

Position Sensors











IDT at a Glance

Founded	1980		
Workforce	Approximately 1,800 employees		
Headquarters	San Jose, California		
Core Expertise	Timing, high-speed mixed-signal design, serial interconnects, memory interfaces, power management, radio frequency (RF), automotive ASICs, battery management ICs, sensor signal conditioner ICs and environmental sensors		
Sales Channels	Worldwide network of direct, manufacturers' representatives and distribution sales		
Financials	FY16 revenue - \$697M Cash and investments - \$351M		
Research and Development	Over \$100M+/ year, leading to 900+ issued or pending patents		

Complete mixed-signal solutions for the communications, computing, consumer, automotive and industrial segments









IDT Business Units

Markets & **Applications**

COMPUTING & COMMUNICATIONS



Mobile & Cloud **Drive Converged** Infrastructures

High Performance I/O, Memory IF, new NVM, Timing, **CONSUMER**



Mobile Data Drives Wireless Charging, Sensing

> Wireless Charging, Sensors, and Timing

AUTOMOTIVE & INDUSTRIAL



Autos are Servers on Wheels, Robotics, **Industry 4.0**

Sensors, Actuators and Motor Control, Timing, Memory IF & Energy Management

Solutions & Opportunities

Megatrends & Drivers

RF, Energy Management

Timing

Timing & Sync

Timing & Freq Gen

Timing & Freq Gen

Power & Energy Smart Power Smart Power Smart Power

Sensing Sensors Sensors Sensors

RF & Signal Processing Signal Integrity Signal Conditioning Signal Conditioning

Core Competence







Fully Certified Global Automotive Supplier

ISO 9002:1994 (1993) ISO 14001:1994 (1999) ISO 9001:2000 (2000) ISO/TS 16949:200 2 (2007) ISO 9001:2004 (2010) ISO 9001:2008 (2010) BS OSHAS 18001:2007 (2013)

ISO/TS 16949 (2016)











Automotive & Industrial Focus Products

Actuator & MC Energy Mgmt



Sensor Solutions

Power Solutions

IDI

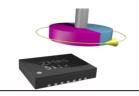
ASIC / ASSP





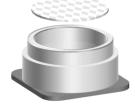






- Intelligent battery sensor
- Arc fault detection
- Integrated Mirror Control ICs
- Inductive Position Sensors
- MR SSC
- PS Systems
- · e-Motors















- Optical Sensors
- Thermopile Sensors
- Gas Sensors
- Humidity Sensors
- Low Pressure

- · IVI PMIC / DPU
- FuSa PMIC / DPU
- Digital Controllers
- DrMOS

- Sensor Signal Conditioning
- Customer Specific Products











Position Sensors











Position Sensor Success Story



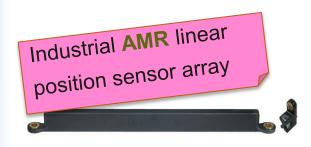
 Former ZMDI has a long history with Position Sensors in the market.

 Over 200M Magnetic Position Sensor SSC (Sensor Signal Conditioner)
 ASICs have been sold to automotive and industrial customers.

Automotive AMR Angle sensor for throttle or pedal position















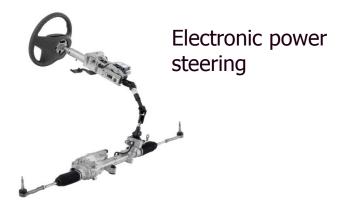


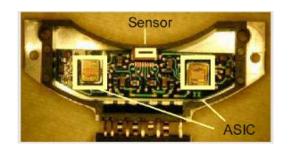
Sensor Signal Conditioner AMR ASIC

 More than 120m Position Sensor ASIC's in the field



 More than 110m Torque Sensor ASIC's in the field













Selected Home Appliance Applications

- White goods
- Washing machine
- Dryer
- Dishwasher
- **–** ...



- RC-Servo
- Joystick
- Toy-Robots
- Pedals
- ...



- Volume control
- Hi-Fi Audio
- Car-Radio
- Temperature Control
- ...











Selected Industrial Applications

Robotics

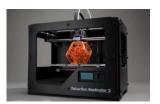
- Warehouse robots
- Industrial robots
- Surgical robots
- UAV/Drones
- Humanoid robots

– ...



