

# Trabalho 2 SEP

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Implementação em MATLAB, e aplicando ao sistema IEEE14 barras e IEEE33 barras.

## IEEE 14 Barras

```
% [      NUM      TIPO      V      TETA      PG      QG      PD      QD      GSH      BSH ]
barras = [
    1  2  1.060 0.0 232.4 -16.9  0.0    0.0    0.0    0.0 0 0
    2  1  1.045 0.0 40.0  42.4 21.70 12.70    0.0    0.0 -40 50
    3  1  1.010 0.0  0.0  23.4 94.20 19.00    0.0    0.0 0 40
    4  0  1.000 0.0  0.0  0.0 47.80 -3.90    0.0    0.0 0  0
    5  0  1.000 0.0  0.0  0.0  7.60  1.600    0.0    0.0 0  0
    6  1  1.070 0.0  0.0  12.2 11.20  7.500    0.0    0.0 -6 24
    7  0  1.000 0.0  0.0  0.0  0.0  0.0    0.0    0.0 0  0
    8  1  1.090 0.0  0.0  17.4  0.0  0.0    0.0    0.0 -6 24
    9  0  1.000 0.0  0.0  0.0 29.50 16.60    0.0   19.0 0  0
   10  0  1.000 0.0  0.0  0.0  9.00  5.800    0.0    0.0 0  0
   11  0  1.000 0.0  0.0  0.0  3.50  1.800    0.0    0.0 0  0
   12  0  1.000 0.0  0.0  0.0  6.10  1.600    0.0    0.0 0  0
   13  0  1.000 0.0  0.0  0.0 13.50  5.800    0.0    0.0 0  0
   14  0  1.000 0.0  0.0  0.0 14.90  5.000    0.0    0.0 0  0 ];
```

```
%      [FR      TO      R      X      BShtotal      Tap ]
linhas = [
1  2  0.01938 0.05917 0.05280 0
1  5  0.05403 0.22304 0.04920 0
2  3  0.04699 0.19797 0.04380 0
2  4  0.05811 0.17632 0.03400 0
2  5  0.05695 0.17388 0.03460 0
3  4  0.06701 0.17103 0.01280 0
4  5  0.01335 0.04211 0 0
4  7  0.0 0.20912 0 0.978
4  9  0.0 0.55618 0 0.969
5  6  0.0 0.25202 0 0.932
6  11 0.09498 0.19890 0 0
6  12 0.12291 0.25581 0 0
6  13 0.06615 0.13027 0 0
7  8  0.0 0.17615 0 0
7  9  0.0 0.11001 0 0
9  10 0.03181 0.08450 0 0
9  14 0.12711 0.27038 0 0
10 11 0.08205 0.19207 0 0
12 13 0.22092 0.19988 0 0
13 14 0.17093 0.34802 0 0 ];
```

Ref= 1;

```

% =====
% Leitura dos dados de entrada

[NumBarras,~] = size(barras);
[NumLinhas,~] = size(linhas);

% Linhas
% Init das variaveis
de = zeros(NumLinhas,1);
para = zeros(NumLinhas,1);
R = zeros(NumLinhas,1);
X = zeros(NumLinhas,1);
B = zeros(NumLinhas,1);
G = zeros(NumLinhas,1);
Tap = zeros(NumLinhas,1);

for i=1:NumLinhas
    de(i) = linhas(i,1);
    para(i) = linhas(i,2);
    R(i) = linhas(i,3);
    X(i) = linhas(i,4);
    B(i) = 1/X(i);
    G(i) = 1/(R(i) + 0.0001);
    Tap(i) = linhas(i,6);
end

% Desconsiderando taps
Tap = ones(NumLinhas,1);

% Barras
% Init das variaveis
Tipo = zeros(NumBarras,1);
V = zeros(NumBarras,1);
Teta = zeros(NumBarras,1);
Pg = zeros(NumBarras,1);
Qg = zeros(NumBarras,1);
Pd = zeros(NumBarras,1);
Qd = zeros(NumBarras,1);
Gsh = zeros(NumBarras,1);
Bsh = zeros(NumBarras,1);

for i=1:NumBarras
    Tipo(i) = barras(i,2);
    V(i) = barras(i,3);
    Teta(i) = barras(i,4);
    Pg(i) = barras(i,5);
    Qg(i) = barras(i,6);
    Pd(i) = barras(i,7);
    Qd(i) = barras(i,8);
    Gsh(i) = barras(i,9);

