



# Vedant Chavan Computer Vision & AI Engineer

[✉](mailto:vedantchavan097@gmail.com) vedantchavan097@gmail.com [📞](tel:+4915143560223) +49 151 43560223 [LinkedIn](https://linkedin.com/in/vedant-chavan-97ml/) linkedin.com/in/vedant-chavan-97ml/  
[🔗](http://vedantsanjaychavan.de) vedantsanjaychavan.de/ [GitHub](https://github.com/vedantchavan004) github.com/vedantchavan004 [📍](#) 59555 Lippstadt, Germany  
[📄](#) Available Immediately | Open to Relocation

## Profile

Computer Vision & AI Engineer with expertise in **3D perception, sensor fusion, and spatial data processing** for robotics and autonomous systems. Experienced in **stereo vision, point-cloud reconstruction, and GPU-optimized model deployment** using PyTorch, CUDA, and ONNX. Passionate about developing **scalable, real-time AI** that bridges the physical and digital worlds.

## Skills

**3D Perception:** Stereo Vision, Multi-Sensor Fusion, Triangulation, Calibration, 3D Reconstruction, Point Cloud Processing, SLAM  
**Deep Learning:** 2D/3D Detection, Tracking, Segmentation, Anomaly Detection  
**Frameworks & Tools:** PyTorch, TensorFlow, OpenCV, ONNX Runtime, CUDA, Unreal Engine 5, COLMAP, Open3D, Docker  
**Programming:** Python (advanced), C++ (intermediate), Bash  
**Optimization & Deployment:** TensorRT, Quantization, AWS, CI/CD (GitHub Actions)  
**Generative AI / LLMs:** LangChain, FAISS, Streamlit, Hugging Face, Prompt Engineering

## Experience

- 03/2024 – 11/2024 **Master's Thesis - Stereo Vision for Adaptive Headlight Systems**  
Lippstadt, Germany  
Hella GmbH & Co. KGa (FORVIA HELLA)
  - Developed a **lightweight stereo-depth CNN** for long-range perception; achieved **3% D1-all error** on KITTI.
  - Generated **9000 synthetic stereo pairs** in Unreal Engine 5 simulating lighting and weather variations; fine-tuned with real data for robust generalization.
  - Combined depth maps with YOLO for 3D localization and trajectory estimation in varying illumination.
  - Reduced inference latency from **120 to 70 ms** with ONNX Runtime; containerized pipeline for reproducible deployment.
- 08/2023 – 02/2024 **AI Research Intern - Intelligent Perception (ADAS)**  
Lippstadt, Germany  
Hella GmbH & Co. KGa (FORVIA HELLA)
  - Enhanced YOLOv8 for nighttime scenes, boosting mAP by 30% through augmentation and hyperparameter tuning.
  - Developed **stereo triangulation and calibration** for 3D localization and lane estimation.
  - Created and benchmarked **multi-object tracking pipelines** (DeepSORT, feature matching, OpenCV) validated with laser ground truth.
  - Assessed **DINO, SAM, and DETR** for foundation-model adaptation in automotive perception.
  - Automated dataset workflows with **Docker**, enabling reproducible GPU training.

## Selected Projects

- 06/2025 – 07/2025 **3D Scene Reconstruction and Gaussian Splatting**
  - Reconstructed dense 3D scenes from **COLMAP** point clouds using **Gaussian Splatting** to generate photorealistic spatial data for digital twin workflows.
  - Evaluated reprojection accuracy and spatial fidelity across multiple camera poses, ensuring high-quality, scalable real-time 3D visualizations.
- 05/2025 – 06/2025 **Visual Anomaly Detection for PCB Inspection (OpenCV / PyTorch)**
  - Developed an **unsupervised** anomaly-detection model using **PaDiM** and Mahalanobis distance; achieved **99% pixel-level accuracy** on MVTec AD.
  - Visualized defect maps and feature embeddings for explainable AI analysis.

- 02/2025 – 03/2025 **Cloud Vision Pipeline (AWS / FastAPI / ONNX)**  
• Deployed a real-time segmentation microservice on **AWS (EC2/ECR)** using **FastAPI** and **Docker**.  
• Reduced inference latency to under 30ms with ONNX Runtime and automated CI/CD workflows.
- 03/2025 – 04/2025 **Chatbot with Retrieval-Augmented Generation (RAG)**  
Built a **retrieval-augmented chatbot** using FAISS & LangChain; deployed on Hugging Face Spaces with Streamlit UI for interactive Q&A.
- 10/2022 – 02/2023 **Vision-Guided Bin-Picking for Industrial Robotics**  
• Developed a YOLO-based **6D pose-estimation** (detection and orientation) system for ABB robot pick-and-place tasks in dynamic environments.  
• Trained on hybrid synthetic (Blender) and real datasets to reach **98% detection accuracy**.

## Education

- 10/2021 – 01/2025 **M.Eng. Engineering Sciences – Mechatronics**  
Rosenheim, Technische Hochschule Rosenheim  
Germany
- 09/2020 – 04/2021 **PG Diploma - Advanced Computing**  
Pune, India Centre for Development of Advanced Computing (CDAC)
- 06/2015 – 09/2019 **B.Tech - Mechanical Engineering**  
Vellore, India Vellore Institute of Technology

## Certificates

- Oracle Cloud Infrastructure 2025 Certified Generative AI Professional
- Generative Deep Learning with TensorFlow (2025)
- Advanced Computer Vision with TensorFlow (2025)
- Stanford Machine Learning (2022)

## Languages

**English:** C1 (fluent) | **German:** B1 (intermediate)