Deadlocks

Objectives

- To develop a description of deadlocks,
 - which prevent sets of concurrent processes from completing their tasks
- To present a number of different methods for
 - preventing or
 - avoiding deadlocks in a computer system

- System consists of finite no of resources
 - To be distributed among a number of competing processes
- Resources are partitioned into several types,
 - Each consisting of some number of identical instances.

- Resource types
 - Memory space
 - CPU cycles
 - Files
 - I/O devices (such as printers and DVD drives)
- If a system has two CPUs,
 - then the resource type CPU has two instances

- Resource types R_1, R_2, \ldots, R_m
- Each resource type R_i has W_i instances.
- A process may utilize a resource in only the following sequence:
 - request
 - use
 - release

Request

- The process requests the resource.
- If the request cannot be granted immediately
- If the resource is being used by another process
- then the requesting process must wait until it can acquire the resource

Use

- The process can operate on the resource
- If the resource is a printer, the process can print on the printer

Release

The process releases the resource.

Deadlock

- A set of processes is in a deadlocked state when
 - every process in the set is waiting for an event that can be caused only by another process in the set.
- The events with which we are concerned are
 - resource acquisition and
 - release

Deadlock

- The resources may be either
 - physical resources (for example, printers, tape drives, memory space, and CPU cycles) or
 - logical resources (for example, files, semaphores, and monitors).

Deadlock involving the same resource type

- Consider a system with 3 CD RW drives and 3 processes.
 - Each process holds one CD RW drives.
 - If each process now requests another drive
 - The three processes will be in a deadlocked state.
 - Each is waiting for the event "CD RW drive is released," which can be caused by one of the other waiting processes.
- Deadlock involving the same resource type.

Deadlock involving different resources

- Deadlocks may also involve different resource types.
- Consider a system with one printer and one DVD drive.
 Suppose that
 - Process Pi is holding the DVD drive
 - Process Pj is holding the printer.
 - If Pi requests the printer
 - If Pj requests the DVD drive,
 - A deadlock occurs.

Deadlock Characterization

Deadlock can arise if the following four conditions hold simultaneously.

- Mutual exclusion
- Hold and wait
- No preemption
- Circular wait

Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

Mutual exclusion:

- Only one process at a time can use a resource
- If another process requests that resource, the requesting process must be delayed until the resource has been released

Hold and wait:

 A process holding at least one resource is waiting to acquire additional resources held by other processes

Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

No preemption

- Resources cannot be preempted
- A resource can be released only voluntarily by the process holding it, after that process has completed its task

Circular wait

- There exists a set $\{P_0, P_1, ..., P_n\}$ of waiting processes such that
- P₀ is waiting for a resource that is held by P₁,
- P_1 is waiting for a resource that is held by P_2 , ...,
- P_{n-1} is waiting for a resource that is held by P_n ,
- P_n is waiting for a resource that is held by P_0 .

Deadlock with Mutex Locks

 Deadlocks can occur via system calls, locking, etc.

Resource-Allocation Graph

A set of vertices V and a set of edges E.

V is partitioned into two types:

$$-P = \{P_1, P_2, ..., P_n\},\$$

 the set consisting of all the processes in the system

$$-R = \{R_1, R_2, ..., R_m\},$$

 the set consisting of all resource types in the system

Resource-Allocation Graph

A set of vertices *V* and a set of edges *E*.

request edge -

- directed edge $P_i \rightarrow R_j$
- P_i Process requested an instance of Resource type R_i
- P_i is currently waiting for that resource

assignment edge -

- directed edge $R_j \rightarrow P_i$
- R_i Resource has been allocated to Process P_i

Resource-Allocation Graph (Cont.)

Process



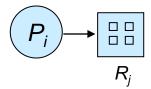
Resource Type with 4 instances-



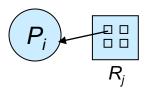
- Resource may have more than 1 instance
- Each such instance is a dot within the square

Resource-Allocation Graph (Cont.)

- P_i requests instance of R_i
 - Request edge points only to the square

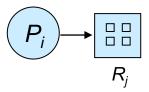


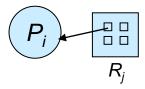
- P_i is holding an instance of R_i
 - Assignment edge also designates one of the dots in the square



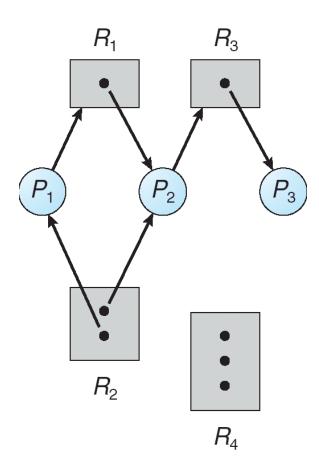
Resource-Allocation Graph (Cont.)

- P_i requests instance of R_i
 - When process requests, the request edge is inserted in the graph
 - When request is granted, request edge is transformed to assignment edge the resource
 - When Resource not needed, assignment edge is deleted

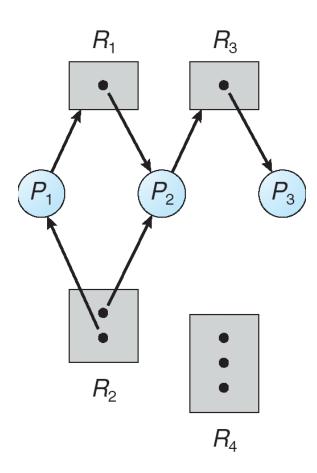




Example of a Resource Allocation Graph



Example of a Resource Allocation Graph



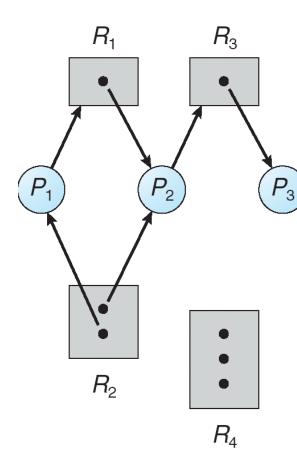
Sets P,R,E

- P={P1,P2,P3}
- R={R1,R2,R3}

Resource Instances

- R1=1 Instance
- R2=2 instances
- R3=1 instances
- R4=3 instances

Example of a Resource Allocation Graph



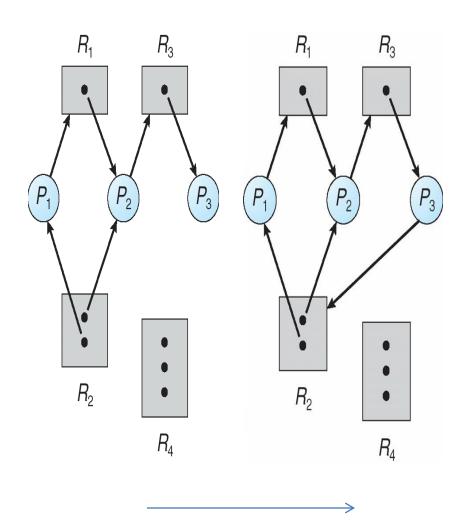
Process states:

