

# Heterogeneous core-mantle boundary heat flux in thermo-chemical core convection

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# Abstract

Thermal coupling between convection in Earth's mantle and core was proposed to explain asymmetric features of the geomagnetic field during the history of the Earth. The coupling is caused by laterally varying heat transport from the core to the mantle, induced by lateral temperature gradients in the lower-most mantle. Clues for the temperature gradients were found by seismic tomography.

This numerical study aims to explore the influence of these non-uniform boundary conditions, as compared to uniform heat flux and isothermal boundary conditions on thermo-chemical core convection and some distinct dynamo properties.

In our model the heat flux pattern is modeled by a single spherical harmonic of degree and order 2. This setting conserves equatorial symmetry, but imposes azimuthal heat flux gradients.

Today, convection in the Earth's core is assumed to be driven predominantly by a combination of thermal and compositional buoyancy sources located at the inner-core boundary. Thermal and compositional diffusivities differ by orders of magnitude. The resulting differences in the dynamical behavior of the two components demand an approach with distinct transport equations and boundary conditions for temperature and chemical concentration. Simulations for five different ratios of thermal and chemical driving are made.

We observe that fixed flux conditions promote larger flow scales and an increase of mean kinetic energy densities. The imposed flux pattern locks the outer core flow to the mantle and therefore breaks its azimuthal symmetry, even for relatively low thermal forcing ratios of 20 %. Despite of the symmetry breaking, stable and dipolar dynamos can be maintained due to the partly chemical forcing with its uniform boundary conditions. Additionally, the chemical component partly adopts to the geometry of the heat flux pattern because advective transport of concentration is more effective in regions of increased heat flux.

## 1 Introduction and Motivation

### 1.1 A thermo-chemical approach to dynamo modeling

### 1.2 Why use heterogeneous heat flux boundary conditions?

## 2 Modeling core convection and dynamo action

Rotating convection and dynamo action in Earth's core is a topic that has been explored by many authors (REFS ???). There exist various ideas of how to formulate a set of equations that depicts all relevant physical processes and that is still as simple and therefore numerically economical as possible. Computation time is the limiting factor when it comes to the question how realistic models of the inner core can be. The gap between the relevant physical parameters expected for the Earth and the param-

eters that are in range of numerical modeling is still big. It cannot be expected that this gap will be closed only with the help of the increasing computational resources that will become available within the next years. Alternatives to waiting for larger computers that allow to explore earth-like parameters have to be found. Asymptotic models are one possibility already revealing promising results (REFS ???).

A question that is closely related to the numerical costs and therefore to the accessible parameter range is the choice of the geometry. Most models are either Cartesian with periodic boundary conditions (BC) or spherical shell models. The latter are of course more realistic for the Earth but numerically more costly and therefore even less earth-like with regard to computational feasible parameters. In this work, a spherical model is used in order to be as earth-like as possible in a geometrical way. As a trade-off, parameter regimes in which Cartesian models could advance, are unreachable here.

We model the electrically conducting liquid outer core. It is enclosed by the inner-core boundary (ICB) at the bottom and the core-mantle boundary (CMB) at the top. Convection is driven by destabilizing thermal and compositional gradients across the sphere. For the compositional component, fixed chemical concentrations at the ICB and the CMB are imposed (Dirichlet BC). The thermal forcing is maintained by introducing a fixed in- and outflux of heat (Neumann BC). The heat flux at the CMB is laterally heterogeneous, i.e., there exist regions of higher and lower heat flux than lateral average. The inner core and mantle are assumed to be insulating and therefore have no influence on the evolution of magnetic fields.

In the following all relevant equations are introduced. There exist numerous detailed derivations so that this description will be held relatively short (REFS ???).

## 2.1 Frame of reference

The liquid outer core (LOC) is modeled in a spherical shell with an inner radius  $R_i$  and an outer radius  $R_o$ . It is bounded by the ICB at the bottom the CMB at the top. The shell thickness is chosen according to what is expected for today's state of the Earth and defined over the ratio between  $R_i$  and  $r_o$ :  $a = R_i / R_o = 0.35$ .

The LOC is constantly rotating about the z-axis of a Cartesian system. The angular velocity  $\Omega$  is invariant in time. The effect of the rotation on the frame of reference will be discussed when it comes to the equation of motion. In the course of this study, it is quite nearby to chose spherical coordinates (???).

