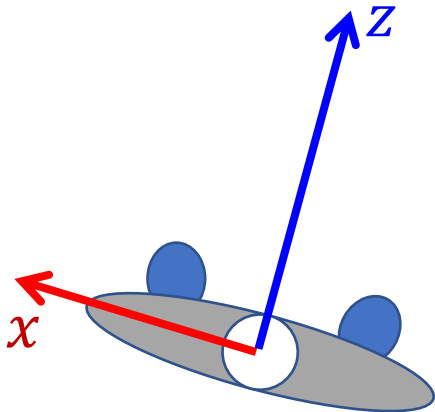


$$R = \theta \mathbf{e}_y$$

$$\mathbf{t} = (t_x, 0, t_z)$$



$$R, \mathbf{t}$$