- Process P1 is holding an instance of resource type R2 and is waiting for an instance of resource type R1.
- Process P2 is holding an instance of R1 and an instance of R2 and is waiting for an instance of R3.
- Process P3 is holding an instance of R3.
- E={P1->R1,P2->R3,R1->P2,
 R2->P2,R2->P1,R3->P3}

Basic Facts

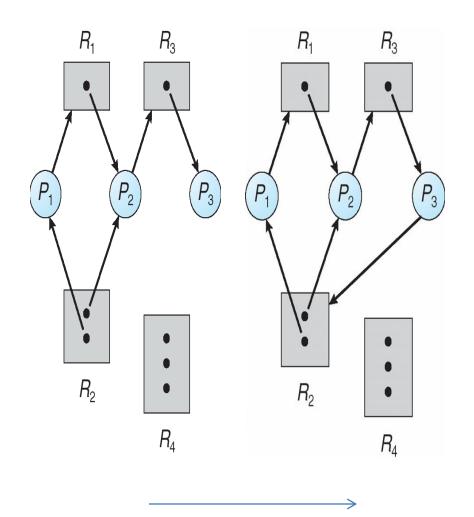
- If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
 - Deadlock may exist
 - if only one instance per resource type, then deadlock
 - In this case, cycle is both necessary and sufficient condition for deadlock
 - if several instances per resource type, possibility of deadlock
 - In this case, cycle is necessary but not sufficient condition for existence of deadlock

Resource Allocation Graph With A Deadlock



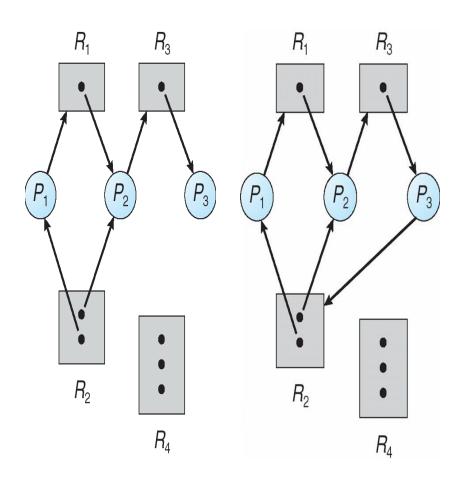
- If P3 requests an instance of resource R2?
- Since no resource instance is free, a request edge P3->R2 is added

Resource Allocation Graph With A Deadlock



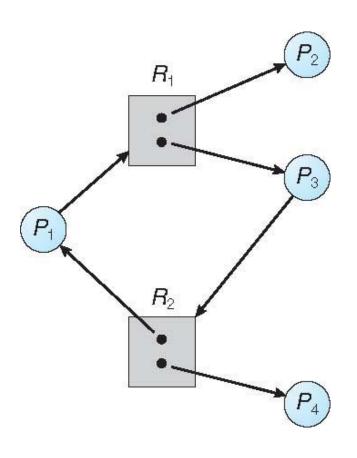
- So, Now Two cycles exist –
 P1->R1->P2->R3->P3->R2->P1
 P2->R3->P3->R2->P2
- P1,P2,P3 are deadlocked

Resource Allocation Graph With A Deadlock



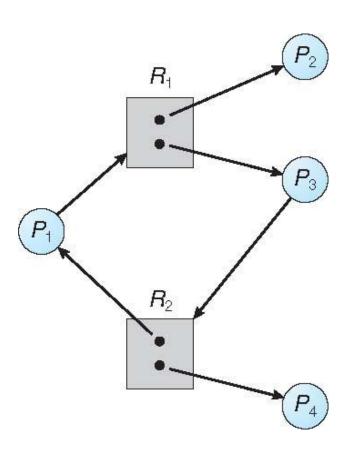
- P1,P2,P3 are deadlocked
- Process P2 is waiting for the resource R3, which is held by process P3. Process P3 is waiting for either process P1 or process P2 to release resource R2.
- In addition, process P1 is waiting for process P2 to release resource R1.
- Circular Wait

Resource Allocation Graph With A Cycle But No Deadlock



- One cycle exist –
 P1->R1->P3->R2->P1
- Still No Deadlock
- 7

Resource Allocation Graph With A Cycle But No Deadlock



- Still No Deadlock
- P4 may release its instance of resource R2, which can be allocated to P3
- Thus, Breaking the cycle

Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
 - Deadlock prevention
 - Deadlock avoidance

Methods for Handling Deadlocks

- If the system does not apply either a Deadlock prevention or Deadlock avoidance,
 - then deadlock may occur

Methods for Handling Deadlocks

- Then Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system;
 - used by most operating systems, including UNIX

Restrain the ways request can be made

- Prevent the occurrence of a deadlock
- Provides a set of methods for ensuring that
- at least one of the necessary conditions cannot hold.
- by constraining how requests for resources can be made.

Restrain the ways request can be made

- Mutual Exclusion –
- ME not required for sharable resources (e.g., read-only files);
 - Eg-If several processes attempt to open a read-only file at the same time, they can be granted simultaneous access to the file.

Restrain the ways request can be made

- Mutual Exclusion –
- ME must hold for non-sharable resources
 - Eg- A printer cannot be simultaneously shared by several processes.

Restrain the ways request can be made

Hold and Wait

- Must guarantee that whenever a process requests a resource,
- it does not hold any other resources

Hold and Wait

- Method 1
 - Require process to request and be allocated all its resources
 - before it begins execution,
 - Implement this provision by requiring that system calls requesting resources for a process
 - precede all other system calls.

Hold and Wait

- Method 2
 - allow process to request resources
 - only when the process has none allocated to it.
 - A process may request some resources and use them
 - Before it can request any additional resources
 - It must release all the resources that it is currently allocated.

Hold and Wait- Difference between these two protocols

- Consider a process that
 - copies data from a DVD drive to a file on disk,
 - sorts the file, and
 - then prints the results to a printer.

Hold and Wait- Difference between these two protocols

Method 1

- If all resources must be requested at the beginning of the process,
- The process must initially request the DVD drive, disk file, and printer.
- It will hold the printer for its entire execution, even though it needs the printer only at the end.

