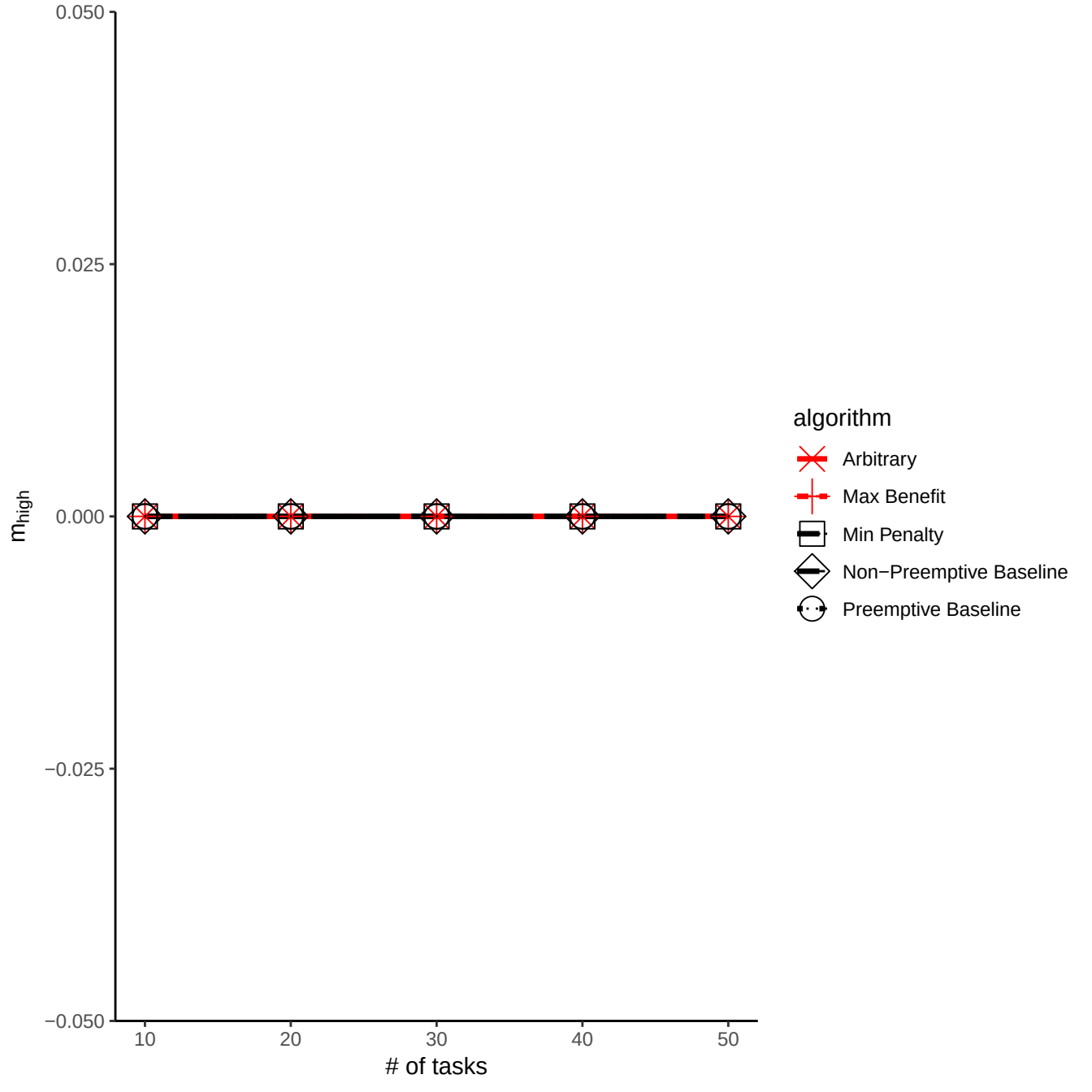
0.050
0.025
0.000
−0.025
−0.050
m_{high}
10
20
30
40
50
# of tasks
algorithm
Arbitrary
Max Benefit
Min Penalty
Non−Preemptive Baseline
Preemptive Baseline