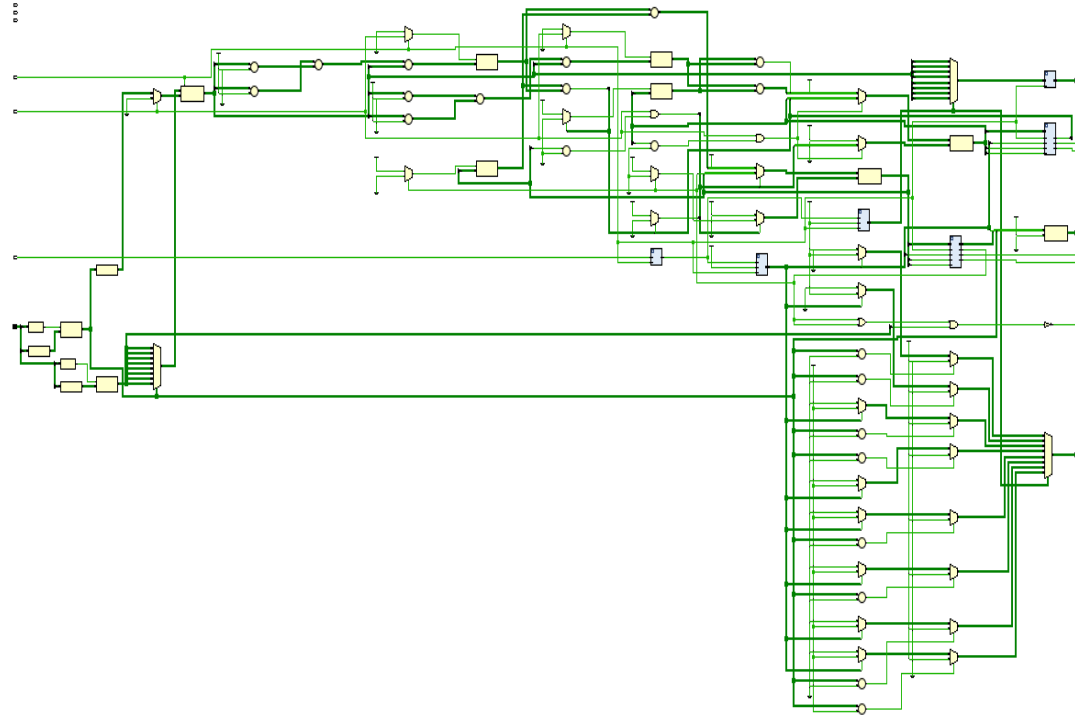
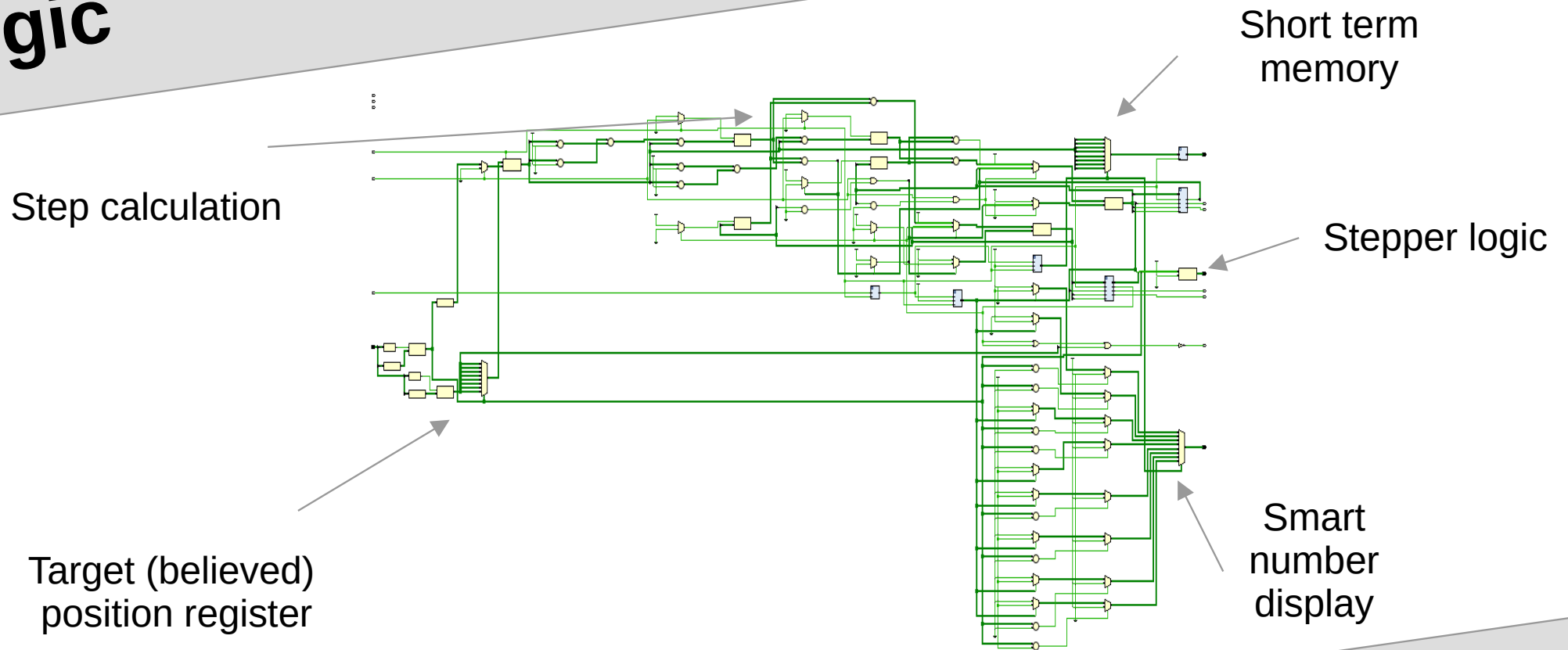


