## UNIT I:

## **BLOOM'S LEVEL 2: UNDERSTAND**

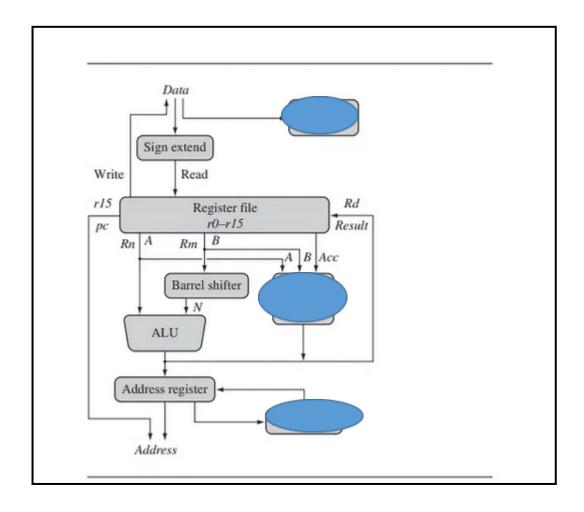
- 1. DIFFRENTIATE BETWEEN MICROPROCESSORS AND MICROCONTROLLERS WITH A NEAT BLOCK DIAGRAM.
- 2. LIST AND EXPLAIN THE FOUR MAJOR DESIGN RULES OF RISC PHILOSOPHY.
- 3. DIFFERTIATE BETWEEN RISC AND CISC PROCESSORS.
- 4. LIST AND EXPLAIN IN DETAIL THE ARM DESIGN PHILOSOPHY.
- 5. JUSTIFY WHY ARM INSTRUCTION SET IS SUITABLE FOR EMBEDDED APPLICATIONS.
- 6. WITH A NEAT BLOCK DIAGRAM OF AN ARM-BASED EMBEDDED DEVICE, EXPLAIN THE FOLLOWING:
  - ARM PROCESSOR
  - CONTROLLERS
  - PERIPHERALS
  - BUS
- 7. WRITE A NOTE ON THE FOLLOWING:
  - ARM BUS TECHNOLOGY
  - AMBA BUS PROTOCOL
  - MEMORY
  - PERIPHERALS
- 8. WITH A NEAT BLOCK DIAGRAM EXPLAIN THE ARM CORE DATA FLOW MODEL.
- 9. LIST OUT THE VARIOUS REGISTERS OF ARM 7. COMMENT ON ITS WIDTH, AND SPECIAL PURPOSE OF REGISTERS R13, R14 AND R15.
- 10. DRAW THE NEAT BLOCK DIAGRAM OF CPSR AND COMMENT ON THE SIGNIFICANCE OF **N, Z, C AND V** FLAGS?
- 11. LIST THE VARIOUS MODES OF OPERATION OF ARM 7.
- 12. DEFINE PIPELINE. HOW MANY STAGES OF PPELINE IS AVAILABLE FOR ARM7. ILLUSTRATE THE PIPELINE OPERATION FOR THE FOLLOWING INSTRUCTIONS:
  - a. ADD R0,R1,R2
  - b. AND R3,R4,R5
  - c. SUB R6, R7, R8

# **BLOOM'S LEVEL 3: APPLY**

1. WHICH OF THE FOLLOWING STATEMENTS ARE TRUE WITH RESPECT TO ARM 7 ARCHITECTURE.

- a. EACH PROCESSOR MODE IS EITHER PREVILEGED OR NONPREVILEGED.
- b. PREVILEGED MODE ALLOWS FULL READ WRITE ACCESS TO THE CPSR.
- c. THE NEGATIVE FLAG 'N' IS SET WHEN BIT 31 OF THE RESULT IS BINARY 1.
- d. THE ZERO FLAG 'Z' IS USED TO INDICATE EQUALITY.
- e. THE CARRY FLAG 'C' IS SET WHEN THE RESULT CAUSES AN UNSIGNED CARRY.
- f. THE OVERFLOW FLAG 'V' IS SET WHEN THE RESULT CAUSES SIGNED OVERFLOW.

BLOOM'S LEVEL 4: ANALYZE: ANALYZE THE ARM CORE DATAFLOW MODEL SHOWN IN FIGURE BELOW AND IDENTIFY THE MASKED BLOCKS AND THEIR SIGNIFICANCE.