Office Automation

- 3D printers
- 3D scanner
- Security cameras
- ___



Industrial Automation

- Encoder module
- Electrical motors



Building Automation

- Flaps in air condition
- Window shutter
- Marquees
- Doors
- Valves
- Actuators







Selected Robot Applications

Consumer Robot

- Wheel motor gearbox motors using position sensors for wheel control
- Head movement position sensors for position control
- Joint motor control and position feedback



Consumer Robot

 Position Sensors replace low performance potentiometers in servos for improved robot performance



 Industrial servo modules profit from Position Sensors



Drones

 Position sensors enabling improved payload capacity and performance, e.g. camera stability















Inductive Position Sensor Solutions





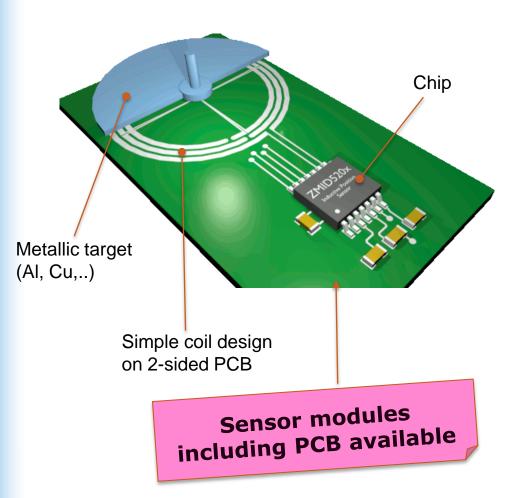








IDT Inductive Position Sensors



- Ultra-thin solution Small form factor, no magnet required
- Total stray field immunity ISO 11452-8 compliant
- No external sensor needed the sensor is a PCB coil
- Compliant to auto standards -AECQ-100, ESD, EMC, ISO26262
- Suitable for high temperature
- On and off-axis capability and alignment

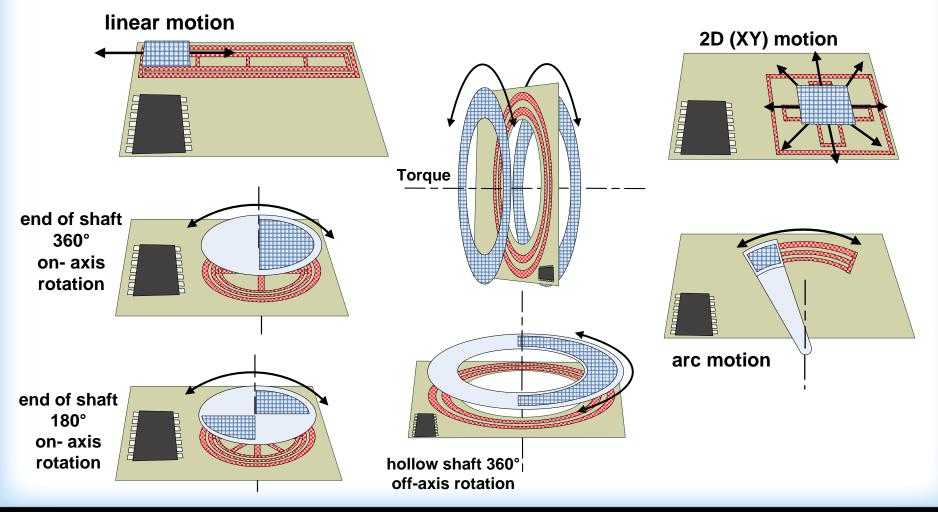








Position Sensors Typical Inductive Applications

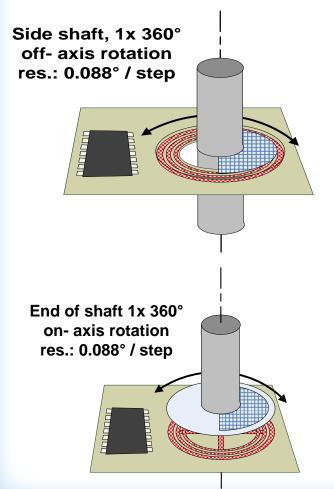


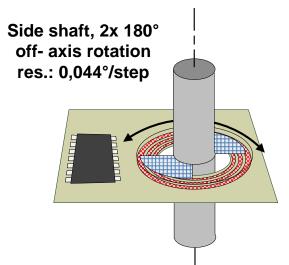






Position Sensors Typical Inductive Motor Applications





- End of shaft and side shaft configuration
- Suitable for any number of rotor pole pairs Full Resolution (4096 steps) within one pole pair
- Full 360° or arc coil design for off-axis