**253050 – stepper driver**

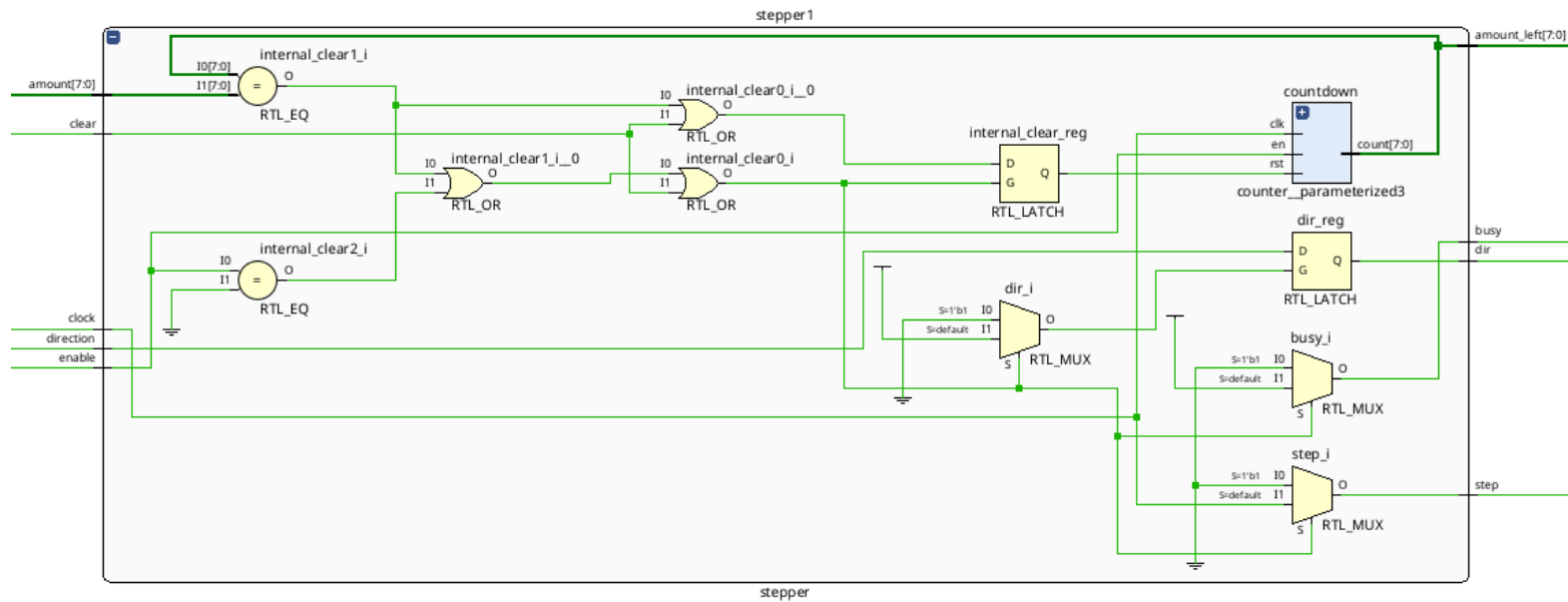
# logic



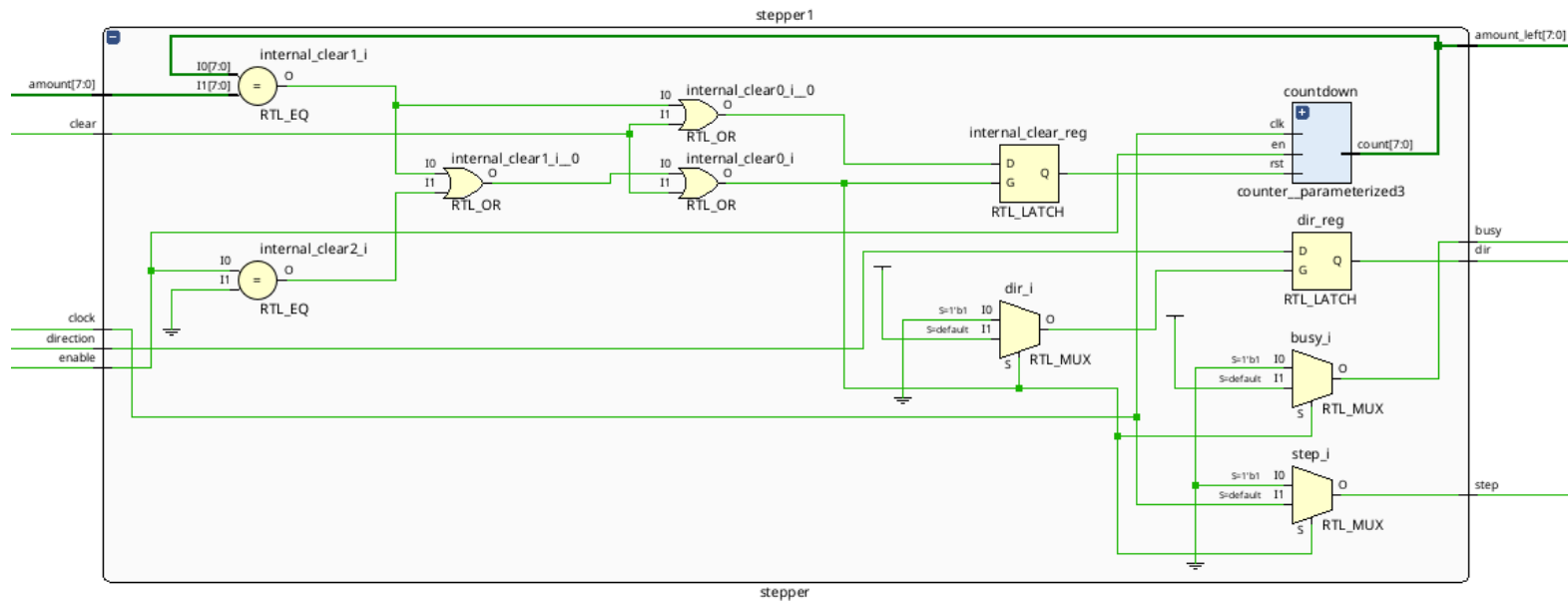
# logic



# Stepper logic



# Stepper logic



# issues

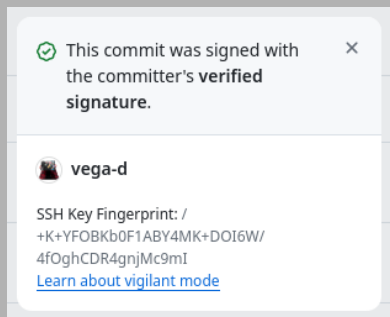
- no auto-home function achieved
- the hardware fell apart before I could finish the software
- the number inputting system could be more intuitive
- math is done dirty-dirty

# Bonus points (ig?)

- the project actually works
- I set a goal at the beginning of the project and I did achieve the goal
- everything is on github

## Bonus bonus points (maaybe?)

- all git commits are signed with a public key using a smartcard HSM



# Dirty Math

```
reg1_motor1(7 downto 0) <=
std_logic_vector(to_unsigned(to_integer(unsigned(reg_targetposition_motor1))-
to_integer(unsigned(reg_currentposition_motor1)), 8));
```



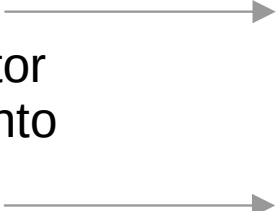
# Dirty Math

```
reg1_motor1(7 downto 0) <=
    std_logic_vector(
        to_unsigned(
            to_integer(
                unsigned(reg_targetposition_motor1)
            )
            -
            to_integer(
                unsigned(reg_currentposition_motor1)
            ),
        8)
    );
```

# Dirty Math

Convert  $\text{std\_logic\_vector}$  binary arrays into integers


```
reg1_motor1(7 downto 0) <=
    std_logic_vector(
        to_unsigned(
            to_integer(
                unsigned(reg_targetposition_motor1)
            )
            -
            to_integer(
                unsigned(reg_currentposition_motor1)
            ),
        8)
    );
```



# Dirty Math


Do math

```
reg1_motor1(7 downto 0) <=
  std_logic_vector(
    to_unsigned(
      to_integer(
        unsigned(reg_targetposition_motor1)
      )
      -
      to_integer(
        unsigned(reg_currentposition_motor1)
      ),
    8)
  );
```



# Dirty Math

Convert integer back  
into unsigned  
std\_logic\_vector  
binary array



```
reg1_motor1(7 downto 0) <=
  std_logic_vector(
    to_unsigned(
      to_integer(
        unsigned(reg_targetposition_motor1)
      )
      -
      to_integer(
        unsigned(reg_currentposition_motor1)
      )
    ),
    8)
  );
```

**End**

**“**

This presentation totally was not  
made 1h before you saw it

**”**