Lecture 14: Joins!

Announcements: Two Hints

- You may want to do Trigger activity for project 2.
 - We've noticed those who do it have less trouble with project!
 - Seems like we're good here © Exciting for us!
- We posted an activity for you to do on your own... it may overlap heavily with a ps #3 problem... (this is not necessary but helpful).
 - The solutions will not be posted.
- Sorry the Google lecture was not recorded! Last minute thing...

1. Nested Loop Joins

What you will learn about in this section

1. RECAP: Joins

1. Nested Loop Join (NLJ)

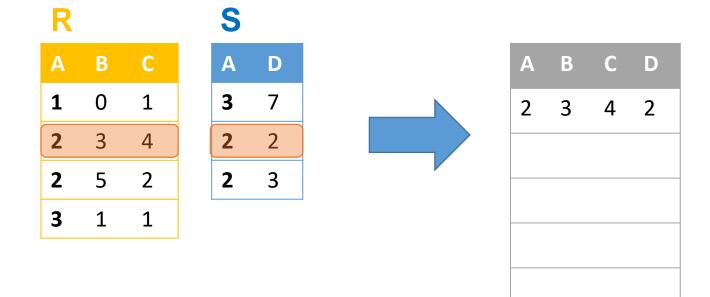
1. Block Nested Loop Join (BNLJ)

1. Index Nested Loop Join (INLJ)

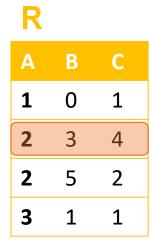
Joins

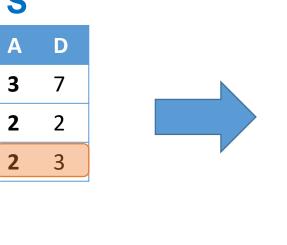
RECAP: Joins

 $\mathbf{R}\bowtie \mathbf{S}$ | SELECT R.A,B,C,D FROM R, S WHERE R.A = S.A



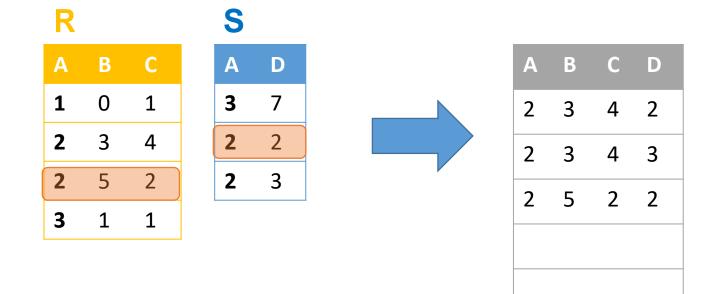
 $\mathbf{R}\bowtie \mathbf{S}$ | SELECT R.A,B,C,D FROM R, S WHERE R.A = S.A



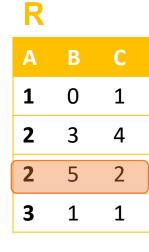


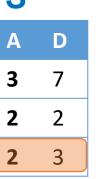
Α	В	С	D
2	3	4	2
2	3	4	3

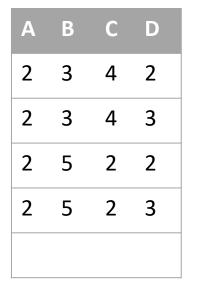
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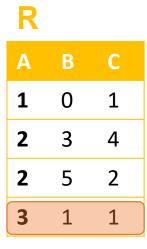
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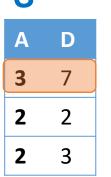


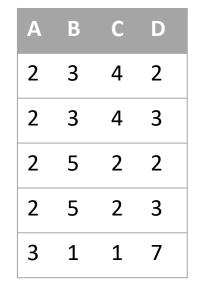




 $\mathbf{R}\bowtie \mathbf{S}$ | SELECT R.A,B,C,D FROM R, S WHERE R.A = S.A





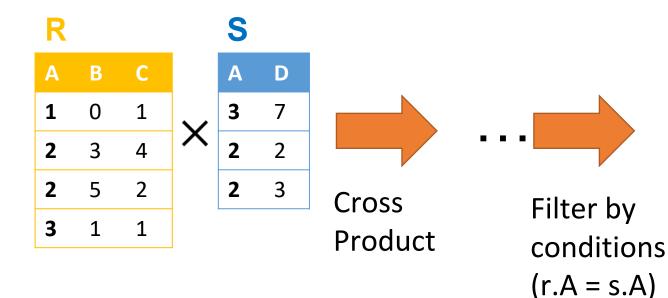


Semantically: A Subset of the Cross Product

 $\mathbf{R}\bowtie S$

SELECT R.A,B,C,D FROM R, S WHERE R.A = S.A

Example: Returns all pairs of tuples $r \in R$, $s \in S$ such that r.A = s.A



A	В	С	D
2	3	4	2
2	3	4	3
2	5	2	2
2	5	2	3
3	1	1	7

Can we actually implement a join in this way?

Notes

• We write $R \bowtie S$ to mean join R and S by returning all tuple pairs where **all shared attributes** are equal

• We write $R \bowtie S$ on A to mean join R and S by returning all tuple pairs where **attribute(s)** A are equal

 For simplicity, we'll consider joins on two tables and with equality constraints ("equijoins")

However joins *can* merge > 2 tables, and some algorithms do support non-equality constraints!

Nested Loop Joins

Notes

We are again considering "IO aware" algorithms:
 care about disk IO

- Given a relation R, let:
 - T(R) = # of tuples in R
 - P(R) = # of pages in R

Recall that we read / write entire pages with disk IO

Note also that we omit ceilings in calculations...
 good exercise to put back in!

```
Compute R ⋈ S on A:
  for r in R:
  for s in S:
   if r[A] == s[A]:
    yield (r,s)
```

```
Compute R ⋈ S on A:
    for r in R:
    for s in S:
        if r[A] == s[A]:
            yield (r,s)
```

Cost:

P(R)

1. Loop over the tuples in R

Note that our IO cost is based on the number of *pages* loaded, not the number of tuples!

```
Compute R ⋈ S on A:
   for r in R:
   for s in S:
    if r[A] == s[A]:
       yield (r,s)
```

Cost:

$$P(R) + T(R)*P(S)$$

- 1. Loop over the tuples in R
- 1. For every tuple in R, loop over all the tuples in S

Have to read *all of S* from disk for *every tuple in R!*

```
Compute R ⋈ S on A:
  for r in R:
  for s in S:
   if r[A] == s[A]:
    yield (r,s)
```

Cost:

$$P(R) + T(R)*P(S)$$

- 1. Loop over the tuples in R
- 1. For every tuple in R, loop over all the tuples in S
- 1. Check against join conditions

Note that NLJ can handle things other than equality constraints... just check in the *if* statement!

```
Compute R ⋈ S on A:
  for r in R:
  for s in S:
   if r[A] == s[A]:
    yield (r,s)
```

What would **OUT** be if our join condition is trivial (if TRUE)?

OUT could be bigger than P(R)*P(S)... but usually not that bad

Cost:

$$P(R) + T(R)*P(S) + OUT$$

- 1. Loop over the tuples in R
- 1. For every tuple in R, loop over all the tuples in S
- 1. Check against join conditions
- 1. Write out (to page, then when page full, to disk)

```
Compute R ⋈ S on A:
  for r in R:
   for s in S:
    if r[A] == s[A]:
      yield (r,s)
```

Cost:

$$P(R) + T(R)*P(S) + OUT$$

What if R ("outer") and S ("inner") switched?



$$P(S) + T(S)*P(R) + OUT$$

Outer vs. inner selection makes a huge difference-DBMS needs to know which relation is smaller!

IO-Aware Approach

Given **B+1** pages of memory

```
Compute R \bowtie S \ on \ A:
  for each B-1 pages pr of R:
     for page ps of S:
       for each tuple r in pr:
         for each tuple s in ps:
           if r[A] == s[A]:
              yield (r,s)
```

Cost:

P(R)

1. Load in B-1 pages of R at a time (leaving 1 page each free for S & output)

Note: There could be some speedup here due to the fact that we're reading in multiple pages sequentially however we'll ignore this here!

Given **B+1** pages of memory

```
Compute R \bowtie S \ on \ A:
  for each B-1 pages pr of R:
     for page ps of S:
       for each tuple r in pr:
         for each tuple s in ps:
            if r[A] == s[A]:
              yield (r,s)
```

Cost:

$$P(R) + \frac{P(R)}{B-1}P(S)$$

- 1. Load in B-1 pages of R at a time (leaving 1 page each free for S & output)
- 1. For each (B-1)-page segment of R, load each page of S

Note: Faster to iterate over the *smaller* relation first!

Given **B+1** pages of memory

```
Compute R ⋈ S on A:
   for each B-1 pages pr of R:
    for page ps of S:
     for each tuple r in pr:
        for each tuple s in ps:
        if r[A] == s[A]:
        yield (r,s)
```

Cost:

$$P(R) + \frac{P(R)}{B-1}P(S)$$

- 1. Load in B-1 pages of R at a time (leaving 1 page each free for S & output)
- 1. For each (B-1)-page segment of R, load each page of S
- 1. Check against the join conditions

BNLJ can also handle non-equality constraints

Given **B+1** pages of memory

```
Compute R ⋈ S on A:
   for each B-1 pages pr of R:
    for page ps of S:
      for each tuple r in pr:
        for each tuple s in ps:
        if r[A] == s[A]:
        yield (r,s)
```

Again, **OUT** could be bigger than P(R)*P(S)... but usually not that bad

Cost:

$$P(R) + \frac{P(R)}{B-1}P(S) + OUT$$

- 1. Load in B-1 pages of R at a time (leaving 1 page each free for S & output)
- 1. For each (B-1)-page segment of R, load each page of S
- 1. Check against the join conditions

1. Write out

BNLJ vs. NLJ: Benefits of IO Aware

- In BNLJ, by loading larger chunks of R, we minimize the number of full disk reads of S
 - We only read all of S from disk for every (B-1)-page segment of R!
 - Still the full cross-product, but more done only in memory

NLJ

$$P(R) + T(R)*P(S) + OUT$$

BNL

$$P(R) + T(R)*P(S) + OUT$$
 $P(R) + \frac{P(R)}{B-1}P(S) + OUT$

BNLJ is faster by roughly $\frac{(B-1)T(R)}{P(R)}$!

BNLJ vs. NLJ: Benefits of IO Aware

- **&** Example:
 - R: 500 pages
 - S: 1000 pages
 - 100 tuples / page
 - We have 12 pages of memory (B = 11)

Ignoring OUT here...

