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New York, USA

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in vedantparnaik

vedantparnaik

FDUCATION

University at Buffalo, SUNY

Buffalo, NY

Master of Science in Engineering and Applied Science

Aug '22 - May '24

• Coursework: Software Development, Generative AI, Deep Learning, Robotics Algorithms, Advanced Machine Learning.

Savitribai Phule Pune University (SPPU)

Pune, India

Bachelor of Engineering in Computer Science

Aug '17 - Mav '21

• Coursework: Analysis of Algorithms, Data Structures and Algorithms, Object-Oriented Programming, Database Management System, Computer Networks, Natural Language Processing, Embedded Programming.

TECHNICAL SKILLS

Languages and Frameworks: Python, Java, J2EE, C++, C, JavaScript, HTML5, Perl, Bash, SQL, TypeScript, React.js, Spring. Data and Tools: Git, GitHub, Docker, Jenkins, Jira, REST API, Kubernetes, MySQL, MongoDB, NoSQL, Airflow, Kafka, CI/CD. Cloud Services: AWS (EC2, S3, Lambda, API Gateway, CodeDeploy, CloudWatch), Azure, GCP.

ML Frameworks: FastAPI, NumPy, Pandas, Matplotlib, TensorFlow, Scikit-learn, PyTorch, NLTK, CUDA, HuggingFace.

EXPERIENCE

University at Buffalo, SUNY Software Engineer Intern

New York, USA

May '23 - Aug '23

- Designed a neural network combining convolutional layers for feature extraction, and LSTMs for temporal analysis, achieving 72% accuracy in predicting the stage of Parkinson.
- Created a structured dataset from 15 diverse tests, integrating data from the National Institute of Health, USC.
- Developed personalized treatment plans, leveraging insights from model predictions and integrating SHAP (SHapley Additive exPlanations) for transparency in decision-making.

University at Buffalo, SUNY

New York, USA

Student Researcher

Sep '22 - Dec '22

- Architected a multi-label classification pipeline using stacking ensemble techniques (XGBoost, CATBoost) on the UC Irvine HCV dataset for Hepatitis Classification.
- Implemented feature engineering, hyperparameter tuning, and cross-validation, achieving 94.73% accuracy on unseen data.
- Classified stages of Hepatitis C, approaching the SOTA benchmark of 96% with robust model generalization and low bias-variance tradeoff.

IndiaFirst Robotics

Pune, India

Software Engineer Intern

Aug '19 - April '20

- Military UTV to detect landmines: Worked on designing a UTV on NVIDIA Jetson with mine detection sensor, IMU, GPS, and LiDAR for navigation and mark location with 0.5-meter precision.
- Implemented Image segmentation and depth estimation on the UTV using the KITTI dataset, achieving 2-meter accuracy and establishing spatial relationships for real-time navigation and obstacle avoidance.
- Two-wheel Self-balancing Robot: Developed software systems for a prototype of EvoBOT for grasping, carrying tasks, and path traversal on slopes, rough terrains, and slippery surfaces.

PROJECT HIGHLIGHTS

Equity Research Chatbot | Node.js, React, MongoDB, Docker, AWS, Hugging Face [GitHub]

Jun '24 - Jul '24

- Engineered an automated chatbot to streamline equity research by retrieving and analyzing financial news articles.
- Built with a Node is backend, React frontend, and MongoDB for search history; used Hugging Face for article processing and Pinecone for semantic search, achieving 92% accuracy.
- Deployed on AWS with Docker and CI/CD via GitHub Actions, reducing analysis time by 85%.

ASL (American Sign Language) Fingerspelling Recognition | CNNs and Transformer Models [GitHub]

Dec '23 - Apr '24

- Composed a CNN with TensorFlow and Keras, achieving 85% validation accuracy in classifying ASL fingerspelling images, leveraging Mediapipe for hand landmark detection and keypoint extraction.
- Utilized a Transformer model to capture temporal dependencies in hand keypoints, boosting recognition accuracy, and compiled the model with the Adam optimizer and dropout layers to prevent overfitting.
- Achieved top 10% ranking in Kaggle competition with 74.3% test accuracy by implementing hyperparameter tuning.

LEADERSHIP AND HONORS

• Awarded All India Rank 1 among 80 participating colleges in an International Robotics Competition. Developed a manually controlled robot and an autonomous horse-robot with GAIT movement. June '19

• Orchestrated chapter operations as President of Information Systems Audit and Control Associa-

May '21

tion Committee, India; attended by over 1200 students and foreign delegates.