LAB Experiments

- Implement the activity selection problem to get a clear understanding of greedy approach.
- Get a detailed insight of dynamic programming approach by the implementation of Matrix Chain Multiplication problem and see the impact of parenthesis positioning on time requirements for matrix multiplication.
- Compare the performance of Dijkstra and Bellman ford algorithm for the single source shortest path problem.
- Through 0/1 Knapsack problem, analyze the greedy and dynamic programming approach for the same dataset.
- Implement the sum of subset and N Queen problem.
- Compare the Backtracking and Branch & Bound Approach by the implementation of 0/1 Knapsack problem. Also compare the performance with dynamic programming approach.

ANSWERS

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1>#include <stdio.h>
void activitySelection(int start[], int finish[], int n) {
   int i, j;
   printf("Selected activities: \n");
  i = 0;
   printf("%d ", i);
  for (j = 1; j < n; j++) {
     if (start[j] >= finish[i]) {
        printf("%d ", j);
        i = j;
  }
}
int main() {
  int n, i;
   printf("Enter the number of activities: ");
  scanf("%d", &n);
   int start[n], finish[n];
   printf("Enter start times:\n");
  for (i = 0; i < n; i++)
      printf("Start time of activity %d: ", i+1);
      scanf("%d", &start[i]);
  }
  printf("Enter finish times:\n");
  for (i = 0; i < n; i++) {
      printf("Finish time of activity %d: ", i+1);
      scanf("%d", &finish[i]);
  }
  activitySelection(start, finish, n);
  return 0;
```

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}
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2>#include <stdio.h>
#include inits.h>
int mcm(int p[], int n)
  int m[n][n];
  int i, j, k, L, q;
  for (i = 1; i < n; i++)
     m[i][i] = 0;
  printf("Initial m matrix:\n");
  for (i = 1; i < n; i++) {
     for (j = 1; j < n; j++) {
       printf("%d ", m[i][j]);
     printf("\n");
  printf("\n");
  for (L = 2; L < n; L++) {
     printf("Processing chain length %d:\n", L);
     for (i = 1; i < n - L + 1; i++) {
       j = i + L - 1;
       m[i][j] = INT_MAX;
       for (k = i; k \le j - 1; k++) {
          q = m[i][k] + m[k + 1][i] + p[i - 1] * p[k] * p[i];
          %d + %d + %d = %d\n",
             k, i, k, k + 1, j, p[i - 1], p[k], p[j], m[i][k], m[k + 1][j], p[i - 1] * p[k] * p[j], q);
          if (q < m[i][j]) {
             m[i][j] = q;
             printf(" Updating m[%d][%d] = %d\n", i, j, m[i][j]);
          }
       }
     printf("\n");
     printf("M matrix after processing chain length %d:\n", L);
     for (i = 1; i < n; i++)
       for (j = 1; j < n; j++) {
          printf("%d ", m[i][j]);
       printf("\n");
     printf("\n");
  }
  return m[1][n - 1];
}
int main()
  int n;
  printf("Enter the number of matrices: ");
  scanf("%d", &n);
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int arr[n + 1];
  printf("Enter the dimensions of the matrices (p0 p1 ... pn): ");
  for (int i = 0; i <= n; i++) {
     scanf("%d", &arr[i]);
  printf("Minimum number of multiplications is %d\n", mcm(arr, n + 1));
  return 0;
}
3>#include <stdio.h>
#include <limits.h>
#define V 9
int minDistance(int dist[], int sptSet[]) {
  int min = INT_MAX, min_index;
  for (int v = 0; v < V; v++) {
     if (\operatorname{sptSet}[v] == 0 \&\& \operatorname{dist}[v] <= \min) \{
        min = dist[v];
        min index = v;
  return min_index;
void dijkstra(int graph[V][V], int src) {
  int dist[V], sptSet[V], prev[V];
  for (int i = 0; i < V; i++) {
     dist[i] = INT_MAX;
     sptSet[i] = 0;
     prev[i] = -1;
  dist[src] = 0;
  for (int count = 0; count < V - 1; count++) {