- NLJ: Cost = 500 + 50,000*1000 = 50 Million IOs ~= 140 hours
- BNLJ: Cost = $500 + \frac{500*1000}{10} = 50$ Thousand IOs ~= 0.14 hours

A very real difference from a small change in the algorithm!

Smarter than Cross-Products

Smarter than Cross-Products: From Quadratic to Nearly Linear

- All joins that compute the full cross-product have some quadratic term
 - For example we saw:

BNL
$$P(R) + \frac{P(R)}{B-1}P(S) + OUT$$

NLJ P(R) + T(R)P(S) + OUT

- Now we'll see some (nearly) linear joins:
 - ~ O(P(R) + P(S) + OUT), where again OUT could be quadratic but is usually better

We get this gain by *taking advantage of structure*- moving to equality constraints ("equijoin") only!

Index Nested Loop Join (INLJ)

```
Compute R ⋈ S on A:
   Given index idx on S.A:
   for r in R:
    s in idx(r[A]):
    yield r,s
```

Cost:

$$P(R) + T(R)*L + OUT$$

where L is the IO cost to access all the distinct values in the index; assuming these fit on one page, $L \sim 3$ is good est.

We can use an index (e.g. B+ Tree) to avoid doing the full cross-product!

Joins: A Cage Match

Message: It's all about the memory!

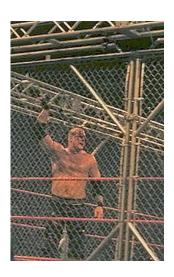
Today's Lecture

1. Sort-Merge Join (SMJ)

1. Hash Join (HJ)

1. The Cage Match: SMJ vs. HJ

1. Sort-Merge Join (SMJ)



What you will learn about in this section

1. Sort-Merge Join

1. "Backup" & Total Cost

1. Optimizations

1. ACTIVITY: Sequential Flooding

Sort Merge Join (SMJ): Basic Procedure

To compute $R \bowtie S$ on A:

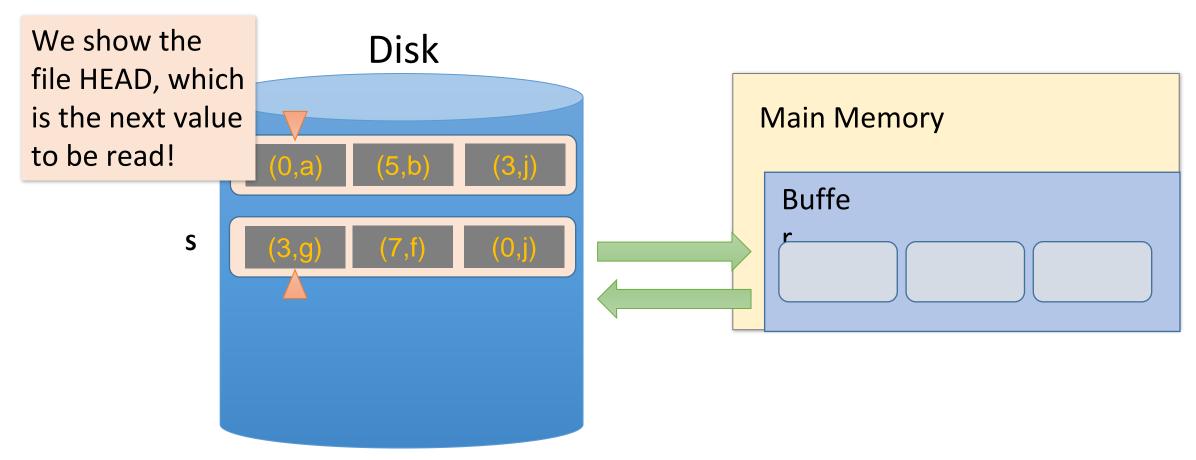
- 1. Sort R, S on A using *external merge sort*
- 2. Scan sorted files and "merge"
- 3. [May need to "backup"- see next subsection]

Note that we are only considering equality join conditions here

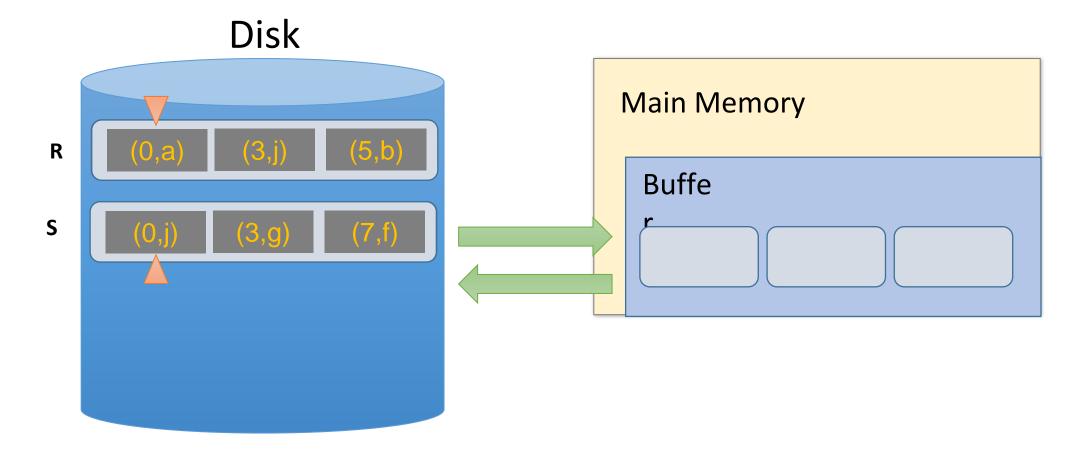
Note that if R, S are already sorted on A, SMJ will be awesome!

SMJ Example: $R \bowtie S \ on \ A$ with 3 page buffer

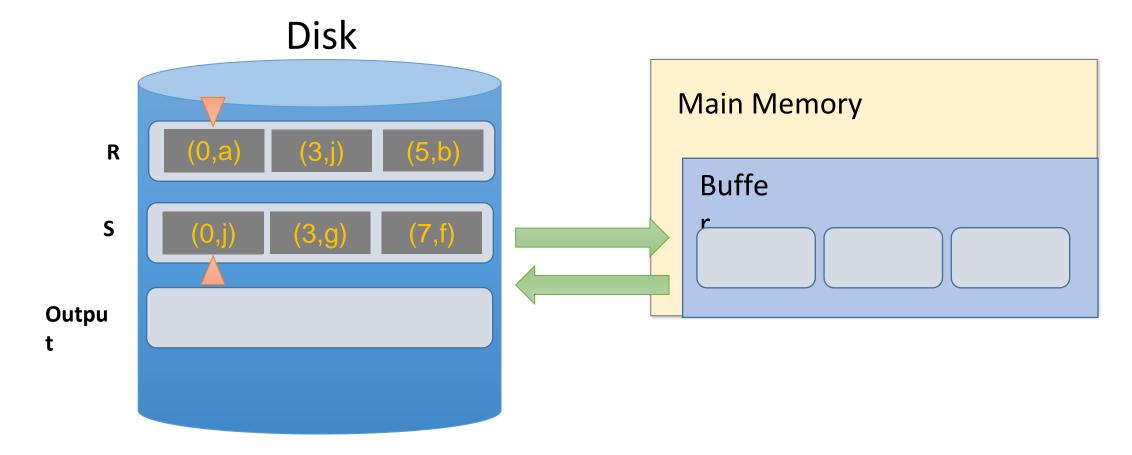
• For simplicity: Let each page be one tuple, and let the first value be A



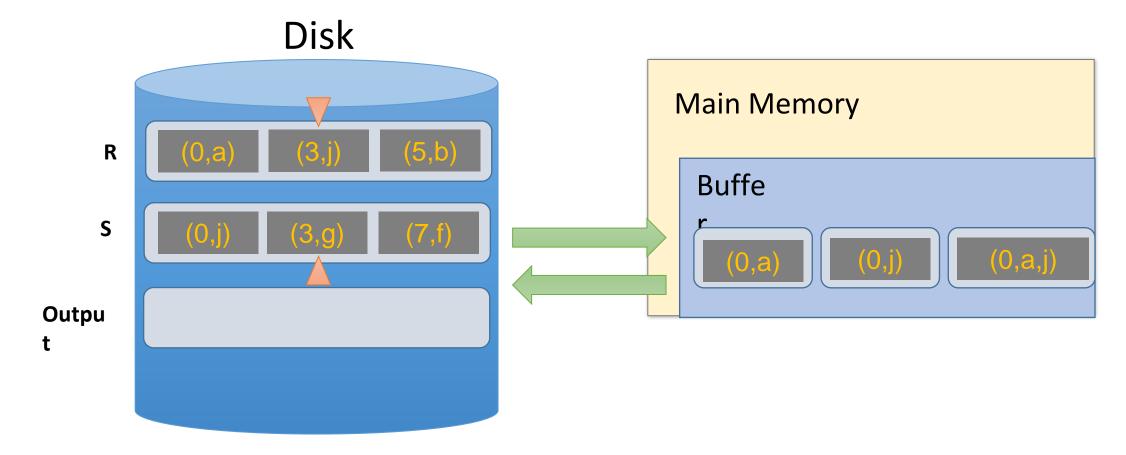
1. Sort the relations R, S on the join key (first value)



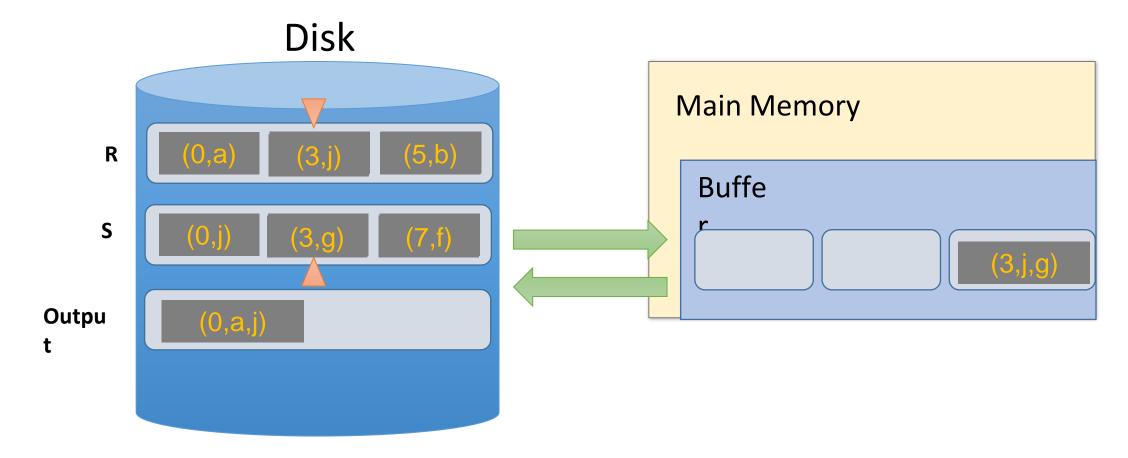
2. Scan and "merge" on join key!