## UNIT 2:

## **BLOOM'S LEVEL 2: UNDERSTAND**

- 1. LIST AND EXPLAIN THE VARIOUS DATA TRANSFER INSTRUCTIONS OF ARM7 WITH PROPER SYNTAX AND AN EXAMPLE.
- 2. WITH A NEAT BLOCK DIAGRAM EXPLAIN THE SIGNIFICANCE OF BARRE SHIFTER AND ALU.
- 3. LIST AND EXPLAIN THE BASIC 'C' DATA TYPES.
- 4. LIST AND EXPLAIN THE FOLLOWING INSTRUCTIONS OF ARM7 WITH PROPER SYNTAX AND AN EXAMPLE FOR EACH.
  - a. SHIFT INSTRUCTIONS
  - b. ROTATE INSTRUCTIONS
  - c. ARITHMETIC INSTRUCTIONS
  - d. LOGICAL INSTRUCTIONS
  - e. COMPARISON INSTRUCTIONS
  - f. MULTIPLY INSTRUCTIONS
  - g. BRANCH INSTRUCTIONS
  - h. LOAD STORE INSTRUCTIONS
  - i. SWAP INSTRUCTION
  - j. PROGRAM STATUS REGISTER INSTRUCTIONS

## **BLOOM'S LEVEL 3: APPLY**

- 1. DEVELOP AN ASSEMBLY LANGUAGE PROGRAM (ALP) TO PERFORM BLOCK DATA TRANSFER.
- 2. DEVELOP AN ALP TO GENERATE THE SERIES: 5, 10,15,20,25. HINT: USE MLA INSTRUCTION.
- 3. DEVELOP AN ALP TO COMPUTE THE FACTORIAL OF A GIVEN NUMBER AND STORE THE RESULT IN RAM LOCATION.
- 4. DEVELOP AN ALP FIND THE LARGEST NUMBER IN AN ARRAY AND STORE IT IN RAM LOCATION.
- 5. DEVELOP AN ALP TO ILLUSTRATE THE SIGNIFICANCE OF LOGICAL OPERATIONS.
- 6. DEVELOP AN ALP TO ILLUSTRATE THE WORKING OF SHIFT AND ROTATE INSTRUCTIONS.
- 7. DEVELOP AN ALP TO ILLUSTRATE THE WORKING OF SWAP INSTRUCTION.
- 8. DEVELOP AN ALP TO ILLUSTRATE THE WORKING OF LOAD STORE INSTRUCTIONS
- 9. DEVELOP AN ALP TO ILLUSTRATE THE WORKING OF PROGRAM STATUS REGISTER INSTRUCTIONS

## **BLOOM'S LEVEL 4: ANALYZE:**

- 1. ANALYZE THE GIVEN PIECE OF CODE AND ANSWER THE FOLLOWING:
  - a. WHAT IS THE CONTENT OF RO,R1 AND R2.
  - b. COMMENT ON THE STATUS OF NZCV FLAGS AFTER EXECUTING THE LAST INSTRUCTION.

```
| Study Projects from No. 100 to the results | State |
```

2. ANALYZE THE GIVEN PIECE OF CODES ('C' CODE AND COMPILER OUTPUT) AND ANSWER THE FOLLOWING:

```
int checksum_v1(int *data)
{
   char i;
   int sum = 0;

   for (i = 0; i < 64; i++)
   {
      sum += data[i];
   }
   return sum;
}</pre>
```

```
checksum v1
       MOV
                                ; r2 = data
               r2,r0
       MOV
               r0,#0
                                ; sum = 0
       MOV
               r1,#0
                                ; i = 0
checksum v1 loop
       LDR
              r3,[r2,r1,LSL #2] ; r3 = data[i]
       ADD
                                ; r1 = i+1
               r1,r1,#1
               rl,rl,#0xff
       AND
                                ; i = (char)rl
               r1,#0x40
       CMP
                                ; compare i, 64
                                ; sum += r3
       ADD
               r0,r3,r0
               checksum_v1_loop
       BCC
                               ; if (i<64) loop
       MOV
               pc,r14
                                 ; return sum
```

- WHAT IS THE DRAWBACK OF USING CHAR DATA TYPE FOR DECLARING THE LOCAL VARIABLES IN ARM7 'C' PROGRAM?
- IN THE COMPILER OUTPUT HOW CAN WE AVOID THE INSTRUCTION AND R1,R1,#0XFF
- WHAT IS THE USE OF BCC INSTRUCTION?
- WHY PC IS UPDATED WITH R14 CONTENT? CAN WE REPLACE R14 BY ANY OTHER REGISTER?
- 3. ANALYZE THE GIVEN PIECE OF CODE AND ANSWER THE FOLLOWING:
  - WHICH DATA TYPE IS USED TO DECLARE THE LOCAL VARIABLE?
  - WHAT IS THE MODIFICATION THAT IS REQUIRED IN THE COMPILER OUTPUT IF THE VARIABLE SUM IS 16-BIT.

```
checksum v2
       MOV
               r2,r0
                               ; r2 = data
       MOV
               r0.#0
                                ; sum = 0
              r1,#0
       MOV
                                i = 0
checksum_v2_loop
              r3,[r2,r1,LSL #2] ; r3 = data[i]
       LDR
       ADD
              r1,r1,#1
                                ; r1++
       CMP
              r1,#0x40
                               ; compare i, 64
              r0,r3,r0
                               ; sum += r3
       ADD
       BCC
              checksum_v2_loop ; if (i<64) goto loop
       MOV
              pc,r14
                               ; return sum
```

