# **Operating Systems Assignment-2**

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## Introduction

The prescribed undertaking entailed the conception and realization of a Character Device Driver replete with specified functionalities. This comprehensive report meticulously expounds upon the chosen methodology, provides an in-depth elucidation of the underlying concepts, delves into the intricacies of the implementation process, and outlines the resulting outcomes of the assignment.

## **Problem Statement**

The aim was to fabricate a character device driver capable of receiving parameters (specifically, kernel\_version and time) upon insertion. Successful insertion hinged upon a congruent kernel version, and upon achievement, the major number, minor number, and timer value were mandated to be displayed. Furthermore, the driver was designed to execute designated tasks in a predetermined sequence prior to removal (rmmod), encompassing actions such as reading from the device and capturing the username.

## Methodology

The development process adhered to a meticulously structured approach:

- 1. Verified kernel version compatibility by leveraging the KERNEL\_VERSION macro.
- Dynamically allocated a device number through the utilization of alloc\_chrdev\_region and subsequently registered it.
- 3. Established a device class and device using the functions class\_create and device create.
- 4. Initialized a cdev struct and seamlessly incorporated it through the <a href="cdev\_add">cdev\_add</a> mechanism.
- Implemented essential file operations, encompassing open, release, read, and write functionalities.

- 6. Employed kernel memory allocation (kmalloc) for the creation of a driver-specific buffer.
- 7. Utilized a wait queue (wait\_queue\_head\_t) for effective synchronization.
- 8. Devised and implemented a kernel thread via kthread\_create to manage and respond to wait events.
- 9. Employed a timer to facilitate the handling of time-related actions in a timely manner.

## **Explanation**

#### **Kernel Version Validation**

- Objective: Ensuring seamless compatibility between the driver and the operational kernel is pivotal for the sustained stability and optimal functionality of the system.
- Implementation: The utilization of the KERNEL\_VERSION macro serves as a robust mechanism for dynamically comparing the module's version with the kernel version at runtime.
- Significance: Discrepancies in versioning may precipitate unpredictable behavior or, in extreme cases, system crashes.

#### **Device Initialization Process**

- Objective: The allocation and registration of a distinctive device number stand as fundamental prerequisites for the identification and efficient management of devices within the system.
- Implementation: The dynamic acquisition of a device number is orchestrated through the judicious application of the alloc\_chrdev\_region function.
- Significance: The device number, comprising both major and minor identifiers, plays a pivotal role in facilitating the systematic management of multiple devices.

### **Cdev Initialization and Integration**

 Objective: The intrinsic representation of the character device via the cdev structure necessitates seamless integration for effective system acknowledgment.

- Implementation: The initiation of the cdev structure is accomplished through the cdev\_init function, followed by the subsequent integration into the kernel using cdev\_add.
- Consequence of Failure: An unsuccessful addition jeopardizes the recognition of the driver by the system.

### **Kernel Memory Allocation Protocol**

- Objective: The allocation of kernel memory serves as a critical cornerstone in providing a secure and controlled environment for the driver's operations.
- Implementation: The allocation of memory is achieved through the judicious use of the kmalloc function, with the driver's core functionality intricately intertwined with this allocated memory space.
- Potential Pitfalls: Failures in memory allocation may precipitate undefined behavior or result in the malfunctioning of the driver.

#### **Wait Queue and Thread Orchestration**

- Objective: The seamless synchronization between read and write operations is orchestrated through the strategic utilization of a wait queue and the initiation of a dedicated kernel thread.
- Implementation: The initiation of the wait queue is accomplished using init\_waitqueue\_head, complemented by the creation of a kernel thread via kthread create.
- Thread's Role: The kernel thread actively manages events arising from both read and write operations, ensuring a harmonious synchronization.

#### **Timer Configuration Framework**

- Objective: The strategic deployment of a timer proves instrumental in executing time-sensitive tasks, thereby guaranteeing the timely execution of specific actions.
- Implementation: The timer\_setup function stands as the linchpin for initializing the timer, while mod\_timer dictates the specified expiration time.
- Temporal Significance: The prescribed time intervals play a critical role in ensuring the completion of designated actions within the stipulated timeframe.

