

## КУРСОВАЯ РАБОТА

Вариант  
по дисциплине «Вычислительная математика»

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## 1.Текст программы

```
#include <fstream>
#include "fmin.h"
#include <math.h>
#include <iomanip>
#include <iostream>
#include <fstream>
#include "quanc8.h"
#include "rkf45.h"
using namespace std;
#define ndim 40
#define M_PI 3.16159265358979323846
#define INDX(i, j) (i) * ndim + (j)
double func(double x)
{
    return x*x - tan(M_PI*x/3);
}
double intFunc(double x) {
    return pow(x - pow(x,3), 0.5);
}
void MyFunc(float t, float *y, float *dy)
{
    double ti;
    double errest, flag;
    int col;
    quanc8(intFunc, 0, 0.5, 0.0001, 0.0001, &ti, &errest, &col, &flag);
    ti *= 0.4493982;

    double omega0;
    double Error;
    double TOL=1e-6;
    int flagMin;
    omega0 = 1.142206 * fmin(0, 10, func, TOL, Error, flagMin);
    double mu = 0.1;
    dy[0]=(y[1]*y[1]-y[0])/ti;
    dy[1]=y[2];
    dy[2]=2*mu*(dy[1] - (y[0]*dy[1] + y[1]*dy[0])) - pow(omega0, 2)*y[1];
    return;
}
int main ()
{
    ofstream out("out.txt");
    double A, B, C;
    double m[ndim * ndim];
    double cond;
    int ipvt[3];
    int workFlag;
    double b[3] = {50, -30, -35};
    m[INDX(0,0)] = 46; m[INDX(0,1)] = -24; m[INDX(0,2)] = -42;
    m[INDX(1,0)] = -24; m[INDX(1,1)] = 16; m[INDX(1,2)] = 18;
    m[INDX(2,0)] = -42; m[INDX(2,1)] = 18; m[INDX(2,2)] = 49;
    decomp(3, ndim, m, &cond, ipvt, &workFlag);
    solve(3, ndim, m, b, ipvt);
    A = b[0]; B = b[1]; C = b[2];

    double T = 10;
    float y[3];
    y[0] = C; y[1] = A; y[2] = B;
    float RE = 1e-6;
    float AE = 1e-6;
    int iflag = 1;
    int iwork[ 50 ];
    float work[ 50 ];
    float t = 0, tout = 0;
```

```

for (tout =0; tout <= T; tout+=0.2) {
    RKF45(MyFunc, 3, y, &t, &tout, &RE, &AE, &iflag, work, iwork);
    cout << "t = " << t << " z = " << y[0] <<
        " V = " << y[1] << " V' = " << y[2] << " flag = " << iflag << endl; }

return 0;
}