Hold and Wait- Difference between these two protocols

Method 2

- The process to request initially only the DVD drive and disk file.
- It copies from the DVD drive to the disk and then releases both the DVD drive and the disk file.
- The process must then again request the disk file and the printer.
- After copying the disk file to the printer, it releases these two resources
- Terminates.

Hold and Wait- Difference between these two protocols

- Two main disadvantages.
- First Method, resource utilization may be low,
 - since resources may be allocated but unused for a long period.
- Second Method, starvation is possible.
 - A process that needs several popular resources may have to wait indefinitely,
 - because at least one of the resources that it needs is always allocated to some other process.

No Preemption –

- Method 1
- If a process that is holding some resources requests another resource that cannot be immediately allocated to it,
 - then all resources currently being held are released
 - Preempted resources are added to the list of resources
- Process will be restarted only when
 - it can regain its old resources, as well as
 - the new ones that it is requesting

No Preemption –

- Method 2-
- If a process requests some resources,
 - If they are not available,
 - check If they are allocated to some other process that is waiting for additional resources.
- If so, we
 - preempt the desired resources from the waiting process and
 - allocate them to the requesting process.

No Preemption –

- Method 2-
- If the resources are
 - neither available
 - nor held by a waiting process,
 - the requesting process must wait.
- While it is waiting,
 - some of its resources may be preempted,
 - but only if another process requests them.
- A process can be restarted only
 - when it is allocated the new resources it is requesting and
 - recovers any resources that were preempted while it was waiting.

- Circular Wait –
- Impose a total ordering of all resource types,
- Requires that each process requests resources in an increasing order of enumeration

Circular Wait

- Resources R = { R1, R2, ..., Rm}
- Assign to each resource type a unique integer number,
 - which allows us to compare two resources
 - to determine whether one precedes another in our ordering.
- Define a one-to-one function

where N is the set of natural numbers.

- Circular Wait
- For example, if the set of resource types R
 includes tape drives, disk drives, and printers,
 then the function F might be defined as follows:

```
    F (tape drive) = 1
    F (disk drive) = 5
    F (printer) = 12
```

- A process that wants to use the tape drive and printer at the same time
 - must first request the tape drive and then request the printer.

Circular Wait

- A process can initially request any number of instances of a resource type, Ri.
- After that, the process can request instances of resource type Rj
- If and only if F(Rj) > F(Ri)

Disadvantages of Deadlock prevention??

- Possible side effects of preventing deadlocks, are
 - low device utilization and
 - reduced system throughput.
- An alternative method for avoiding deadlocks
 - Deadlock Avoidance
 - is to require additional information about how resources are to be requested

A priori

- In Latin a priori means "what comes first."
- A priori understandings are the assumptions that come before the rest of the assessment, argument, or analysis.

Requires that the system has some additional *a priori* information available

- Simplest and most useful model requires that
 - each process declare the maximum number
 of resources of each type that it may need

- Given this a priori information,
 - it is possible to construct an algorithm
 - That ensures that the system will never enter a deadlocked state.
 - Such an algorithm defines the deadlock-avoidance approach.

- The deadlock-avoidance algorithm
 - dynamically examines the resource-allocation state
 - to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by
 - the number of available resources,
 - the number of allocated resources,
 - and the maximum demands of the processes

Safe State

- A state is safe if
 - the system can allocate resources to each process
 (up to its maximum) in some order and
 - still avoid a deadlock.
- Everytime When a process requests an available resource, system must decide
 - if immediate allocation leaves the system in a safe state

Safe State

- System is in safe state if there exists a sequence $\langle P_1, P_2, ..., P_n \rangle$ of ALL the processes in the systems such that for each P_i ,
 - the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with j < i

Safe State

That is:

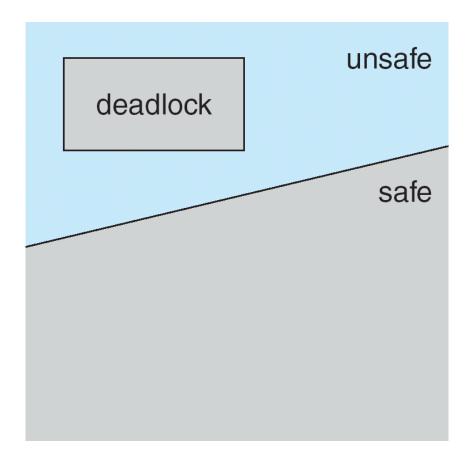
- If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished (j < i)
- When P_j is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate
- When P_i terminates, P_{i+1} can obtain its needed resources, and so on

Basic Facts

- If a system is in safe state ⇒ no deadlocks
- If a system is in unsafe state ⇒ possibility of deadlock

 Avoidance ⇒ ensure that a system will never enter an unsafe state.

Safe, Unsafe, Deadlock State



Avoidance Algorithms

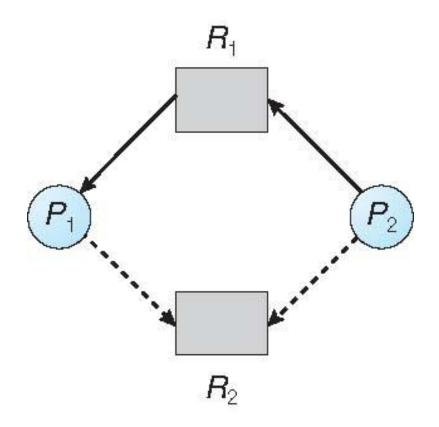
- Single instance of a resource type
 - Use a resource-allocation graph

- Multiple instances of a resource type
 - Use the banker's algorithm

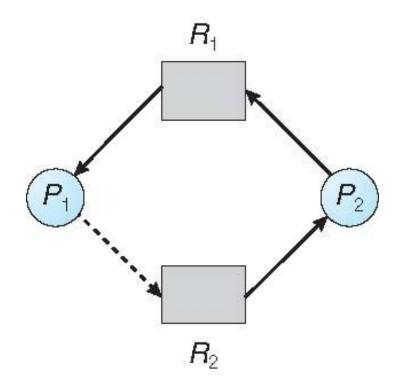
Resource-Allocation Graph Scheme

- Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request resource R_i ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system

Resource-Allocation Graph

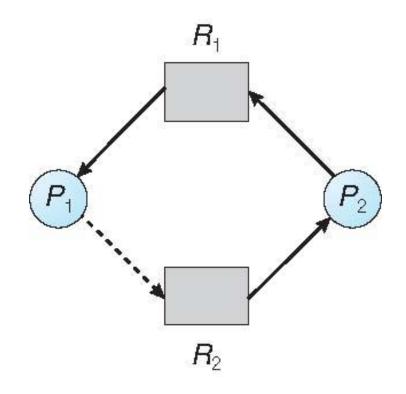


Unsafe State In Resource-Allocation Graph



Resource-Allocation Graph Algorithm

- Suppose that process P_i requests a resource R_i
- The request can be granted only
 - if converting the request edge to an assignment edge
 - does not result in the formation of a cycle in the resource allocation graph



Banker's Algorithm

Multiple instances

- Each process must a priori claim maximum use
 - This number may not exceed the total number of resources in the system.