## 2.2 Equation of continuity

Per definition, the mass  $\mathcal{M}$  of a material volume  $\mathcal{V}(t)$  with a density  $\rho$ , moving with a velocity  $\mathbf{u}(\mathbf{r}, t)$  in a fluid is conserved:

$$\frac{d\mathcal{M}(\mathcal{V})}{dt} = \frac{d}{dt} \int_{\mathcal{V}(t)} \rho(\mathbf{r}, t) d^3r = 0 \quad (1)$$

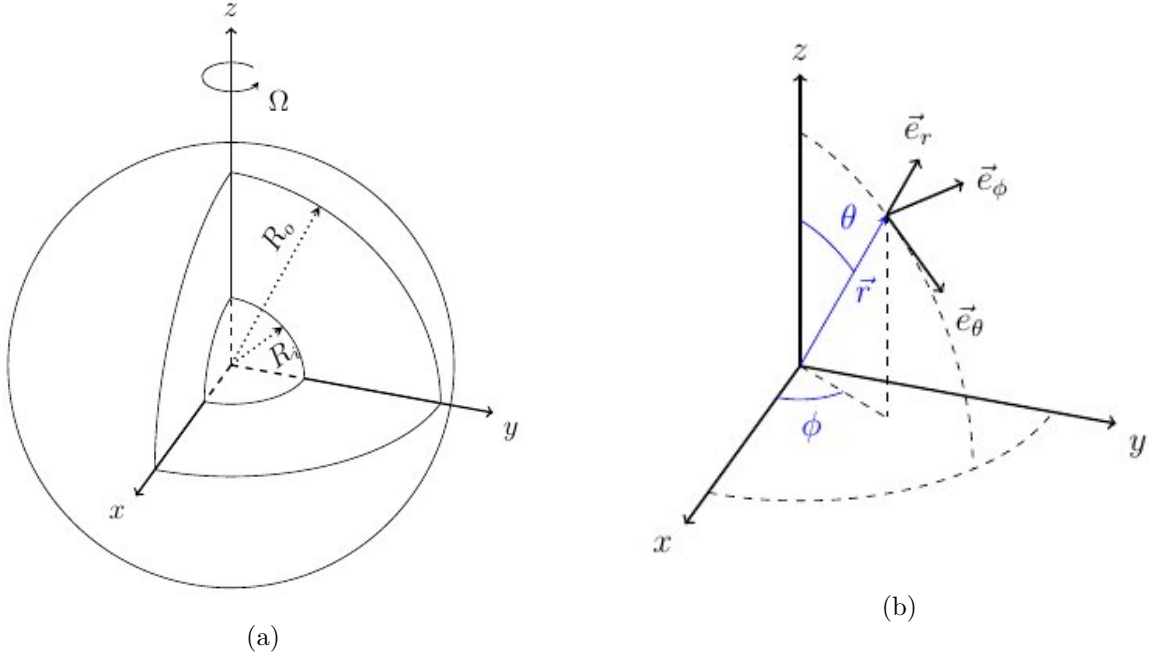


Figure 1: (a) (REFS ???) Sketch of the liquid outer core. It is bounded by the two spheres of radii  $R_i$  and  $R_o$ . The rotation axis is the cartesian z-axis. (b) This work uses spherical coordinates with unit vectors  $\mathbf{e}_r$ ,  $\mathbf{e}_\phi$  and  $\mathbf{e}_\theta$

Using Reynold's Transport Theorem (Appendix ???) and then applying Gauss's Theorem, this yields

$$\int_{\mathcal{V}(t)} \frac{\partial \rho}{\partial t} d^3r + \oint_{\partial \mathcal{V}(t)} \rho \mathbf{u} \cdot d\mathbf{s} = \int_{\mathcal{V}(t)} \left[ \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) \right] d^3r = 0. \quad (2)$$

Since this has to hold for all possible material volumes  $\mathcal{V}$ , one gets

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0, \quad (3)$$

the general form of the equation of continuity. The introduction of the *material derivative*  $\frac{D}{Dt} = \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla$  suggests another useful formulation:

$$\frac{\partial \rho}{\partial t} + \rho \nabla \cdot \mathbf{u} + \mathbf{u} \cdot \nabla \rho = \frac{D\rho}{Dt} + \rho \nabla \cdot \mathbf{u} = 0. \quad (4)$$

## 2.3 Equation of momentum

In an inertial, non-rotating frame of reference, the change of momentum of a material volume  $\mathcal{V}$  can be written as

$$\begin{aligned}
\frac{d}{dt} \int_{\mathcal{V}(t)} (\rho u_j) d^3r &= \int_{\mathcal{V}(t)} \left[ \frac{\partial(\rho u_j)}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_j) u_i \right] d^3r \\
&= \int_{\mathcal{V}(t)} \left[ \rho \frac{\partial u_j}{\partial t} + u_j \frac{\partial \rho}{\partial t} + \rho u_j \frac{\partial u_i}{\partial x_i} + u_i \rho \frac{\partial u_j}{\partial x_i} + u_i u_j \frac{\partial \rho}{\partial x_i} \right] d^3r \\
&= \int_{\mathcal{V}(t)} \left[ u_j \left( \frac{\partial \rho}{\partial t} + \rho \nabla \cdot \mathbf{u} + \mathbf{u} \cdot \nabla \rho \right) + \rho \left( \frac{\partial u_j}{\partial t} + \mathbf{u} \cdot \nabla u_j \right) \right] d^3r \\
&= \int_{\mathcal{V}(t)} \rho \frac{Du_j}{Dt} d^3r.
\end{aligned}$$

