

1st HOMEWORK
Mathematical Modeling Q Class - KM184701

**AUTOWASHER SPRING VIBRATIONS MODELING
AND ITS SIMULATION**



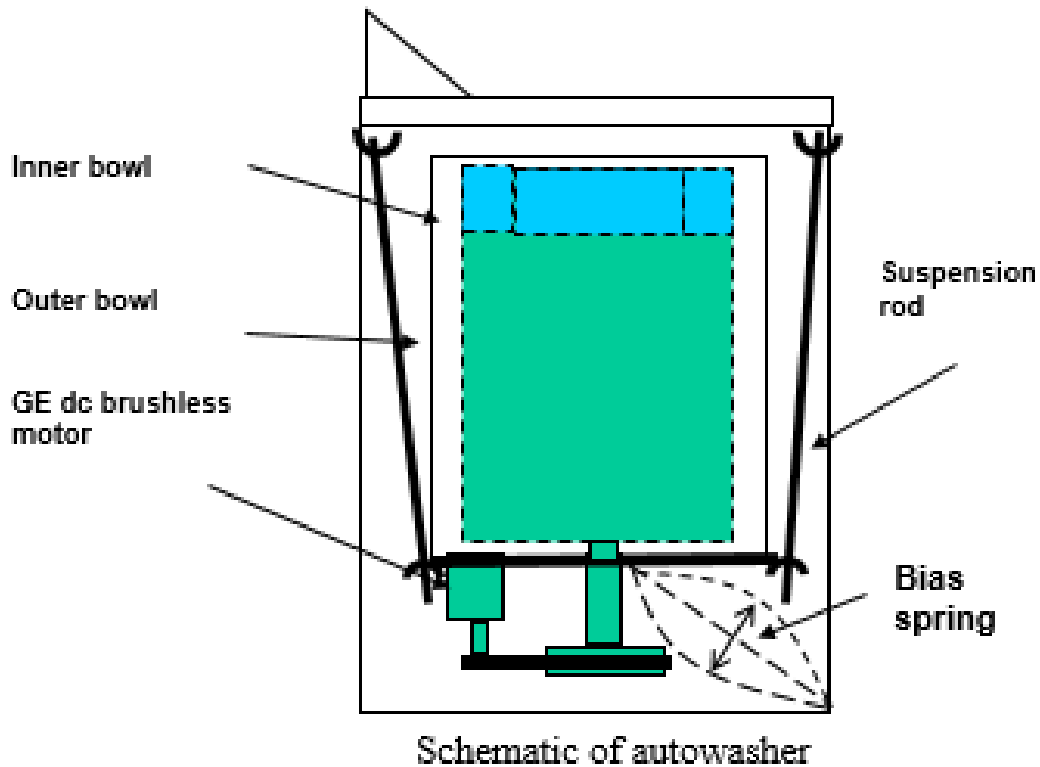
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Autowasher Spring Vibrations Problem

Bias spring resonance problems encountered during the development of the suspension for the F and P electronic autowasher "Gentle Annie" (1985). At 1100 rpm when the washing machine was in spin mode the bias spring would vibrate wildly and make contact with the pulley.



Part I

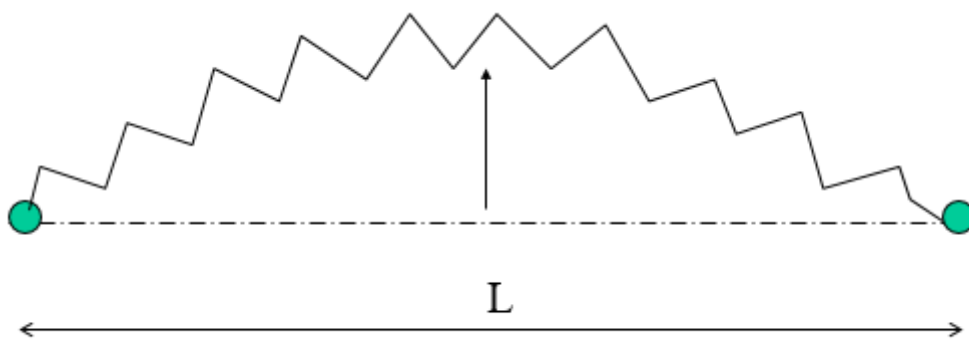
Modeling the Problem

The spring was long and slender like an elastic string. I recalled something I had learned in Engineering Mathematics II (The Predecessor of MM3):

How to derive the equation governing small transverse vibrations of an elastic string that is stretched to length L and then fixed at its endpoints.