### **Sequential Execution Blueprint**

- Rationale: The meticulously structured sequence of actions post-insertion is designed to rigorously evaluate the driver's functionality and its prowess in synchronization.
- Temporal Sensitivity: The adherence to the specified timeframes is paramount, as the actions must be seamlessly executed within the stipulated durations to meet the assignment's stringent requirements.

### Handling 'rmmod' Protocol

- Logic: Upon removal, the driver diligently scrutinizes whether the prescribed actions were diligently completed within the allocated timeframe.
- Outcome Determination: The success or failure of the removal process hinges on the completion status and the meticulous adherence to the preordained sequential order.

#### **Outcome Showcase**

- Scenario of Success:
  - Insertion: insmod mymodule.ko kernel version=6,5 timer=30

Transition to superuser mode after running make

```
Activities Terminal Nov121755

wenkatasai24 // ~/OS >> make

make -C /lib/modules/6.5.9-100.fc37.x86_64/build M=/home/venkatasai24/OS modules
make[1]: Entering directory '/usr/src/kernels/6.5.9-100.fc37.x86_64'

CC [M] /home/venkatasai24/OS/file.o
MODPOST /home/venkatasai24/OS/file.o
MODPOST /home/venkatasai24/OS/file.o
LD [M] /home/venkatasai24/OS/file.ko
BTF [M] /home/venkatasai24/OS/file.ko
Skipping BTF generation for /home/venkatasai24/OS/file.ko
Skipping BTF generation for /home/venkatasai24/OS/file.ko
Skipping at f generation f gene
```

- Post-compilation: dmesg Output
- Successful execution of device read (cat /dev/cdd\_device) and write (echo "username" >/dev/cdd\_device).
- Removal (rmmod mymodule) displaying "Successfully completed the actions within time" in dmesg.

#### Unsuccessful Scenario:

Insertion with an incompatible kernel version

```
Activites Terminal New12 17:58

Revit venkatassi24 // ~/05 >> make
make -c /\in\/modules/6.5.9-100.fc37.x86_64/build M=/home/venkatasai24/05 modules
make[1]: Entering directory '/usr/src/kernels/6.5.9-100.fc37.x86_64'
make[1]: Leaving directory '/usr/src/kernels/6.5.9-100.fc37.x86_64'
venkatasai24 // ~/05 >> su
Password:
[root@localhost OS]# insmod file.ko kernel_version=5,4 time=30
insmod: ERROR: could not insert module file.ko: Operation not permitted
[root@localhost OS]# dmesg|tail -1
[ 5659.579976] Not compatible with this Kernel Version
[root@localhost OS]# exit
exit
```

Expiration of the timer

```
Venkatasai24 // ~/OS >> su

Password:
[rootelocalhost OS]# insmod file.ko kernel_version=6,5 time=10
[rootelocalhost OS]# cat /dev/cdd_device

Default
[rootelocalhost OS]# echo "$USER " > /dev/cdd_device
[rootelocalhost OS]# rmmodfile

bash: rmmodfile: command not found...
[rootelocalhost OS]# rmmod file
[rootelocalhost OS]# memod file
[rootelocalhost OS]# memod file
[rootelocalhost OS]# desey | tail -23
[ 5551.211256] Kernel Module Removed Successfully...
[ 5650.579976] Not compatible with this Kernel Version
[ 5692.884023] Kernel Module Inserted Successfully...
[ 5692.884023] Major No. is 507

Minor Number is 0

Timer Span is 10 secs
[ 5692.884631] Timer Started
[ 5692.884727] Creating a Thread on wait function
[ 5692.884727] Tread Created successfully
[ 5692.884737] Waiting For Event...
```

- Attempted write operation before reading
- Multiple occurrences of both reads and writes

```
Authories | Terminal | Nev121756 | Nev1217
```

## Conclusion

In response to the specified problem statements, a character device driver has been developed with meticulous attention to detail. The design and implementation process focused on meeting the outlined requirements, ensuring seamless integration into the existing system. Through careful consideration of best practices, the driver not only fulfills the explicit criteria but also emphasizes efficiency, reliability, and maintainability. This development represents a commitment to delivering solutions that not only meet expectations but also demonstrate a dedication to excellence in software craftsmanship.