Change of momentum can happen through either *volume forces*  $\mathbf{f}$  or *surface forces*  $\mathbf{t}$ :

$$\int_{\mathcal{V}} \rho \frac{D\mathbf{u}}{Dt} d^3r = \int_{\mathcal{V}} \mathbf{f} d^3r + \oint_{\partial\mathcal{V}} \mathbf{t} ds \quad (5)$$

If a frame of reference is rotating - as in this case - it is no longer an inertial system and therefore pseudo forces have to be expected. Under the assumption of a constant rotation with the angular velocity  $\Omega$  and a fixed rotation axis parallel to the Cartesian z-axis, the change of a quantity  $\mathbf{P}$  in the rotating frame of reference and its change in the non-rotating inertial frame relate as

$$\left( \frac{d\mathbf{P}}{dt} \right)_F = \left( \frac{d\mathbf{P}}{dt} \right)_R + \Omega \times \mathbf{P}, \quad (6)$$

where the subscripts  $F$  and  $R$  indicate the *fixed* and the *rotating* frame. Applying rule (6) twice to a position vector  $\mathbf{r}$  yields

$$\mathbf{a}_F = \mathbf{a}_R + 2\Omega \times \mathbf{u}_R + \Omega \times (\Omega \times \mathbf{r}) \quad (7)$$

for accelerations  $\mathbf{a}$ .  $2\Omega \times \mathbf{u}_R$  is the Coriolis force and  $\Omega \times (\Omega \times \mathbf{r})$  the centripetal force.

With the help of (7),  $\frac{D\mathbf{u}}{Dt}$  can be transferred from the inertial frame to the frame of reference:

$$\frac{D\mathbf{u}_F}{Dt} = \frac{D\mathbf{u}_R}{Dt} + 2\Omega \times \mathbf{u}_R + \Omega \times (\Omega \times \mathbf{r}) \quad (8)$$

From now on, the subscripts  $F$  and  $R$  will be cut and all quantities will be measured in the rotating frame. With (8), (5) changes to

$$\int_{\mathcal{V}} \rho \frac{D\mathbf{u}}{Dt} d^3r = \int_{\mathcal{V}} \mathbf{f} d^3r + \oint_{\partial\mathcal{V}} \mathbf{t} ds - \int_{\mathcal{V}} \rho (2\Omega \times \mathbf{u} + \Omega \times (\Omega \times \mathbf{r})) d^3r. \quad (9)$$

Another pseudo force that generally appears in rotating systems is the *Poincaré force*. Precession driven flows are the most prominent example from geophysics where it plays

a dominant role (Tilgner, 2007).

The *Cauchy Theorem* relates the surface forces  $\mathbf{t}$  to the stress tensor  $\underline{\tau}$  linearly via  $\mathbf{t} = \underline{\tau} \cdot \mathbf{n}$ , where  $\mathbf{n}$  is the normal vector. The surface term in (9) can thus be transformed to

$$\oint_{\partial V} \mathbf{t} ds = \int_V \nabla \cdot \underline{\tau} d^3r, \quad (10)$$

where  $\nabla \cdot \underline{\tau} = -\nabla p + \mu \nabla^2 \mathbf{u}$  will be used as a reasonable simplification in the context of the Boussinesq approximation (see section 2.7). This expression of  $\nabla \cdot \underline{\tau}$  is valid for Newtonian fluids and it is based on the assumption of a solenoidal velocity field ( $\nabla \cdot \mathbf{u} = 0$ ) and a homogeneous dynamic viscosity  $\mu$  throughout the fluid.

The body forces  $\mathbf{f}$  are the *buoyancy force*  $\mathbf{f}_g = \mathbf{g}\rho$  and the *Lorentz force*  $\mathbf{f}_l = \mathbf{j} \times \mathbf{B}$ . The latter will be discussed in section 2.4.

In the following, the gravitational field  $\mathbf{g}$  will be discussed in more detail. As mentioned before, the system underlies an asymmetric heat flux at the CMB. This results in an asymmetric temperature field for which the penetration depth of the temperature perturbation to a spherical symmetric solution depends on the amplitude of the heat flux heterogeneity. Following the linear equation of state from the Boussinesq approximation (see section 2.7), this results in a density variation proportional to the temperature variation:  $\delta\rho \sim \delta T$ .