```

```

    Bsh(i) = barras(i,10);
end

% Potencias em PU
Pg = Pg/100;
Qg = Qg/100;
Pd = Pd/100;
Qd = Qd/100;

% =====
% Matriz B_linha

B_linha = zeros(NumBarras,NumBarras);

for i=1:NumLinhas
    K = de(i);
    M = para(i);
    B_linha(K,K) = B_linha(K,K) + B(i)/(Tap(i)^2); % diagonal principal considerando tap
    B_linha(M,M) = B_linha(M,M) + B(i); % diagonal principal
    B_linha(K,M) = B_linha(K,M) - B(i)/Tap(i); % Fora da diagonal principal
    B_linha(M,K) = B_linha(M,K) - B(i)/Tap(i); % Fora da diagonal principal
end

% =====
% Fluxo de potencia linearizado

B_REF = Ref;
B_linha(B_REF,B_REF) = 10^20; % Infinito
Teta= B_linha\(-Pd+Pg); % inv

```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 4.588513e-21.

```

% Perdas
erro_min = 1e-6;
erro = 1;
perdas = zeros(NumBarras,1);
Pperdas = zeros(NumLinhas,1);
Iteracoes = 0;

while erro > erro_min
    Teta_antigo = Teta;
    % Calculo de Pperdas = Gkm*(Teta(K)-Teta(M))^2
    for i=1:NumLinhas

        K = de(i);
        M = para(i);
        Pperdas(i) = G(i)*(Teta(K)-Teta(M))^2/100;
    end
end

```

```

        perdas(K) = Pperdas(i)/2;
        perdas(M) = Pperdas(i)/2;
    end
    % Calculo de Teta
    Teta= B_linha\(-Pd+Pg-perdas); % inv
    % Erro
    erro = max(abs(Teta-Teta_antigo));
    Iteracoes= Iteracoes+1;
end

```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 4.588513e-21.  
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```

Pkm = zeros(NumLinhas,1);

for i=1:NumLinhas
    K = de(i);
    M = para(i);
    Pkm(i) = (Teta(K)-Teta(M))*B(i)/Tap(i); % Pkm = Pk - Pm
end

```

```

% Variaveis de saida
disp('Fluxo de potencia linearizado - IEEE 14 Barras - Pd = 100%')

```

Fluxo de potencia linearizado - IEEE 14 Barras - Pd = 100%

```
disp('Theta: ')
```

Theta:

```
disp(Teta)
```

```

-0.0000
-0.1290
-0.2949
-0.2771
-0.2480
-0.3570
-0.3432
-0.3432
-0.3731
-0.3778
-0.3710
-0.3766
-0.3797
-0.3987

```

```
disp('Pkm: ')
```

Pkm:

```
disp(Pkm)
```

```
2.1802
1.1117
0.8380
0.8399
0.6841
-0.1041
-0.6921
0.3163
0.1727
0.4328
0.0702
0.0765
0.1740
-0.0000
0.2716
0.0548
0.0945
-0.0352
0.0155
0.0545
```

```
disp('Número de Iterações')
```

Número de Iterações

```
disp(Iteracoes)
```

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## IEEE 33 Barras

