

Computational Statistics

Hyperspherical VAE

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10th JAN 2024



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2018 paper from Tim R. Davidson *et al.* [DFDC⁺]

- Replacing the Gaussian prior and approximate posterior distributions with a von Mises-Fisher distribution
- Goal: better model data with a hyperspherical latent structure
- Various experiments, where the \mathcal{S} -VAE (von Mises-Fisher distributions) often outperforms the \mathcal{N} -VAE (Gaussian distributions) in low dimensions



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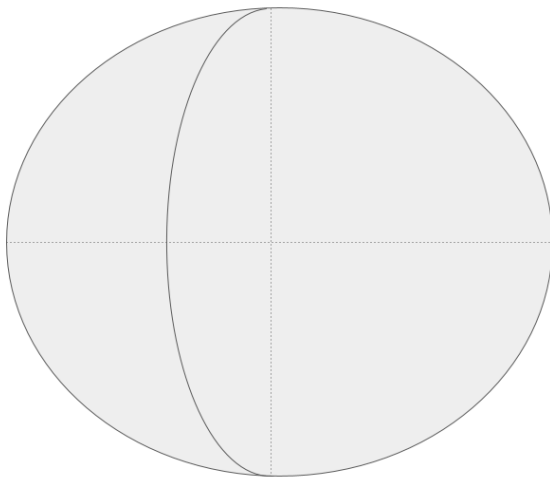
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Démontrer que la méthode de sampling marche



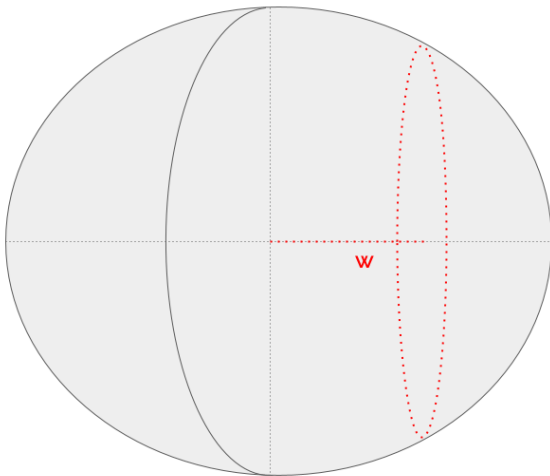
Sampling w from $g(w|\kappa, \theta)$



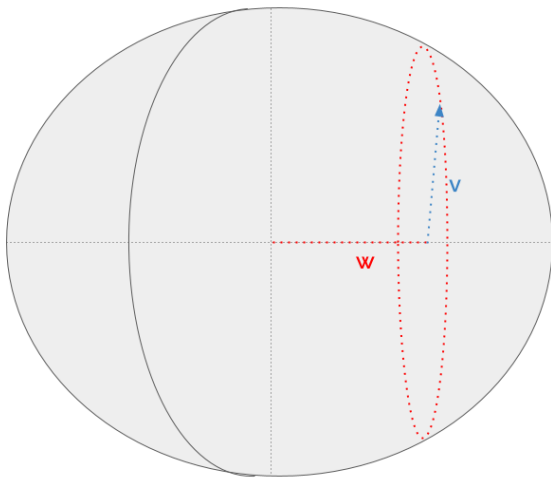
S^2 : unit sphere in \mathbb{R}^3



Sampling w



Sampling w



Sampling w

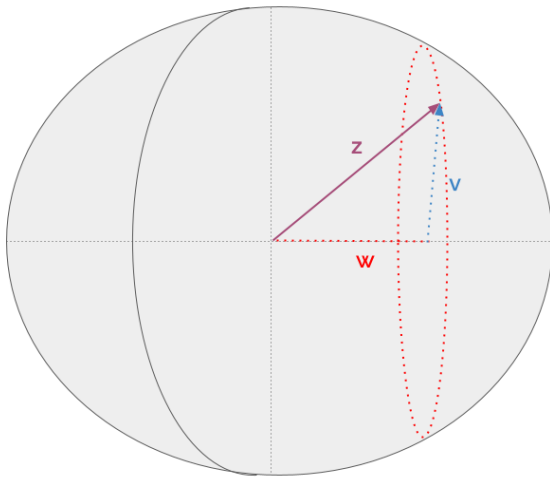


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Reparameterization Trick

The authors use a reparameterization trick that has been extended to distributions that can be sampled using rejection sampling [NRLB20].

Algorithm 1 Reparameterized Rejection Sampling (from [NRLB20])

```
1:  $i \leftarrow 0$ 
2: repeat
3:    $i \leftarrow i + 1$ 
4:   Propose  $\varepsilon_i \sim s(\varepsilon)$ 
5:   Simulate  $u_i \sim \mathcal{U}[0, 1]$ 
6: until  $u_i < \frac{g(h(\varepsilon_i, \theta); \theta)}{r(h(\varepsilon_i, \theta); \theta)}$ 
7: return  $\varepsilon_i$ 
```



By noting $\pi(\varepsilon|\theta)$ the distribution of the resulting ε , we have

$$\nabla_{\theta} \mathbb{E}_{g(\varepsilon|\theta)}[\dots] = \mathbb{E}_{\pi(\varepsilon|\theta)}[\dots] = \mathbb{E}_{(\varepsilon_i, U_i)_i}[\dots]$$

Problem: $(\varepsilon_i, U_i)_{i \in \mathbb{N}}$ is not a random variable (it is a stochastic process)
No reference to a convergence proof in [DFDC⁺, NRLB20, PBJ12, MG14]



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Experiments on link prediction

- Expliquer l'expérience (tâche à faire, données, negative sampling)
reproduire l'expérience
- data (Ines)
- implementer les modèles (Victor VGAE)
- gradients pour le hyperspherical VAE
- courbes d'entraînement dans le cas normal
- entraînement et evaluation



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Conclusion and Discussion

- Quite meaningful contribution in low dimensions
- Algorithm not really useful in high dimensions, due to vanishing surface problem and soap bubble effect of the \mathcal{N} -VAE
- Much less variance parameters (1 vs. d for \mathcal{N} -VAE), so possibly less expressivity
- vérifier différentes dimensions de l'espace latent
- et algo vraiment utile en petite ou moyenne dimension ?





Tim R. Davidson, Luca Falorsi, Nicola De Cao, Thomas Kipf, and Jakub M. Tomczak.

Hyperspherical variational auto-encoders.



Andriy Mnih and Karol Gregor.

Neural variational inference and learning in belief networks, 2014.



Christian A. Naesseth, Francisco J. R. Ruiz, Scott W. Linderman, and David M. Blei.

Reparameterization gradients through acceptance-rejection sampling algorithms, 2020.



John Paisley, David Blei, and Michael Jordan.

Variational bayesian inference with stochastic search, 2012.