Side shaft, 6x 60°

off-axis rotation

res.: 0,015°/step

arc coil shape for limited space



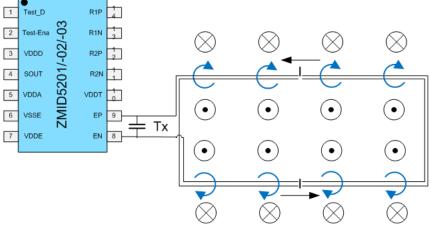
Inductive Sensor: functional principle

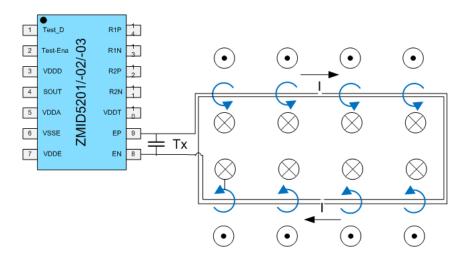






Transmit coil: magnetic field generation





An LC oscillator generates a magnetic field in a wire loop. Inside the loop the magnetic field is nearly homogeneous.

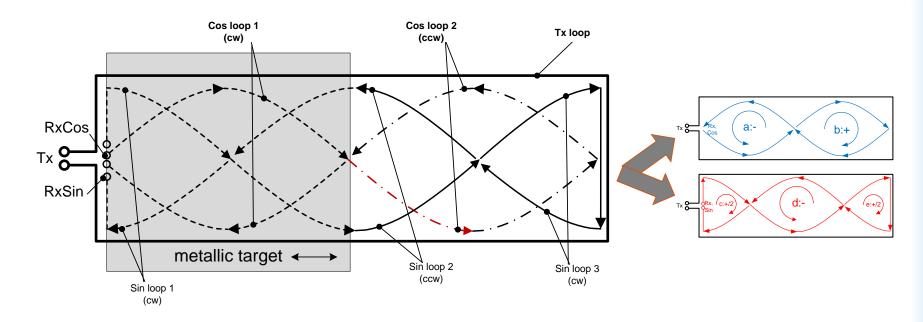
The polarity of the magnetic field depends on the direction of current in the loop.

The ZMID520x oscillates at ~1-5Mhz





Linear coil design: Tx and Rx coils



Shown here is a final design for a linear motion position sensor with transmit coil, receive coils+ target .

However, for easier understanding , in the following slides the RxSine and RxCosine coils will be shown on separate graphs.

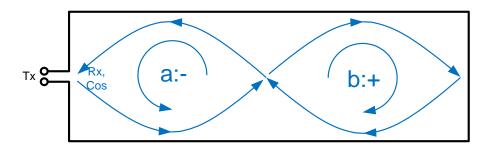






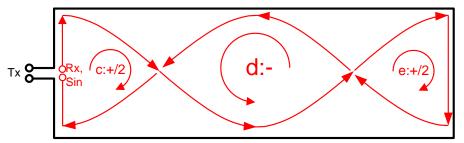


Receive coils: Rx voltage generation



$$Va = -1$$

 $Vb = 1$
 $Vcos= Va + Vb = 0$



$$Vc = 1/2$$

$$Vd = -1$$

$$Ve = 1/2$$

$$Vsin = Vc+Vd+Ve = 0$$

Inside the Transmit coil area, a first receive coil (Rx Cos), shaped like a lying "8" and a second receive coil (Rx Sin), shifted by half a period are placed.

In each Rx loop, a voltage is generated, which is dependent on:

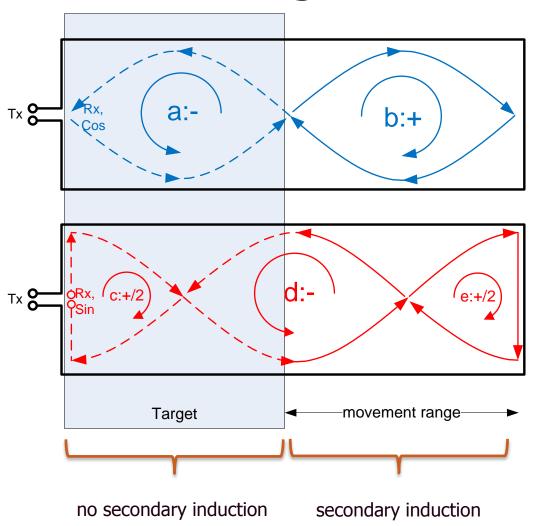
- the magnetic field strength
- 2. the area exposed by the loop (Va = Vb = Vc).

