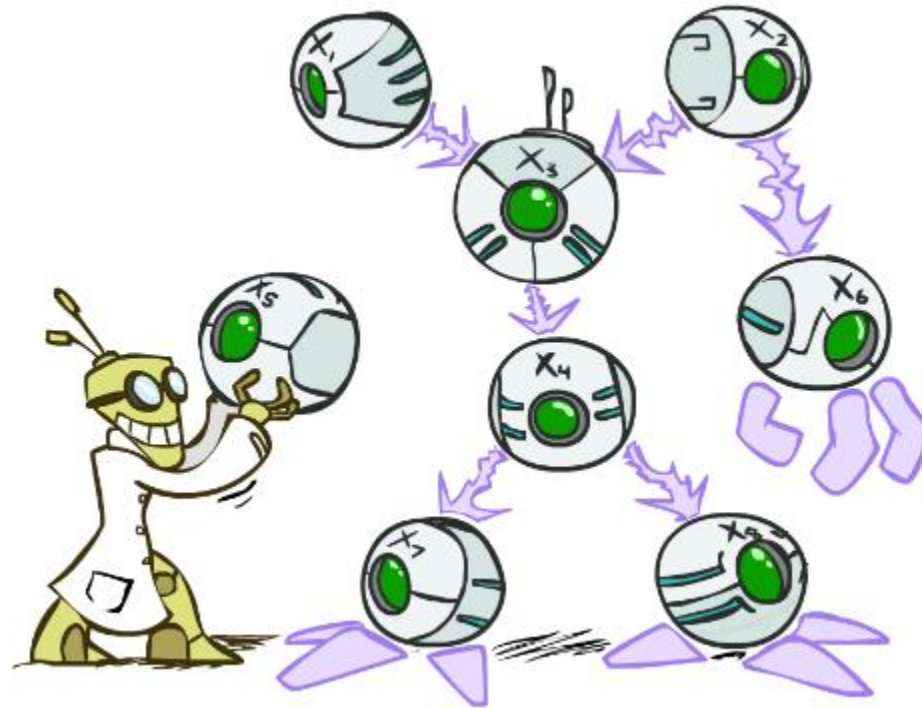


Artificial Intelligence

Bayes' Nets

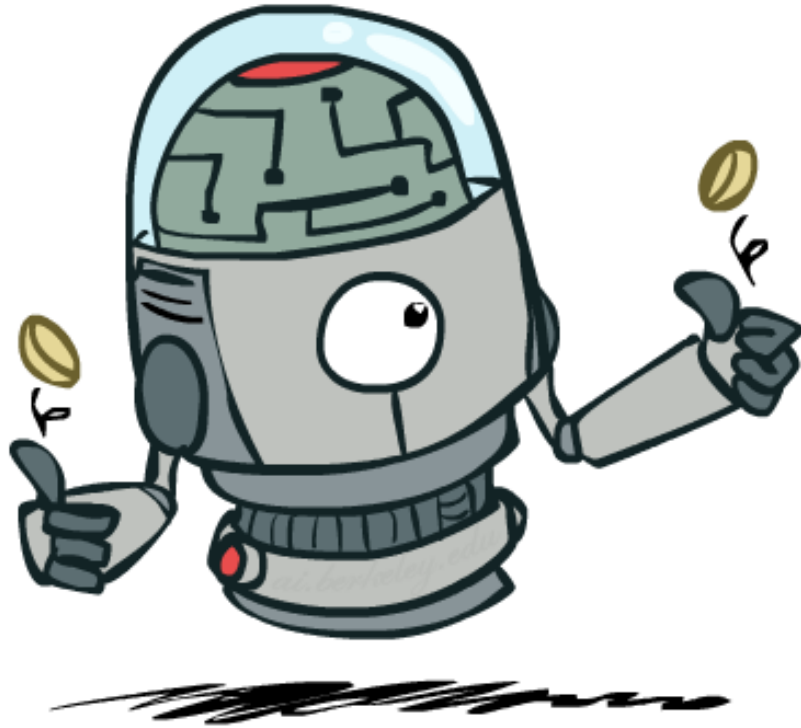


Probabilistic Models

- Models describe how (a portion of) the world works
- **Models are always simplifications**
 - May not account for every variable
 - May not account for all interactions between variables
 - “All models are wrong; but some are useful.”
– George E. P. Box
- What do we do with probabilistic models?
 - We (or our agents) need to reason about unknown variables, given evidence
 - Example: explanation (diagnostic reasoning)
 - Example: prediction (causal reasoning)



Independence



Independence

- Two variables are *independent* iff:

$$\forall x, y : P(x, y) = P(x)P(y)$$

- This says that their joint distribution *factors* into a product two simpler distributions
- Another form:

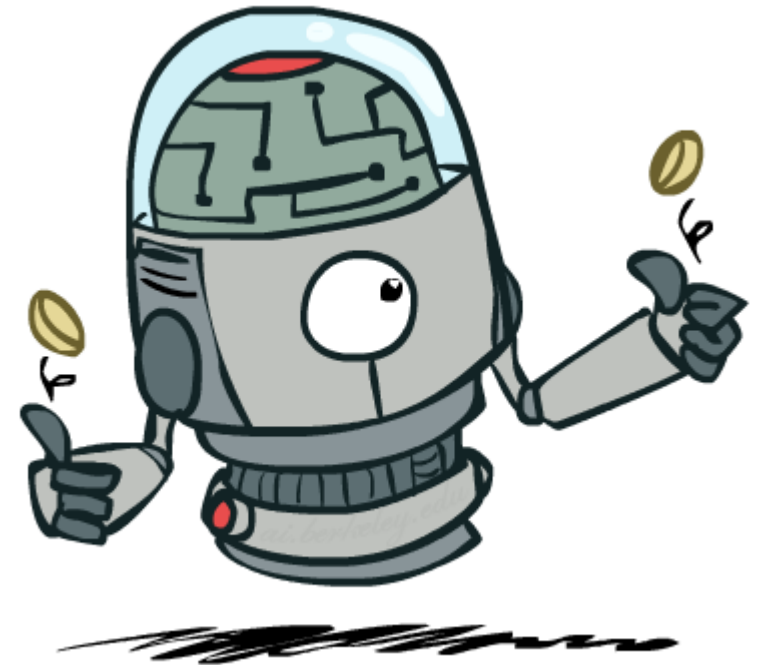
$$\forall x, y : P(x|y) = P(x)$$

$$\forall x, y : P(y|x) = P(y) \text{ alternative}$$

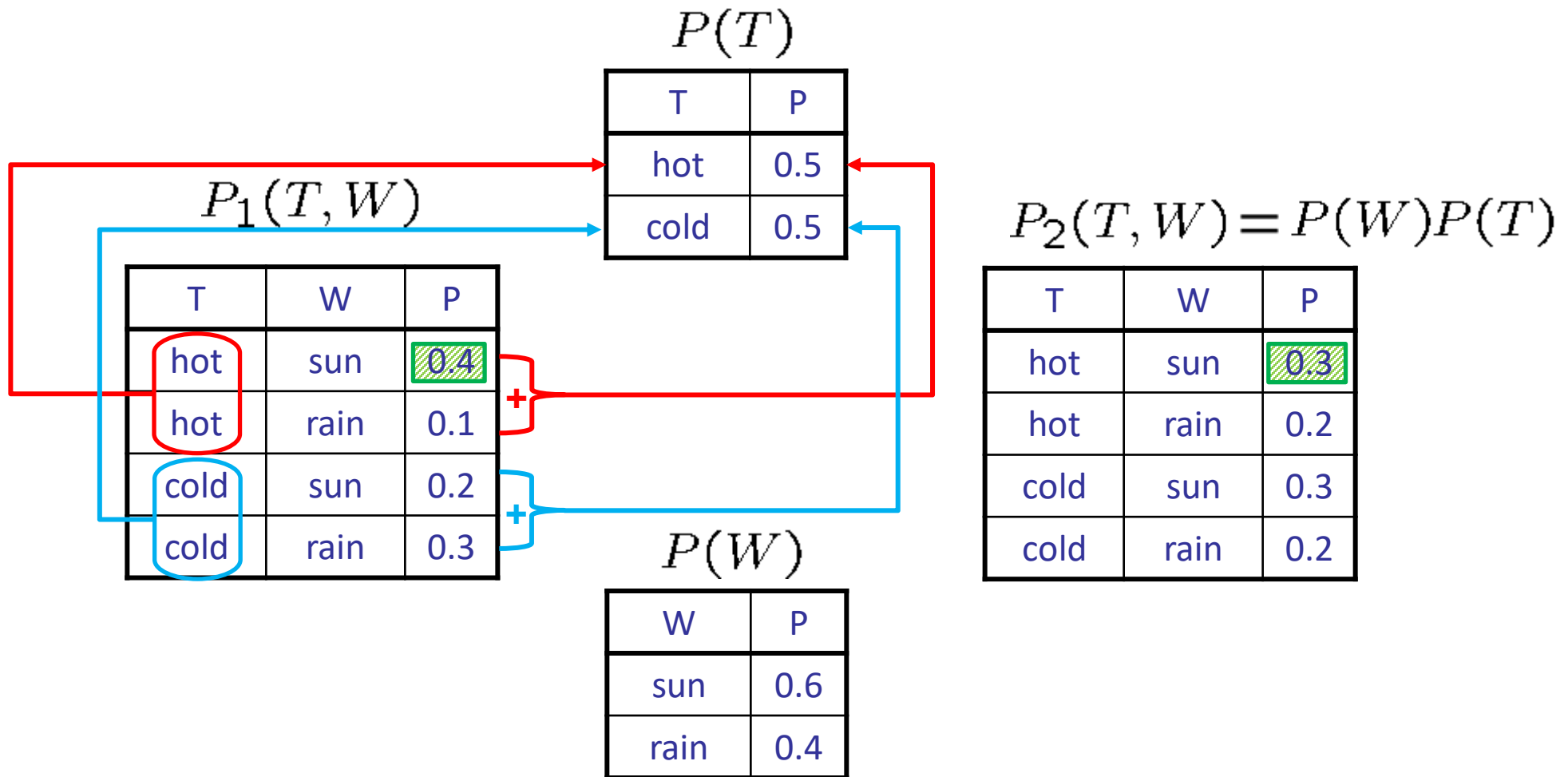
- We write: $X \perp\!\!\!\perp Y$

- Independence is a simplifying *modeling assumption*

- Empirical* joint distributions: at best “close” to independent
- What could we assume for {Weather, Traffic, Cavity, Toothache}?