```

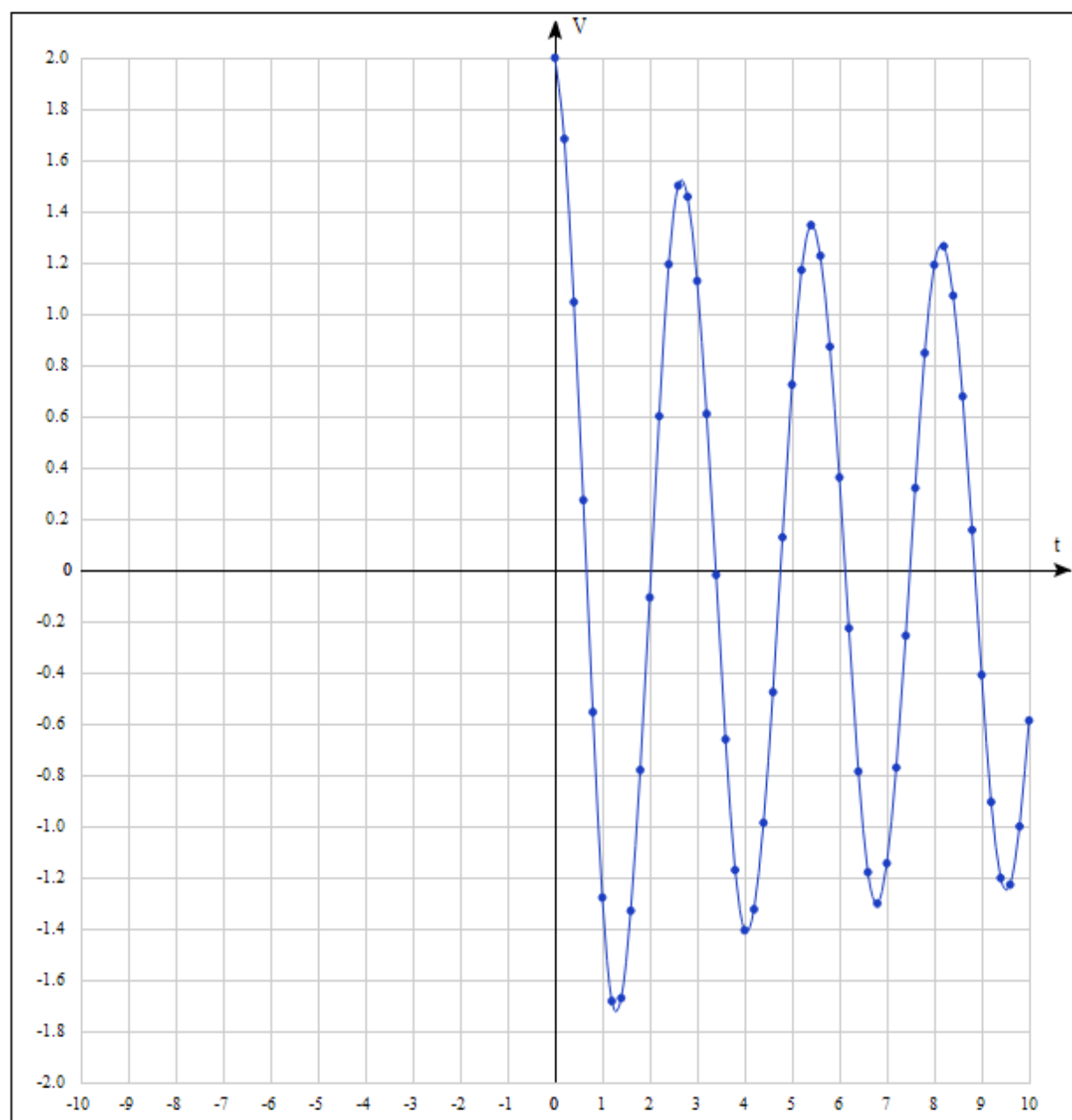
## 2.Результаты тестирования

```

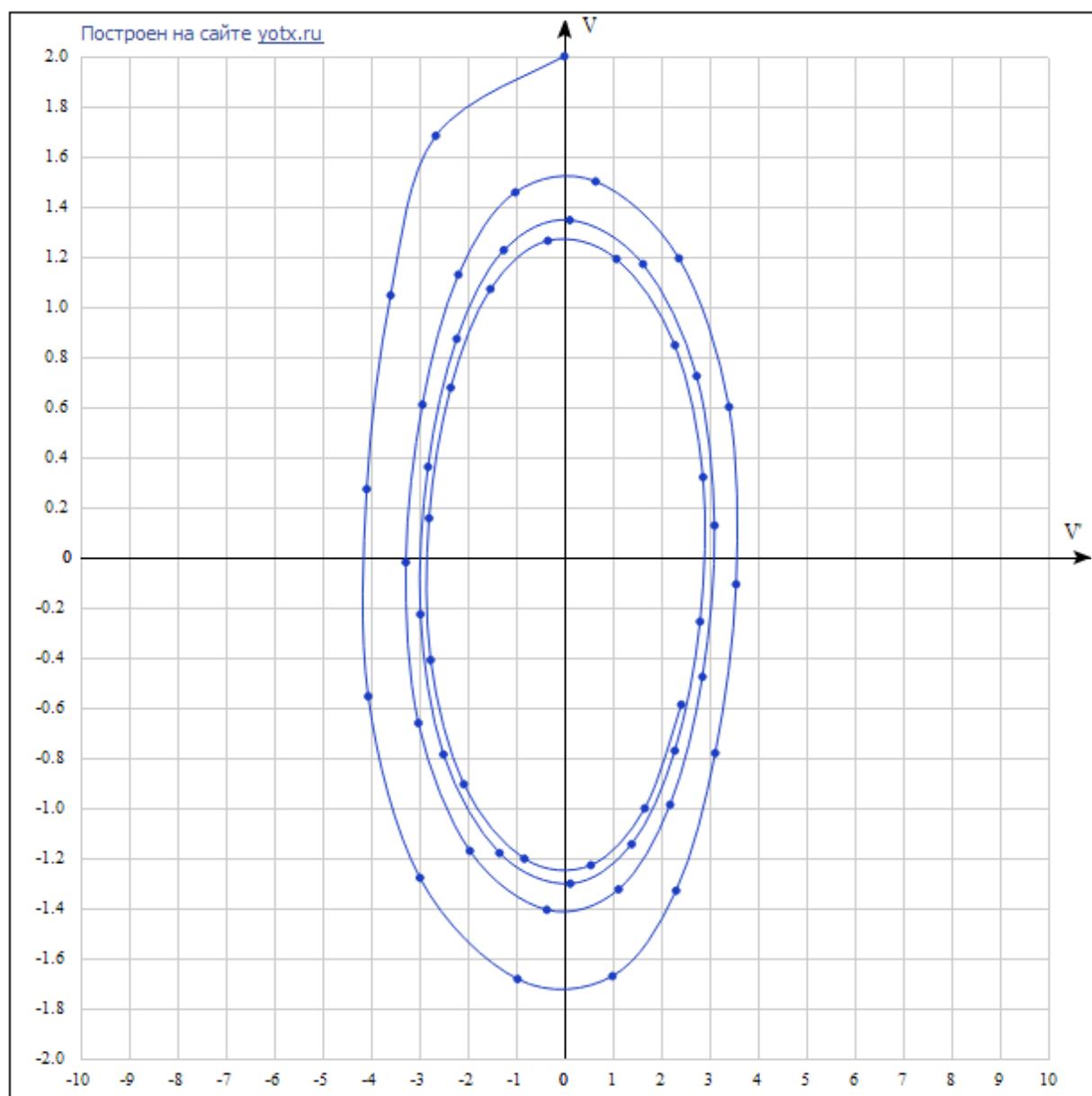
t = 0 z = 1 U = 2 U' = -2.26979e-015 flag = 2
t = 0.2 z = 3.04244 U = 1.68295 U' = -2.65804 flag = 2
t = 0.4 z = 1.8509 U = 1.04616 U' = -3.59121 flag = 2
t = 0.6 z = 0.544467 U = 0.272828 U' = -4.0865 flag = 2
t = 0.8 z = 0.178156 U = -0.554352 U' = -4.05494 flag = 2
t = 1 z = 1.00294 U = -1.2786 U' = -2.98626 flag = 2
t = 1.2 z = 2.29258 U = -1.68273 U' = -0.968415 flag = 2
t = 1.4 z = 2.82625 U = -1.6711 U' = 0.994559 flag = 2
t = 1.6 z = 2.25202 U = -1.3301 U' = 2.30898 flag = 2
t = 1.8 z = 1.15716 U = -0.780949 U' = 3.11808 flag = 2
t = 2 z = 0.28713 U = -0.107156 U' = 3.55011 flag = 2
t = 2.2 z = 0.181053 U = 0.600907 U' = 3.40325 flag = 2
t = 2.4 z = 0.921285 U = 1.19359 U' = 2.36744 flag = 2
t = 2.6 z = 1.87938 U = 1.50055 U' = 0.646103 flag = 2
t = 2.8 z = 2.19504 U = 1.45723 U' = -1.01352 flag = 2
t = 3 z = 1.67598 U = 1.12858 U' = -2.19002 flag = 2
t = 3.2 z = 0.796054 U = 0.609865 U' = -2.9343 flag = 2
t = 3.4 z = 0.167012 U = -0.019015 U' = -3.27726 flag = 2
t = 3.6 z = 0.218254 U = -0.66098 U' = -3.01752 flag = 2
t = 3.8 z = 0.931933 U = -1.17116 U' = -1.95373 flag = 2