     int u = minDistance(dist, sptSet);
     sptSet[u] = 1;
     for (int v = 0; v < V; v++) {
        if (!sptSet[v] && graph[u][v] && dist[u] != INT_MAX && dist[u] + graph[u][v] < dist[v]) {
           dist[v] = dist[u] + graph[u][v];
           prev[v] = u;
     }
  }
  printf("Dijkstra Algorithm - Shortest distances and paths from source vertex %d:\n", src);
  for (int i = 0; i < V; i++) {
     printf("%d \t %d \t Path: ", i, dist[i]);
     int path[V], pathIndex = 0;
     for (int j = i; j != -1; j = prev[j]) {
        path[pathIndex++] = j;
     for (int j = pathIndex - 1; j >= 0; j--) {
        printf("%d ", path[j]);
     printf("\n");
  }
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}
void bellmanFord(int graph[V][V], int src) {
   int dist[V], prev[V];
   for (int i = 0; i < V; i++) {
      dist[i] = INT_MAX;
      prev[i] = -1;
   dist[src] = 0;
   for (int i = 1; i < V; i++) {
     for (int u = 0; u < V; u++) {
         for (int v = 0; v < V; v++) {
           if (graph[u][v] != 0 \&\& dist[u] != INT_MAX \&\& dist[u] + graph[u][v] < dist[v]) {
              dist[v] = dist[u] + graph[u][v];
              prev[v] = u;
           }
        }
     }
   }
   printf("\nBellman-Ford Algorithm - Shortest distances and paths from source vertex %d:\n",
src);
   for (int i = 0; i < V; i++) {
      printf("%d \t %d \t Path: ", i, dist[i]);
      int path[V], pathIndex = 0;
     for (int j = i; j != -1; j = prev[j]) {
         path[pathIndex++] = j;
      for (int j = pathIndex - 1; j >= 0; j--) {
         printf("%d ", path[j]);
      printf("\n");
}
int main() {
   int graph[V][V] = {
      \{0, 4, 0, 0, 0, 0, 0, 8, 0\},\
      \{4, 0, 8, 0, 0, 0, 0, 0, 0, 0\}
      \{0, 8, 0, 7, 0, 4, 0, 0, 0\},\
      \{0, 0, 7, 0, 9, 14, 0, 0, 0\},\
      \{0, 0, 0, 9, 0, 10, 0, 0, 0\},\
      \{0, 0, 4, 14, 10, 0, 2, 0, 0\},\
      \{0, 0, 0, 0, 0, 2, 0, 1, 6\},\
      \{8, 0, 0, 0, 0, 0, 1, 0, 7\},\
      \{0, 0, 0, 0, 0, 0, 6, 7, 0\}
   };
   int source;
   printf("Enter the source vertex (0 to 8): ");
   scanf("%d", &source);
   printf("\nDijkstra's Algorithm Results:\n");
   dijkstra(graph, source);
   printf("\nBellman-Ford Algorithm Results:\n");
   bellmanFord(graph, source);
   return 0;
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}
4>#include <stdio.h>
#define MAX_ITEMS 100
// Greedy Approach: 0/1 Knapsack
float greedyKnapsack(int values[], int weights[], int n, int W) {
  float ratio[n];
  int i, j;
  for (i = 0; i < n; i++)
     ratio[i] = (float)values[i] / weights[i];
  // Sort items by value/weight ratio in descending order
  for (i = 0; i < n-1; i++) {
     for (j = i+1; j < n; j++) {
        if (ratio[i] < ratio[j]) {
          float tempRatio = ratio[i];
           ratio[i] = ratio[j];
           ratio[j] = tempRatio;
           int tempValue = values[i];
           values[i] = values[j];
           values[j] = tempValue;
           int tempWeight = weights[i];
           weights[i] = weights[j];
           weights[j] = tempWeight;
     }
  }
  int currentWeight = 0;
  float totalValue = 0.0;
  // Pick items based on greedy approach
  for (i = 0; i < n; i++) {
     if (currentWeight + weights[i] <= W) {
        currentWeight += weights[i];
        totalValue += values[i];
  }
  return totalValue;
}
// Dynamic Programming Approach: 0/1 Knapsack (Optimal Solution)
int knapsack(int values[], int weights[], int n, int W) {
  int dp[n+1][W+1];
  int i, w;
  for (i = 0; i \le n; i++) {
     for (w = 0; w \le W; w++) {
        if (i == 0 || w == 0) {
           dp[i][w] = 0;
        } else if (weights[i-1] <= w) {</pre>
           dp[i][w] = (values[i-1] + dp[i-1][w - weights[i-1]] > dp[i-1][w])?