4. ANALYZE THE GIVEN PIECE OF CODES ('C' CODE AND COMPILER OUTPUT) AND ANSWER THE FOLLOWING:

```
short checksum_v3(short *data)
{
  unsigned int i;
  short sum=0;

  for (i=0; i<64; i++)
{
    sum = (short)(sum + data[i]);
    che
    }
    return sum;
}</pre>
```

```
checksum v3
           r2,r0 ; r2 = data
      MOV
                        ; sum = 0
            r0,#0
      MOV
      MOV
            r1.#0
                          : i = 0
checksum v3 loop
            r3,r2,r1,LSL #1 ; r3 = &data[i]
      ADD
           r3,[r3,#0] ; r3 = data[i]
      LDRH
           rl,rl,#l ; i++
      ADD
           r1,#0x40 ; compare i, 64
      CMP
      ADD
           r0,r3,r0
                          ; r0 = sum + r3
           r0,r0,LSL #16
      MOV
           r0,r0,ASR #16 ; sum = (short)r0
      MOV
            checksum v3 loop ; if (i<64) goto loop
      BCC
      MOV
            pc,rl4
                           ; return sum
```

HOW CAN WE REDUCE THESE INSTRUCTIONS IN THE COMPILER OUTPUT?

```
O ADD r3,r2,r1,LSL #1

MOV r0,r0,LSL #16

MOV r0,r0,ASR #16
```

REWRITE THE 'C' CODE TO REDUCE THESE INSTRUCTIONS.

## UNIT 3:

## LEVEL 2:

- 1. LIST AND EXPLAIN THE VARIOUS REGISTERS OF ARM 7 USED FOR CONFIGURING PORTS AS GPIO, INPUT/OUTPUT AND SET/CLEAR .
- 2. WHAT VALUE HAS TO BE LOADED INTO THE REGISTERS
  - TO CONFIGURE PORT 0 (P0.0-P0.15) PINS AS INPUT?
  - TO CONFIGURE PORT 0 (P0.15-P0.31) PINS AS INPUT?
  - TO CONFIGURE PORT 0 (P0.0-P0.15) PINS AS OUTPUT?
  - TO CONFIGURE PORT 0 (P0.15-P0.31) PINS AS OUTPUT?
  - TO CONFIGURE PORT 0 (P1.16-P1.31) PINS AS INPUT?
  - TO CONFIGURE PORT 0 (P1.16-P1.31) PINS AS OUTPUT?
  - WHETHER THE PINS P1.0-P1.15 ARE AVAILABLE AS GPIO?
- 3. LIST AND EXPLAIN THE REGISTERS USED TO CONTROL GPIO REGISTERS(IOPIN, IODIR,IOSET,IOCLR)

## LEVEL 3:

- 1. DEVELOP AN EMBEDDED 'C' PROGRAM TO BLINK THE LEDS CONNECTED TO PORT 0 PINS(P0.16-P0.23).
- 2. DEVELOP AN EMBEDDED 'C' PROGRAM TO IMPLEMENT 8-BIT BINARY COUNTER ON PORT 0 PINS (P0.16-P0.23).
- 3. DEVELOP AN EMBEDDED 'C' PROGRAM TO INTERFACE DAC WITH ARM7 TO GENERATE THE FOLLOWING WAVEFORMS:
  - SQUARE WAVE
  - TRIANGULAR WAVE
- 4. DEVELOP AN EMBEDDED 'C' PROGRAM TO INTERFACE THE RELAY WITH ARM7.
- 5. DEVELOP AN EMBEDDED 'C' PROGRAM TO BLINK THE BUILTIN LED CONNECTED TO PIN NUMBER 5 OF ARDUINO UNO.
- 6. DEVELOP AN EMBEDDED 'C' PROGRAM TO INTERFACE LDR SENSOR CONNECTED TO PIN NUMBER 13 OF ARDUINO UNO.
- 7. DEVELOP AN EMBEDDED 'C' PROGRAM TO INTERFACE BUZZER CONNECTED TO PIN NUMBER 9 OF ARDUINO UNO.