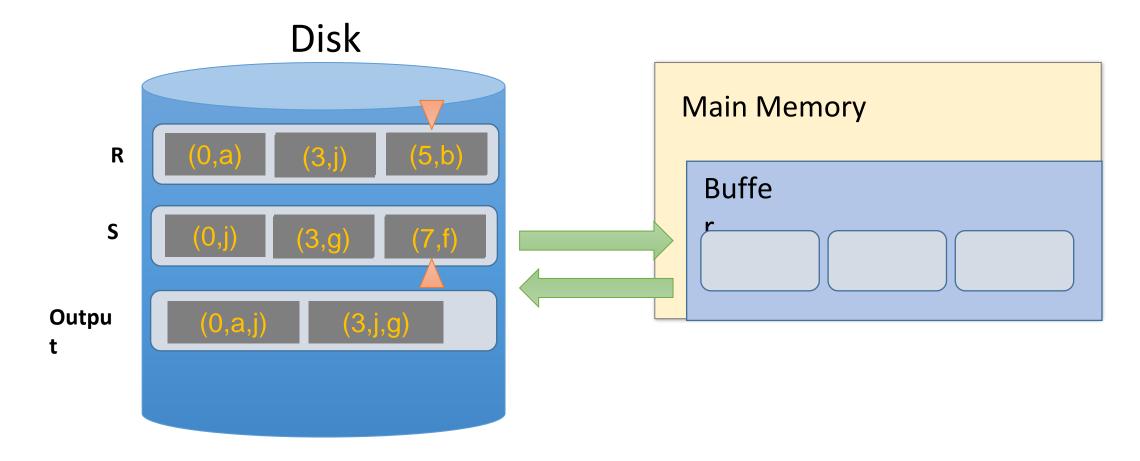
2. Scan and "merge" on join key!



2. Scan and "merge" on join key!

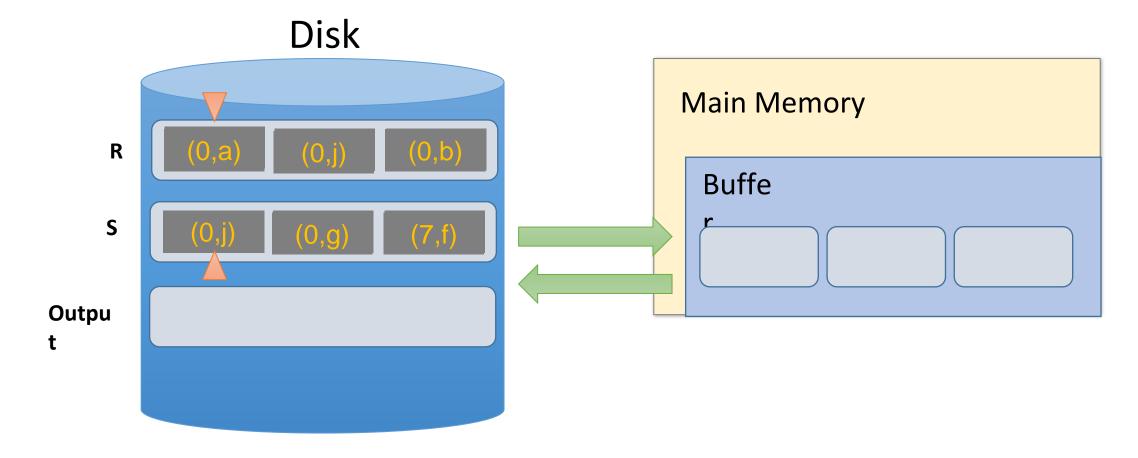


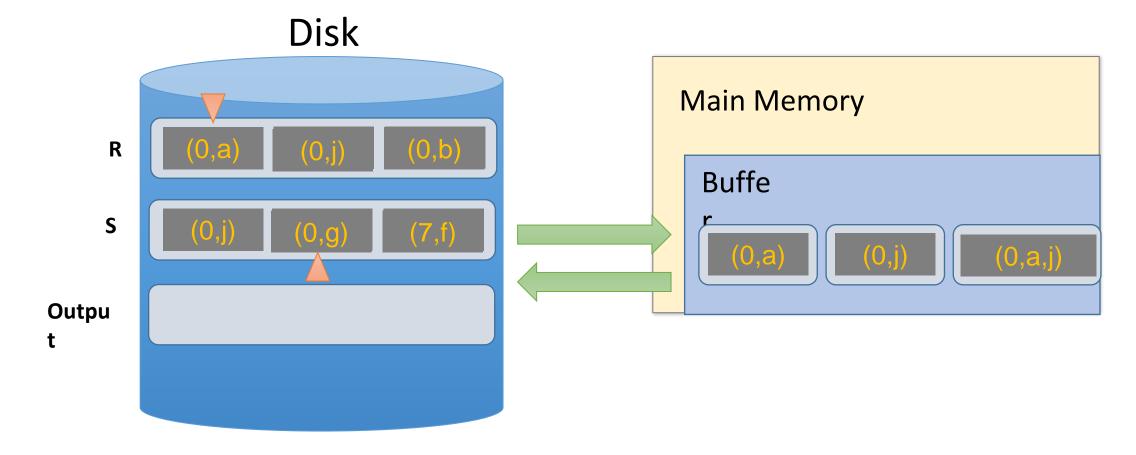
2. Done!

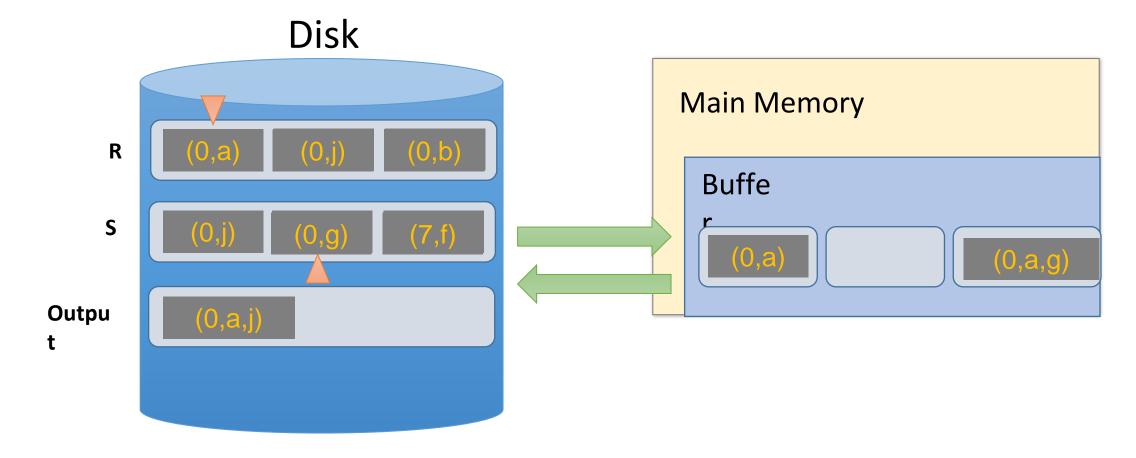


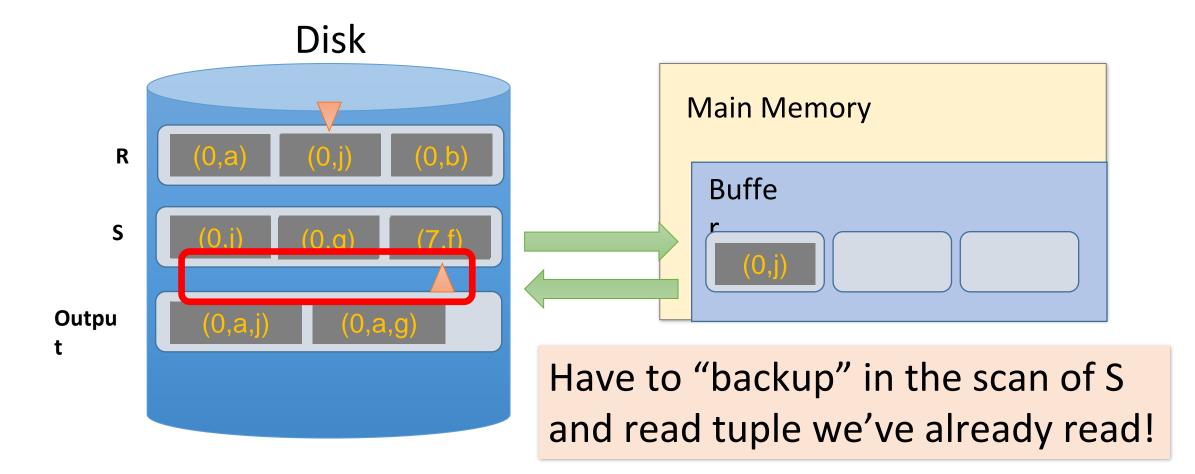
Lecture 15 > Section 1 > Backup

What happens with duplicate join keys?









Backup

- At best, no backup 2 scan takes P(R) + P(S) reads
 - For ex: if no duplicate values in join attribute
- At worst (e.g. full backup each time), scan could take P(R) * P(S) reads!
 - For ex: if *all* duplicate values in join attribute, i.e. all tuples in R and S have the same value for the join attribute
 - Roughly: For each page of R, we'll have to back up and read each page of S...
- Often not that bad however, plus we can:
 - Leave more data in buffer (for larger buffers)
 - Can "zig-zag" (see animation)

SMJ: Total cost

Cost of SMJ is cost of sorting R and S...

- Plus the cost of scanning: ~P(R)+P(S)
 - Because of backup: in worst case P(R)*P(S); but this would be very unlikely

Plus the cost of writing out: ~P(R)+P(S) but in worst case T(R)*T(S)

Recall: Sort(N)
$$\approx 2N \left(\left[\log_B \frac{N}{2(B+1)} \right] + 1 \right)$$

Note: this is using repacking, where we estimate that we can create initial runs of length $\sim 2(B+1)$

SMJ vs. BNLJ: Steel Cage Match

- If we have 100 buffer pages, P(R) = 1000 pages and P(S) = 500 pages:
 - Sort both in two passes: 2 * 2 * 1000 + 2 * 2 * 500 = 6,000 IOs
 - Merge phase 1000 + 500 = 1,500 IOs
 - = 7,500 IOs + OUT

What is BNLJ?

