

Problem Wk.14.2.6: Robot Race Results (optional)

The culmination of 6.01 is a race between robots moving through a maze. Your robot navigates the maze by dynamically building a map of the obstacles and dynamically planning a route to the goal. It is not given information about its initial position within the maze.

The results of running `mapAndRaceBrain.py`, with your mapper and planner code, are two numbers, a printout looking something like this:

```
Total steps: 320
Elapsed time in seconds: 209.554840088
```

That's the number of soar primitive steps it took to execute your plan, and the amount of elapsed time it took. These numbers will be your 'score'. Note that we are aiming for low scores!

1. Enter the steps your robot took to navigate the maze: steps
2. Enter the elapsed time your robot took to navigate the maze: seconds

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6.01SC Introduction to Electrical Engineering and Computer Science
Spring 2011

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