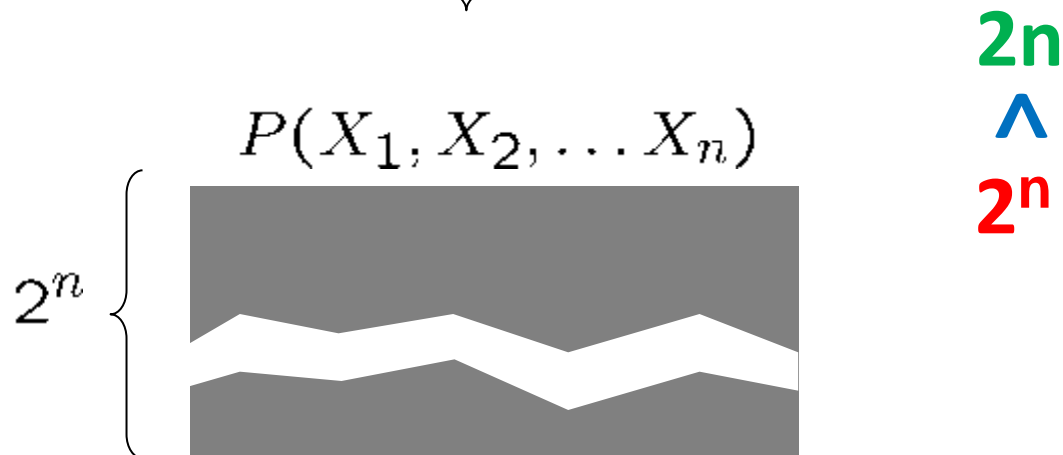
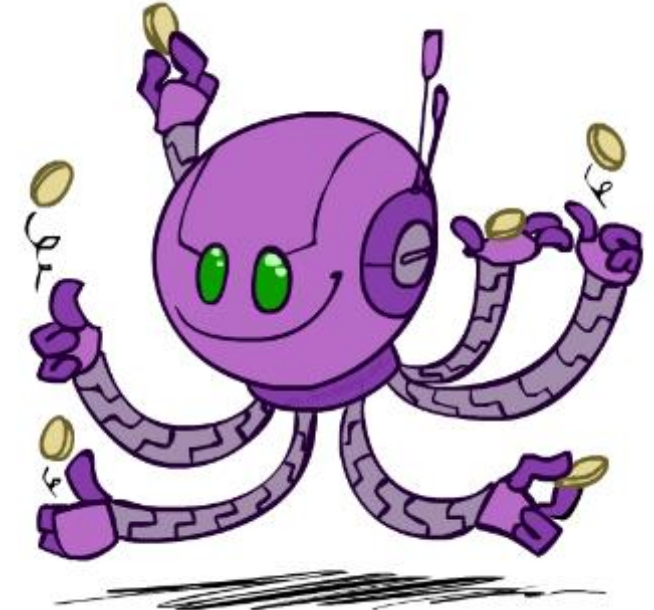
Example: Independence?



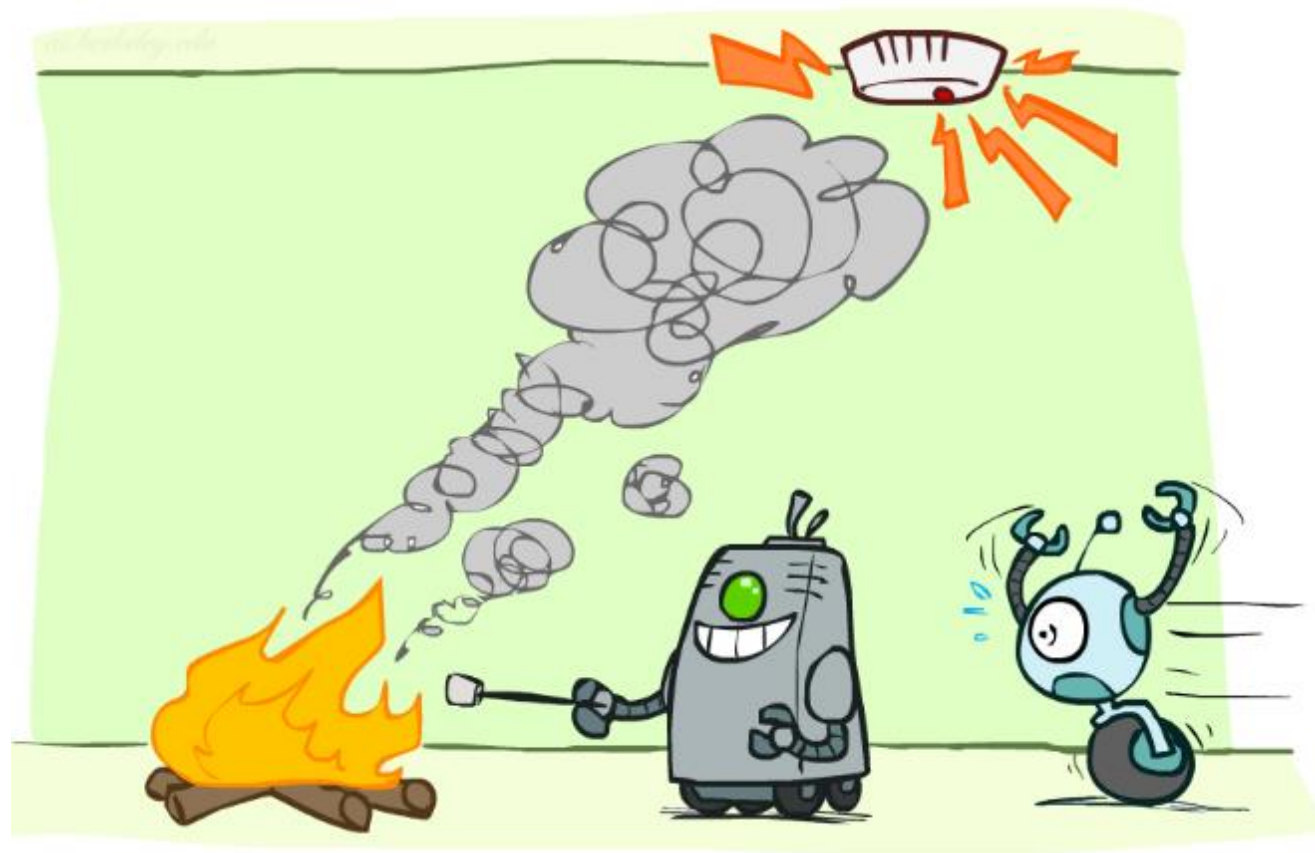
Example: Independence

- N fair, independent coin flips:

$P(X_1)$		$P(X_2)$		\dots		$P(X_n)$	
H	0.5	H	0.5			H	0.5
T	0.5	T	0.5			T	0.5

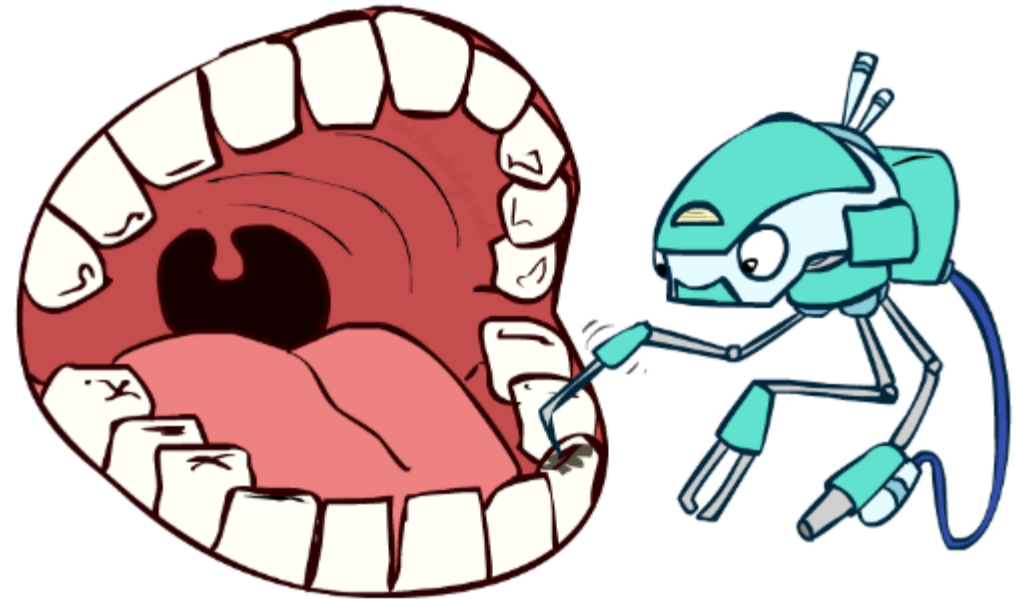


Conditional Independence



Conditional Independence

- $P(\text{Toothache}, \text{Cavity}, \text{Catch})$
- If I have a cavity, the probability that the probe catches in it doesn't depend on whether I have a toothache:
 - $P(+\text{catch} \mid +\text{toothache}, +\text{cavity}) = P(+\text{catch} \mid +\text{cavity})$
- The same independence holds if I don't have a cavity:
 - $P(+\text{catch} \mid +\text{toothache}, -\text{cavity}) = P(+\text{catch} \mid -\text{cavity})$
- Catch is *conditionally independent* of Toothache given Cavity:
 - $P(\text{Catch} \mid \text{Toothache}, \text{Cavity}) = P(\text{Catch} \mid \text{Cavity})$
- Equivalent statements:
 - $P(\text{Toothache} \mid \text{Catch}, \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity})$
 - $P(\text{Toothache}, \text{Catch} \mid \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity}) P(\text{Catch} \mid \text{Cavity})$
 - One can be derived from the other easily



In analogy with independence

$$\forall x, y : P(x|y) = P(x)$$

$$\forall x, y : P(y|x) = P(y)$$

$$\forall x, y : P(x, y) = P(x)P(y)$$

Conditional Independence

- Unconditional (absolute) independence very rare (why?)
- *Conditional independence* is our most basic and robust form of knowledge about uncertain environments.
- X is conditionally independent of Y given Z

$$X \perp\!\!\!\perp Y \mid Z$$

if and only if:

$$\forall x, y, z : P(x, y|z) = P(x|z)P(y|z)$$

$$P(x|y, z) = \frac{P(x, y, z)}{P(y, z)}$$

or, equivalently, if and only if

$$\forall x, y, z : P(x|z, y) = P(x|z)$$

$$\forall x, y, z : P(y|z, x) = P(y|z)$$

$$= \frac{P(z)P(x, y|z)}{P(y, z)} = \frac{P(z)P(x|z)P(y|z)}{P(y, z)}$$

$$= \frac{P(z)P(x|z)P(y|z)}{P(z)P(y|z)} = P(x|z)$$

Conditional Independence

- What about this domain:

- Traffic
- Umbrella
- Raining

$$T \perp\!\!\!\perp U | R$$

$$U \perp\!\!\!\perp T | R$$

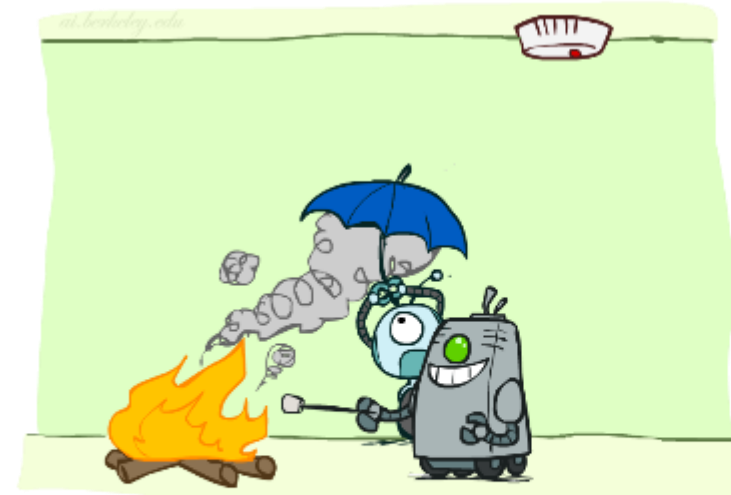
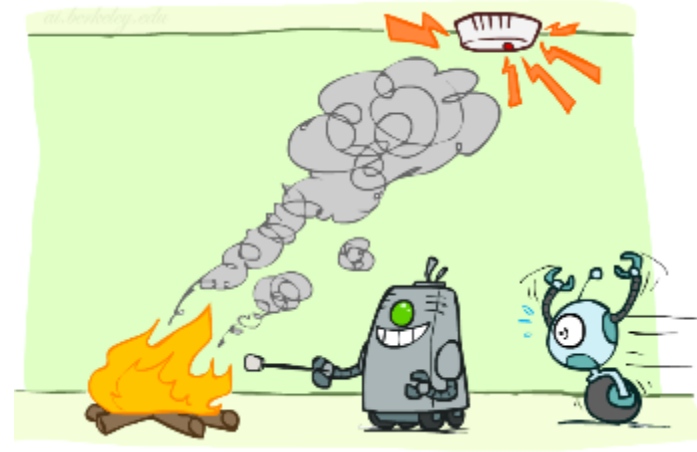


Conditional Independence

- What about this domain:

- Fire
- Smoke
- Alarm

$$F \perp\!\!\!\perp A | S$$



Conditional Independence and the Chain Rule

- Chain rule: $P(X_1, X_2, \dots, X_n) = P(X_1)P(X_2|X_1)P(X_3|X_1, X_2) \dots$

- Trivial decomposition:

$$P(\text{Traffic}, \text{Rain}, \text{Umbrella}) = P(\text{Rain})P(\text{Traffic}|\text{Rain})P(\text{Umbrella}|\text{Rain}, \text{Traffic})$$

- With assumption of conditional independence:

$$P(\text{Traffic}, \text{Rain}, \text{Umbrella}) = P(\text{Rain})P(\text{Traffic}|\text{Rain})P(\text{Umbrella}|\text{Rain})$$

- Bayes' nets / graphical models help us express conditional independence assumptions



$$P(Y|X_1, X_2, \dots, X_K)$$

2^K combinations

Ghostbusters Chain Rule

- Each sensor depends only on where the ghost is
- That means, the two sensors are conditionally independent, given the ghost position
- T: Top square is red
B: Bottom square is red
G: Ghost is in the top

- Givens:

$$P(+g) = 0.5$$

$$P(-g) = 0.5$$

$$P(+t \mid +g) = 0.8$$

$$P(+t \mid -g) = 0.4$$

$$P(+b \mid +g) = 0.4$$

$$P(+b \mid -g) = 0.8$$

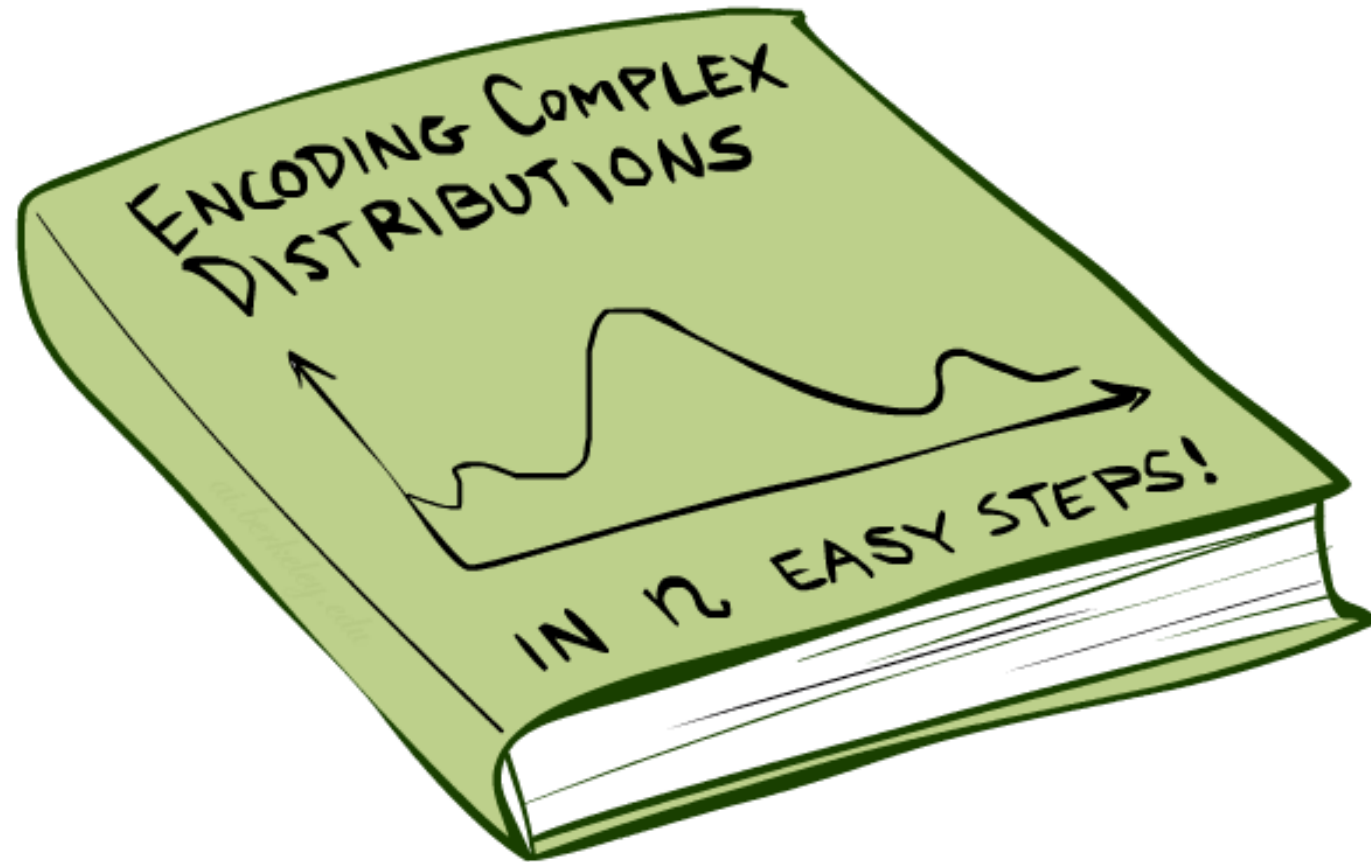


$$P(T,B,G) = P(G) P(T \mid G) P(B \mid G)$$

T	B	G	P(T,B,G)
+t	+b	+g	0.16
+t	+b	-g	0.16
+t	-b	+g	0.24
+t	-b	-g	0.04
-t	+b	+g	0.04
-t	+b	-g	0.24
-t	-b	+g	0.06
-t	-b	-g	0.06

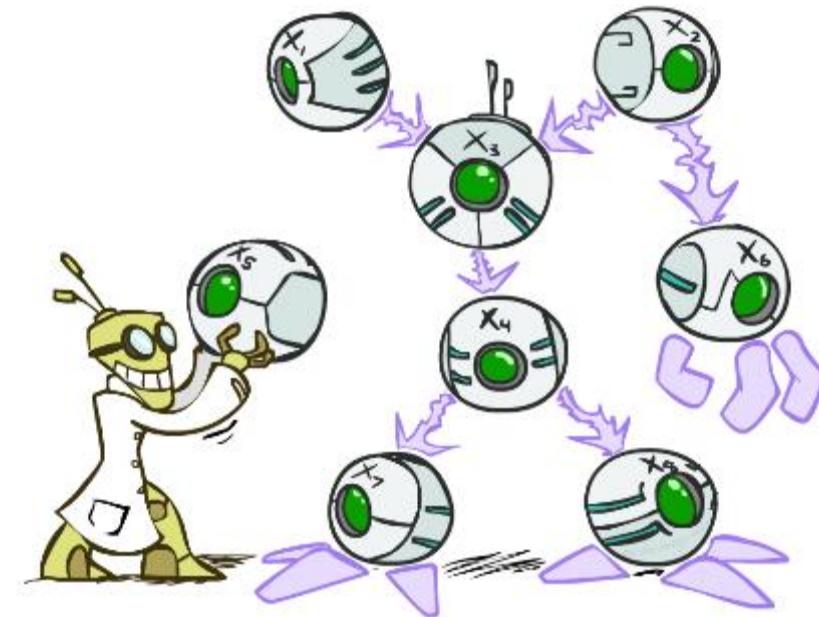


Bayes' Nets: Big Picture

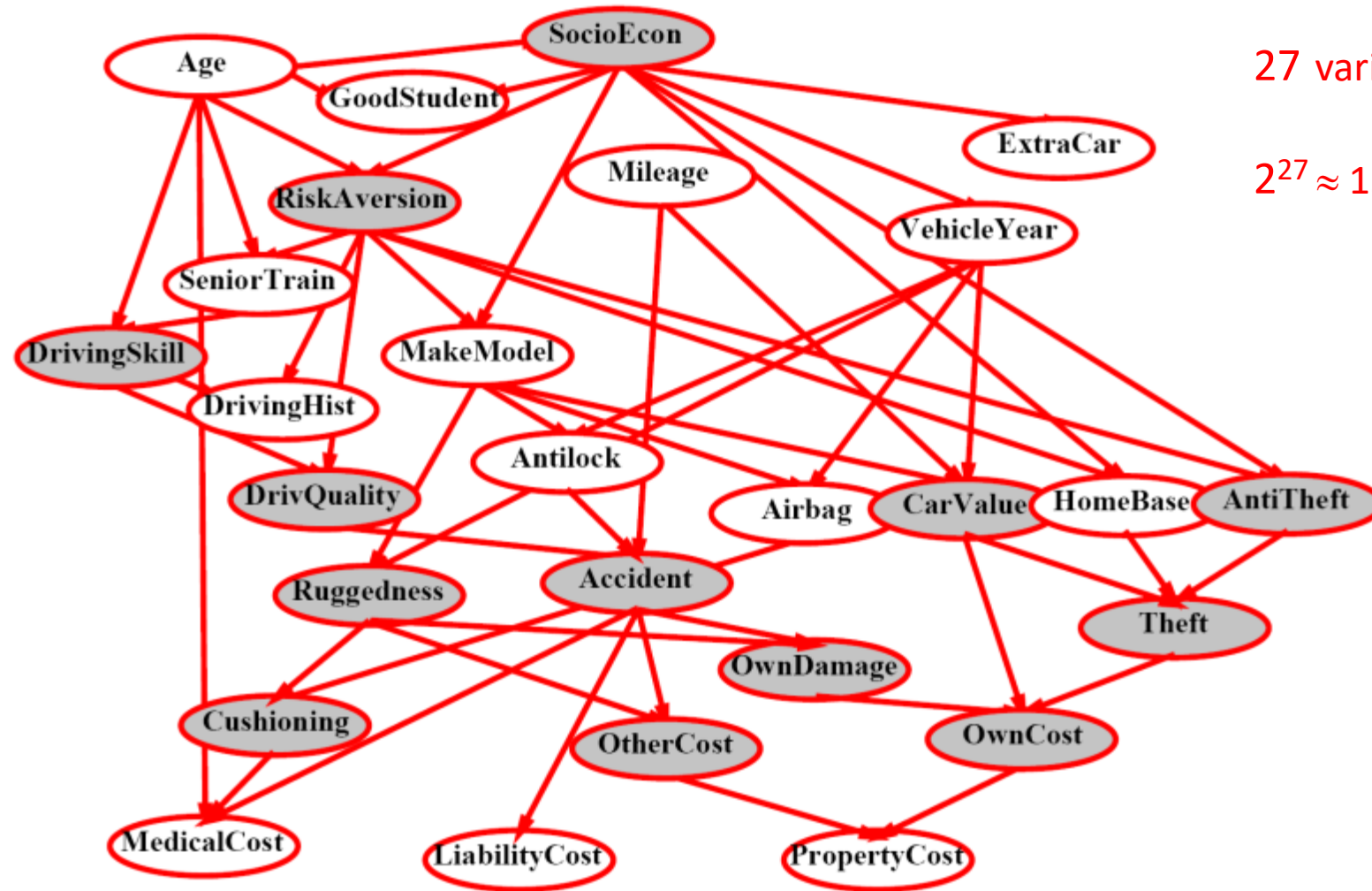


Bayes' Nets: Big Picture

- Two problems with using full joint distribution tables as our probabilistic models:
 - Unless there are only a few variables, the joint is WAY too big to represent explicitly
 - Hard to learn (estimate) anything empirically about more than a few variables at a time
- **Bayes' nets:** a technique for describing complex joint distributions (models) using simple, local distributions (conditional probabilities)
 - More properly called **graphical models**
 - We describe how variables locally interact
 - Local interactions chain together to give global, indirect interactions