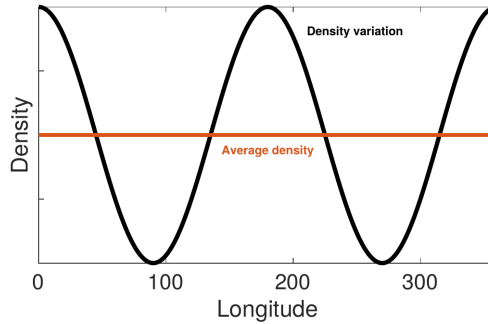


Figure 2: Sketch of the density along the equator, near the CMB. The deviation (black) from the average density (red) results from the asymmetric heat flux at the CMB which has a asymmetric temperature field as a consequence.

The total density can be split into one spherical symmetric part  $\bar{\rho}(r)$  that only depends on the radial level  $r$  and the density variation due to the heat flux pattern  $\delta\bar{\rho}(r, \vartheta, \varphi)$ :

$$\rho(r, \vartheta, \varphi) = \bar{\rho}(r) + \delta\bar{\rho}(r, \vartheta, \varphi). \quad (11)$$

In case of a heat flux pattern proportional to the spherical harmonic  $\mathcal{Y}_2^2$ , the dependence of  $\delta\bar{\rho}$  on  $\varphi$  is  $\pi$ -periodic (see Figure 2) so that it can be expressed by the product  $\delta\bar{\rho}(r, \vartheta, \varphi) = \mathcal{C}(r, \vartheta) \cdot \cos(2\varphi)$ .  $\mathcal{C}$  is only a function of  $r$  and  $\vartheta$ .

*Gauss's* gravity law (Blakely, 1996) states

$$\nabla \cdot \mathbf{g} = -4\pi G\rho(r, \vartheta, \varphi). \quad (12)$$

Integration over a sphere of radius  $r$  and application of Gauss's theorem yields

$$\begin{aligned}
\int_{\mathcal{V}(r)} \nabla \cdot \mathbf{g} dV &= \int_0^\pi \int_0^{2\pi} r^2 \sin(\vartheta) d\vartheta d\varphi \mathbf{g} \cdot \mathbf{e}_r = -4\pi G \int_0^r \int_0^\pi \int_0^{2\pi} \sin(\vartheta) r'^2 \rho(r, \vartheta, \varphi) dr' d\vartheta d\varphi \\
&= -4\pi G \int_0^r \int_0^\pi \int_0^{2\pi} \sin(\vartheta) r'^2 [\dot{\rho}(r') + \delta \dot{\rho}(r', \vartheta, \varphi)] dr' d\vartheta d\varphi \\
&= -8\pi^2 G \int_0^r \dot{\rho}(r') dr' - 4\pi G \int_0^r \int_0^\pi \sin(\vartheta) r'^2 \mathcal{C}(r', \vartheta) \left( \int_0^{2\pi} \cos(2\varphi) d\varphi \right) dr' d\vartheta \\
&= -8\pi^2 G \int_0^r \dot{\rho}(r') dr'
\end{aligned}$$

Because the integration of  $\delta \dot{\rho}(r', \vartheta, \varphi)$  over  $\varphi$  drops out for every value of  $r$  and  $\vartheta$ ,  $\mathbf{g}$  can be expressed by

$$\mathbf{g}(\mathbf{r}) = -\frac{4\pi G}{r^2} \int_0^r \dot{\rho}(r') r'^2 dr' \quad (13)$$

and it is worth noticing that  $\mathbf{g}$  has the same form as in the spherical symmetric case (Blakely, 1996).

The buoyancy force term  $\mathbf{g}\rho$  will be further discussed in section 2.7.

## 2.4 Maxwell equations, Lorentz force and induction equation

The liquid outer core consists of a metallic and therefore conducting fluid. Electric currents may evolve, create magnetic fields and these again may generate currents and influence the flow field. The induction equation is a transport equation for a magnetic fields  $\mathbf{B}$  'hosted' by a fluid moving with a velocity  $\mathbf{u}$ . The Lorentz force characterizes the influence of the magnetic field on the flow field, whereas the Maxwell equations describe how electric and magnetic fields interact through charges and currents. They form a basis for the 'magnetic part' of Magnetohydrodynamics (MHD).