•
$$500 + 1000* \left[\frac{500}{98} \right] = 6,500 \text{ IOs} + \text{OUT}$$

- But, if we have 35 buffer pages?
 - Sort Merge has same behavior (still 2 passes)
 - BNLJ? <u>15,500 IOs + OUT!</u>



SMJ is ~ linear vs. BNLJ is quadratic... But it's all about the memory.

A Simple Optimization: Merges Merged!

Given **B+1** buffer

• SMJ is composed of a *sort phase* and a *merge phase*

pages

- During the sort phase, run passes of external merge sort on R and S
 - Suppose at some point, R and S have <= B (sorted) runs in total
 - We could do two merges (for each of R & S) at this point, complete the sort phase, and start the merge phase...
 - OR, we could combine them: do one B-way merge and complete the join!

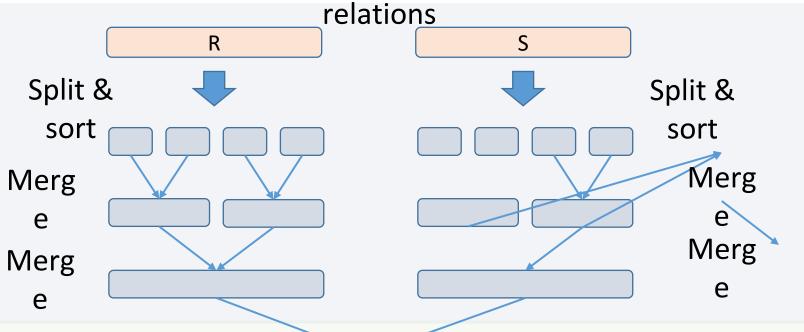
Un-Optimized SMJ

Given **B+1** buffer

pages

Unsorted input

Sort Phase (Ext. Merge Sort)



Merge / Join Phase

Joined output file created!

Simple SMJ Optimization

Given **B+1** buffer

Split &

sort

Merg

e

pages

S

Unsorted input

Sort Phase (Ext. Merge Sort)

Merge / Join

<= B total runs

relations R Split & sort Merg е

> B-Way Merge / Join

Phase Joined output file created!

Simple SMJ Optimization

Given **B+1** buffer

- 8 Now, on this last pass, we only do P(R) + P(S) IOs to complete the join!
- If we can initially split R and S into B total runs each of length approx. <= 2(B+1), assuming repacking lets us create initial runs of $\sim 2(B+1)$ then we only need 3(P(R) + P(S)) + OUT for SMJ!
 - 2 R/W per page to sort runs in memory, 1 R per page to B-way merge / join!
- How much memory for this to happen?
 - $\frac{P(R)+P(S)}{B} \le 2(B+1) \Rightarrow \sim P(R)+P(S) \le 2B^2$
 - Thus, $max{P(R), P(S)} \le B^2$ is an approximate sufficient condition

See Lecture 15, Slide 13-14 – to clarify this slide.

If the larger of R,S has <= B² pages, then SMJ costs **3(P(R)+P(S)) + OUT**!

Takeaway points from SMJ

If input already sorted on join key, skip the sorts.

- SMJ is basically linear.
- Nasty but unlikely case: Many duplicate join keys.

SMJ needs to sort **both** relations

• If max { P(R), P(S) } < B² then cost is 3(P(R)+P(S)) + OUT

4. Hash Join (HJ)



What you will learn about in this section

1. Hash Join

1. Memory requirements

Recall: Hashing

- Magic of hashing:
 - A hash function h_B maps into [0,B-1]
 - And maps nearly uniformly
- A hash **collision** is when x != y but $h_B(x) = h_B(y)$
 - Note however that it will <u>never</u> occur that x = y but $h_B(x) != h_B(y)$
- We hash on an attribute A, so our has function is $h_B(t)$ has the form $h_B(t.A)$.
 - Collisions may be more frequent.

Recall: Mad Hash Collisions





Say something here to justify this slide's existence? [TODO]

Hash Join: High-level procedure

To compute R ⋈ S on A:

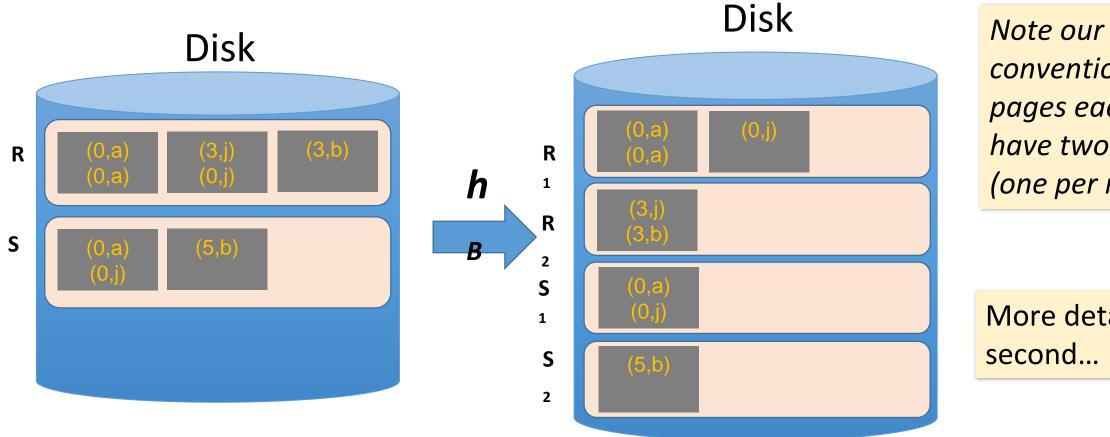
Note again that we are only considering equality constraints here

 Partition Phase: Using one (shared) hash function h_B, partition R and S into B buckets

- Matching Phase: Take pairs of buckets whose tuples have the same values for h, and join these
 - Use BNLJ here; or hash again → either way, operating on small partitions so fast!

We *decompose* the problem using h_B , then complete the join

1. Partition Phase: Using one (shared) hash function h_B , partition R and S into **B** buckets

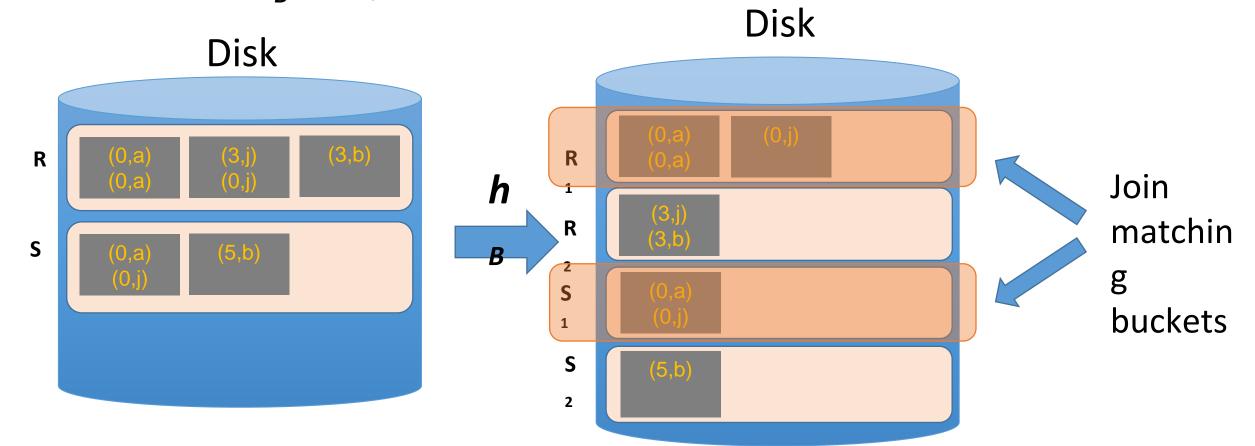


Note our new convention: pages each have two tuples (one per row)

More detail in a

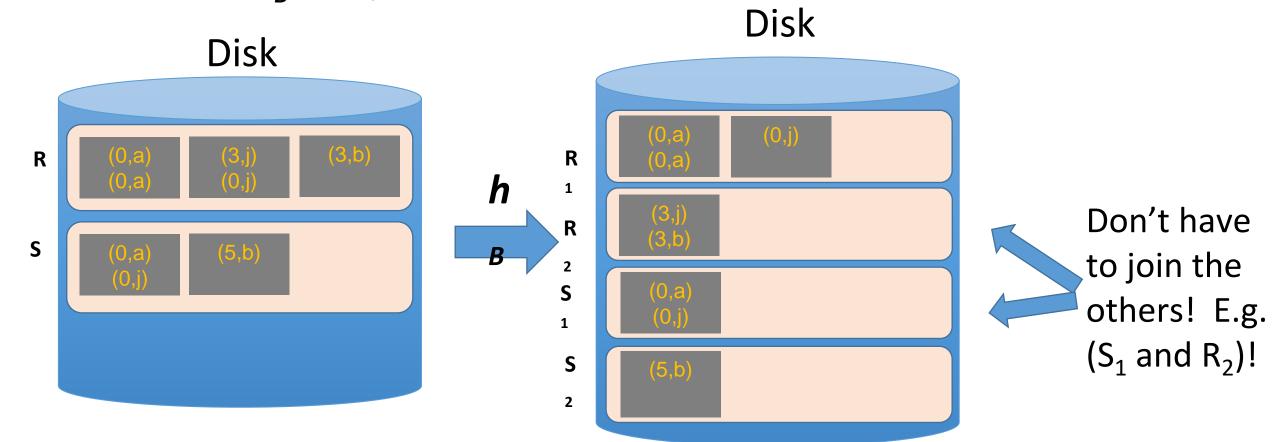
Hash Join: High-level procedure

2. Matching Phase: Take pairs of buckets whose tuples have the same values for h_B , and join these



Hash Join: High-level procedure

2. Matching Phase: Take pairs of buckets whose tuples have the same values for h_B , and join these



Goal: For each relation, partition relation into **buckets** such that if $h_B(t.A) = h_B(t'.A)$ they are in the same bucket

Given B+1 buffer pages, we partition into B buckets:

- We use B buffer pages for output (one for each bucket), and 1 for input
 - The "dual" of sorting.
 - For each tuple t in input, copy to buffer page for h_B(t.A)
 - When page fills up, flush to disk.

How big are the resulting buckets?

Given **B+1** buffer pages

- Given N input pages, we partition into B buckets:
 - 12 Ideally our buckets are each of size ~ N/B pages
- What happens if there are hash collisions?
 - Buckets could be > N/B
 - We'll do several passes...
- What happens if there are duplicate join keys?
 - Nothing we can do here... could have some skew in size of the buckets

How big do we want the resulting buckets?

