Split the `planning/control` packages into a separate container #5081

New issue

⊘ Closed   🗒 3 tasks   **youtalk** opened this issue on Aug 13 · 0 comments · Fixed by #5194

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youtalk commented on Aug 13   `Member`

- ☐ ⊙ **Build only RViz plugin packages and split them into a separate container** #5076
- ☐ ⊙ **Reorganize the `autoware.universe/common` packages** #5077
- ☐ ⊙ **Reorganize the `autoware.universe/evaluator` packages** #5078

Create a build stage that includes only the autoware.universe/planning and autoware.universe/control packages. This is part of the second step in the Discussions post. Since separating planning and control into different containers might introduce performance issues, they will temporarily remain in the same container.

https://github.com/orgs/autowarefoundation/discussions/4661#discussioncomment-9995806

🏷 **youtalk** added `type:containers` `component:openadkit` labels on Aug 13

👤 **youtalk** self-assigned this on Sep 6

↗ **youtalk** mentioned this issue on Sep 7

feat(docker): separation from `universe-devel` stage to `universe-planning-control-devel` stage #5194   ⑂ Merged

🗒 5 tasks

⊘ **youtalk** closed this as completed in #5194 on Sep 9

Assignees

👤 youtalk

Labels

`component:openadkit`
`type:containers`

Projects

None yet

Milestone

No milestone

Development

Successfully merging a pull request may close this issue.

⑂ **feat(docker): separation from `univer…`**
autowarefoundation/autoware

1 participant

👤