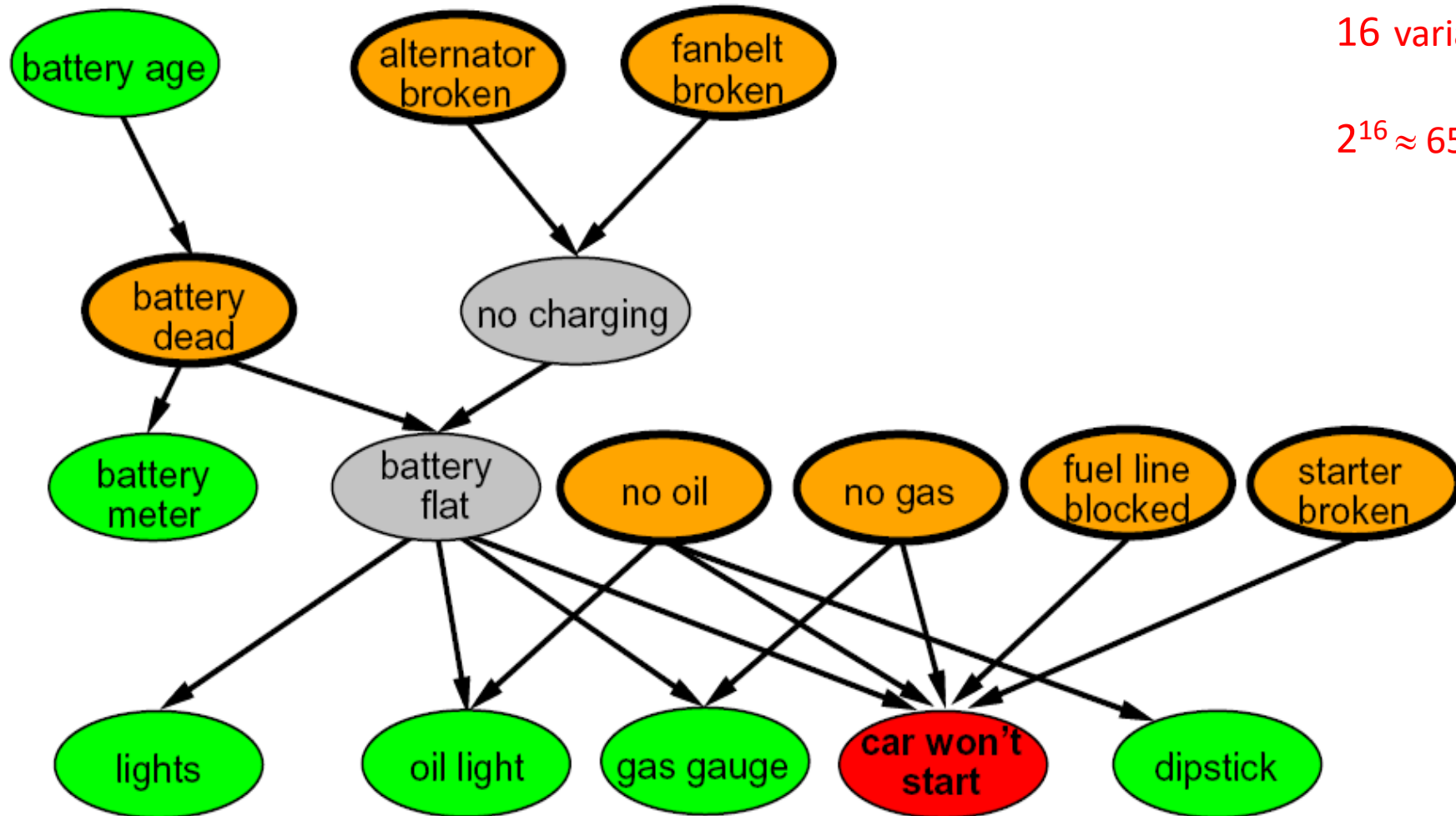
Example Bayes' Net: Insurance



27 variables

$2^{27} \approx 134$ million entries

Example Bayes' Net: Car

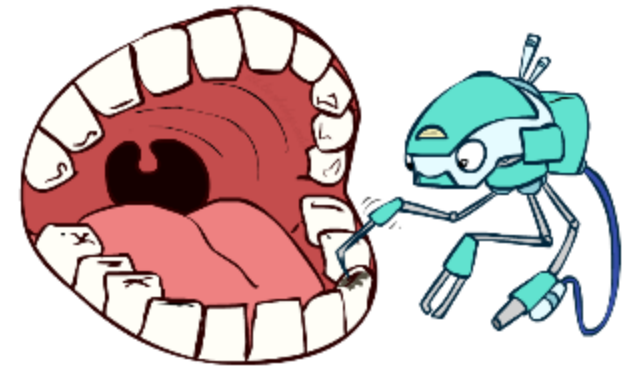
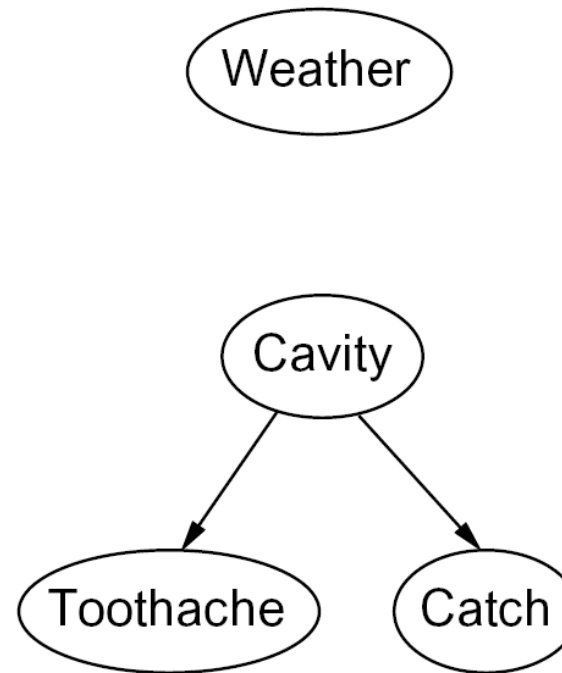


16 variables

$2^{16} \approx 65\,500$ entries

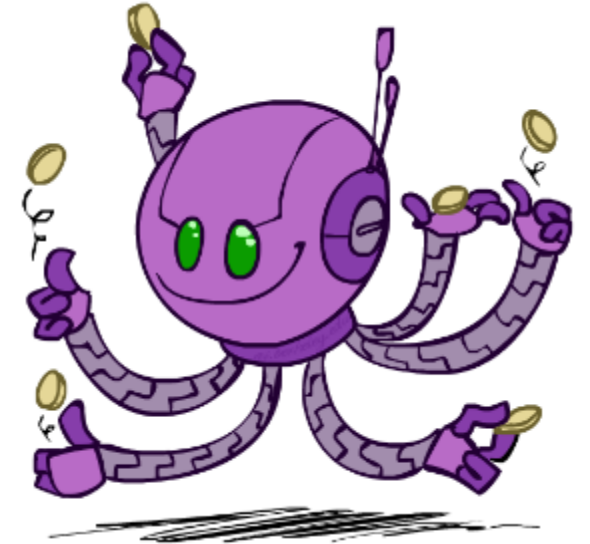
Graphical Model Notation

- **Nodes: variables (with domains)**
 - Can be assigned (observed) or unassigned (unobserved)
- **Arcs: interactions**
 - Similar to CSP constraints
 - Indicate “direct influence” between variables
 - Formally: encode conditional independence (more later)
- For now: imagine that arrows mean direct causation (in general, they don't!)



Example: Coin Flips

- N independent coin flips



- No interactions between variables: **absolute independence**

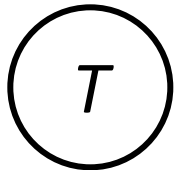
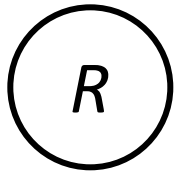
Example: Traffic

- Variables:

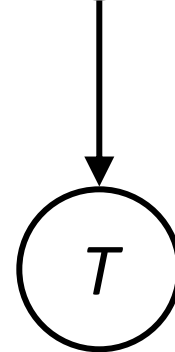
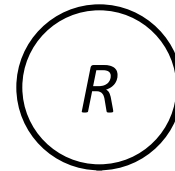
- R: It rains
- T: There is traffic



- Model 1: independence



- Model 2: rain causes traffic



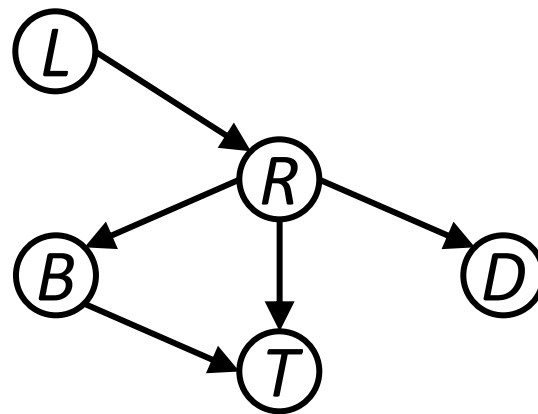
- Why is an agent using model 2 better?

Example: Traffic II

- Let's build a causal graphical model!