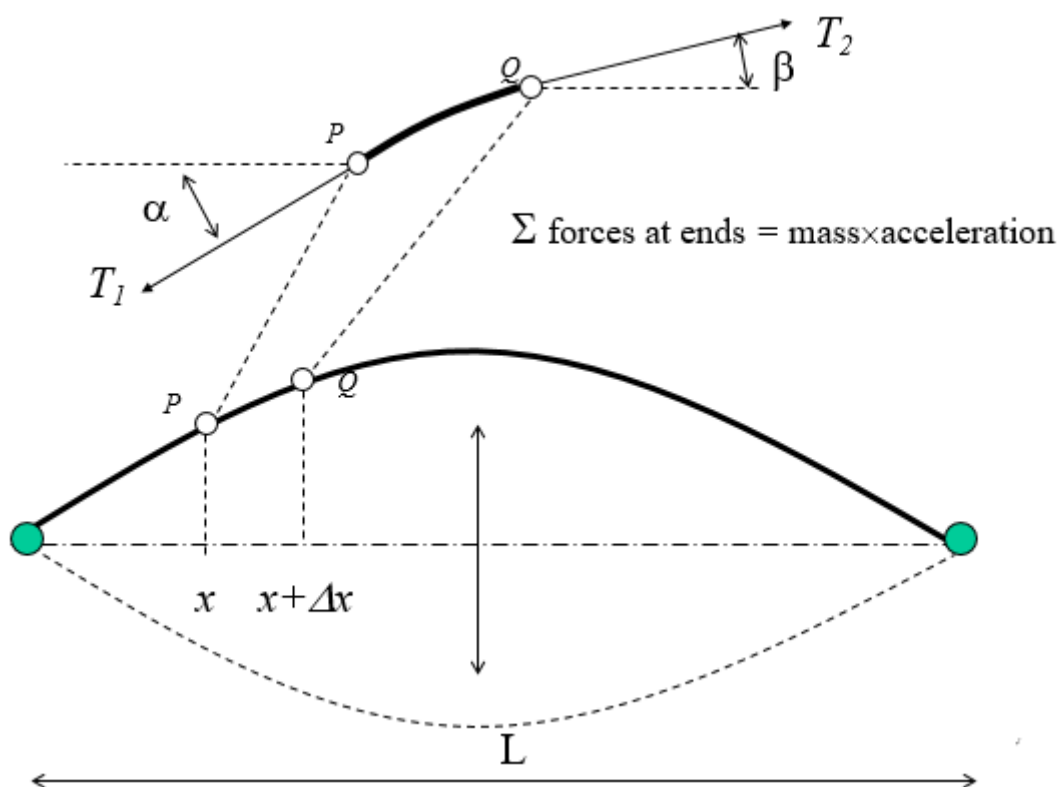
Assumption

- Mass per unit length is constant

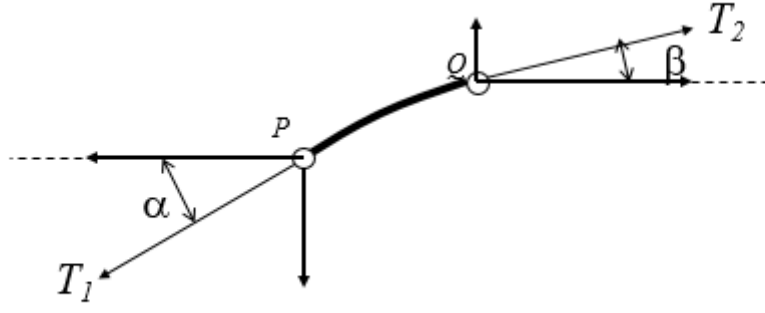


- Gravity can be neglected
- Motion is in one plane

Modelling the spring as an elastic string. Consider a "free body diagram" of a string segment :



Now consider the forces acting on this string segment. we will find the deflection $u(x, t)$ at any point x and $t > 0$.