Without a target, the resulting receive voltage is 0, as the generated voltages cancel each other.





Placing a metallic target



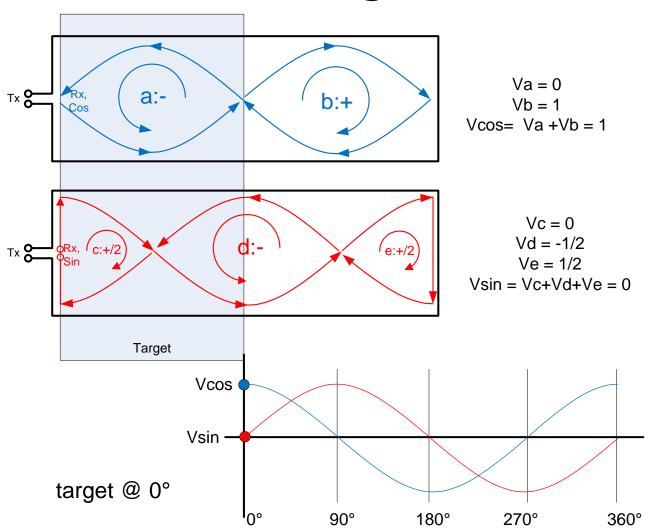
If a metallic target is placed over the coils, the transmitted energy below the target is dissipated as eddy currents in the target and does not induce a secondary voltage in the Receiver coils in that area.







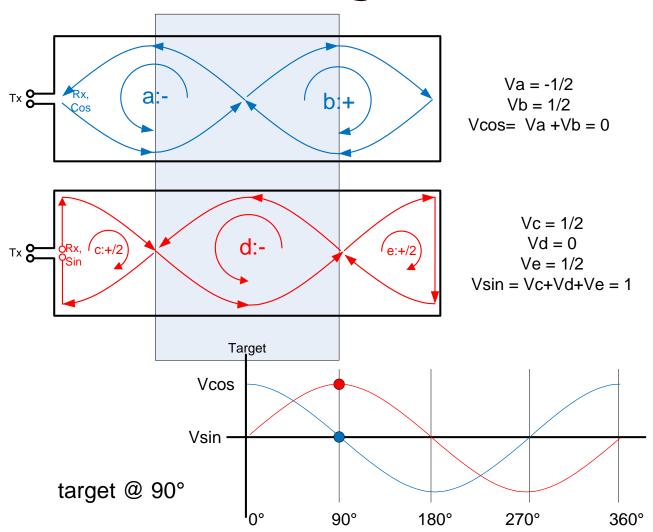
Target at 0°



At 0°, Vcos is positive maximum and Vsin is 0.



Target at 90°



At 90°, Vcos is 0 and Vsin is positive maximum.

