

Split the sensing/perception packages into a separate container #5079


New issue

Closed

3 tasks

Tracked by #5082

youtalk opened this issue on Aug 13 · 0 comments · Fixed by #5164



youtalk commented on Aug 13

Member

☐

Build only RViz plugin packages and split them into a separate container #5076

☐

Reorganize the autoware.universe/common packages #5077


☐

Reorganize the autoware.universe/evaluator packages #5078

Create a build stage that includes only the [autoware.universe/sensing](#) and [autoware.universe/perception](#) packages. This is part of the second step in the Discussions post. Since separating sensing and perception into different containers might introduce performance issues, they will temporarily remain in the same container.

<https://github.com/orgs/autowarefoundation/discussions/4661#discussioncomment-9995806>

Assignees

 youtalk

Labels

component:openadkit

type:containers

Projects

None yet

Milestone


No milestone

Development

Successfully merging a pull request may close this issue.

feat(docker): separation from autowa...
autowarefoundation/autoware


 youtalk added type:containers component:openadkit labels on Aug 13

 youtalk mentioned this issue on Aug 13

Build the CUDA packages with the sensing / perception container as the parent #5082

1 task

Closed

 youtalk mentioned this issue on Sep 3

feat(docker): separation from autoware-universe stage to

Merged

1 participant



autoware-universe-sensing-
perception stage #5164

 4 tasks



 **youtalk** self-assigned this on Sep 3



 **youtalk** closed this as completed in [#5164](#) on Sep 4