```
% Dados:
```

```
% [      NUM      TIPO      V      TETA      PG      QG      PD      QD      GSH      BSH ]
barras = [
    1      0      1.0000      0.0000      0      0      100.0      60.0      0.0      0.0;
    2      0      1.0000      0.0000      0      0      90.0      40.0      0.0      0.0;
    3      0      1.0000      0.0000      0      0      120.0      80.0      0.0      0.0;
    4      0      1.0000      0.0000      0      0      60.0      30.0      0.0      0.0;
    5      0      1.0000      0.0000      0      0      60.0      20.0      0.0      0.0;
    6      0      1.0000      0.0000      0      0      200.0     100.0      0.0      0.0;
    7      0      1.0000      0.0000      0      0      200.0     100.0      0.0      0.0;
    8      0      1.0000      0.0000      0      0      60.0      20.0      0.0      0.0;
    9      0      1.0000      0.0000      0      0      60.0      20.0      0.0      0.0;
   10      0      1.0000      0.0000      0      0      45.0      30.0      0.0      0.0;
   11      0      1.0000      0.0000      0      0      60.0      35.0      0.0      0.0;
   12      0      1.0000      0.0000      0      0      60.0      35.0      0.0      0.0;
   13      0      1.0000      0.0000      0      0      120.0      80.0      0.0      0.0;
```

14	0	1.0000	0.0000	0	0	60.0	10.0	0.0	0.0;
15	0	1.0000	0.0000	0	0	60.0	20.0	0.0	0.0;
16	0	1.0000	0.0000	0	0	60.0	20.0	0.0	0.0;
17	0	1.0000	0.0000	0	0	90.0	40.0	0.0	0.0;
18	0	1.0000	0.0000	0	0	90.0	40.0	0.0	0.0;
19	0	1.0000	0.0000	0	0	90.0	40.0	0.0	0.0;
20	0	1.0000	0.0000	0	0	90.0	40.0	0.0	0.0;
21	0	1.0000	0.0000	0	0	90.0	40.0	0.0	0.0;
22	0	1.0500	0.0000	0	0	90.0	50.0	0.0	0.0;
23	0	1.0000	0.0000	0	0	420.0	200.0	0.0	0.0;
24	0	1.0000	0.0000	0	0	420.0	200.0	0.0	0.0;
25	0	1.0500	0.0000	0	0	60.0	25.0	0.0	0.0;
26	0	1.0500	0.0000	0	0	60.0	25.0	0.0	0.0;
27	0	1.0000	0.0000	0	0	60.0	20.0	0.0	0.0;
28	0	1.0000	0.0000	0	0	120.0	70.0	0.0	0.0;
29	0	1.0000	0.0000	0	0	200.0	600.0	0.0	0.0;
30	0	1.0000	0.0000	0	0	150.0	70.0	0.0	0.0;
31	0	1.0000	0.0000	0	0	210.0	100.0	0.0	0.0;
32	0	1.0000	0.0000	0	0	60.0	40.0	0.0	0.0;
33	2	1.0000	0.0000	0	0	0.0	0.0	0.0	0.0

];

%	[FR	TO	R	X	BSHtotal	Tap	Tapmin	Tapmax]	
linhas	= [	33	1	0.0922	0.0470	0	0	0	0;
		1	2	0.4930	0.2511	0	0	0	0;
		2	3	0.3660	0.1864	0	0	0	0;
		3	4	0.3811	0.1941	0	0	0	0;
		4	5	0.8190	0.7070	0	0	0	0;
		5	6	0.1872	0.6188	0	0	0	0;
		6	7	0.7114	0.2351	0	0	0	0;
		7	8	1.0300	0.7400	0	0	0	0;
		8	9	1.0440	0.7400	0	0	0	0;
		9	10	0.1966	0.0650	0	0	0	0;
		10	11	0.3744	0.1238	0	0	0	0;
		11	12	1.4680	1.1550	0	0	0	0;
		12	13	0.5416	0.7129	0	0	0	0;
		13	14	0.5910	0.5260	0	0	0	0;
		14	15	0.7463	0.5450	0	0	0	0;
		15	16	1.2890	1.7210	0	0	0	0;
		16	17	0.7320	0.5740	0	0	0	0;
		1	18	0.1640	0.1565	0	0	0	0;
		18	19	1.5042	1.3554	0	0	0	0;
		19	20	0.4095	0.4784	0	0	0	0;
		20	21	0.7089	0.9373	0	0	0	0;
		2	22	0.4512	0.3083	0	0	0	0;
		22	23	0.8980	0.7091	0	0	0	0;
		23	24	0.8960	0.7011	0	0	0	0;
		5	25	0.2030	0.1034	0	0	0	0;

```

25      26      0.2842      0.1447      0      0      0      0;
26      27      1.0590      0.9337      0      0      0      0;
27      28      0.8042      0.7006      0      0      0      0;
28      29      0.5075      0.2585      0      0      0      0;
29      30      0.9744      0.9630      0      0      0      0;
30      31      0.3105      0.3619      0      0      0      0;
31      32      0.3410      0.5302      0      0      0      0;
];

```

```

Sb = 1e6;      % Potencia Base
Vb = 12.66e3; % Tensão Base
Zb = Vb^2/Sb;
linhas(:,3:4) = linhas(:,3:4)/Zb;

```

```

barras(:,7:8) = barras(:,7:8)*1e3/Sb;

```

```

ref = 1;
% =====
% Leitura dos dados de entrada

```

```

[~,~] = size(barras);

```

```

[~,~] = size(linhas);

```

```

[NumBarras,NumBCol] = size(barras);
[NumLinhas,NumLCol] = size(linhas);

```

```

% Linhas
% Init das variaveis
de = zeros(NumLinhas,1);
para = zeros(NumLinhas,1);
R = zeros(NumLinhas,1);
X = zeros(NumLinhas,1);
B = zeros(NumLinhas,1);
G = zeros(NumLinhas,1);
Tap = zeros(NumLinhas,1);

```

```

for i=1:NumLinhas
    de(i) = linhas(i,1);
    para(i) = linhas(i,2);
    R(i) = linhas(i,3);
    X(i) = linhas(i,4);
    B(i) = 1/X(i);
    G(i) = 1/(R(i) + 0.00001);
    Tap(i) = linhas(i,6);
end

```