Given **B+1** buffer pages

- Ideally, our buckets would be of size $\leq B-1$ pages
 - 1 for input page, 1 for output page, B-1 for each bucket
- Recall: If we want to join a bucket from R and one from S, we can do BNLJ in linear time if for one of them (wlog say R), $P(R) \leq B 1!$
 - And more generally, being able to fit bucket in memory is advantageous

Recall for BNLJ:

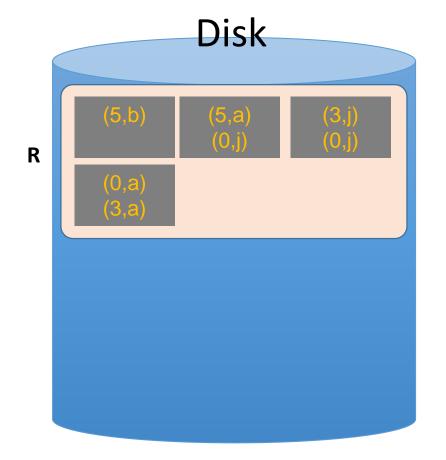
$$P(R) + \frac{P(R)P(S)}{B-1}$$

- We can keep partitioning buckets that are > B-1 pages, until they are $\leq B-1$ pages
 - Using a new hash key which will split them...

We'll call each of these a "pass" again...

Given B+1 = 3 buffer pages

We partition into B = 2 buckets using hash function h_2 so that we can have one buffer page for each partition (and one for input)

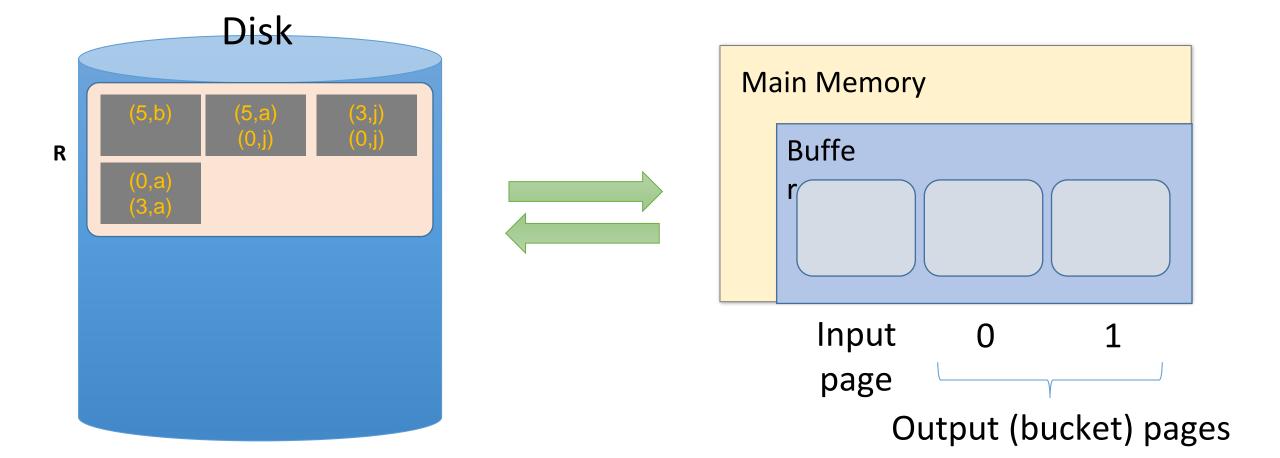


For simplicity, we'll look at partitioning one of the two relations- we just do the same for the other relation!