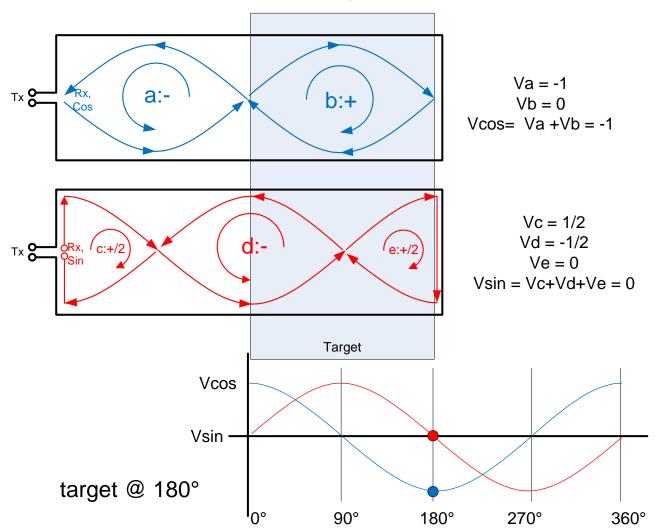






Target at 180°

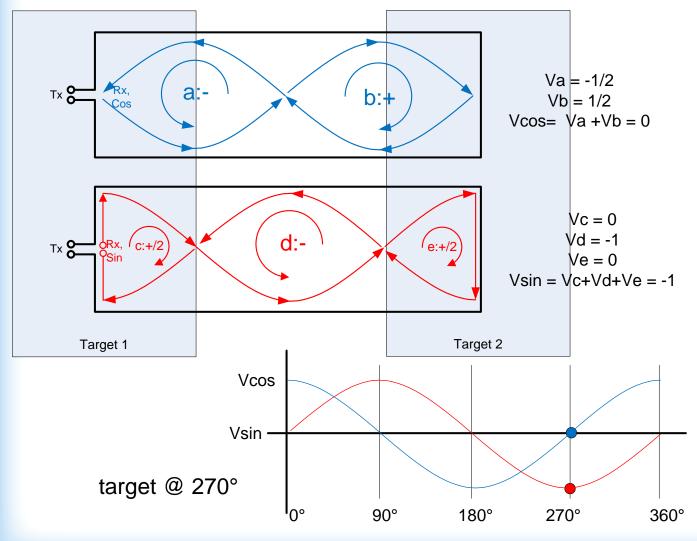
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At 180°, Vcos is negative minimum and Vsin is 0.

Target at 270°

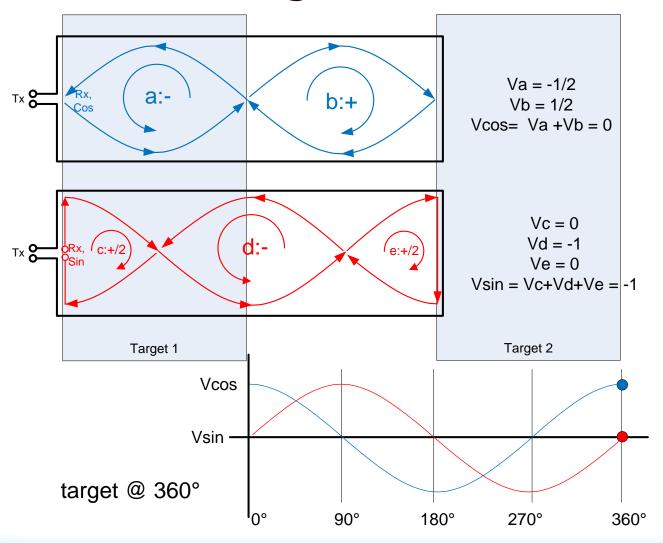


Linear motion sensors can be further extended beyond 180° by adding a second target. At 270°, Vcos is 0 and Vsin is negative minimum.





Target at $360^{\circ} = 0^{\circ}$

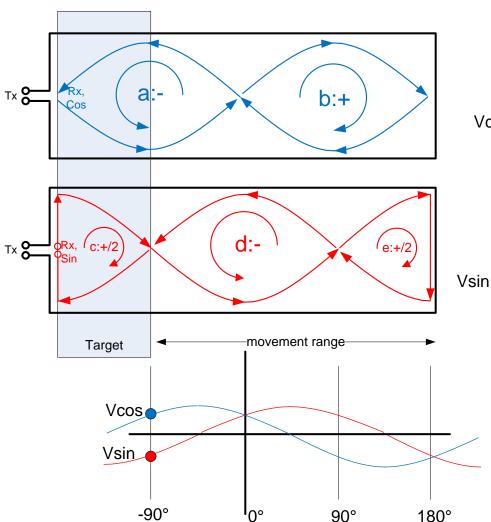


Linear motion sensors can be further extended beyond 180° by adding a second target. At 360°, Vcos is positive maximum and Vsin is 0.