Banker's Algorithm

 When a process requests a resource it may have to wait

 When a process gets all its resources it must return them in a finite amount of time

Banker's Algorithm

- A resource allocation and deadlock avoidance algorithm.
- This algorithm test for safety simulating
 - the allocation for predetermined maximum possible amounts of all resources,
 - then makes an "s-state" check to test for possible activities,
 - before deciding whether allocation should be allowed to continue.

Data Structures for the Banker's Algorithm

Available:

n = number of processes

Vector of length *m*.

m = number of resources types.

- If available [j] = k, there are k instances of resource type R_j available

Max:

- n x m matrix.
- If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i

Allocation:

- n x m matrix.
- If Allocation[i,j] = k then P_i is currently allocated k instances of R_i

Need:

- n x m matrix.
- If Need[i,j] = k, then P_i may need k more instances of R_i to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$

Safety Algorithm

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

<u>Work = Available</u> <u>Finish [i] = false for i = 0, 1, ..., n- 1</u>

- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$

(Add the process in the safe sequence)

If no such *i* exists, go to step 4

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == **true** for all i, then the system is in a safe state

Example of Banker's Algorithm

5 processes P₀ through P₄;

3 resource types:

A (10 instances), B (5instances), and C (7 instances)

• Snapshot at time T_0 :

	<u> Allocation</u>	<u> Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_1	200	3 2 2	
P_2	302	902	
P_3	211	222	
P_{4}	002	433	

Example (Cont.)

The content of the matrix Need is defined to be Max – Allocation

Need
 Need
$$[i, j] = Max [i, j] - Allocation [i, j]$$
 ABC
 P_0
 7 4 3

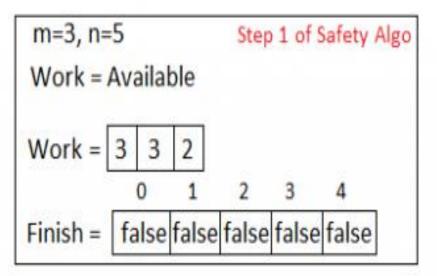
 P_1
 1 2 2

 P_2
 6 0 0

 P_3
 0 1 1

 P_4
 4 3 1

• The system is in a safe state since the sequence $\langle P_1, P_3, P_4, P_2, P_0 \rangle$ satisfies safety criteria



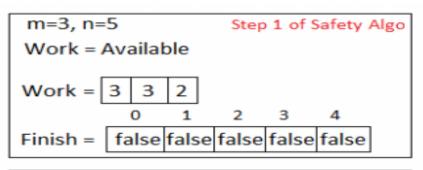
n = number of processesm = number of resources types

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

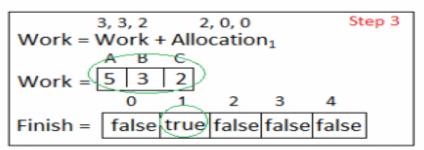
Process	Need				
	Α	В	С		
P ₀	7	4	3		
P ₁	1	2	2		
P ₂	6	0	0		
P ₃	0	1	1		
P ₄	4	3	1		
73					

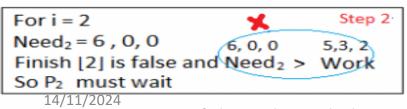
Prof. Shweta Dhawan Cl



For i = 0 Step 2
Need₀ = 7, 4, 3 7,4,3 3,3,2
Finish [0] is false and Need₀ > Work
So P₀ must wait But Need
$$\leq$$
 Work

For
$$i = 1$$
 Step 2:
Need₁ = 1, 2, 2 3,3,2
Finish [1] is false and Need₁ < Work
So P₁ must be kept in safe sequence





Prof. Shweta Dhawan Chachra

n = number of processes

m = number of resources types

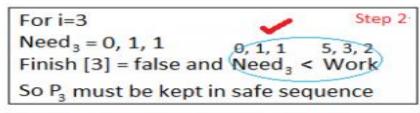
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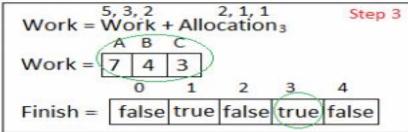
Work = Available
Finish
$$[i]$$
 = false for i = 0, 1, ..., n - 1

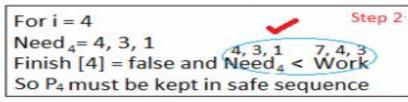
- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$ If no such *i* exists, go to step 4
- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

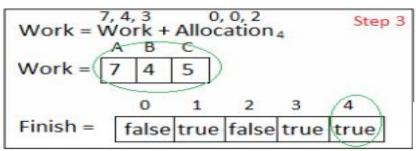
Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
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P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need				
	Α	С			
Po	7	4	3		
P ₁	1	2	2		
P ₂	6	0	0		
P ₃	0	1 4	1		
P ₄	4	3	1		







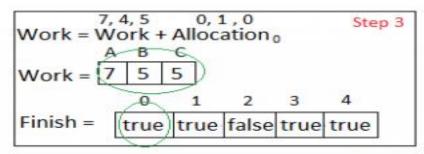


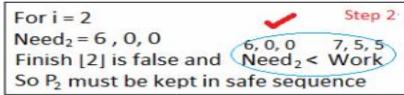
Let Work and Finish be vectors of length m and n, respectively. Initialize:

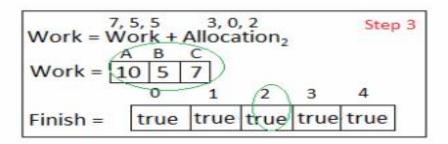
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- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P4 Dhay	0-0-2	4 3 3	

Process	Need				
	Α	С			
P ₀	7	4	3		
P ₁	1	2	2		
P ₂	6	0	0		
P ₃	0	1	1		
P ₄	4	3_	1		
P ₃		1	1		







```
Finish [i] = true for 0 \le i \le n
Hence the system is in Safe state
```

The safe sequence is P1,P3, P4,P0,P2

Let Work and Finish be vectors of length m and n, respectively. Initialize:

Work = Available
Finish
$$[i]$$
 = false for i = 0, 1, ..., n -1

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) Need_i ≤ WorkIf no such *i* exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

	Process	Allocation	Max	Available
		АВС	АВС	АВС
P_2	P ₀	0 1 0	7 5 3	3 3 2
	P ₁	2 0 0	3 2 2	
	P ₂	3 0 2	9 0 2	
	P ₃	2 1 1	2 2 2	
Prof. Shy	veta Dhav	van ⁰ Chachra	4 3 3	

Process	Need				
	Α	С			
Po	7	4	3		
P ₁	1	2	2		
P ₂	6	0	0		
P ₃	0	1	1		
P ₄	4	3	1		

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Resource-Request Algorithm for Process P_i

 $Request_i = request \ vector for process P_i$.

