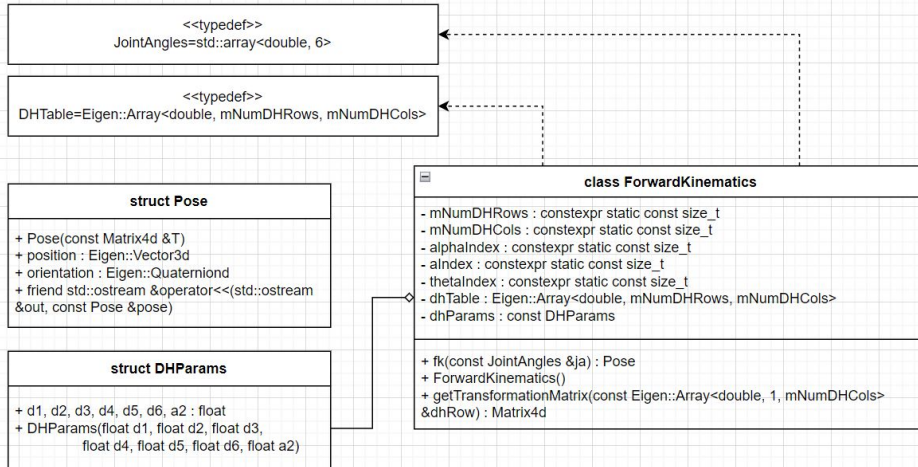# ACME Manipulator Arm Path Planning – Group 1

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Overview

- Manipulator arm path planner that solves Inverse Kinematics (IK) for Acme.
- Systemantics India's A3C Serial manipulator as a demonstration of this solver's capabilities

Approach

- Vedant will be the UML/activity diagram creator and design keeper. Also the owner of the GitHub Repository.
- Jerry and Aaqib will be using pair programming swapping roles after design for implementation phase.
- C++14/17 that can be integrated with ROS2 for visual simulation.
- Ubuntu 22.04; C++ standard lib, lib-eigen

Class UML Diagrams

Management/ Timeline

- Implementation:
  - Forward Kinematics: 3 days
  - Inverse Kinematics: 11 days