In the scope of core convection, a reduced form of the Maxwell equations (Pre-Maxwell equations) suffices (REF Davidson ???):

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} \quad (\text{Ampère's law}) \quad (14a)$$

$$\nabla \cdot \mathbf{j} = 0 \quad (\text{Charge conservation}) \quad (14b)$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad (\text{Faraday's law}) \quad (14c)$$

$$\nabla \cdot \mathbf{B} = 0 \quad (\text{No magnetic monopoles}) \quad (14d)$$

Additionally, an extended version of *Ohm's law* for moving conductors

$$\mathbf{j} = \sigma(\mathbf{E} + \mathbf{u} \times \mathbf{B}) \quad (15)$$



and an expression for the *Lorentz force*

$$\mathbf{f}_l = \mathbf{j} \times \mathbf{B} = \frac{1}{\mu_0}(\nabla \times \mathbf{B} \times \mathbf{B}) \quad (16)$$

are needed.  $\mathbf{E}$  describes the electric field,  $\mathbf{j}$  the current density,  $\mu_0$  the vacuum permeability and  $\sigma$  the conductivity of the fluid.

The *induction equation*, a transport equation for the magnetic field, can be derived using (14c), (15) and the solenoidal character of  $\mathbf{B}$  (14d) and  $\mathbf{u}$ :

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla(\mathbf{u} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B}, \quad (17)$$

where  $\eta = \frac{1}{\sigma \mu_0}$  is the magnetic diffusivity.

## 2.5 Conservation of energy

The conservation of internal energy in a fluid reads

$$\rho \frac{De}{Dt} = -\nabla \cdot \mathbf{q}_T - p(\nabla \cdot \mathbf{u}) + \Phi, \quad (18)$$

where the internal energy per unit mass is described by  $e$ . It can be changed by either *volume compression*  $-p(\nabla \cdot \mathbf{u})$ , *viscous dissipation*  $\Phi$  or a *heat flux*  $\mathbf{q}_T$  through the fluid surface. In the context of the Boussinesq approximation (section 2.7), viscous dissipation  $\Phi$  is negligible and  $\nabla \cdot \mathbf{u} = 0$ . Furthermore, using the *Fourier law*  $\mathbf{q}_T = -k_T \nabla T$  and the *perfect gas* approximation  $e = c_p T$ , (18) can be transformed to

$$\frac{DT}{Dt} = \kappa_T \nabla^2 T. \quad (19)$$

Here,  $\kappa_T = \frac{k}{c_p \rho}$  is the thermal diffusivity and  $T$  the fluid temperature. Internal sources of  $e$  in the liquid outer core are completely omitted in this study.

The derivation of equation (19) was adopted from Kundu and Cohen (2008).

## 2.6 Conservation of the light component

The light component is released at the ICB as the inner core slowly crystallizes. It serves as an additional source of buoyancy. In this model, the light component per unit mass,  $C$ , can only change by a flux  $\mathbf{q}_C$  through the surface of the fluid. According to the equation for the conservation of the internal energy in section 2.5,

$$\rho \frac{DC}{Dt} = -\nabla \cdot \mathbf{q}_C$$

can be transformed to

$$\frac{DC}{Dt} = \kappa_C \nabla^2 C, \quad (20)$$

using  $\mathbf{q}_C = -k_C \nabla C$  and introducing  $\kappa_C = \frac{k_C}{\rho}$ .

## 2.7 The Boussinesq approximation

In most geophysical applications of fluid dynamics, the Boussinesq approximation is a reasonable simplification of the full equations.

Starting from an adiabatic reference state, density, pressure, temperature and composition can be separated into a reference state value (denoted by an overbar) that is only dependent on the radial level  $r$  and a fluctuating part (denoted by a prime):

$$T = \bar{T}(r) + T', \quad C = \bar{C}(r) + C', \quad \rho = \bar{\rho}(r) + \rho', \quad p = \bar{p}(r) + p' \quad (21)$$

Further on, it is assumed that the typical length scale of the system (here: the shell thickness  $d$ ) is small compared to the scale heights in the reference state. Perturbations to that state shall be small compared to the adiabat. As a result, the reference state becomes independent of position.

Whether the assumption of a negligible small superadiabaticity is valid in the context of core convection is still debated (Anufriev et al., 2005). The alternative is to model either the fully compressible equations or to use the anelastic approximation that, in contrast to the Boussinesq model, allows density stratification. Jones (2007) extensively discusses the implications of the choice of one of these approaches.

From the approximation it follows for the system of equations that

- the equation of state takes a linear form:

$$\rho' = -\bar{\rho}(\alpha_T T' + \alpha_C C'), \quad (22)$$

where  $\alpha_T$ , and  $\alpha_C$  signify the thermal and compositional expansion coefficient.

- the equation of continuity transforms to

$$\nabla \cdot \mathbf{u} = 0 \quad (\text{solenoidal character of } \mathbf{u}). \quad (23)$$

- the dissipative heating term can be neglected in the equation of momentum and internal energy (see section 2.3 and 2.5).
- the material properties such as  $\alpha_T$ ,  $\alpha_C$ ,  $\mu$ ,  $c_P$ ,  $\eta$ ,  $\kappa_T$  and  $\kappa_C$  stay constant throughout the fluid.