                   values[i-1] + dp[i-1][w - weights[i-1]] : dp[i-1][w];
        } else {
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dp[i][w] = dp[i-1][w];
       }
    }
  }
  return dp[n][W];
int main() {
  int n, W, i;
  printf("Enter the number of items: ");
  scanf("%d", &n);
  int values[n], weights[n];
  printf("Enter the values and weights of the items:\n");
  for (i = 0; i < n; i++)
     printf("Item %d - Value: ", i + 1);
     scanf("%d", &values[i]);
     printf("Item %d - Weight: ", i + 1);
     scanf("%d", &weights[i]);
  }
  printf("Enter the capacity of the knapsack: ");
  scanf("%d", &W);
  printf("\nGreedy Approach: Maximum value = %.2f\n", greedyKnapsack(values, weights, n, W));
  printf("Dynamic Programming Approach: Maximum value = %d\n", knapsack(values, weights,
n, W));
  return 0;
}
5>// SUM OF SUBSET
#include <stdio.h>
#include <stdbool.h>
bool subsetSum(int arr[], int n, int sum, int subset[], int* subsetSize) {
  if (sum == 0) {
     return true;
  if (n == 0 || sum < 0) {
     return false;
  if (subsetSum(arr, n - 1, sum, subset, subsetSize)) {
     return true;
  }
  if (arr[n - 1] \le sum) {
     subset[(*subsetSize)++] = arr[n - 1];
     if (subsetSum(arr, n - 1, sum - arr[n - 1], subset, subsetSize)) {
        return true;
      'subsetSize)--;
  }
  return false;
```

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}
int main() {
  int n, sum;
  printf("Enter number of elements: ");
  scanf("%d", &n);
  int arr[n];
  printf("Enter the elements: ");
  for (int i = 0; i < n; i++) {
     scanf("%d", &arr[i]);
  printf("Enter the sum to check: ");
  scanf("%d", &sum);
  int subset[n];
  int subsetSize = 0;
  if (subsetSum(arr, n, sum, subset, &subsetSize)) {
     printf("Subset with the given sum: ");
     for (int i = 0; i < subsetSize; i++) {
        printf("%d ", subset[i]);
     printf("\n");
  } else {
     printf("No subset with the given sum exists.\n");
  }
  return 0;
}
// N QUEEN PROBLEM
#include <stdio.h>
#include <stdbool.h>
#define MAX_N 30
int board[MAX_N];
int leftDiagonal[2 * MAX_N - 1], rightDiagonal[2 * MAX_N - 1], column[MAX_N];
void printSolution(int N) {
  for (int i = 0; i < N; i++) {
     for (int j = 0; j < N; j++) {
        if (board[i] == j)
          printf("Q ");
        else
          printf(". ");
     printf("\n");
}
bool isSafe(int row, int col, int N) {
  return !column[col] && !leftDiagonal[row - col + N - 1] && !rightDiagonal[row + col];
}
void placeQueen(int row, int col, int N) {
  column[col] = 1;
  leftDiagonal[row - col + N - 1] = 1;
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rightDiagonal[row + col] = 1;
  board[row] = col;
}
void removeQueen(int row, int col, int N) {
  column[col] = 0;
  leftDiagonal[row - col + N - 1] = 0;
  rightDiagonal[row + col] = 0;
}
bool solveNQ(int row, int N) {
  if (row == N) {
     printSolution(N);
     return true;
  }
  for (int col = 0; col < N; col++) {