If $Request_i[j] = k$ then process P_i wants k instances of resource type R_i

- 1. If $Request_i \leq Need_i$ go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2. If $Request_i \leq Available$, go to step 3. Otherwise P_i must wait, since resources are not available
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;;
Allocation; = Allocation; + Request;;
Need; = Need; - Request;;
```

- Apply Safety Algorithm
 - □ If safe \Rightarrow the resources are allocated to P_i
 - □ If unsafe $\Rightarrow P_i$ must wait, and the old resource-allocation state is restored

Example: P_1 Request (1,0,2)

Process	Allocation	Max	Available
	АВС	АВС	АВС
P ₀	0 1 0	7 5 3	3 3 2
P ₁	2 0 0	3 2 2	
P ₂	3 0 2	9 0 2	
P ₃	2 1 1	2 2 2	
P ₄	0 0 2	4 3 3	

Process	Need			
	Α	В	С	
P ₀	7	4	3	
P ₁	1	2	2	
P ₂	6	0	0	
P ₃	0	1	1	
P ₄	4	3	1	

• Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2) \Rightarrow$ true

<u> Allocation</u>	<u>Need</u>	<u> Available</u>
ABC	ABC	ABC
010	743	230
302	020	
302	600	
211	011	
002	431	
	ABC 010 302 302 211	ABC ABC 010 743 302 020 302 600 211 011

- Executing safety algorithm shows that sequence $\langle P_1, P_3, P_4, P_0, P_2 \rangle$ satisfies safety requirement
- Can request for (3,3,0) by P₄ be granted?

Example: Explanation

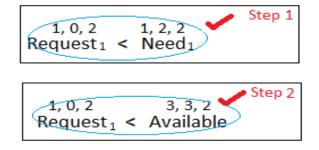
Allocation

 What will happen if process P1 requests one additional instance of resource type A and two instances of resource type C?

Process

	1	/ L D U					\rightarrow	
	Po	0 1 0	7 5 3	3 3 2	P ₀	7	4	3
	P ₁	2 0 0	3 2 2		P ₁	1	2	2
	P ₂	3 0 2	9 0 2	1	P ₂	6	0	0
	P ₃	2 1 1	2 2 2		P ₃	0	1	1
АВС	P ₄	0 0 2	4 3 3		P ₄	4	3	1
Request, = 1, 0, 2		•						

To decide whether the request is granted we use Resource Request algorithm



Allocation ₁	Available — Requet = Allocation + Requed = Request = Req		Step 3
Process	Allocation	Need	Available
	АВ С	а в с	АВС
P ₀	0 1 0	7 4 3	2 3 0
P ₁	(3 0 2)	0 2 0	
P ₂	3 0 2	6 0 0	
P ₃	2 1 1	0 1 1	
P ₄	0 0 2	4 3 1	

Available

Max

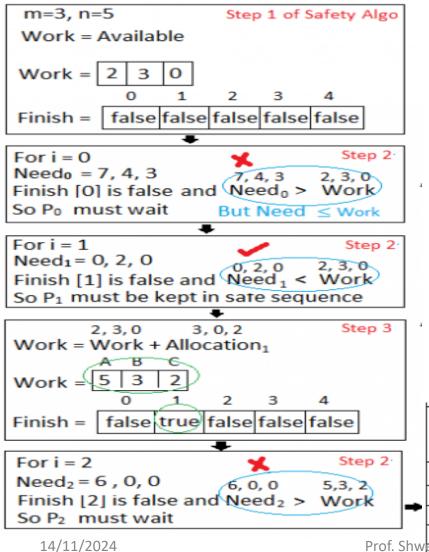
ABC

Process

Need

A B C

We must determine whether this new system state is safe. To do so, we again execute Safety algorithm again

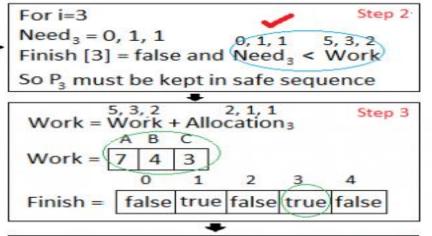


1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

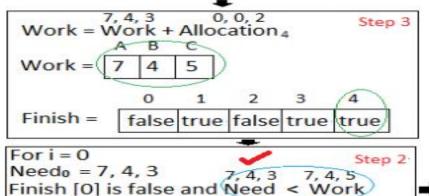
- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) *Need_i* ≤ *Work*If no such *i* exists, go to step 4
- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

Process	Allocation	Need	Available
	АВС	а в с	АВС
P ₀	0 1 0	7 4 3	2 3 0
P ₁	(3 0 2)	0 2 0	
P ₂	3 0 2	6 0 0	
P ₃	2 1 1	0 1 1	
eta <mark>P</mark> anawan	^{Cna} 6 2	4 3 1	

We must determine whether this new system state is safe. To do so, we again execute Safety algorithm again







So Pomust be kept in safe sequence

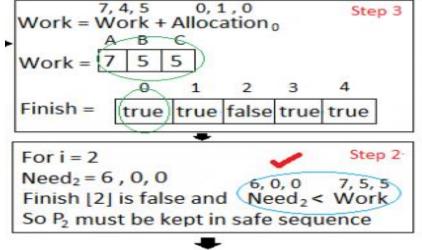
1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

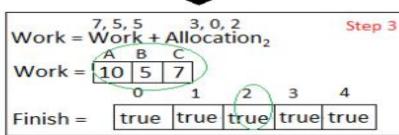
Work = Available
Finish
$$[i]$$
 = false for i = 0, 1, ..., n - 1

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$ If no such i exists, go to step 4
- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

Process	Allocation	Need	Available
	АВС	A B C	АВС
P ₀	0 1 0	7 4 3	230
P ₁	(3 0 2 >	0 2 0	
P ₂	3 0 2	6 0 0	
P ₃	2 1 1	0 1 1	
P ₄	0 0 2	4 3 1	

We must determine whether this new system state is safe. To do so, we again execute Safety algorithm again





Finish [i] = true for $0 \le i \le n$ Step 4 Hence the system is in Safe state

The safe sequence is P1,P3, P4,P0,P2

Hence the new system state is safe, so
we can immediately grant the request
14/11/2024
for process P₁

1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively. Initialize:

Work = Available
Finish
$$[i]$$
 = false for i = 0, 1, ..., n - 1

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$

If no such i exists, go to step 4

- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If **Finish** [i] == **true** for all i, then the system is in a safe state

Process	Allocation	Need	Available
	АВС	а в с	A B C
P ₀	0 1 0	7 4 3	2 3 0
P ₁	(3 0 2)	0 2 0	
P ₂	3 0 2	6 0 0	
P ₃	2 1 1	0 1 1	
Dhe Wan Ch	0 0 2	4 3 1	8

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Why Banker's algorithm is named so?

Why Banker's algorithm is named so?

- Banker's algorithm is named so because it is used in banking system to check whether loan can be sanctioned to a person or not.
- Suppose there are <u>n number of account holders in a bank and</u> the total sum of their money is S.
- If a person applies for a loan then the bank
 - first subtracts the loan amount from the total money that bank has and
 - if the <u>remaining amount is greater than S then only the loan is sanctioned.</u>

Why Banker's algorithm is named so?

- It is done because if all the account holders comes to withdraw their money then the bank can easily do it.
- Bank would never allocate its money in such a way that it can no longer satisfy the needs of all its customers.
- The bank would try to be in safe state always.