An important advantage of the modified equations is that sound waves are *filtered out*. This reduces the numerical costs without curtailing any relevant physical processes, since the short time scales of sound waves does not have to be resolved numerically. In the differential form, the equation of momentum (9) now reads

$$\frac{D\mathbf{u}}{Dt} = -2\boldsymbol{\Omega} \times \mathbf{u} - \nabla \left( \frac{\pi'}{\bar{\rho}} \right) + \nu \nabla^2 \mathbf{u} + \frac{1}{\mu_0 \bar{\rho}} (\nabla \times \mathbf{B}) \times \mathbf{B} + \frac{\mathbf{g}}{\bar{\rho}} \rho', \quad (24)$$

where  $\nu = \mu/\bar{\rho}$  is the new kinematic viscosity. The centrifugal potential is incorporated into the pressure fluctuation term  $\pi' = p' - \frac{\bar{\rho}\Omega^2 s^2}{2}$ , where  $s$  is the distance from the z-axis in cylindrical coordinates. The hydrostatic pressure gradient of the reference state  $\nabla \bar{p}$  is balanced by the gravity force  $\mathbf{g}\bar{\rho}$  so that only  $\rho'$  appears equation (24).

## 2.8 Boundary conditions

This section is dedicated to the boundary conditions.

For the velocity field they are chosen to be *no-slip*, e.g.  $\mathbf{u} = 0$  on the ICB ( $r = R_i$ ) and the CMB ( $r = R_0$ ), in order to be comparable to other studies. Several authors state that these *rigid* BC reflect what is realistic for the interaction between the inner, the outer core and the mantle (Christensen and Aubert, 2006; Glatzmaier and Roberts, 1995; Trümper et al., 2012). On the other hand, Zhang and Busse (1987) or Kuang and Bloxham (1997) argue that the Ekman layers which result from rigid boundaries are be negligibly thin in the Earth’s core due to its extremely small viscosity. Because today’s numerical models are forced to use a far too high viscosity, they over emphasize the effect of Ekman layers and therefore *stress-free* BC are more appropriate. For a better comparison, this work follows the approach that was used by related studies (Aubert et al., 2008; Hori et al., 2014; Olson and Christensen, 2002).

According to Trümper et al. (2012), Dirichlet type BC are chosen for the chemical component. A compositional gradient,  $\Delta C = C'_{\text{ICB}} - C'_{\text{CMB}}$ , is imposed across the shell. In a more earth-like scenario, one would apply Neumann type conditions with fixed compositional influx at the ICB and zero outflux at the CMB Braginsky and Roberts (1995). This would further increase the complexity of the model and is therefore adjourned in this case.

The mantle is assumed to be an insulator due to its rocky content (Dormy et al., 1998). The question whether the inner core should be treated as an insulator or not was discussed by Wicht (2002). He found that the effect of a conducting inner core on the flow field and the magnetic field is rather small. It is hence reasonable to chose  $\sigma = 0$  in the inner core in order not to be obliged to solve the induction equation in the full sphere. In the mantle and the core, the magnetic field  $\mathbf{B}$  is the solution to

$$\mathbf{B} = -\nabla\Phi \quad (25)$$

with  $\Phi$  being a scalar potential that follows the Laplace equation

$$\nabla^2\phi = 0. \quad (26)$$

The BC are expressed through the fact that  $\mathbf{B}$  has to match the solution of (25) at the ICB and the CMB.

The thermal BC is of the Neumann type and will be discussed in more detail in the following section.

### 2.8.1 CMB - heat flux pattern

A heat flux balance between the inner and the outer core boundary is assumed. The total influx at the ICB  $Q_i$  equals the total outflux  $Q_o$  at the CMB:

$$-Q_i = Q_o \quad (27)$$

$$\Leftrightarrow \int_{S_{\text{ICB}}} \kappa \nabla T|_{\text{ICB}} \cdot \mathbf{e}_r dS = \int_{S_{\text{CMB}}} \kappa \nabla T|_{\text{CMB}} \cdot \mathbf{e}_r dS \quad (28)$$

$$\Leftrightarrow \int_{S_{\text{ICB}}} \left. \frac{\partial T}{\partial r} \right|_{\text{ICB}} dS = \int_{S_{\text{CMB}}} \left. \frac{\partial T}{\partial r} \right|_{\text{CMB}} dS \quad (29)$$

