Open

namespace with autoware

autowarefoundation/autoware.universe# 9305



xmfcx commented 3 days ago

Contributor

@esteve recently I've came across this file:

https://github.com/autowarefoundation/autoware/blob/0dd0 8838d0ebc154bf698ee1b8d157a456eb044f/docker/Docke rfile

It is referencing some packages by the names, when prefixing, you might need to create a PR against autoware repository as well.

It has recently caused an issue here:

• % fix(docker): add autoware prefix to map_loader #5451



esteve commented 3 days ago

Contributor Author

@xmfcx thanks, I hadn't seen that file.





This was referenced yesterday

refactor(glog_component): prefix package and namespace with autoware

፤ጎ Open

autowarefoundation/autoware_tools#15 8

refactor(glog_component): prefix package and namespace with autoware

፤ን Open

autowarefoundation/awsim_labs_sensor _kit_launch#10

refactor(glog_component): prefix package and namespace with autoware

፤ን Open

autowarefoundation/sample_sensor_kit_ launch#110

refactor(glog_component): prefix package and namespace with autoware



autowarefoundation/single_lidar_sensor _kit_launch#4 refactor(glog_component): prefix ፤ጎ Open package and namespace with autoware autowarefoundation/autoware_launch#1 245 refactor(global_parameter_loader): ፤ጎ Open prefix package and namespace with autoware tier4/pacmod_interface#87 refactor(global_parameter_loader): ፤ጎ Open prefix package and namespace with autoware autowarefoundation/autoware_tools#15 9

፤ጎ Open

refactor(global_parameter_loader): prefix package and namespace with autoware

autowarefoundation/autoware_launch#1 246