Process		Alloc	ation			М	ax			Avai	lable	
	Α	В	С	D	Α	В	С	D	Α	В	С	D
P0	0	0	1	2	0	0	1	2	1	5	2	0
P1	1	0	0	0	1	7	5	0				
P2	1	3	5	4	2	3	5	6				
P3	0	6	3	2	0	6	5	2				
P4	0	0	1	4	0	6	5	6				

Consider the following snapshot of a system-

Answer the following questions using the Banker's algorithm-

- (i) What are the total instances of Resources
- (ii) What is the content of the matrix need?
- (iii) Is the system in a safe state?
- (iv) If a request from process P1 arrives for (0,4,2,0), can the request be granted immediately?

Exercise 1

Process		Alloc	ation			М	ax			Avai	lable	
	Α	В	С	D	Α	В	С	D	Α	В	С	D
P0	0	0	1	2	0	0	1	2	1	5	2	0
P1	1	0	0	0	1	7	5	0				
P2	1	3	5	4	2	3	5	6				
Р3	0	6	3	2	0	6	5	2				
P4	0	0	1	4	0	6	5	6				

(i) What are the total instances of Resources

Process		Alloc	ation			М	ax			Avai	lable			N	eed	
	Α	В	С	D	Α	В	С	D	Α	В	С	D	Α	В	С	D
P0	0	0	1	2	0	0	1	2	1	5	2	0	0	0	0	0
P1	1	0	0	0	1	7	5	0					0	7	5	0
P2	1	3	5	4	2	3	5	6					1	0	0	2
Р3	0	6	3	2	0	6	5	2					0	0	2	0
P4	0	0	1	4	0	6	5	6					0	6	4	2

Content of the matrix need

Step 1: in row of process PO, use formula

Need=Max - Allocation

Step 2: Follow step 1 above for all other processes i.e. P1, P2, P3, P4, P5.

Result given above.

Process		Alloc	ation			М	ах			Avai	lable			Ne	eed	-
	Α	В	C	D	Α	В	C	D	Α	В	С	D	Α	В	С	D
PO	0	0	1	2	0	0	1	2	1	5	2	0	0	0	0	0
P1	1	0	0	0	1	7	5	0					0	7	5	0
P2	1	3	5	4	2	3	5	6					1	0	0	2
Р3	0	6	3	2	0	6	5	2					0	0	2	0
P4	0	0	1	4	0	6	5	6					0	6	4	2

Work=[1,5,2,0] For P) Need \leq Work, so Safe Sequence=<P0> Work=[1,5,2,0]+[0,0,1,2] Work=[1,5,3,2] For P1, Need is not \leq Work P1 must wait For P2, Need \leq Work i.e. [1,0,0,2]<[1,5,3,2] So Safe Sequence=<P0,P2> Work=[1,5,3,2]+[1,3,5,4] =[2,8,8,6]

1. Let **Work** and **Finish** be vectors of length *m* and *n*, respectively. Initialize:

- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == **true** for all i, then the system is in a safe state

Process		Alloc	ation			М	ах			Avai	lable			N	eed	
	Α	В	С	D	Α	В	С	D	Α	В	С	D	Α	В	С	D
P0	0	0	1	2	0	0	1	2	1	5	2	0	0	0	0	0
P1	1	0	0	0	1	7	5	0					0	7	5	0
P2	1	3	5	4	2	3	5	6					1	0	0	2
Р3	0	6	3	2	0	6	5	2					0	0	2	0
P4	0	0	1	4	0	6	5	6					0	6	4	2

Work=[2,8,8,6]
For P3, Need ≤Work
[0,0,2,0]<Work
Safe Sequence=<P0,P2,P3>
Work=[2,8,8,6]+[0,6,3,2]
=[2,14,11,8]
For P4, Need ≤ Work
[0,6,4,2]<Work
Safe Sequence=<P0,P2,P3,P4>
Work=[2,14,11,8]+[0,0,1,4]
=[2,14,12,12]

1. Let **Work** and **Finish** be vectors of length *m* and *n*, respectively. Initialize:

Work = Available Finish [i] = false for i = 0, 1, ..., n-1

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == **true** for all i, then the system is in a safe state

Process		Alloc	ation			М	ах			Avai	lable			N	eed	-
	Α	В	C	D	Α	В	C	D	Α	В	C	D	Α	В	С	D
P0	0	0	1	2	0	0	1	2	1	5	2	0	0	0	0	0
P1	1	0	0	0	1	7	5	0					0	7	5	0
P2	1	3	5	4	2	3	5	6					1	0	0	2
Р3	0	6	3	2	0	6	5	2					0	0	2	0
P4	0	0	1	4	0	6	5	6					0	6	4	2

Work=[2,14,12,12] Now for P1, Need ≤ Work [0,7,5,0]<Work Safe Sequence=<P0,P2,P3,P4,P1> Work=[2,14,12,12]+[1,0,0,0] =[3,14,12,12] Thus, System is in a safe state

1. Let **Work** and **Finish** be vectors of length *m* and *n*, respectively. Initialize:

Work = Available Finish [i] = false for i = 0, 1, ..., n- 1

- 2. Find an *i* such that both:
 - (a) *Finish* [*i*] = *false*
 - (b) $Need_i \leq Work$

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == true for all i, then the system is in a safe state

Deadlock Detection

Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
 - examines the state of the system to determine whether a deadlock has occurred
- Recovery scheme

Detection Algorithm

Detection Algorithm

- Single Instance of all Resources Types
- Several Instances of Resource Types

Single Instance of Each Resource Type

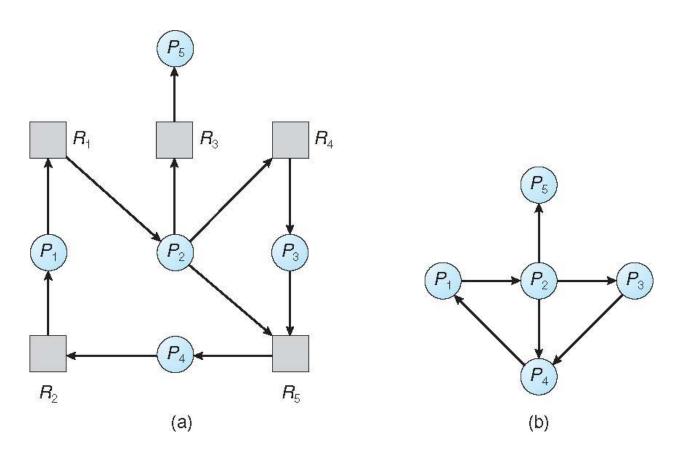
Detection Algorithm

- If only a single instance of all resources are there,
 - Use a variant of the resource-allocation graph, called a wait-for graph.
 - Obtain this graph from the resource-allocation graph by removing the resource nodes and collapsing the appropriate edges

Single Instance of Each Resource Type

- Maintain wait-for graph
 - Nodes are processes
 - $-P_i \rightarrow P_j$ if P_i is waiting for P_j
- Periodically invoke an algorithm that searches for a cycle in the graph.
- If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of n^2 operations, where n is the number of vertices in the graph

Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph

Corresponding wait-for graph

Several Instances of a Resource Type

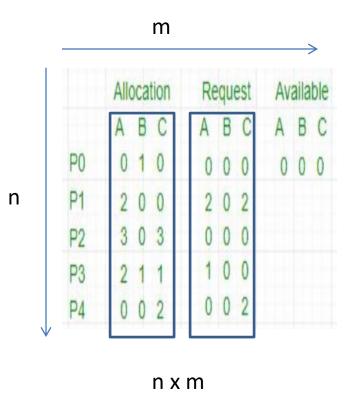
m=no of resources n=no of processes

- Available: A vector of length m indicates the number of available resources of each type
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process
- Request: An $n \times m$ matrix indicates the current request of each process. If Request[i][j] = k, then process P_i is requesting k more instances of resource type R_j .

Several Instances of a Resource Type

m=no of resources n=no of processes

- Available
- Allocation
