```
2
3
   * Seven-segment display library for AVR-GCC.
4
   * ATmega328P (Arduino Uno), 16 MHz, AVR 8-bit Toolchain 3.6.2
5
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8
9
   10
11
12 /* Includes ------*/
13 #define F CPU 16000000
14 #include <util/delay.h>
15 #include "gpio.h"
16 #include "segment.h"
17
18 /* Variables ------*/
19 // Active-low digit 0 to 9
20 uint8_t segment_value[] = {
21
     // abcdefgDP
                // Digit 0
22
      0b00000011,
                  // Digit 1
23
      0b10011111,
                // Digit 2
24
     0b00100101,
25
     0b00001101,
                  // Digit 3
26
                  // Digit 4
     0b10011001,
                  // Digit 5
27
     0b01001001,
     0b01000001,
                  // Digit 6
28
               // Digit 7
29
     0b00011111,
                  // Digit 8
30
      0b00000001,
31
      0b00001001
                  // Digit 9
32 };
33
34 // Active-high position 0 to 3
35 uint8_t segment_position[] = {
36
     // p3p2p1p0....
37
      0b00010000,
                  // Position 0
               // Position 1
// Position 2
38
      0b00100000,
39
      0b01000000,
40
      0b10000000
                  // Position 3
41 };
42
43
44 /* Function definitions -----*/
45 void SEG_init(void)
46 {
      /* Configuration of SSD signals */
47
48
      GPIO_config_output(&DDRD, SEGMENT_LATCH);
      GPIO config output(&DDRD, SEGMENT CLK);
49
50
      GPIO_config_output(&DDRB, SEGMENT_DATA);
51 }
52
53 /*-----*/
```

```
54 void SEG update shift regs(uint8 t segments, uint8 t position)
55 {
 56
        uint8 t bit number;
 57
        segments = segment_value[segments];
                                                 // 0, 1, ..., 9
 58
        position = segment_position[position]; // 0, 1, 2, 3
 59
 60
        // Pull LATCH, CLK, and DATA low
        GPIO write low(&PORTD, SEGMENT LATCH);
 61
        GPIO_write_low(&PORTD, SEGMENT_CLK);
 62
        GPIO_write_low(&PORTB, SEGMENT_DATA);
 63
 64
        // Wait 1 us
 65
 66
        _delay_us(1);
 67
 68
        // Loop through the 1st byte (segments)
 69
        // a b c d e f g DP (active low values)
 70
        for (bit_number = 0; bit_number < 8; bit_number++)</pre>
 71
             // Output DATA value (bit 0 of "segments")
 72
 73
             if ((segments & 1) == 0)
                 GPIO_write_low(&PORTB, SEGMENT_DATA);
 74
 75
             else
 76
                 GPIO_write_high(&PORTB, SEGMENT_DATA);
 77
 78
             // Wait 1 us
 79
            _delay_us(1);
 80
            // Pull CLK high
 81
 82
            GPIO_write_high(&PORTD, SEGMENT_CLK);
 83
 84
             // Wait 1 us
 85
            _delay_us(1);
 86
 87
             // Pull CLK low
 88
            GPIO_write_low(&PORTD, SEGMENT_CLK);
 89
             // Shift "segments"
 90
 91
             segments = segments >> 1;
 92
        }
 93
 94
        // Loop through the 2nd byte (position)
 95
        // p3 p2 p1 p0 . . . (active high values)
        for (bit_number = 0; bit_number < 8; bit_number++)</pre>
 96
 97
 98
             // Output DATA value (bit 0 of "position")
             if ((position % 2) == 0)
 99
100
                 GPIO_write_low(&PORTB, SEGMENT_DATA);
101
             else
                 GPIO write high(&PORTB, SEGMENT DATA);
102
103
104
           // Wait 1 us
105
           _delay_us(1);
106
```

```
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107
           // Pull CLK high
108
           GPIO_write_high(&PORTD, SEGMENT_CLK);
109
110
           // Wait 1 us
           _delay_us(1);
111
112
113
           // Pull CLK low
           GPIO_write_low(&PORTD, SEGMENT_CLK);
114
115
116
            // Shift "position"
117
            position = position >> 1;
118
        }
119
        // Pull LATCH high
120
121
        GPIO_write_high(&PORTD, SEGMENT_LATCH);
122
        // Wait 1 us
123
124
        _delay_us(1);
125 }
126
127 /*-----
                        */
128 /* SEG clear */
129 void SEG_clear(void)
130 {
131
        uint8 t bit number, segments = 0b11111111, position = 0;
132
        // Pull LATCH, CLK, and DATA low
133
134
        GPIO_write_low(&PORTD, SEGMENT_LATCH);
135
        GPIO_write_low(&PORTD, SEGMENT_CLK);
        GPIO_write_low(&PORTB, SEGMENT_DATA);
136
137
138
        // Wait 1 us
139
        _delay_us(1);
140
141
        // Loop through the 1st byte (segments)
142
        // a b c d e f g DP (active low values)
143
        for (bit_number = 0; bit_number < 8; bit_number++)</pre>
144
145
            // Output DATA value (bit 0 of "segments")
146
            if ((segments & 1) == 0)
                GPIO_write_low(&PORTB, SEGMENT_DATA);
147
148
            else
                GPIO write high(&PORTB, SEGMENT DATA);
149
150
151
            // Wait 1 us
152
            _delay_us(1);
153
154
            // Pull CLK high
            GPIO write high(&PORTD, SEGMENT CLK);
155
156
157
            // Wait 1 us
```

158

159

_delay_us(1);

```
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```
160
             // Pull CLK low
161
             GPIO_write_low(&PORTD, SEGMENT_CLK);
162
             // Shift "segments"
163
164
             segments = segments >> 1;
165
        }
166
        // Loop through the 2nd byte (position)
167
        // p3 p2 p1 p0 . . . (active high values)
168
169
        for (bit_number = 0; bit_number < 8; bit_number++)</pre>
170
             // Output DATA value (bit 0 of "position")
171
172
             if ((position % 2) == 0)
                 GPIO write low(&PORTB, SEGMENT DATA);
173
174
             else
175
                 GPIO_write_high(&PORTB, SEGMENT_DATA);
176
177
            // Wait 1 us
178
            _delay_us(1);
179
            // Pull CLK high
180
            GPIO_write_high(&PORTD, SEGMENT_CLK);
181
182
            // Wait 1 us
183
184
            _delay_us(1);
185
186
            // Pull CLK low
            GPIO_write_low(&PORTD, SEGMENT_CLK);
187
188
             // Shift "position"
189
190
             position = position >> 1;
191
        }
192
193
        // Pull LATCH high
194
        GPIO_write_high(&PORTD, SEGMENT_LATCH);
195
196
        // Wait 1 us
197
        _delay_us(1);
198
199 }
200
201 /*-----
202 /* SEG clk 2us */
203 void SEG_clk_2us(void)
204 {
205
        // Wait 1 us
206
        _delay_us(1);
207
        // Pull CLK high
208
209
        GPIO_write_high(&PORTD, SEGMENT_CLK);
210
        // Wait 1 us
211
212
        _delay_us(1);
```

```
213
214 // Pull CLK low
215 GPIO_write_low(&PORTD, SEGMENT_CLK);
216 }
```