```

% Desconsiderando taps
Tap = ones(NumLinhas,1);

```

```

% Barras
% Init das variaveis
Tipo = zeros(NumBarras,1);
V = zeros(NumBarras,1);
Teta = zeros(NumBarras,1);
Pg = zeros(NumBarras,1);
Qg = zeros(NumBarras,1);
Pd = zeros(NumBarras,1);
Qd = zeros(NumBarras,1);
Gsh = zeros(NumBarras,1);
Bsh = zeros(NumBarras,1);

for i=1:NumBarras
    Tipo(i) = barras(i,2);
    V(i) = barras(i,3);
    Teta(i) = barras(i,4);
    Pg(i) = barras(i,5);
    Qg(i) = barras(i,6);
    Pd(i) = barras(i,7);
    Qd(i) = barras(i,8);
    Gsh(i) = barras(i,9);
    Bsh(i) = barras(i,10);
end

% Potencias em PU
Pg = Pg/100;
Qg = Qg/100;
Pd = Pd/100;
Qd = Qd/100;

% =====
% Matriz B_linha

B_linha = zeros(NumBarras,NumBarras);

for i=1:NumLinhas
    K = de(i);
    M = para(i);
    B_linha(K,K) = B_linha(K,K) + B(i)/(Tap(i)^2); % diagonal principal considerando tap
    B_linha(M,M) = B_linha(M,M) + B(i); % diagonal principal
    B_linha(K,M) = B_linha(K,M) - B(i)/Tap(i); % Fora da diagonal principal
    B_linha(M,K) = B_linha(M,K) - B(i)/Tap(i); % Fora da diagonal principal
end

% =====
% Fluxo de potencia linearizado

```



```

B_REF = ref;
B_linha(B_REF,B_REF) = 10^20; % Infinito
Teta= B_linha\(-Pd+Pg); % inv

```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.169055e-20.

```

% Perdas
erro_min = 1e-6;
erro = 1;
perdas = zeros(NumBarras,1);
Pperdas = zeros(NumLinhas,1);
Iteracoes = 0;

while erro > erro_min
    Teta_antigo = Teta;
    % Calculo de Pperdas = Gkm*(Teta(K)-Teta(M))^2
    for i=1:NumLinhas

        K = de(i);
        M = para(i);
        Pperdas(i) = G(i)*(Teta(K)-Teta(M))^2/100;
        perdas(K) = Pperdas(i)/2;
        perdas(M) = Pperdas(i)/2;
    end
    % Calculo de Teta
    Teta= B_linha\(-Pd+Pg-perdas); % inv
    % Erro
    erro = max(abs(Teta-Teta_antigo));
    Iteracoes= Iteracoes+1;
end

```

Warning: Matrix is close to singular or badly scaled. Results may be inaccurate. RCOND = 2.169055e-20.

```

Pkm = zeros(NumLinhas,1);

for i=1:NumLinhas
    K = de(i);
    M = para(i);
    Pkm(i) = (Teta(K)-Teta(M))*B(i)/Tap(i); % Pkm = Pk - Pm
end

```

```

% Variaveis de saida
disp('Fluxo de potencia linearizado - IEEE 33 Barras - Pd = 100%')

```

Fluxo de potencia linearizado - IEEE 33 Barras - Pd = 100%

```
disp('Theta: ')
```

Theta:

```
disp(Teta)
```

```
1.0e-03 *
```

```
-0.0000  
-0.0510  
-0.0770  
-0.1026  
-0.1933  
-0.2348  
-0.2476  
-0.2788  
-0.3072  
-0.3094  
-0.3133  
-0.3458  
-0.3631  
-0.3720  
-0.3791  
-0.3952  
-0.3984  
-0.0035  
-0.0263  
-0.0317  
-0.0370  
-0.0689  
-0.1060  
-0.1244  
-0.1992  
-0.2070  
-0.2536  
-0.2859  
-0.2959  
-0.3211  
-0.3272  
-0.3292  
-0.0000
```

```
disp('Pkm: ')
```

```
Pkm:
```

```
disp(Pkm)
```

```
0  
0.0326  
0.0224  
0.0212  
0.0206  
0.0108  
0.0088  
0.0068  
0.0062  
0.0056  
0.0051  
0.0045  
0.0039  
0.0027  
0.0021  
0.0015  
0.0009  
0.0036  
0.0027
```

```
0.0018
0.0009
0.0093
0.0084
0.0042
0.0092
0.0086
0.0080
0.0074
0.0062
0.0042
0.0027
0.0006
```

```
disp('Número de Iterações')
```

Número de Iterações

```
disp(Iteracoes)
```

1

### Conclusão:

Foi observado que a convergência ocorreu rapidamente, principalmente para o sistema de 33 barras em que o resultado convergiu na primeira iteração, demonstrando que as perdas são realmente pequenas. Considera-se o trabalho um sucesso, visto que a implementação foi capaz de convergir e demonstrar as perdas no sistema.