Note: ρ = linear density of string.

Horizontal Direction :

$$T_1 \cos \alpha \approx T_2 \cos \beta \approx T \quad (1)$$

Vertical Direction :

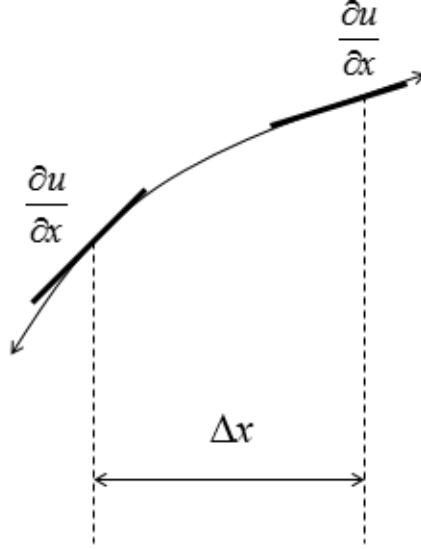
$$T_2 \sin \beta - T_1 \sin \alpha = \rho \Delta x \frac{\partial^2 u}{\partial t^2} \quad (2)$$

Divided equation (2) by equation (1) to get equation (3) :

$$\begin{aligned} \frac{T_2 \sin \beta}{T_2 \cos \beta} - \frac{T_1 \sin \alpha}{T_1 \cos \alpha} &= \rho \frac{\Delta x}{T} \Delta x \frac{\partial^2 u}{\partial t^2} \\ \tan \beta - \tan \alpha &= \rho \frac{\Delta x}{T} \Delta x \frac{\partial^2 u}{\partial t^2} \end{aligned} \quad (3)$$

Note:

- $\tan \alpha$ = string slope at x and,
- $\tan \beta$ = string slope at $x + \Delta x$



Thus

$$\tan \beta = \left[\frac{\partial u}{\partial x} \right]_{x+\Delta x}$$

and get equation (4) :

$$\tan \beta = \left[\frac{\partial u}{\partial x} \right]_x \quad (4)$$

After dividing equation (3) by $T\Delta x$, and substituting equation (4) for the tan functions, we have :

$$\left(\left[\frac{\partial u}{\partial x} \right]_{x+\Delta x} - \left[\frac{\partial u}{\partial x} \right]_x \right) \left(\frac{1}{\Delta x} \right) = \frac{\rho}{T} \frac{\partial^2 u}{\partial t^2}$$

Now let $\Delta x \rightarrow 0$

$$\frac{\left[\frac{\partial u}{\partial x} \right]_{x+\Delta x} - \left[\frac{\partial u}{\partial x} \right]_x}{\Delta x} = \frac{\rho}{T} \frac{\partial^2 u}{\partial t^2}$$

By letting $\Delta x \rightarrow 0$, we have obtained the one dimensional wave equation :

$$\frac{\partial^2 u}{\partial x^2} = \frac{\rho}{T} \frac{\partial^2 u}{\partial t^2}$$

Rearrange and set $c^2 = T/\rho$:

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2} \quad (5)$$

Part II

The Solution to Obtained The Autowasher Spring

Instead of guessing we could start looking for a solution by making the assumption that it will be some function of x multiplied by a function of t :

$$u(x, t) = X(x)T(t)$$

We obtain the solution using the method of

”Separation of Variables”

Substitute the solution $u = X(x)T(t)$ into equation (5):

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

You get :

$$X \frac{\partial^2 T}{\partial t^2} = c^2 \frac{\partial^2 X}{\partial x^2} T$$

Now separate variables (get everything that's a function of x on one side and everything that's a function of t on the other):

$$\frac{\frac{\partial^2 T}{\partial t^2}}{c^2 T} = \frac{\frac{\partial^2 X}{\partial x^2}}{X}$$