- Variables

- T: Traffic
- R: It rains
- L: Low pressure
- D: Roof drips
- B: Ballgame
- C: Cavity

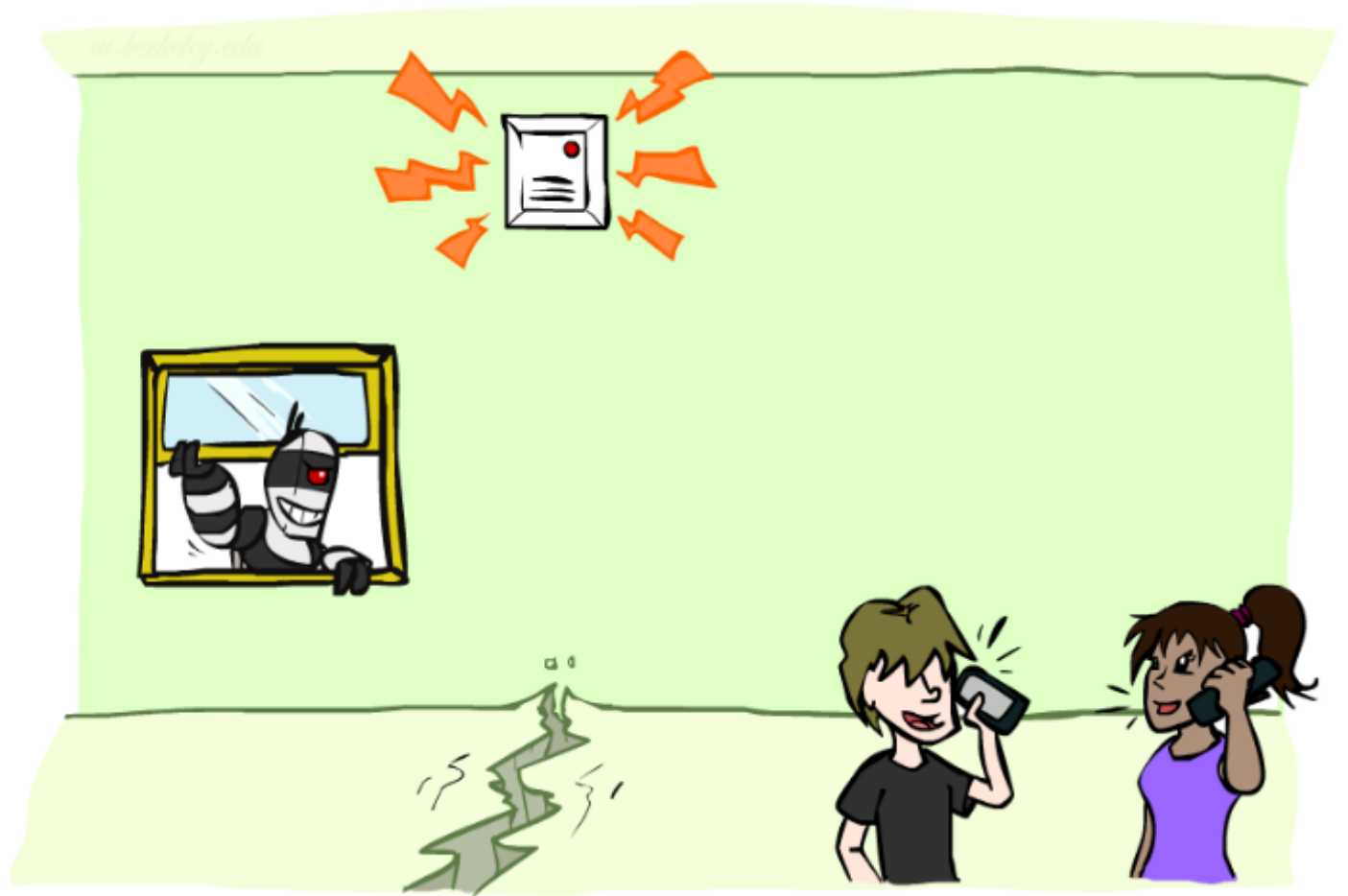
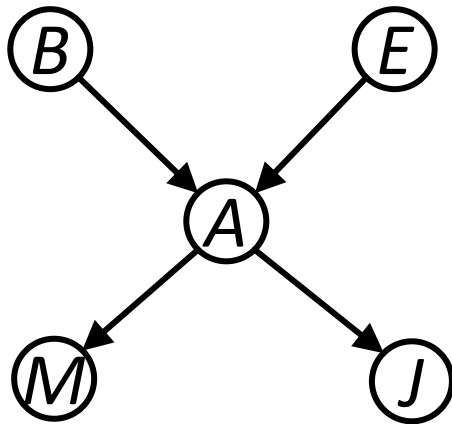


Ⓒ

Example: Alarm Network

■ Variables

- B: Burglary
- A: Alarm goes off
- M: Mary calls
- J: John calls
- E: Earthquake!



Bayes' Net Semantics



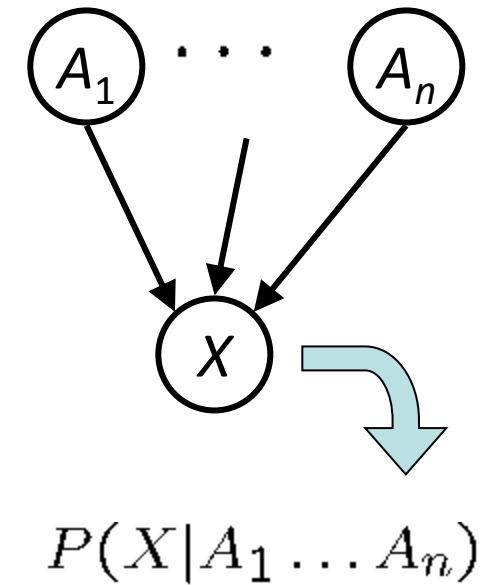
Bayes' Net Semantics



- A set of nodes, one per variable X
- A directed, acyclic graph
- A conditional distribution for each node
 - A collection of distributions over X , one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

- CPT: conditional probability table
- Description of a noisy “causal” process



A Bayes net = Topology (graph) + Local Conditional Probabilities

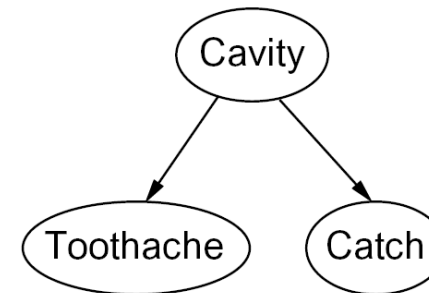
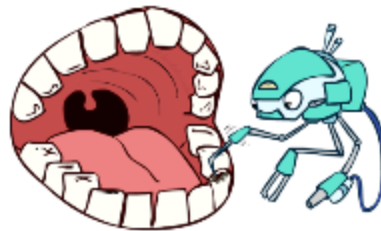
Probabilities in BNs



- Bayes' nets **implicitly** encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

- Example:



$$P(+cavity, +catch, -toothache) = P(+cavity) P(+catch | +cavity) P(-toothache | +cavity)$$

Probabilities in BNs



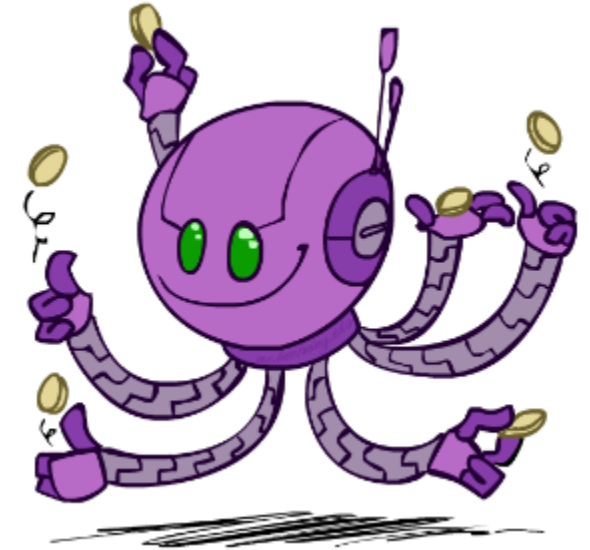
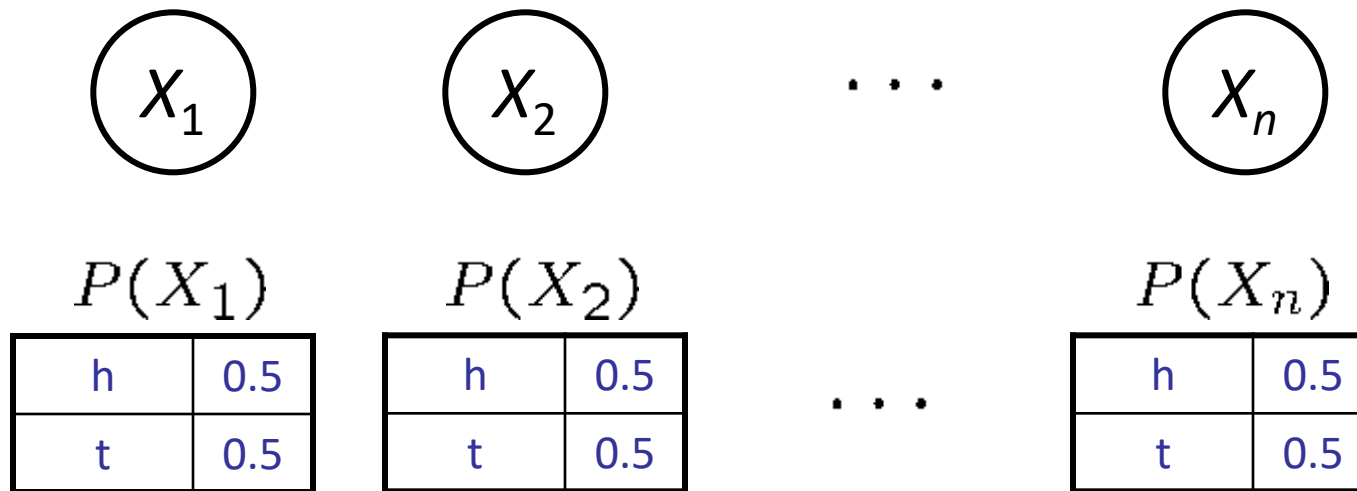
- Why are we guaranteed that setting

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

results in a proper joint distribution?

- Chain rule (valid for all distributions): $P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | x_1 \dots x_{i-1})$
- Assume conditional independences: $P(x_i | x_1, \dots, x_{i-1}) = P(x_i | \text{parents}(X_i))$
 - Consequence: $P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$
- Not every BN can represent every joint distribution
 - The topology enforces certain conditional independencies

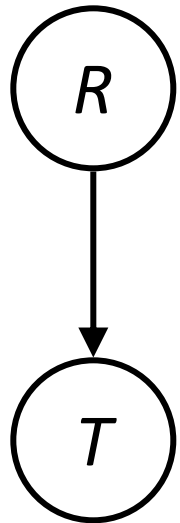
Example: Coin Flips



$$P(h, h, t, h) = 0.5 * 0.5 * 0.5 * 0.5$$

Only distributions whose variables are absolutely independent can be represented by a Bayes' net with no arcs.