Recall: our goal will be to get **B = 2 buckets** of size <= **B-1 1 page each**

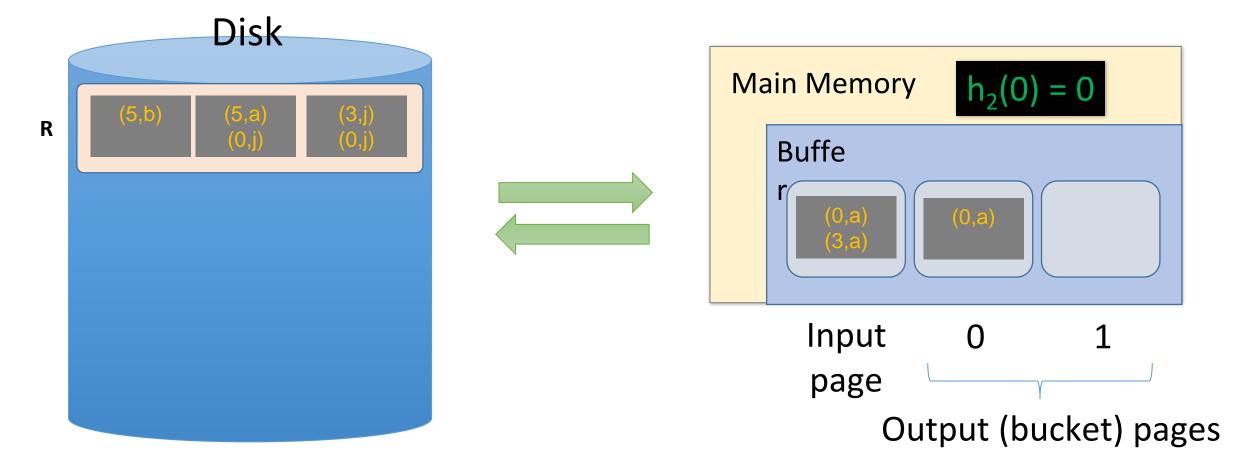
Given B+1=3 buffer pages

1. We read pages from R into the "input" page of the buffer...



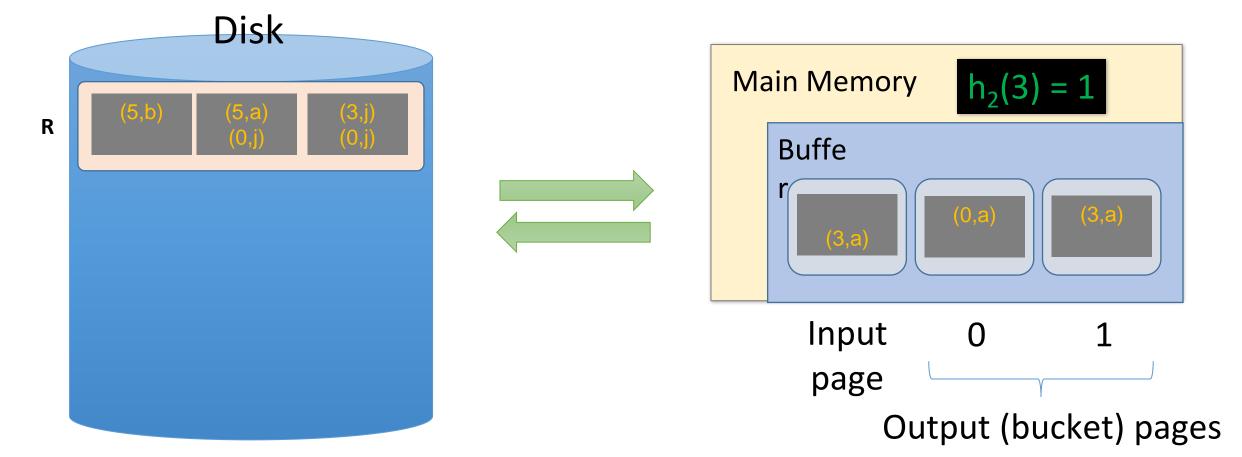
Given **B+1 = 3** buffer pages

2. Then we use **hash function** h_2 to sort into the buckets, which each have one page in the buffer



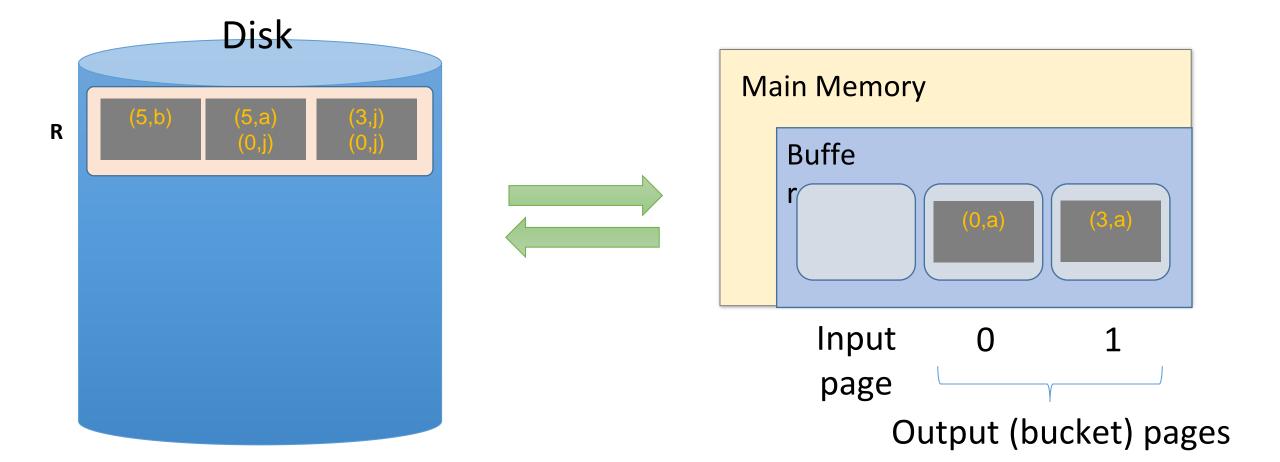
Given B+1 = 3 buffer pages

2. Then we use **hash function** h_2 to sort into the buckets, which each have one page in the buffer



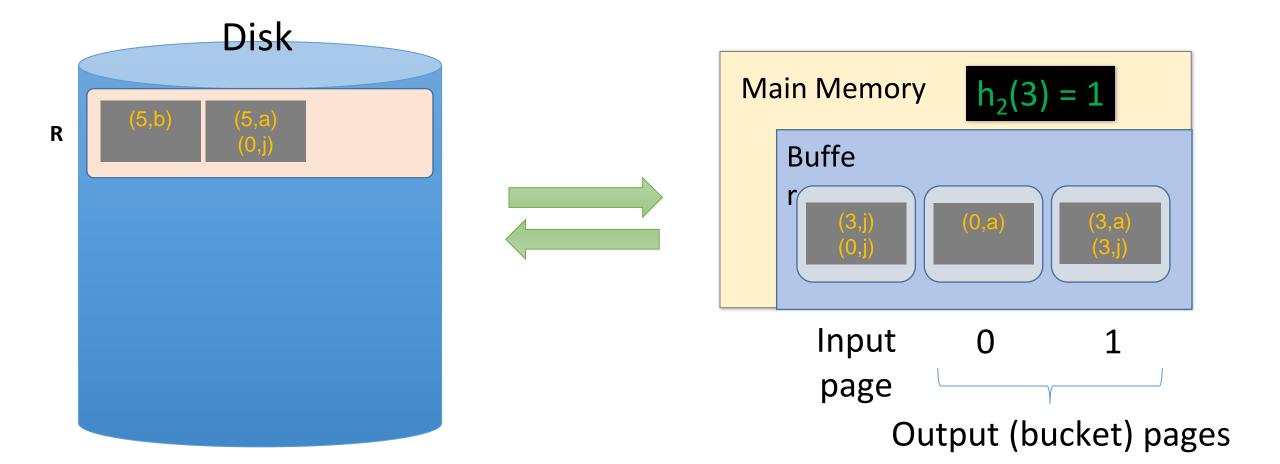
Given B+1=3 buffer pages

3. We repeat until the buffer bucket pages are full...



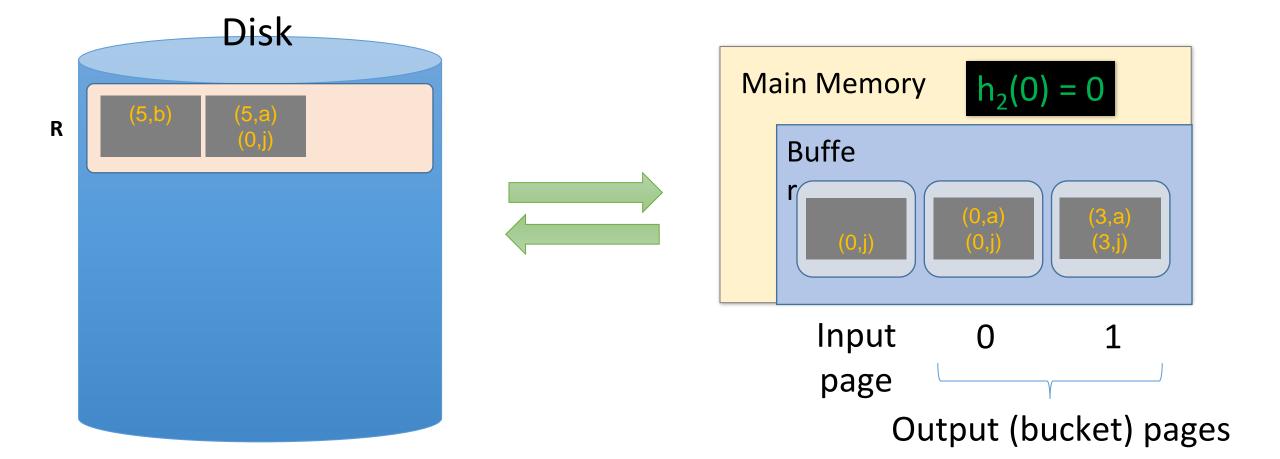
Given B+1=3 buffer pages

3. We repeat until the buffer bucket pages are full...



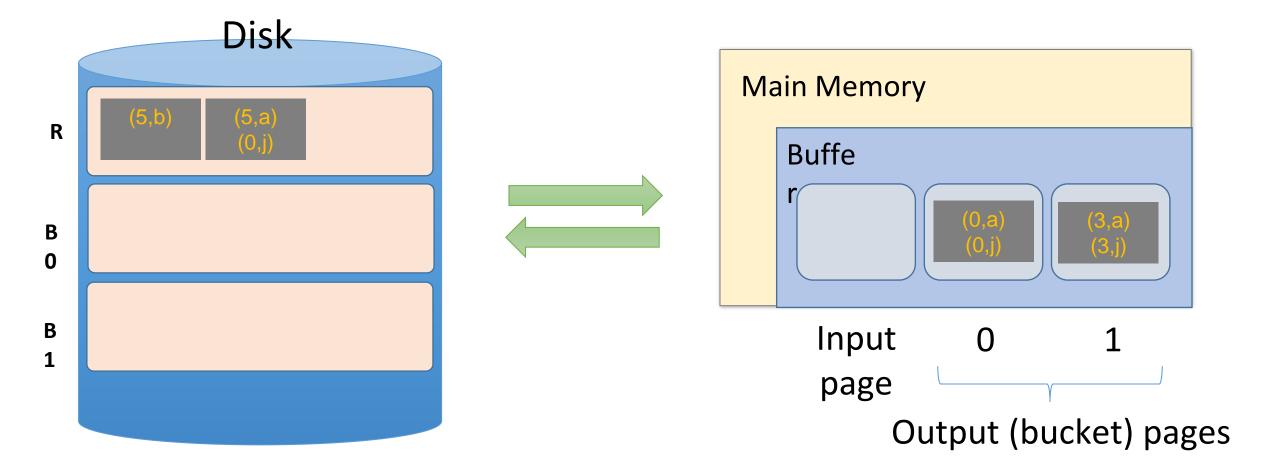
Given **B+1 = 3** buffer pages

3. We repeat until the buffer bucket pages are full...



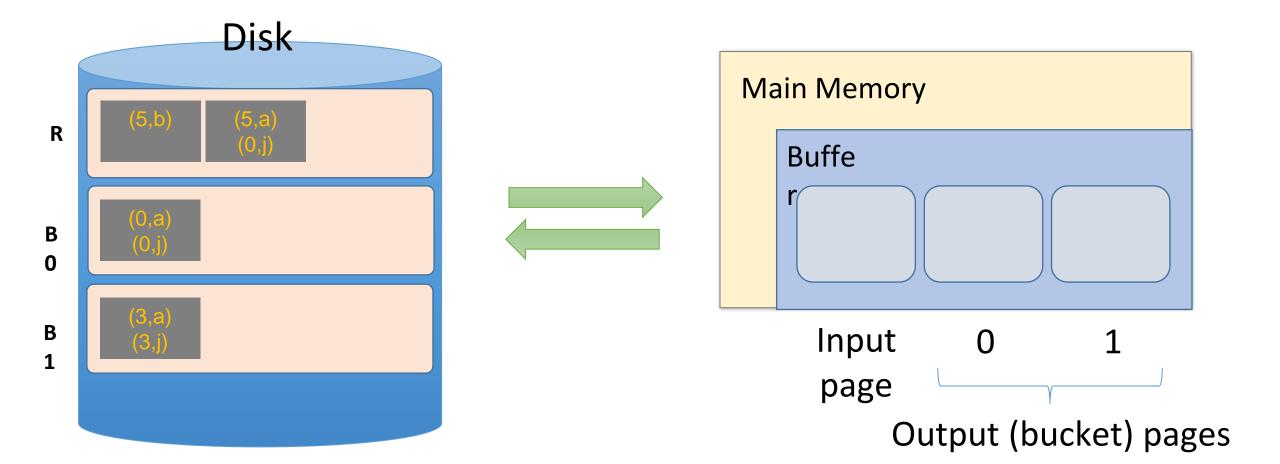
Given B+1=3 buffer pages

3. We repeat until the buffer bucket pages are full... then flush to disk



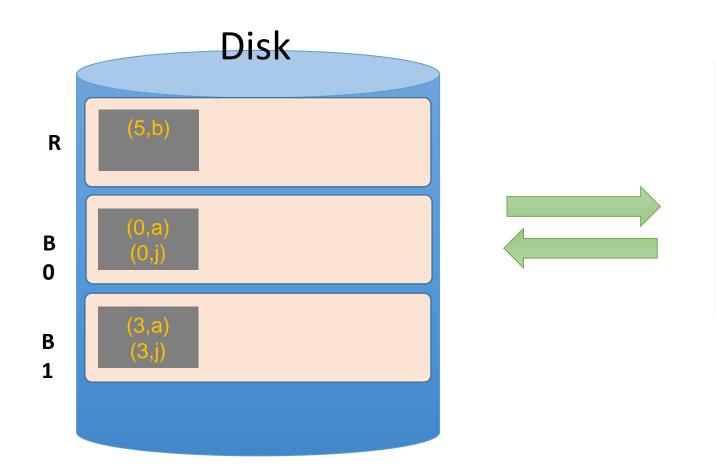
Given **B+1 = 3** buffer pages

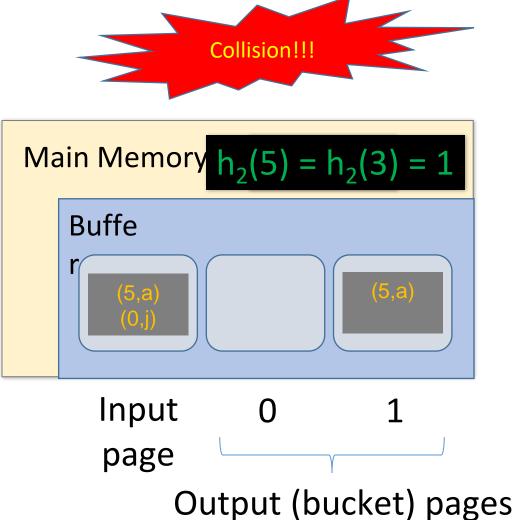
3. We repeat until the buffer bucket pages are full... then flush to disk



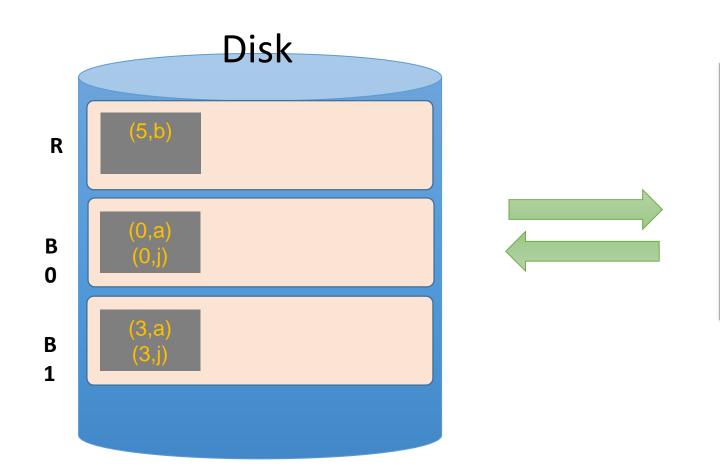
Given **B+1 = 3** buffer pages

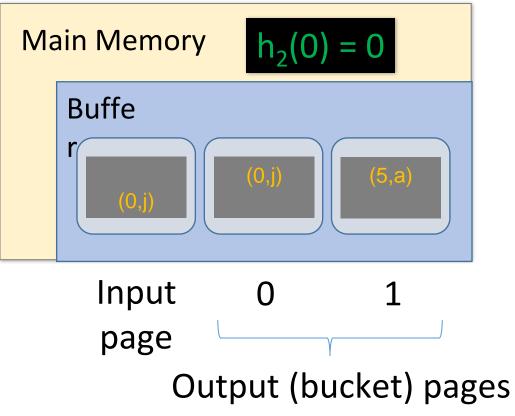
Note that collisions can occur!