t = 4 z = 1.70672 U = -1.40635 U' = -0.36368 flag = 2
t = 4.2 z = 1.86847 U = -1.32464 U' = 1.12123 flag = 2
t = 4.4 z = 1.34338 U = -0.986747 U' = 2.18573 flag = 2
t = 4.6 z = 0.576817 U = -0.476548 U' = 2.85423 flag = 2
t = 4.8 z = 0.106158 U = 0.127545 U' = 3.10423 flag = 2
t = 5 z = 0.273849 U = 0.723769 U' = 2.73513 flag = 2
t = 5.2 z = 0.975125 U = 1.17102 U' = 1.6259 flag = 2
t = 5.4 z = 1.61776 U = 1.34646 U' = 0.1111 flag = 2
t = 5.6 z = 1.65666 U = 1.22651 U' = -1.25248 flag = 2
t = 5.8 z = 1.11229 U = 0.872156 U' = -2.22501 flag = 2
t = 6 z = 0.424302 U = 0.361493 U' = -2.81906 flag = 2
t = 6.2 z = 0.0787037 U = -0.226714 U' = -2.97571 flag = 2
t = 6.4 z = 0.342399 U = -0.786316 U' = -2.49951 flag = 2
t = 6.6 z = 1.03253 U = -1.1798 U' = -1.3403 flag = 2
t = 6.8 z = 1.56391 U = -1.30194 U' = 0.121837 flag = 2
t = 7 z = 1.49744 U = -1.14491 U' = 1.39016 flag = 2
t = 7.2 z = 0.932894 U = -0.771322 U' = 2.28317 flag = 2
t = 7.4 z = 0.310695 U = -0.256142 U' = 2.80444 flag = 2
t = 7.6 z = 0.0747609 U = 0.320165 U' = 2.86667 flag = 2
t = 7.8 z = 0.421106 U = 0.847154 U' = 2.28516 flag = 2
t = 8 z = 1.09551 U = 1.19137 U' = 1.07749 flag = 2