Example: Traffic



$P(R)$

$+r$	$1/4$
$-r$	$3/4$

$P(T|R)$

$+r$	<table><tr><td>$+t$</td><td>$3/4$</td></tr><tr><td>$-t$</td><td>$1/4$</td></tr></table>	$+t$	$3/4$	$-t$	$1/4$
$+t$	$3/4$				
$-t$	$1/4$				
$-r$	<table><tr><td>$+t$</td><td>$1/2$</td></tr><tr><td>$-t$</td><td>$1/2$</td></tr></table>	$+t$	$1/2$	$-t$	$1/2$
$+t$	$1/2$				
$-t$	$1/2$				

$$P(+r, -t) = P(+r) P(-t|+r)$$

$$= \frac{1}{4} * \frac{1}{4} = \frac{1}{16}$$

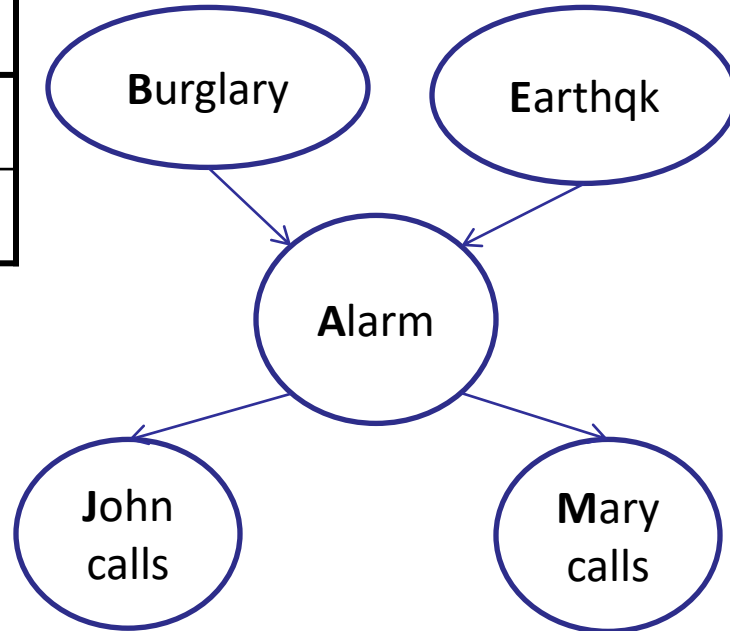


Example: Alarm Network

Node ordering:

B, E, A, J, M

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998



$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= \\
 &= P(+b)P(-e)P(+a|+b, -e) \\
 &\quad P(-j|+a)P(+m|+a)
 \end{aligned}$$

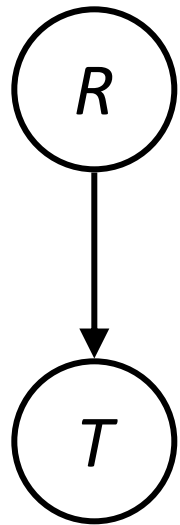
A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

Example: Traffic

- Causal direction



$P(R)$

+r	1/4
-r	3/4

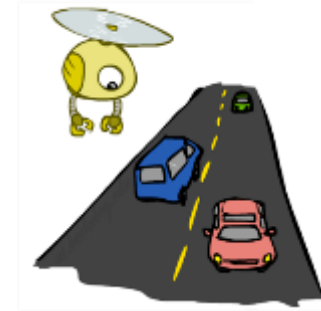
$P(T|R)$

+r	+t	3/4
	-t	1/4

-r	+t	1/2
	-t	1/2

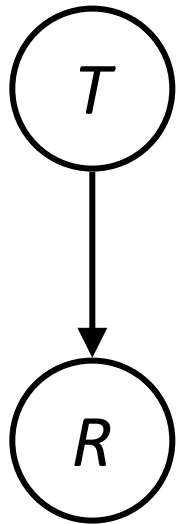
$P(T, R)$

+r	+t	3/16
+r	-t	1/16
-r	+t	6/16
-r	-t	6/16



Example: Reverse Traffic

- Reverse causality?



$P(T)$

+t	9/16
-t	7/16

$P(R|T)$

+t	+r	1/3
	-r	2/3

-t	+r	1/7
	-r	6/7



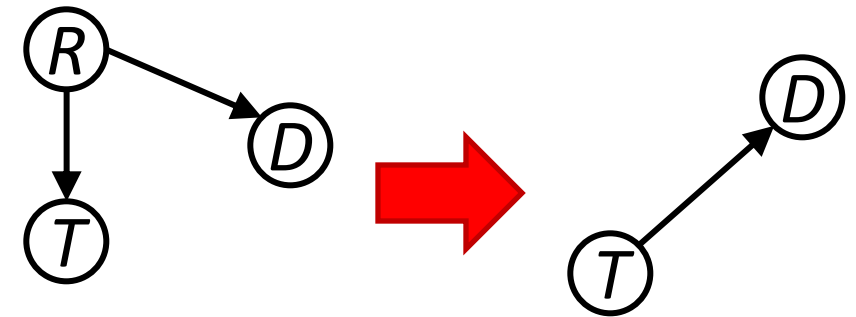
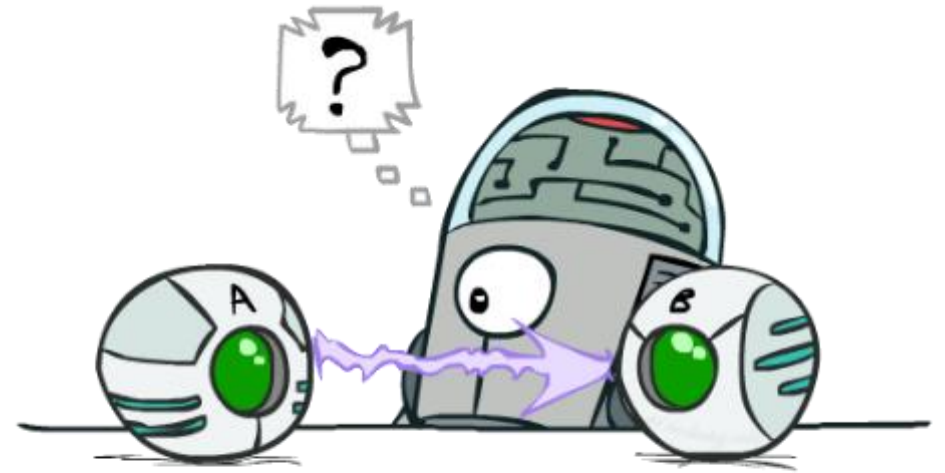
$P(T, R)$

+r	+t	3/16
+r	-t	1/16
-r	+t	6/16
-r	-t	6/16

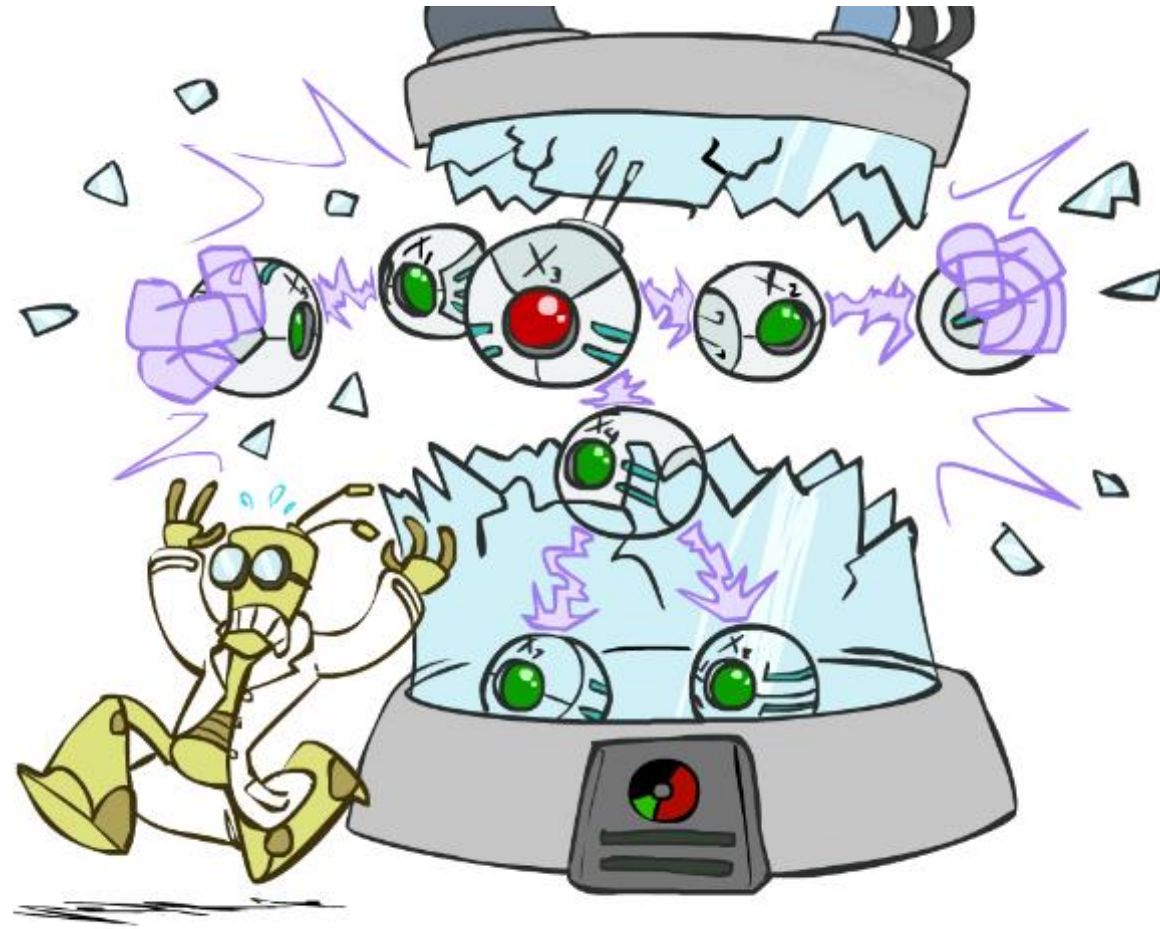
Causality?