For the spectral decomposition it is important to notice that only the 0th order spherical harmonic  $\mathcal{Y}_0^0$  yields values  $\neq 0$  when being integrated over a closed surface  $\mathcal{S}$ :

$$\int_{\mathcal{S}} \frac{\partial T}{\partial r} dS = \int_{\mathcal{S}} \left( \frac{\partial T}{\partial r} \right)_0^0 \mathcal{Y}_0^0 dS, \quad (30)$$

with  $\left( \frac{\partial T}{\partial r} \right)_0^0$  being the spectral coefficient of degree and order 0. Thus, (29) can be transformed into the spectral domain via

$$\int_{S_{\text{ICB}}} \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{ICB}} \mathcal{Y}_0^0 dS = \int_{S_{\text{CMB}}} \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{CMB}} \mathcal{Y}_0^0 dS \quad (31)$$

$$\Leftrightarrow \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{ICB}} R_i^2 = \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{CMB}} R_o^2. \quad (32)$$

This allows to formulate a simple relation between the mean radial temperature gradient at the inner and outer boundary:

$$\left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{ICB}} = \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{CMB}} \frac{R_o^2}{R_i^2} = -\beta \frac{R_o^2}{R_i^2} = -\beta \frac{1}{a^2} \quad (33)$$

with  $\beta := - \left( \frac{\partial T}{\partial r} \right)_0^0 \Big|_{\text{CMB}}$  as prescribed temperature gradient at the CMB.

Since no internal sources of heat are assumed, the stationary form of (19) takes the form of a Laplace equation. It reads

$$\nabla^2 T = 0 \quad (34)$$

and with (33) the appropriate BC are

$$\text{at the ICB: } \left. \frac{\partial T}{\partial r} \right|_{\text{ICB}} = -\beta \frac{1}{a^2} \mathcal{Y}_0^0 \quad (35)$$

$$\text{at the CMB: } \left. \frac{\partial T}{\partial r} \right|_{\text{CMB}} = -\beta \mathcal{Y}_0^0 + \text{Amp}_l^m \mathcal{Y}_l^m. \quad (36)$$

$\text{Amp}_l^m$  is the amplitude of the heat flux heterogeneity for a heat flux pattern  $\mathcal{Y}_l^m$ .

In order to implement the BC into the numerical simulation scheme, a (conductive) solution to (34) has to be found. In spherical coordinates, it reads

$$T = \sum_{l,m} [a_l^m r^l + b_l^m r^{-l-1}] \mathcal{Y}_l^m(\vartheta, \varphi) \quad (37)$$

and its radial derivative

$$\frac{\partial T}{\partial r} = \sum_{l,m} [l a_l^m r^{l-1} - (l+1) b_l^m r^{-l-2}] \mathcal{Y}_l^m(\vartheta, \varphi). \quad (38)$$

At the ICB, (35) and (38) yield

$$-b_0^0 R_i^{-2} = -\beta \frac{1}{a^2} \Rightarrow b_0^0 = \beta R_o^2 \quad (39)$$

for  $l = m = 0$  and the algebraic equation

$$l a_l^m R_i^{l-1} - (l+1) b_l^m R_i^{-l-2} = 0 \quad (40)$$

follows for all  $l > 0$  and  $m > 0$ .

For the CMB, (36) and (38) yield

$$l a_l^m R_o^{l-1} - (l+1) b_l^m R_o^{-l-2} = \text{Amp}_l^m. \quad (41)$$

Since only a heat flux pattern with  $l = m = 2$  will be used here, (40) and (41) simplify to a linear system of equations

$$\begin{pmatrix} 2R_o & -3R_o^{-4} \\ 2R_i & -3R_i^{-4} \end{pmatrix} \begin{pmatrix} a_2^2 \\ b_2^2 \end{pmatrix} = \begin{pmatrix} \text{Amp}_2^2 \\ 0 \end{pmatrix}. \quad (42)$$

Inserting  $a_2^2$ ,  $b_2^2$  and  $b_0^0$  into (37) gives a solution to (34) that respects the boundary conditions (35) and (36):

$$T_{\text{CMB}}(r, \vartheta, \varphi) = \left( a_0^0 + \frac{R_o^2 \beta}{r} \right) \mathcal{Y}_0^0 + \text{Amp}_2^2 \cdot \frac{R_o^2 2a^5 r^3 - 3R_o^2 (a-1)^5 r^2}{6D^4 (a-1)^2 (1-a^5)} \mathcal{Y}_2^2(\vartheta, \varphi) \quad (43)$$

$a_0^0$  is an arbitrary integration constant that is chosen to be 0 in the following. The conductive temperature profile with its spherically asymmetric part will be introduced into the equations in the density fluctuation part  $\rho'$  in section 2.10.

## 2.9 Nondimensional equations

A common procedure in fluid dynamics is to *rescale* the equations introduced so far in order to reduce the number of parameters and to make the relevant physical processes intuitively more accessible. The new scales are adopted from Trümper et al. (2012), they are summarized in table 1.

