




Assign 2 Part 2 2019114009

(col, row) notation

①

from state	action	(1,1)	(2,1)	(1,2)	(2,2)
 (1,1)	right	0.2	0.8	0	0
	up	0.2	0	0.8	0
 (1,2)	right	0	0	0.75	0.25
	down	0.8	0	0.2	0
 (2,1)	left	0.8	0.2	0	0
	up	0	0.2	0	0.8

②

$$ACR \begin{cases} \text{Probab} \rightarrow 0.8 \times 0.25 = 0.2 \\ \text{cost} \rightarrow -4 \end{cases}$$

$$ABR \begin{cases} \text{Probab} \rightarrow 0.8 \times 0.8 = 0.64 \\ \text{cost} \rightarrow -5 \end{cases}$$

here we can see probability wise the optimal solution is ABR while cost wise the optimal solⁿ is ACR. Also this probabilities are given to the respective paths.

If we choose ACR instead of ABR

then is 20% drop in cost. but probability goes down from 64% to 20%.

So, i think ABR is the best path.

(3)

$$U_0(A) = 0 \quad U_0(B) = 0 \quad U_0(C) = 0$$

$$U(R) = 16.5$$

Roll no. = 2019114009

0	16.5
0	0

$$U_1(A) = \max_a [R(A, a) + \gamma \sum_j U_0(j) P(j|A, a)]$$

$$a = \{ \text{up, right} \}$$

$$R(A, a) = R(A, a, j) * P(j|A, a)$$

$j = A, B, C, R$

$$R(A, \text{up}) = 0.8x - 1 + 0.2x - 1 = -1$$

$$R(A, \text{right}) = 0.2x - 1 + 0.8x - 1 = -1$$

$$U_1(A) = \max_a [R(A, \text{up}), R(A, \text{right})]$$

$$\underline{\underline{-1}}$$

$$U_1(B) = \max_a [R(B, a) + \gamma \sum_j U_0(j) P(j|B, a)]$$

$$a = \{left, up\}$$

$$R(B, left) =$$

$$R(B, left) = 0.8 \times -1 + 0.2 \times -1 = -1$$

$$R(B, up) = 0.8 \times -4 + 0.2 \times -1 =$$

$$-3.2 - 0.2$$

$$= -3.4$$

$$U_1(B) = \max_a [(-3.4 + \frac{16.5 \times 0.8}{\times 0.2}), (-1 + \frac{16.5 \times 0.2}{\times 0.2})]$$

$$-3.4, -1$$

$$(-0.76, -1)$$

$$U_1(B) = -0.76$$

$$U_1(C) = \max_a [-0.76, -1.14]$$

$$U_1(C) = \max_a [R(C, a) + \gamma \sum_j U_0(j) P(j|C, a)]$$

$$a = \{Right, down\}$$

$$R(C, right) = 0.25 \times -3 + 0.75 \times -1 = -1.5$$

$$R(C, down) = 0.8 \times -1 + 0.2 \times -2 = -1$$

$$U_1(c) = \max \left[\cancel{(-1.16)}, \cancel{(-1.14)} \right] \\
\max \left[(-1.0), (-0.67) \right] \\
= -0.67$$

itr=1 →

-0.67	16.5
-1	-0.76

itr=2

~~$U_2(A)$~~

$$U_{t+1}(i) = \max_a \left[R(i, a) + \sum_j U_t(j) P(j|i, a) \right]$$

$$U_2(A) = \max_a \left[R(A, a) + \sum_j U_1(j) P(j|A, a) \right]$$

$$a = \{ \text{up, right} \}$$

$$U_2(A) = \max \left[(-1.16), (-1.14) \right]$$

$$\underline{U_2(A) = -1.14}$$

$$U_2(B) = \max_a \left[R(B, a) + \sum_j U_1(j) P(j|B, a) \right]$$

$$a = \{ \text{up, left} \}$$

$$U_2(B) = \max \left[-1.19, -0.79 \right]$$

$$U_2(B) = -0.79$$

$$U_2(C) = \max_a \left[R(C, a) + \sum_j U(j) P(j|C, a) \right]$$

$$a = \{ \text{right, down} \}$$

$$= \max \{ -1.18, -0.77 \}$$

$$U_2(C) = -0.77$$

-0.77	16.5
-1.14	-0.79

iter 3

$$U_3(A) = \max_a \left[R(A, a) + \sum_j U(j) P(j|A, a) \right]$$

$$= \max \{ -1.172, -1.1701 \}$$

$$U_3(A) = -1.1701$$

$$U_3(B) = \max \{ -1.21, -0.79 \}$$

$$= -0.79$$

$$U_3(C) = \max \{ -1.21, -0.791 \}$$

$$= -0.791$$

-0.79	16.5
-1.17	-0.79

(Bellman error)
 delta of
 A and C is
 greater than 0.01
 so continue

Ans 4

$$U_4(A) = \max \left[\begin{array}{l} -1.17, -1.173434 \\ -1.17346 \end{array} \right]$$

$$= -1.173434$$

$$U_4(B) = \max \left[-1.211, -0.79 \right]$$

$$= -0.79$$

$$U_4(C) = \max \left[-1.211, -0.79 \right]$$

$$= -0.79$$

$$-0.793715625$$

-0.79	16.5
-1.173	
-1.173	-0.79

$$\rightarrow -0.791664639$$

now Bellman error is less than 0.01
in all states. So convergence.

Ans 4

If you are at A, next highest utility is B,

A \rightarrow B \rightarrow R would be best acc. to VI

Yes, our previous guess was correct. :)

Ans

B. As we calculated the values of $U_t(B)$, $U_t(A)$ and $U_t(C)$ in ques - 3 -

~~they~~ ^{they} are independent on the R-value (Reward)

So what i observe is that when the value of R is more then $A \rightarrow B \rightarrow R$ is more likely whereas when $A \rightarrow C \rightarrow R$ is more likely in lesser values of R.

Also if you calculate for some more values of R then you will see for smaller values the best path would be $A \rightarrow C \rightarrow R$ and whereas in larger values the path will be $A \rightarrow B \rightarrow R$.

So, obviously there ~~is~~ ^{will} be some value of R for which the cost of the paths $A \rightarrow C \rightarrow R$ and $A \rightarrow B \rightarrow R$ will be same.