Narrow Targets



$$Va = -1/2$$

$$Vb = 1$$

$$Vcos= Va + Vb = 1/2$$

$$Vc = 0$$

$$Vd = -1$$

$$Ve = 1/2$$

$$Vsin = Vc+Vd+Ve = -1/2$$

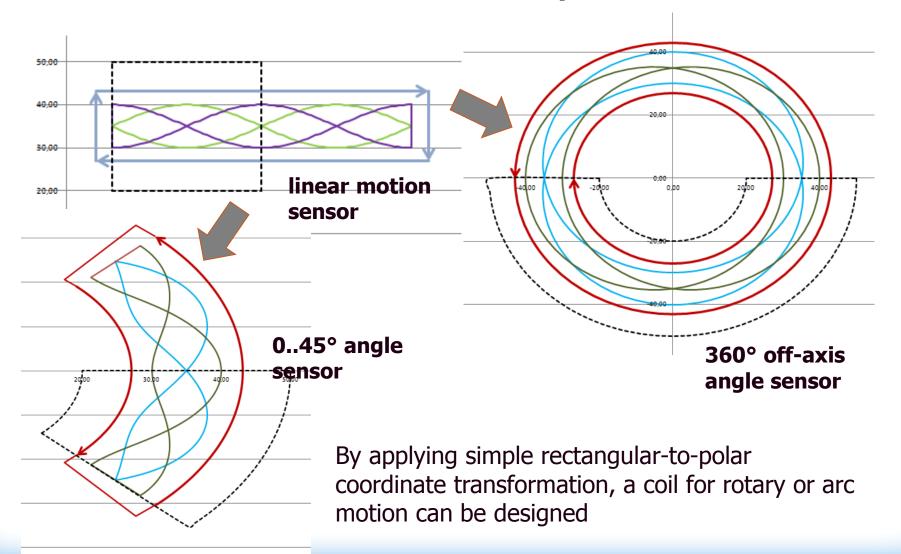
Narrow (or wide) targets allow a longer movement range with the same coil length, but lead to smaller signal amplitudes. The largest signal is created when the target width is ½ period.







from linear to rotary sensors



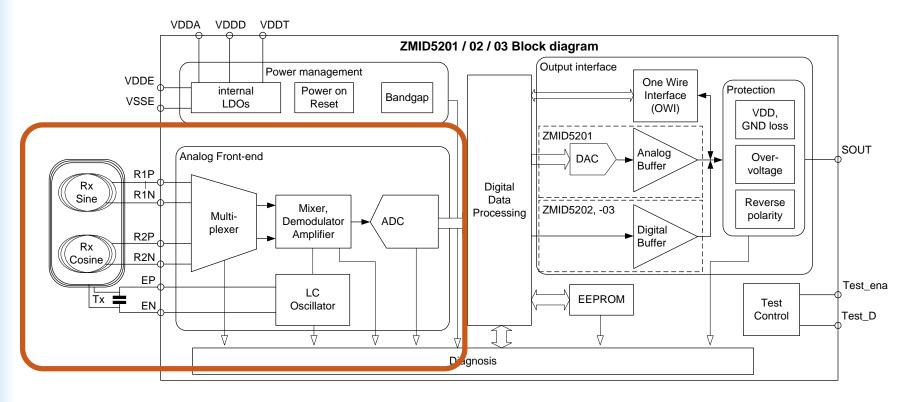








Inside the ZMID520x: Front end



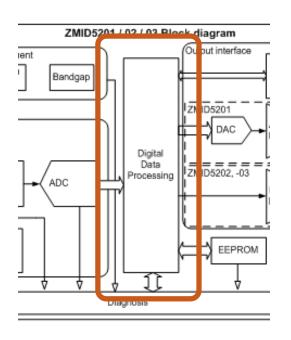
The Tx coil generates a Transmit signal in the (1-5) MHz range The Rx coils pick up the Tx signal, the amplitude is depending on the target position.

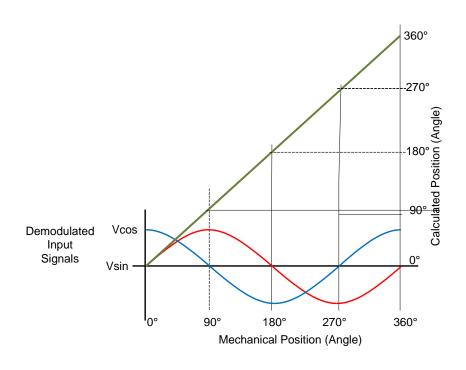
After demodulation and ADC conversion, the Sine and Cosine signals are used to calculate the position.





Inside the ZMID520x: Signal processing





The signal processing unit transforms sine and cosine input signals into angle and magnitude output signals (0 to 360°). In addition, it provides several signal shaping functions