- When Bayes' nets reflect the true causal patterns:
 - Often simpler (nodes have fewer parents)
 - Often easier to think about
 - Often easier to elicit from experts
- BNs need not actually be causal
 - Sometimes no causal net exists over the domain (especially if variables are missing)
 - E.g. consider the variables *Traffic* and *Drips*
 - End up with arrows that reflect correlation, not causation
- What do the arrows really mean?
 - Topology may happen to encode causal structure
 - **Topology really encodes conditional independence**

$$P(x_i | x_1, \dots, x_{i-1}) = P(x_i | \text{parents}(X_i))$$



Bayes' Nets: Independence



Bayes Nets: Assumptions

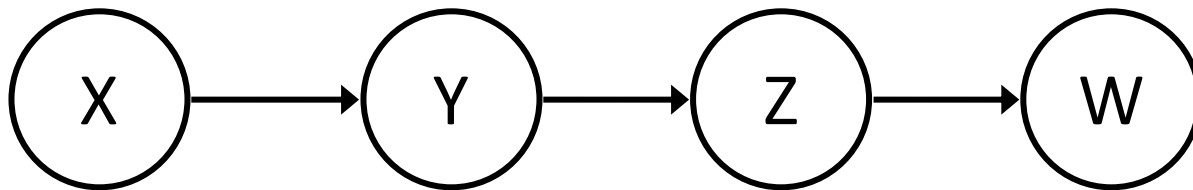
- Assumptions we are required to make to define the Bayes net when given the graph:

$$P(x_i | x_1 \cdots x_{i-1}) = P(x_i | \text{parents}(X_i))$$

- Beyond above “chain rule → Bayes net” conditional independence assumptions
 - Often additional conditional independences
 - They can be read off the graph
- Important for modeling: understand assumptions made when choosing a Bayes net graph



Example



- Conditional independence assumptions directly from simplifications in chain rule:

$$P(X, Y, Z, W) = P(X) P(Y|X) P(Z|X, Y) P(W|X, Y, Z) \leftarrow \text{Chain rule}$$

$$= P(X) P(Y|X) P(Z|Y) P(W|Z) \leftarrow \text{Bayes net assumptions}$$

- Additional implied conditional independence assumptions?

$$Z \perp\!\!\!\perp X|Y \quad W \perp\!\!\!\perp X, Y|Z$$

$$W \perp\!\!\!\perp X|Y$$

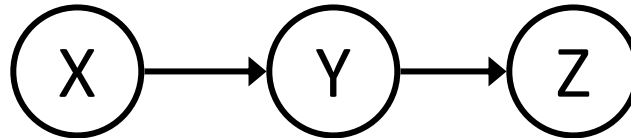
$$P(w|x, y) = \frac{P(w, x, y)}{P(x, y)} = \frac{\sum_z P(w, x, y, z)}{P(x, y)}$$

$$P(w|x, y) \stackrel{?}{=} P(w|y) = \frac{\sum_z P(x)P(y|x)P(z|y)P(w|z)}{P(x, y)} = \frac{P(x)P(y|x) \sum_z P(z|y)P(w|z)}{P(x)P(y|x)}$$

$$= \sum_z P(z|y)P(w|z) = \sum_z P(z|y)P(w|z, y) = \sum_z P(z, w|y) = P(w|y)$$

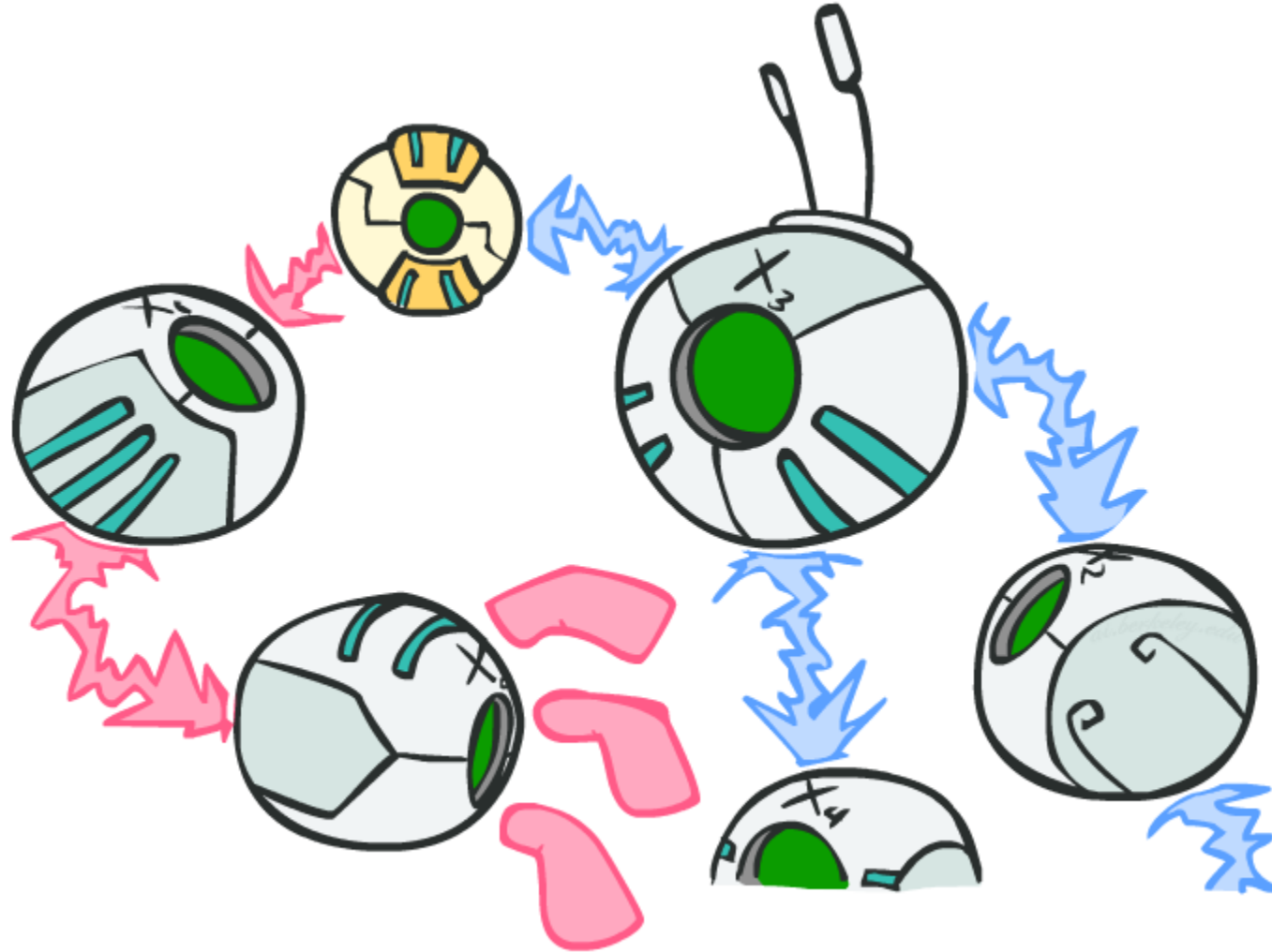
Independence in a BN

- Important question about a BN:
 - Are two nodes independent given certain evidence?
 - If yes, can prove using algebra (tedious in general)
 - If no, can prove with a counter example
 - Example:



- Question: are X and Z necessarily independent?
 - Answer: no. Example: low pressure causes rain, which causes traffic.
 - X can influence Z, Z can influence X (via Y)

Independence properties of triples



Causal Chains

- This configuration is a “causal chain”



X: Low pressure

Y: Rain

Z: Traffic

$$P(x, y, z) = P(x)P(y|x)P(z|y)$$

- Guaranteed X independent of Z ? **No!**

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.

- Example:

- Low pressure causes rain causes traffic, high pressure causes no rain causes no traffic

- In numbers:

$$P(+y \mid +x) = 1, P(-y \mid -x) = 1, \\ P(+z \mid +y) = 1, P(-z \mid -y) = 1$$

Causal Chains

- This configuration is a “causal chain”

- Guaranteed X independent of Z given Y?



X: Low pressure

Y: Rain

Z: Traffic

$$P(x, y, z) = P(x)P(y|x)P(z|y)$$

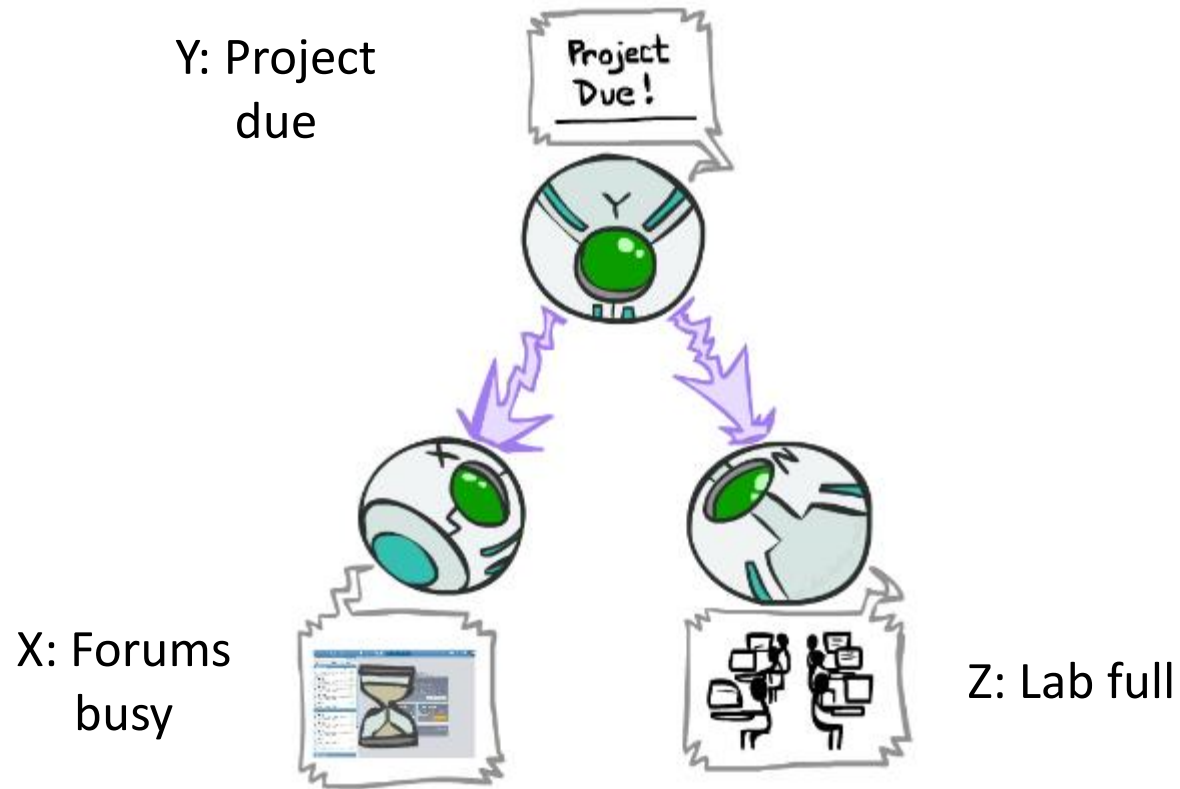
$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(x)P(y|x)P(z|y)}{P(x)P(y|x)} \\ &= P(z|y) \end{aligned}$$

Yes!

- Evidence along the chain “blocks” the influence

Common Cause

- This configuration is a “common cause”



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

- Guaranteed X independent of Z ? **No!**

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.

