```
Configuration: Default
      Coordinate system: Coordinate System1
Mass = 3.817515 kilograms
Volume = 0.003774 cubic meters
Surface area = 3.823056 square meters
Center of mass: ( meters )
         X = 0.000000
         Y = 0.000000
         Z = -0.063728
Principal axes of inertia and principal moments of inertia: ( kilograms * square meters )
Taken at the center of mass.
          Ix = (0.000000, -1.000000, 0.000000)

Iy = (1.000000, 0.000000, 0.000000)

Iz = (0.000000, 0.000000, 1.000000)
                                                                       Px = 0.191380
                                                             Py = 0.614663
                                                            Pz = 0.687908
Moments of inertia: ( kilograms * square meters )
Taken at the center of mass and aligned with the output coordinate system.
         Lxx = 0.614663 Lxy = 0.000000 Lxz = 0.000000
         Lyx = 0.000000 Lyy = 0.191380 Lyz = 0.000000
         Lzx = 0.000000 Lzy = 0.000000 Lzz = 0.687908
Moments of inertia: ( kilograms * square meters )
Taken at the output coordinate system.
         Ixx = 0.630167 Ixy = 0.000000 Ixz = 0.000000 Iyx = 0.000000 Iyy = 0.206884 Iyz = 0.000000 Izx = 0.000000 Izy = 0.000000 Izz = 0.687908
```

Mass properties of table