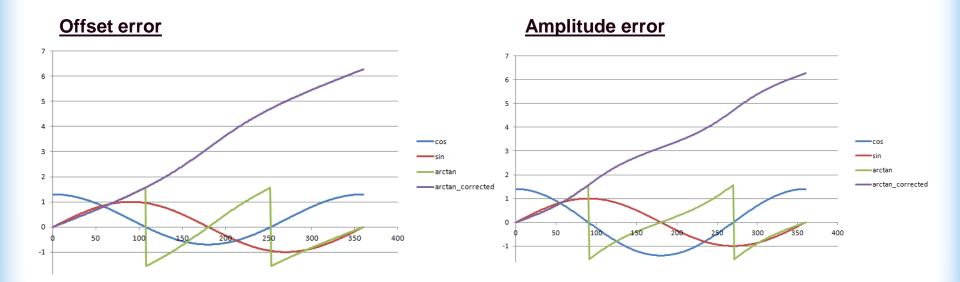




Inside the ZMID520x: Errors

Symmetry:

- Avoiding amplitude and offset errors in coil design
 - Offset errors introducing 1f error in CORDIC output
 - Amplitude mismatch introducing 2f errors in CORDIC output
 - Phase offsets introducing 2f errors in CORDIC output
 - ZMID520x is providing linearization feature



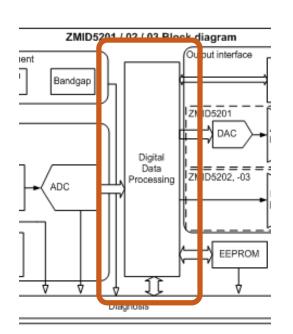


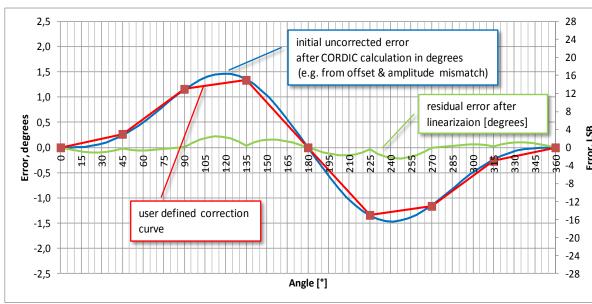






Inside the ZMID520x: Linearization





Non-ideal coil designs lead to angle errors due to distortion, offsets, amplitude or phase matching. These errors can be corrected by a user defined 9-point linearization function.

The resulting error is typically less than 0.2% full scale

Angle range	Error 0.2% FS =	
20° (e.g. Pedal)	0,04 °	
90° (e.g.Throttle)	0,18°	
180° (e.g. robot)	0,36 °	
270° (e.g. Pot.)	0,54 °	
360° (e.g. motor)	0,72 °	

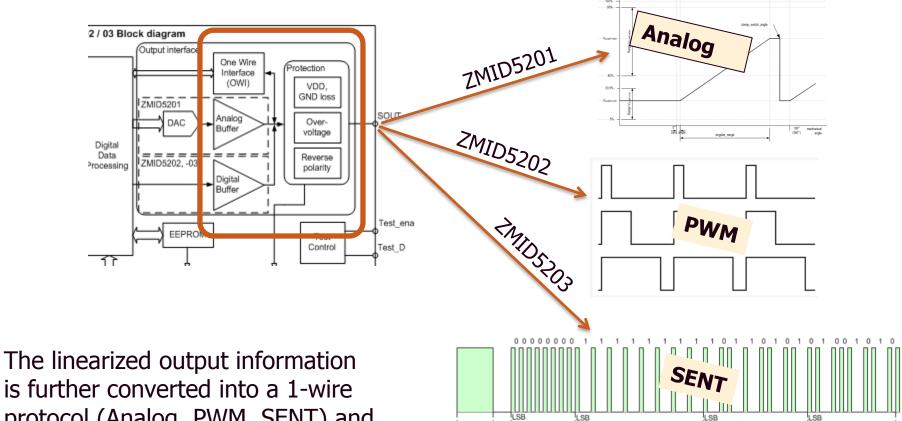








Inside the ZMID520x: Outputs



protocol (Analog, PWM, SENT) and fed to the output pin, which is also protected against overvoltage, short

protected against overvoltage, short circuit or reverse polarity.

The same pin is also used to program the chip.