- Example:

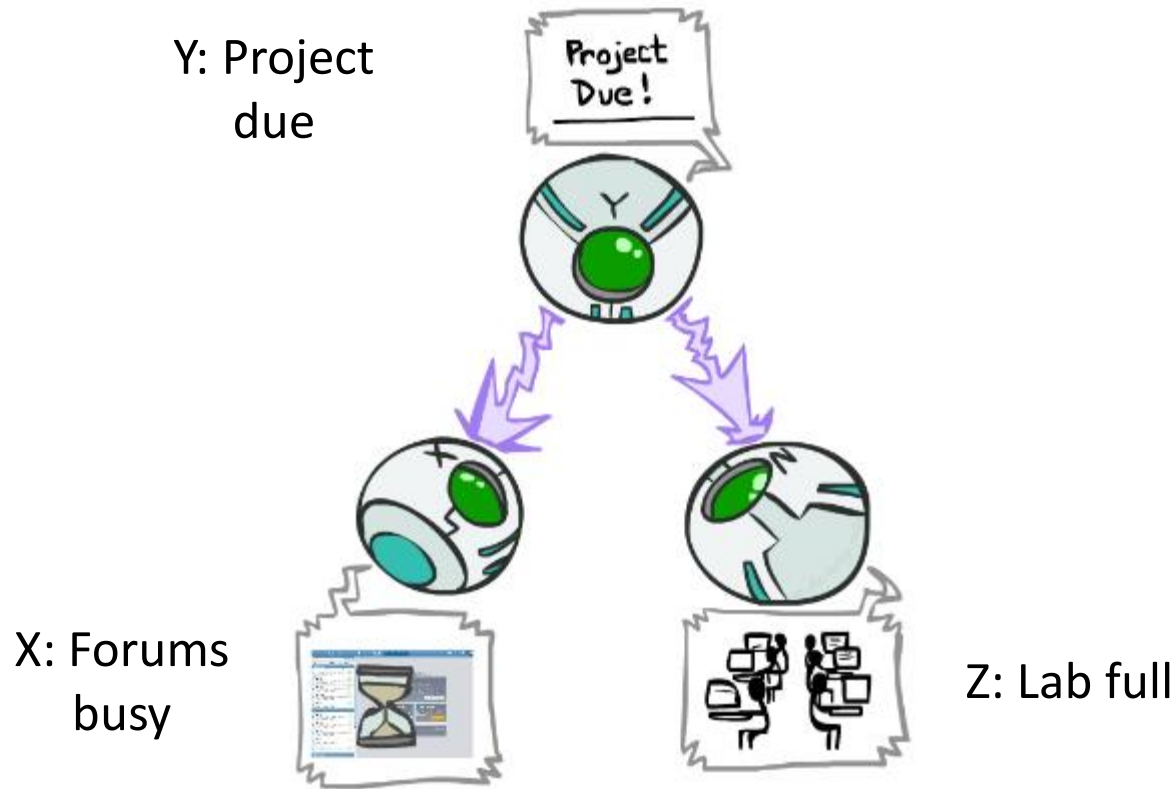
- Project due causes both forums busy and lab full

- In numbers:

$$P(+x \mid +y) = 1, P(-x \mid -y) = 1, \\ P(+z \mid +y) = 1, P(-z \mid -y) = 1$$

Common Cause

- This configuration is a “common cause”
- Guaranteed X and Z independent given Y?



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

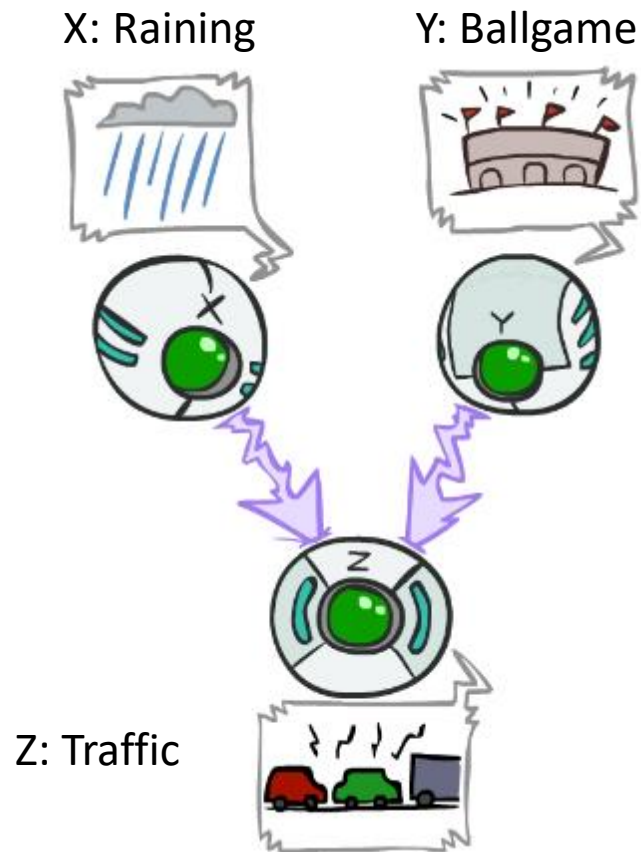
$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(y)P(x|y)P(z|y)}{P(y)P(x|y)} \\ &= P(z|y) \end{aligned}$$

Yes!

- Observing the cause blocks influence between effects.

Common Effect

- Last configuration: two causes of one effect (v-structures)



- Are X and Y independent?

- **Yes**: the ballgame and the rain cause traffic, but they are not correlated

$$P(X, Y, Z) = P(X)P(Y)P(Z|X, Y)$$

$$P(x, y) = \sum_z P(x, y, z) = \sum_z P(x)P(y)P(z|x, y) =$$
$$= P(x)P(y) \underbrace{\sum_z P(z|x, y)}_1 = P(x)P(y)$$

- Are X and Y independent given Z?

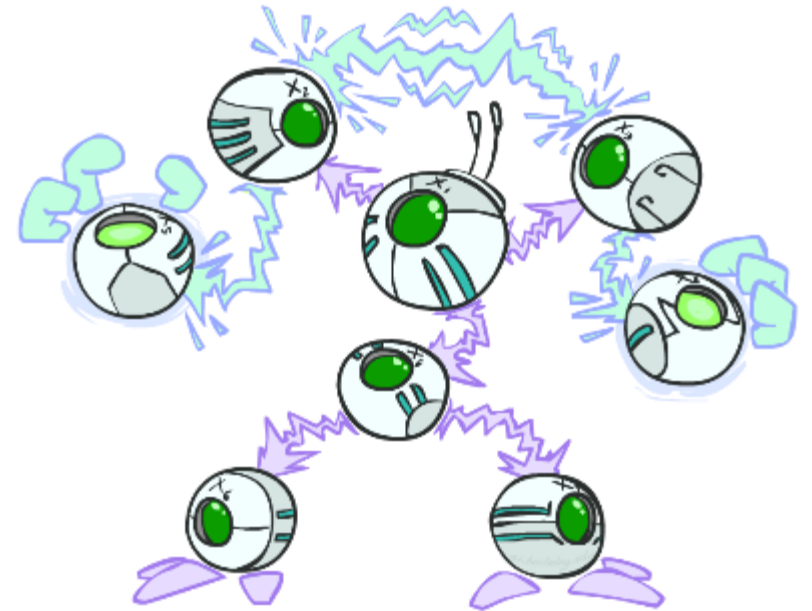
- **No**: seeing traffic puts the rain and the ballgame in competition as explanation.

- **This is backwards from the other cases**

- Observing an effect **activates** influence between possible causes.

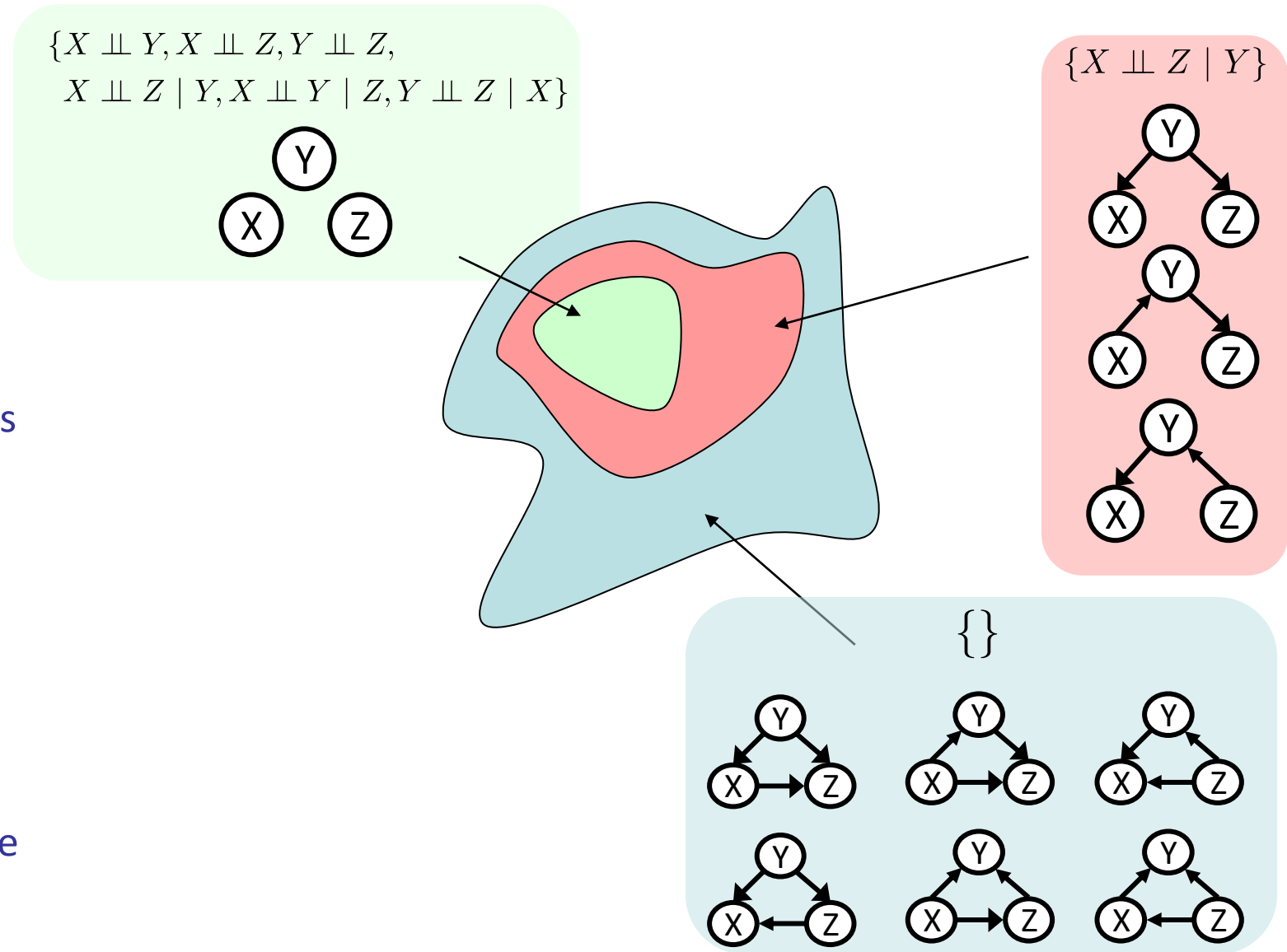
The General Case

- General question: in a given BN, are two variables independent (given evidence)?
- Solution: analyze the graph
- Any complex example can be broken into repetitions of the three canonical cases



Topology Limits Distributions

- Given some graph topology G , only certain joint distributions can be encoded
- The graph structure guarantees certain (conditional) independences
- (There might be more independence)
- Adding arcs increases the set of distributions, but has several costs
- Full conditioning can encode any distribution



Summary

- A Bayes' net is an efficient encoding of a probabilistic model of a domain
 - A directed, acyclic graph, one node per random variable
 - A conditional probability table (CPT) for each node
 - Bayes' nets implicitly encode joint distributions
- Questions we can ask:
 - Inference: given a fixed BN, what is $P(X \mid e)$?
 - Representation: given a BN graph, what kinds of distributions can it encode?
 - Modeling: what BN is most appropriate for a given domain?
- Guaranteed independencies of distributions can be deduced from BN graph structure
- A Bayes' net's joint distribution may have further (conditional) independence that is not detectable until you inspect its specific distribution