Both sides are equal to a constant. Call it k :

$$\frac{\frac{\partial^2 T}{\partial t^2}}{c^2 T} = \frac{\frac{\partial^2 X}{\partial x^2}}{X} = k$$

We get the two equations :

Time (t) only

$$\frac{d^2 T}{dt^2} - k c^2 T = 0$$

Distance (x) only

$$\frac{d^2 X}{dx^2} - k X = 0$$

Choose a sign for the constant that will give you sensible results.

k should be negative

$$k = -\lambda^2$$

you now get 2 differential equations :

$$\frac{d^2 T}{dt^2} - \lambda^2 c^2 T = 0 \quad \frac{d^2 X}{dx^2} + \lambda^2 X = 0 \quad (6)$$

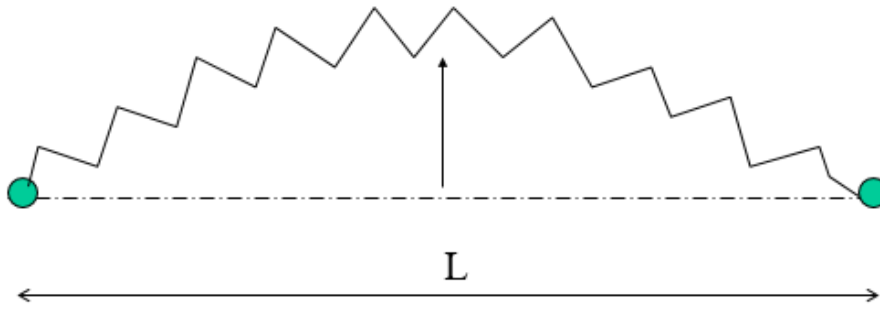
Solutions to T and X are:

$$T = A \sin(\lambda ct) + B \cos(\lambda ct) \quad X = C \sin(\lambda x) + D \cos(\lambda x) \quad (7)$$

The solution for $u(x,t)$ equals X times T :

$$u(x, t) = (A \sin(\lambda x) + B \cos(\lambda x))(C \sin(c\lambda t) + D \cos(c\lambda t)) \quad (8)$$

Boundary Conditions :



At $x = 0, u(0, t) = 0$

$$u(0, t) = X(0)T(t) = B(C \sin(c\lambda t) + D \cos(c\lambda t)) = 0$$

Thus $B = 0$

At $x = L, u(L, t) = 0$

$$u(L, t) = X(L)T(t) = A \sin(\lambda L)(C \sin(c\lambda t) + D \cos(c\lambda t)) = 0$$

So

$$\sin(\lambda L) = 0$$

or $\lambda L = n\pi$, where $n = 0, 1, 2, 3, \dots$

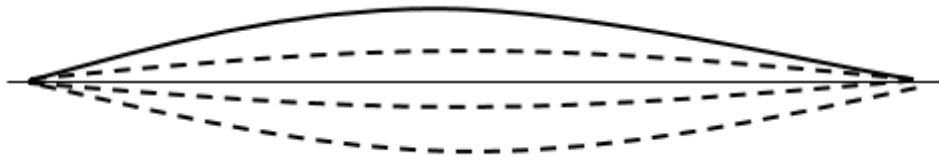
So

$$u_n(x, t) = A_n \sin\left(\frac{n\pi x}{L}\right) \left[C_n \sin\left(\frac{n\pi ct}{L}\right) + D_n \cos\left(\frac{n\pi ct}{L}\right) \right]$$

or

$$u_n(x, t) = \sin\left(\frac{n\pi x}{L}\right) \left[a_n \sin\left(\frac{n\pi ct}{L}\right) + b_n \cos\left(\frac{n\pi ct}{L}\right) \right] \quad (9)$$

$n = 1, 2, 3, \dots$ Note $n = 0$ gives $u_0 = 0$



$$u_1(x, t)$$

"1st Spring Mode"

$$u_1(x, t) = \sin\left(\frac{\pi}{L}\right) \left[a_1 \sin\left(\frac{\pi ct}{L}\right) + b_1 \cos\left(\frac{\pi ct}{L}\right) \right]$$

Part III

MATLAB Simulation