t = 8.2 z = 1.52437 U = 1.26408 U' = -0.340771 flag = 2
t = 8.4 z = 1.36436 U = 1.07135 U' = -1.52784 flag = 2
t = 8.6 z = 0.783611 U = 0.677609 U' = -2.34903 flag = 2
t = 8.8 z = 0.223854 U = 0.156253 U' = -2.79786 flag = 2
t = 9 z = 0.0898094 U = -0.409553 U' = -2.76372 flag = 2
t = 9.2 z = 0.507817 U = -0.905257 U' = -2.079 flag = 2
t = 9.4 z = 1.15875 U = -1.20239 U' = -0.827983 flag = 2
t = 9.6 z = 1.48855 U = -1.22828 U' = 0.548617 flag = 2
t = 9.8 z = 1.24457 U = -1.00127 U' = 1.66252 flag = 2
t = 10 z = 0.654104 U = -0.58741 U' = 2.41653 flag = 2

```

График зависимости  $V$  от  $t$



## График зависимости $V$ от $V'$



### 3.Выводы

По результатам данной курсовой работы были построены графики зависимости  $V$  от  $t$  и  $V$  от  $V'$ .

Погрешность  $\omega_{\text{max}}$ , через подпрограмму QUANC8 составляет 7 знаков после запятой. Погрешность  $x^*$ , через нахождения наименьшего положительного корня функции, составляет 6 знаков после запятой. Из этого следует, что эти погрешности не влияют на конечный результат, так как относительная и абсолютная погрешность подпрограммы RKF45, которая непосредственно решает систему уравнений, дают точность в 6 и 7 знаков соответственно.