Variable	Symbol	Scale
Length	$\mathbf{r}$	$D = R_o - R_i$
Time	$t$	$D^2/\nu$
Velocity	$\mathbf{u}$	$\nu/D$
Temperature	$T$	$\beta D$
Composition	$C$	$\Delta C$
Pressure	$\pi$	$\bar{\rho}\nu^2/D^2$
Magnetic Field	$\mathbf{B}$	$\sqrt{\eta\Omega\mu_0\bar{\rho}}$

Table 1: Overview of the the new scales that are introduced to non-dimensionalize the magnetohydrodynamic system of equations that was introduced in the sections 2.2 to 2.7.

The application of these scales to (23), (24), (19), (20) and (17) yields a system of nondimensional equations:

$$\hat{\nabla} \cdot \hat{\mathbf{u}} = 0, \quad (44a)$$

$$\begin{aligned} \frac{D\hat{\mathbf{u}}}{D\hat{t}} = & -\hat{\nabla}\hat{\pi} - \frac{2}{\text{Ek}}\mathbf{e}_z \times \hat{\mathbf{u}} + \hat{\nabla}^2\hat{\mathbf{u}} + \frac{1}{\text{EkPr}_m} \left( \hat{\nabla} \times \hat{\mathbf{B}} \right) \times \hat{\mathbf{B}} \\ & + (\text{Ra}_T\hat{T}' + \text{Ra}_C\hat{C}')(1-a)\hat{r}\mathbf{e}_r, \end{aligned} \quad (44b)$$

$$\frac{D\hat{T}'}{D\hat{t}} = \frac{1}{\text{Pr}_T}\nabla^2\hat{T}', \quad (44c)$$

$$\frac{D\hat{C}'}{D\hat{t}} = \frac{1}{\text{Pr}_C}\nabla^2\hat{C}' \text{ and} \quad (44d)$$

$$\frac{\partial \hat{\mathbf{B}}}{\partial \hat{t}} = \hat{\nabla}(\hat{\mathbf{u}} \times \hat{\mathbf{B}}) + \frac{1}{\text{Pr}_m}\hat{\nabla}^2\hat{\mathbf{B}}. \quad (44e)$$

Nondimensional quantities are denoted by  $\hat{\cdot}$  and they are related to their dimensional counterparts via  $(\hat{\cdot}) = \text{scale}(\hat{\cdot})$ .

The following parameters of similarity appear in the equations:

$$\begin{aligned} \text{Thermal Rayleigh number :} & \quad \text{Ra}_T = \frac{\alpha_T g \beta D^4}{\nu^2} \\ \text{Compositional Rayleigh number :} & \quad \text{Ra}_C = \frac{\alpha_C g \Delta C D^3}{\nu^2} \\ \text{Ekman number :} & \quad \text{Ek} = \frac{\nu}{\Omega D^2} \\ \text{Thermal Prandtl number :} & \quad \text{Pr}_T = \frac{\nu}{\kappa_T} \end{aligned}$$

Compositional Prandtl number :

$$\text{Pr}_C = \frac{\nu}{\kappa_C}$$

Magnetic Prandtl number :

$$\text{Pr}_m = \frac{\nu}{\eta}$$

The thermal and compositional Rayleigh numbers are measures for the vigor of convection due to thermal and compositional buoyancy sources, respectively. The definitions of  $\text{Ra}_T$  and  $\text{Ra}_C$  slightly differ because of the different scales chosen for temperature and composition (see table 1). ' $\beta D$ ' and ' $\Delta C$ ' refer to either Neumann or Dirichlet type boundary conditions for  $T$  and  $C$ , respectively.

Whether a fluid is constrained rather by rotation or viscosity is described via the Ekman number.

The distinction between a thermal and a compositional Prandtl number is a key feature of this study. It allows for differences in the dynamical response of the system to either thermally or compositionally dominated convective forcing. Roughly spoken, a large Prandtl number promotes viscous effects in a fluid, whereas a small one promotes inertia effects. The magnetic Prandtl number relates viscous and magnetic diffusion and therefore decides how much kinetic energy is needed to sustain a magnetic field.

## 2.10 Conductive and convective Fluctuations

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### **3 Numerical Method**

### **4 State of research**

### **5 Thermo-chemical core convection**

#### **5.1 The temperature field**

#### **5.2 The formation of stationary vortex columns attached to mantle heterogeneities**

### **6 Thermo-chemical dynamo action**

#### **6.1 The creation of radial magnetic flux patches locked to the mantle**

#### **6.2 The influence of chemical forcing on magnetic field properties**

### **7 Summary**

### **8 Conclusion and Outlook**



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