(Logical Inverse)



(Logical Inverse)



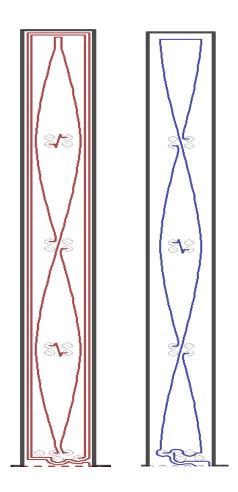
Coil designs @ IDT



Inductive principle coil design

Electrical parameters:

- Transmitter coil
 - Quality factor bigger than 10
 - $Q = (L^*w)/R -> calculated @2.2MHz$
 - Inductance from 1μH up to 30μH
 - Oscillation frequency determined by external capacitor
 - $w = 1/(sqrt(L^*C))$
- Receiver coils
 - No specific requirements on electrical parameters
 - Shape/enclosed area is defining the coupling factor
 - Ideally the receiver coils are shaped sinusoidal
 - Position sensor can handle input signals from a few mV up to 300mV
 - Sensor is equipped with AGC
 - Design can be verified with HF FEM simulation tools









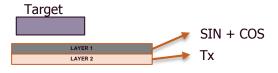
Inductive principle coil design

Avoiding amplitude mismatch:

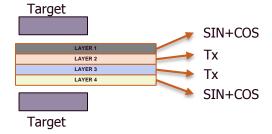
 In the PCB design amplitude mismatch can be avoided by keeping the same distance between receiver coils (SIN,COS) and the moving target

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2 layer PCB:



4 layer PCB:







Position Sensor Module – Solutions Offerings

Sales target	Sensor IC	Coil design	PCB design
Direct, Automotive	Packaged	Customer	
Direct, Automotive	Packaged	IDT (customized, NRE)	Customer
Direct, All markets	Packaged or Chip-on-board	IDT (customized, NRE)	
Distribution, Industrial, Consumer	Packaged or Chip-on-board	IDT (catalog coil & PCB designs, no NRE)	









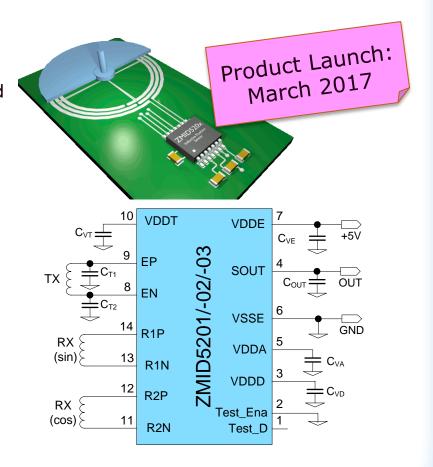
Coming soon, ZMID520X Inductive Position Sensor

Features

- Fully automotive qualified to AECQ-100
- 5V supply
- Overvoltage, reverse polarity, short circuit protected
- Analog output, 1024 steps: ZMID5201
- PWM output, 1024 steps: ZMID5202
- SENT output, 4096 steps: ZMID5203
- High precision: ± 0.2% accuracy

Benefits

- Ultra-thin
 - small form factor
- No magnet needed
 - moving target = copper or aluminum foil
 - low BOM
- Ratiometric measurement
 - tolerant against misalignment of target

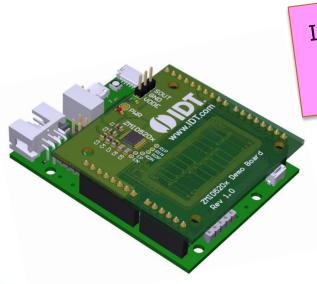






Additional Support Tools

- Good support tools are essential for success!
- Fast installation (5minute rule#1)
- Easy to use and understand (5minute rule#2)
- Video tutorials



Increase professional video material as support tool





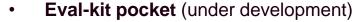






Next Generation evalkit platform

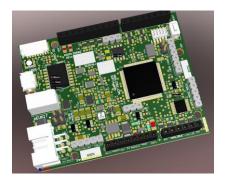
- Eval-kit PRO (available@ product launch)
 - Full Featured Platform
 - USB Isolation
 - ADC 16bit
 - Arduino Compatible
 - Standard evaluation kit



- USB Dongle sized
- Very low cost
- Product Dedicated device



- Tradeshow Demos (under planning)
 - Tablet based approach
 - Android Position sensing apps & widgets
 - Full digital support package (Videos, Guidelines, Docs)











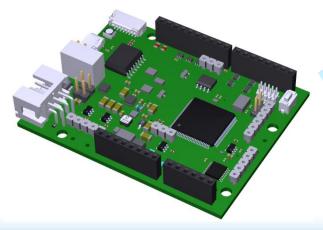


Eval-kit PRO

Inductive Demo board with PCB coil



Eval-kit PRO communication board



Piggy-backed Eval-kit for linear inductive sensing



Credit card sized 5 minute rule proofed









Thank You

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