- Request



Detection Algorithm

m=no of resources n=no of processes

- 1. Let **Work** and **Finish** be vectors of length **m** and **n**, respectively Initialize:
 - (a) Work = Available
 - (b) For i = 0,1,2, ..., n-1, if Allocation; ≠ 0, then Finish[i] = false; otherwise, Finish[i] = true

Initialize Work to Available and Finish to False

- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$

Detection Algorithm (Cont.)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If *Finish[i] == false*, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if *Finish[i] == false*, then P_i is deadlocked

Deadlock Detection

m=no of resources

n=no of processes

- Let Work and Finish be vectors of length m and n, respectively Initialize:
 - (a) Work = Available
 - (b) For i = 0,1,2, ..., n-1, if Allocation_i ≠ 0,
 then
 Finish[i] = false; otherwise, Finish[i] =
 true

Initialize Work to Available and Finish to False

- 2. Find an index *i* such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$

If no such *i* exists, go to step 4

- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked

Safety Algorithm

 Let *Work* and *Finish* be vectors of length m and n, respectively. Initialize:

> Work = Available Finish [i] = false for i = 0, 1, ..., n-1

- 2. Find an *i* such that both:
 - (a) Finish [i] = false
 - (b) Need_i ≤ WorkIf no such *i* exists, go to step 4
- 3. Work = Work + Allocation;
 Finish[i] = true
 go to step 2
- 4. If *Finish* [*i*] == *true* for all *i*, then the system is in a safe state

- Five processes P_0 through P_4 ; three resource types A (7 instances), B (2 instances), and C (6 instances)
- Snapshot at time T_0 :

	<u> Allocation</u>	<u>Request</u>	<u> Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_1	200	202	
P_2	303	000	
P_3	2 1 1	100	
P_4	002	002	

Sequence <P₀, P₂, P₃, P₁, P₄> will result in Finish[i] = true for all i

Initially

- 1. Work = [0, 0, 0] &
- 2. Finish = [false, false, false, false]
- 3. i=0 is selected as both
- 4. Finish[0] = false and [0, 0, 0] < = [0, 0, 0]
- 5. Work =[0, 0, 0]+[0, 1, 0] =>[0, 1, 0] &
- 6. Finish = [true, false, false, false, false]
- 7. i=1,
- 8. Finish[1]=false and [2,0,2]!<=[0,1,0]
- 9. P1 should wait
- 10. i=2 is selected as both
- 11. Finish[2] = false and [0, 0, 0] < =[0, 1, 0]
- 12. Work =[0, 1, 0]+[3, 0, 3] =>[3, 1, 3]
- 13. Finish = [true, false, true, false, false]
 Prof. Shweta Dhawa

Check If

- (a) Finish[i] == false
- (b) Request_i ≤ Work Then

Work = Work + Allocation;
Finish[i] = true

	Allo	ca	tion	Re	qu	est	Av	aila	ble
	A	В	C	A	В	C	A	В	C
P0	0	1	0	0	0	0	0	0	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	0			
P3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

- 1. i=3 is selected as both
- 2. Finish[3] = false and [1, 0, 0] < = [3, 1, 3]
- 3. Work =[3, 1, 3]+[2, 1, 1] =>[5, 2, 4] &
- 4. Finish = [true, false, true, true, false]
- 5. *i=4, is selected as both*
- 6. Finish[4]=[false] and [0,0,2]<=[5,2,4]
- 7. Work=[5,2,4]+[0,0,2]=[5,2,6]
- 8. Finish = [true, false, true, true, true]
- 9. *i*=1 is selected as both
- 10. Finish[1] = false and [2, 0, 2] < = [5, 2, 6]
- 11. Work =[5, 2, 6]+[2, 0, 0] =>[7, 2, 6]
- 12. Finish = [true, true, true, true].

No Finish[i] == false
No deadlock
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Check If

- (a) Finish[i] == false
- (b) Request_i ≤ Work Then

Work = Work + Allocation; Finish[i] = true

If **Finish[i] == false**, for some i, $1 \le i \le n$, then the system is in deadlock state.

	Allocation			Request			Available		
	A	В	C	A	В	C	A	В	C
P0	0	1	0	0	0	0	0	0	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	0			
P3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

Example (Cont.)

P₂ requests an additional instance of type C

	<u>Request</u>
	ABC
P_0	000
P_1	202
P_2	001
P_3	100
P_4	002

Snapshot at time T0:

	Allocation	Allocation Request	
	ABC	ABC	ABC
PO	010	000	000
P1	200	202	
P2	303	001	
P3	211	100	
P4	002	002	

State of system?

- 1. Initially
- 2. Work = [0, 0, 0]
- 3. Finish = [false, false, false, false]
- 4. i=0 is selected as both
- 5. Finish[0] = false and $[0, 0, 0] \le [0, 0, 0]$
- 6. Work =[0, 0, 0]+[0, 1, 0] =>[0, 1, 0] &
- 7. Finish = [true, false, false, false, false]
- 8. i=1,
- 9. Finish[1]=false and [2,0,2]!<=[0,1,0]
- 10. P1 should wait
- 11. Finish = [true, false, false, false, false]
- 12. i=2 is selected as both
- 13. Finish[2] = false and [0, 0, 1]! <= [0, 1, 0]
- 14. P2 should wait
- 15. Finish = [true, false, false, false]

Check If

- (a) Finish[i] == false
- (b) Request_i ≤ Work
 Then
 Work = Work + Allocation_i

vvork = vvork + Allocatioi	7
Finish[i] = true	

	Allocation			Request			Available		
	A	В	C	A	В	C	A	В	C
P0	0	1	0	0	0	0	0	0	0
P1	2	0	0	2	0	2			
P2	3	0	3	0	0	q			
P3	2	1	1	1	0	0			
P4	0	0	2	0	0	2			

- 1. i=3
- 2. Finish[3] = false and [1, 0, 0]! <= [0, 1, 0]
- 3. P3 should wait
- 4. Finish = [true, false, false, false, false]
- 5. i=4,
- 6. Finish[4]=[false] and [0,0,2]<=[0,1,0]
- 7. P4 should wait
- 8. Finish = [true, false, false, false, false]