     if (isSafe(row, col, N)) {
        placeQueen(row, col, N);
        if (solveNQ(row + 1, N))
          return true;
        removeQueen(row, col, N);
  }
  return false;
int main() {
  int N;
  printf("Enter the value of N (size of the board): ");
  scanf("%d", &N);
  if (N > MAX_N) {
     printf("N is too large! Maximum supported N is %d.\n", MAX_N);
     return 0;
  }
  for (int i = 0; i < N; i++) {
     board[i] = -1;
  }
  if (!solveNQ(0, N)) {
     printf("Solution does not exist.\n");
  return 0;
}
6>#include <stdio.h>
#include <stdlib.h>
int n, W;
int *weights, *values;
int maxValBacktracking = 0;
void knapsackBacktracking(int i, int currentWeight, int currentValue) {
  if (i == n) {
     if (currentWeight <= W && currentValue > maxValBacktracking) {
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maxValBacktracking = currentValue;
     }
     return;
  }
  knapsackBacktracking(i + 1, currentWeight, currentValue);
  if (currentWeight + weights[i] <= W) {
     knapsackBacktracking(i + 1, currentWeight + weights[i], currentValue + values[i]);
  }
}
// Branch and Bound approach
typedef struct {
  int level, profit, weight;
} Node;
int bound(Node u) {
  if (u.weight >= W)
     return 0;
  int result = u.profit;
  int j = u.level + 1;
  int totalWeight = u.weight;
  while (j < n && totalWeight + weights[j] <= W) {
     totalWeight += weights[j];
     result += values[j];
     j++;
  if (j < n)
     result += (W - totalWeight) * values[j] / weights[j];
  return result;
}
int knapsackBranchBound() {
  Node u, v;
  u.level = -1;
  u.profit = u.weight = 0;
  int maxProfit = 0;
  Node *queue = (Node*) malloc(n * sizeof(Node));
  int front = 0, rear = 0;
  queue[rear++] = u;
  while (front < rear) {
     u = queue[front++];
     if (u.level == n - 1)
       continue;
     v.level = u.level + 1;
     v.weight = u.weight + weights[v.level];
     v.profit = u.profit + values[v.level];
     if (v.weight <= W && v.profit > maxProfit)
        maxProfit = v.profit;
     if (bound(v) > maxProfit)
        queue[rear++] = v;
     v.weight = u.weight;
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v.profit = u.profit;
     if (bound(v) > maxProfit)
       queue[rear++] = v;
  }
  free(queue);
  return maxProfit;
}
int main() {
  printf("Enter number of items: ");
  scanf("%d", &n);
  printf("Enter the capacity of the knapsack: ");
  scanf("%d", &W);
  weights = (int*) malloc(n * sizeof(int));
  values = (int*) malloc(n * sizeof(int));
  printf("Enter weights and values of the items:\n");
  for (int i = 0; i < n; i++) {
     scanf("%d %d", &weights[i], &values[i]);
  // Backtracking approach
  maxValBacktracking = 0;
  knapsackBacktracking(0, 0, 0);
  printf("Backtracking Maximum Value: %d\n", maxValBacktracking);
  // Branch & Bound approach
  int maxValBranchBound = knapsackBranchBound();
  printf("Branch & Bound Maximum Value: %d\n", maxValBranchBound);
  return 0;
}
```