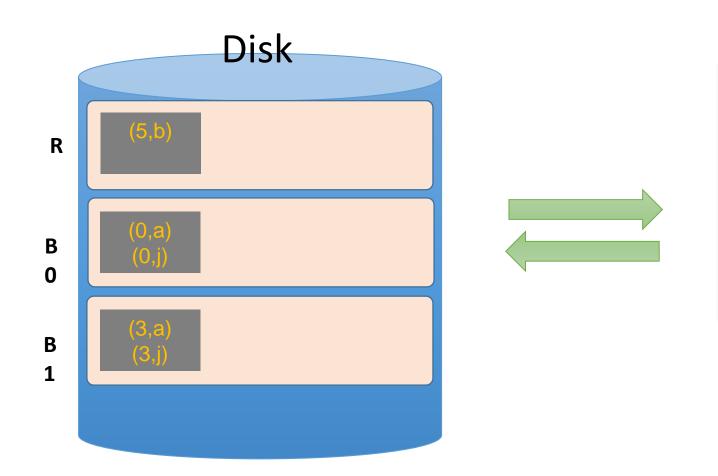


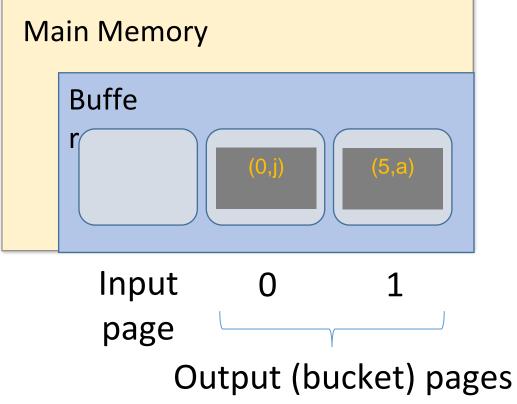
Given B+1=3 buffer pages



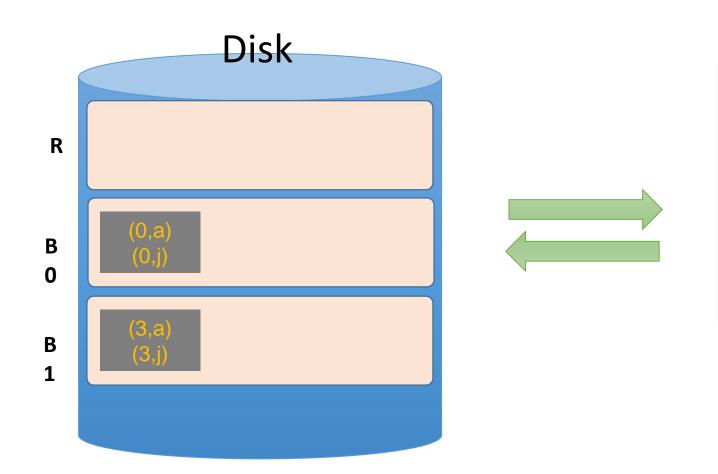


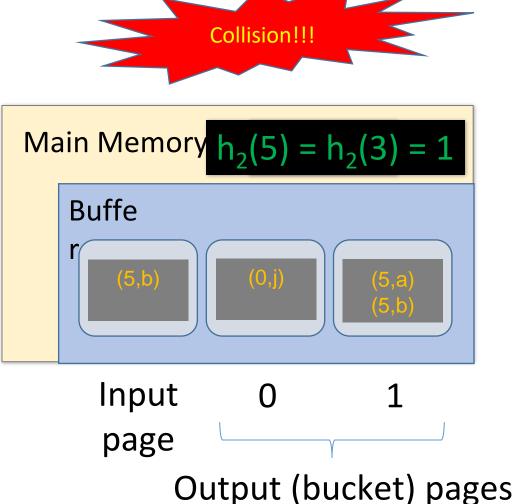
Given **B+1 = 3** buffer pages



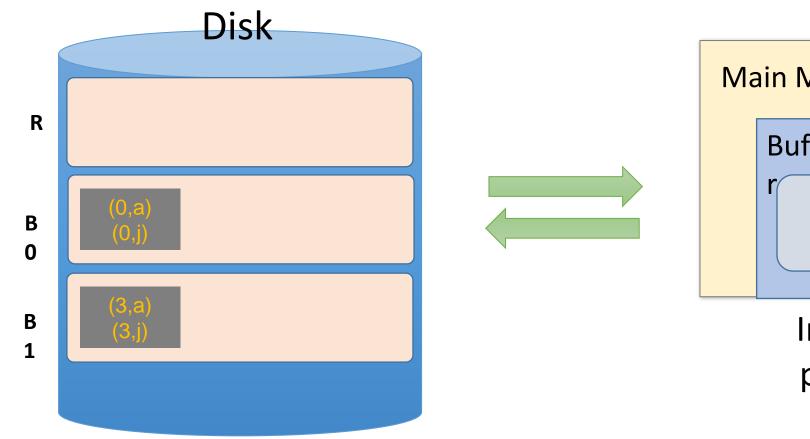


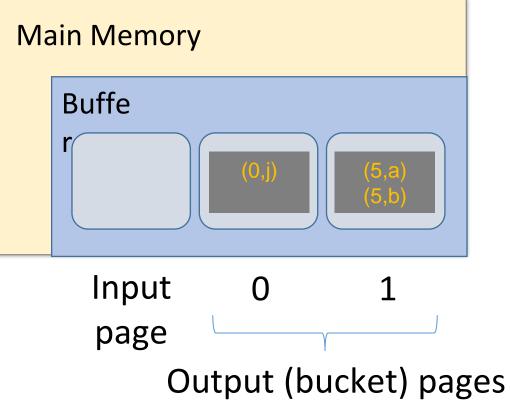
Given B+1=3 buffer pages



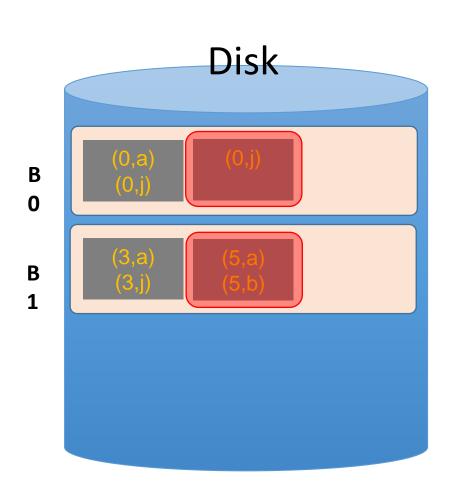


Given **B+1 = 3** buffer pages





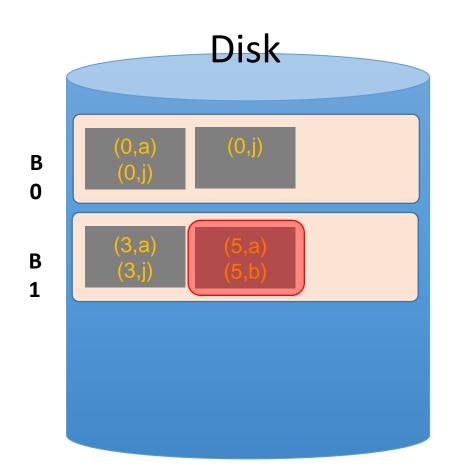
Given B+1=3 buffer pages



We wanted buckets of size **B-1 = 1...** however we got larger ones due to:

- (1) Duplicate join keys
- (2) Hash collisions

Given B+1=3 buffer pages

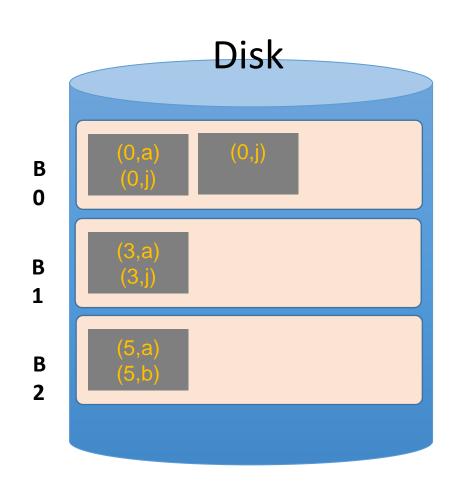


To take care of larger buckets caused by (2) hash collisions, we can just do another pass!

What hash function should we use?

Do another pass with a different hash function, h'_{2,} ideally such that:

$$h'_{2}(3) != h'_{2}(5)$$



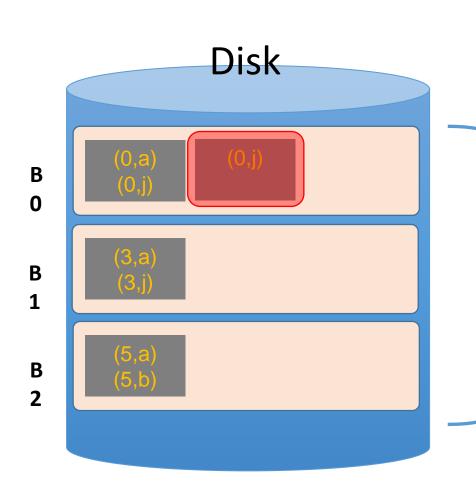
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Given B+1=3 buffer pages

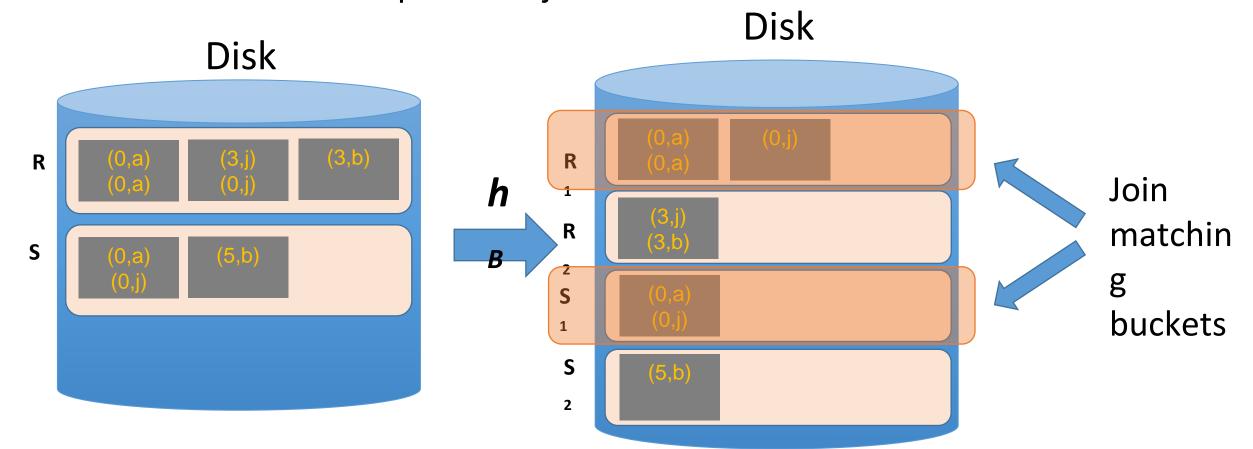


What about duplicate join keys?
Unfortunately this is a problem... but usually not a huge one.