- Finish[i] of P1,P2,P3,P4 = false
- So deadlock
- Thus process P1,P2,P3,P4 are deadlocked.

Check If

- (a) Finish[i] == false
- (b) Request_i ≤ Work Then

Work = Work + Allocation; Finish[i] = true

If **Finish[i] == false**, for some i, $1 \le i \le n$, then the system is in deadlock state.

	Allocation			Request			Available			
	A	В	C	A	В	C	A	В	C	
P0	0	1	0	0	0	0	0	0	0	
P1	2	0	0	2	0	2				
P2	3	0	3	0	0	q				
P3	2	1	1	1	0	0				
P4	0	0	2	0	0	2				

Example (Cont.)

- State of system?
 - Can reclaim resources held by process P₀, but insufficient resources to fulfill other processes; requests
 - Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4

- When should we invoke the detection algorithm?
- Depends on:
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back?
 - one for each disjoint cycle

- If deadlocks occur frequently,
 - then the detection algorithm should be invoked frequently.
 - Resources allocated to deadlocked processes will be idle until the deadlock can be broken.
 - In addition, the number of processes involved in the deadlock cycle may grow.

- If detection algorithm is invoked arbitrarily,
 - there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes "caused" the deadlock.

- Invoking the deadlock-detection algorithm for every resource request
 - will incur considerable overhead in computation time.

- A less expensive alternative is simply to
 - invoke the algorithm at defined intervals-
 - for example, once per hour or whenever CPU utilization drops below 40 percent.

Recovery from Deadlock

- When a detection algorithm determines that
 - a deadlock exists,
- Several alternatives are available-
 - Let the operator deal with the deadlock manually.
 - Let the system recover from the deadlock automatically.

Recovery from Deadlock

- There are two options for breaking a deadlock
 - Process Termination
 - Abort one or more processes to break the circular wait.
 - Resource Preemption
 - Preempt some resources from one or more of the deadlocked processes

- Eliminate deadlocks by aborting processes
- The system reclaims all resources allocated to the terminated processes.
- 2 Methods-
 - Abort all deadlocked processes
 - Abort one process at a time until the deadlock cycle is eliminated

- Abort all deadlocked processes
 - Breaks the deadlock cycle, but at great expense;
 - The deadlocked processes may have computed for a long time,
 - The results of these partial computations must be discarded and probably will have to be recomputed later.

- Abort one process at a time until the deadlock cycle is eliminated.
 - Incurs considerable overhead, since after each process is aborted,
 - Deadlock-detection algorithm must be invoked to determine whether any processes are still deadlocked.

Examples-

- Aborting a process may not be easy.
- If the process was in the midst of updating a file, terminating it
 - will leave that file in an incorrect state.
- 2. If the process was in the midst of printing data on a printer,
 - the system must reset the printer to a correct state before printing the next job.

Abort those processes whose termination will incur the minimum cost.

In which order should we choose to abort?

- Many factors may affect -
 - 1. Priority of the process
 - 2. How long process has computed, and how much longer to completion
 - 3. Resources the process has used
 - 4. Resources process needs to complete
 - 5. How many processes will need to be terminated
 - 6. Is process interactive or batch?

- Successively preempt some resources from processes
- Give these resources to other processes until the deadlock cycle is broken.
- If preemption is used, 3 issues need to be addressed:
 - Selecting a victim
 - Rollback
 - Starvation

Selecting a victim –

- Which resources and Which Processes are to be preempted
- determine the order of preemption to minimize cost.
- Cost factors
 - as the number of resources a deadlocked process is holding
 - Amount of time the process has so far consumed during its execution

 Rollback – return to some safe state, restart process from that state

Rollback -

- If we pre-empt a resource from a process
- Clearly, it cannot continue with its normal execution;
- It is missing some needed resource.

What should be done with that process?

 We must roll back the process to some safe state and restart it from that state.

Safe State-

- It is difficult to determine what a safe state is,
- The simplest solution is a total rollback: abort the process and then restart it.
- Although it is more effective to roll back the process only as far as necessary to break the deadlock, this method requires the system to keep more information about the state of all running processes.

Starvation -

- Same process may always be picked as victim,
- How can we guarantee that resources will not always be pre-empted from the same process?
- Ensure that a process can be picked as a victim" only a (small) finite number of times
- Include number of rollback in cost factor