We call this unevenness in the bucket size **skew**

Now that we have partitioned R and S...

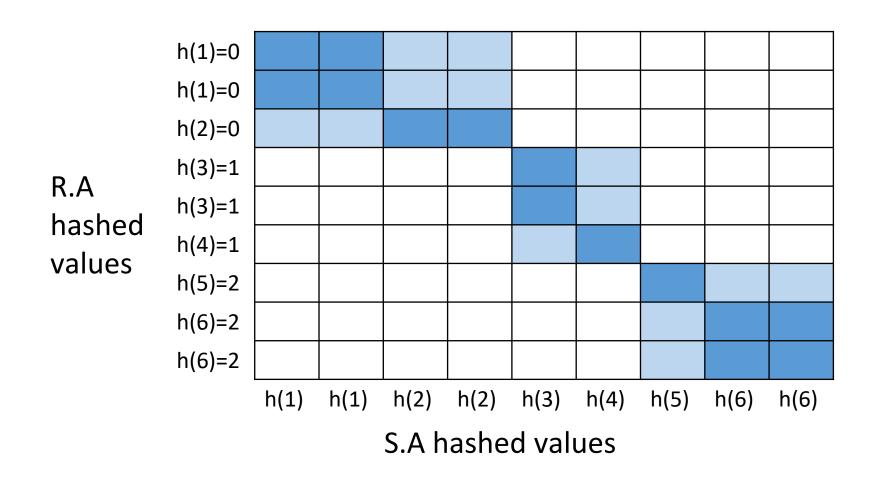
 Now, we just join pairs of buckets from R and S that have the same hash value to complete the join!



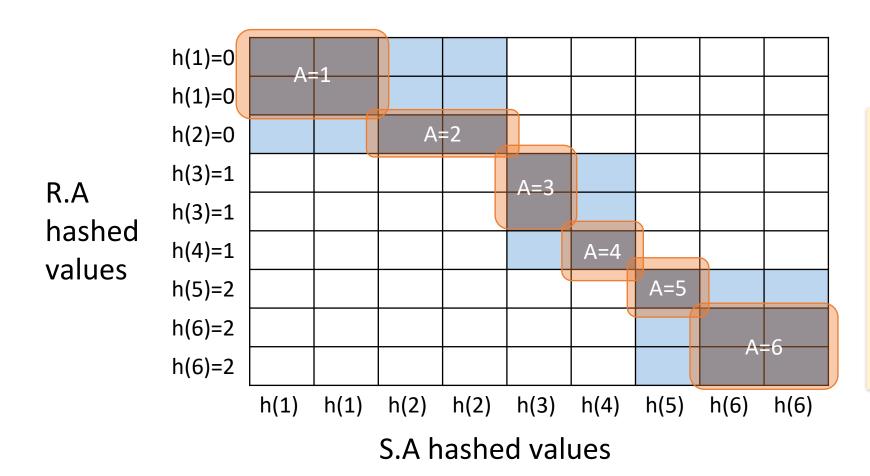
- Note that since x = y → h(x) = h(y), we only need to consider pairs of buckets (one from R, one from S) that have the same hash function value
- If our buckets are $\sim B 1$ pages, can join each such pair using BNLJ in linear time; recall (with P(R) = B-1):

BNLJ Cost:
$$P(R) + \frac{P(R)P(S)}{B-1} = P(R) + \frac{(B-1)P(S)}{B-1} = P(R) + P(S)$$

Joining the pairs of buckets is linear! (As long as smaller bucket <= B-1 pages)



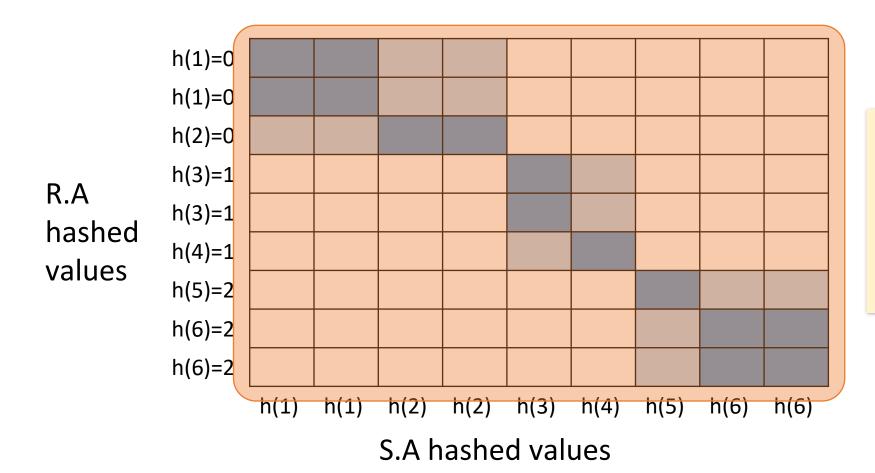
 $R \bowtie S \ on \ A$



 $R \bowtie S \ on \ A$

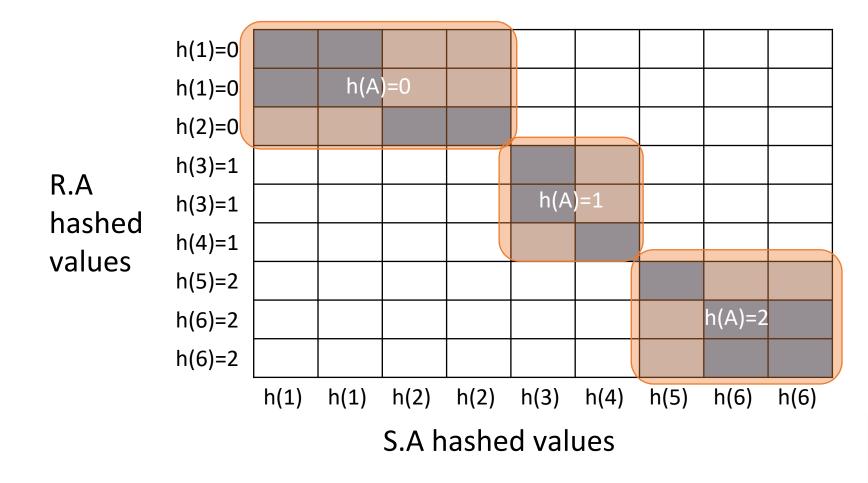
To perform the join, we ideally just need to explore the dark blue regions

= the tuples with same values of the join key A



 $R \bowtie S \ on \ A$

With a join algorithm like BNLJ that doesn't take advantage of equijoin structure, we'd have to explore this *whole grid!*



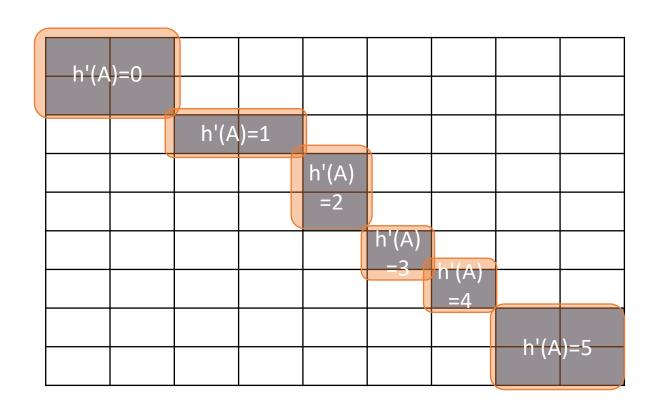
 $R \bowtie S \ on \ A$

With HJ, we only explore the *blue* regions

= the tuples with same values of h(A)!

We can apply BNLJ to each of these regions

R.A hashed values



S.A hashed values

 $R \bowtie S \ on \ A$

An alternative to applying BNLJ:

We could also hash again, and keep doing passes in memory to reduce further!

How much memory do we need for HJ?

• Given B+1 buffer pages

+ WLOG: Assume P(R) <= P(S)

- Suppose (reasonably) that we can partition into B buckets in 2 passes:
 - For R, we get B buckets of size ~P(R)/B
 - To join these buckets in linear time, we need these buckets to fit in B-1 pages, so we have:

$$B-1 \ge \frac{P(R)}{B} \Rightarrow \sim B^2 \ge P(R)$$

Quadratic relationship between *smaller relation's* size & memory!



Hash Join Summary

- Given enough buffer pages as on previous slide...
 - Partitioning requires reading + writing each page of R,S
 - 2(P(R)+P(S)) IOs
 - Matching (with BNLJ) requires reading each page of R,S
 - 2 P(R) + P(S) IOs
 - Writing out results could be as bad as P(R)*P(S)... but probably closer to P(R)+P(S)

HJ takes $^{\sim}3(P(R)+P(S)) + OUT IOs!$

3. The Cage Match

Sort-Merge v. Hash Join



• Given enough memory, both SMJ and HJ have performance:

$$^{\sim}3(P(R)+P(S)) + OUT$$



- "Enough" memory =
 - SMJ: $B^2 > max\{P(R), P(S)\}$
 - HJ: $B^2 > min\{P(R), P(S)\}$

Hash Join superior if relation sizes differ greatly. Why?

Further Comparisons of Hash and Sort Joins

Hash Joins are highly parallelizable.



 Sort-Merge less sensitive to data skew and result is sorted



Summary

- Saw IO-aware join algorithms
 - Massive difference
- Memory sizes key in hash versus sort join
 - Hash Join = Little dog (depends on smaller relation)
- Skew is also a major factor