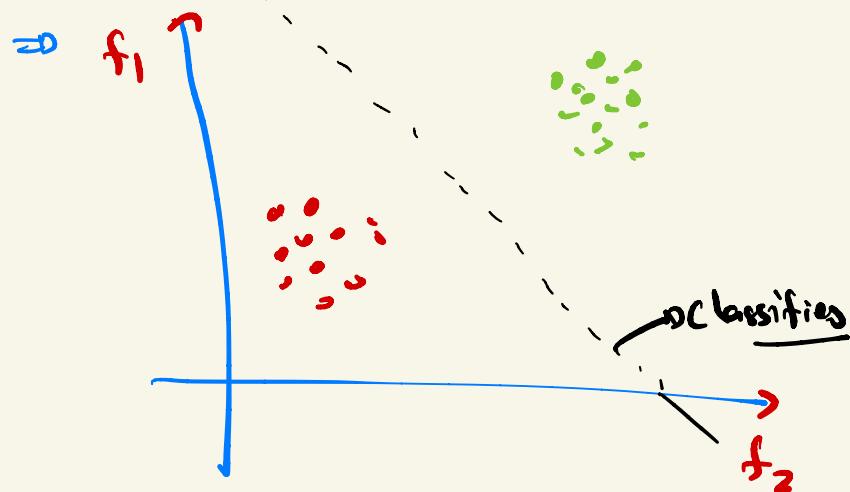
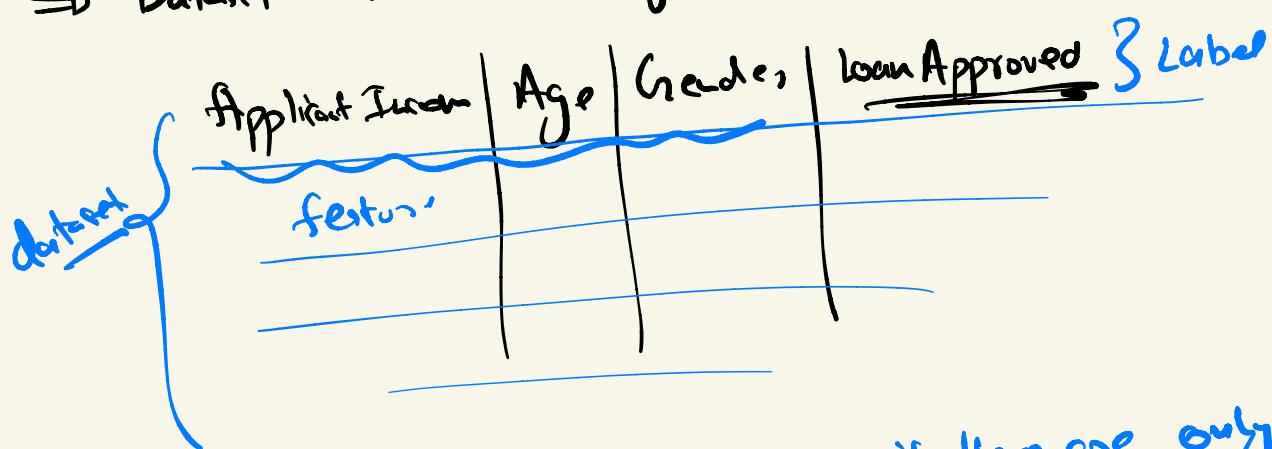



Practice Problems

ReCap →

⇒ Dataset Feature Target / Label

→ line → Explanation



if there are only 2 features

All axis → feature
color → target

⇒ easiest classifier → line

$$y = mx + c$$

Slope y-intercept

[works only in 2D]

$$\omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0$$

Parameters

$\Rightarrow \underline{\text{Vector}} \rightarrow \hat{x} = [x_1 \ x_2 \ x_3 \ \dots \ x_d]$

Length of vector \rightarrow Magnitude $\rightarrow \sqrt{x_1^2 + x_2^2 + \dots + x_d^2}$
 $\|x\|$

L1 Norm = $|x_1| + |x_2| + |x_3| + \dots$

L2 Norm = $\|x\|_2 = \sqrt{x_1^2 + x_2^2 + \dots}$

\Rightarrow Vector $\rightarrow x \rightarrow [x_1 \ x_2 \ x_3]$

$y \rightarrow [y_1 \ y_2 \ y_3]$

dot product $x^T y = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \begin{bmatrix} y_1 & y_2 & y_3 \end{bmatrix}$

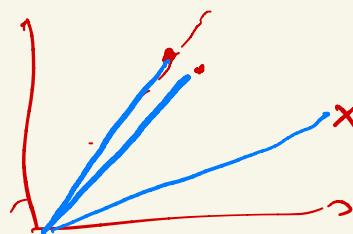
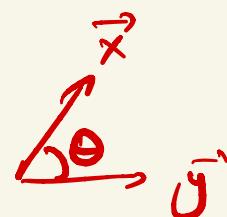
$$\underline{\omega_1 x_1 + \omega_2 x_2 + \omega_0 = 0}$$

$$[\omega_1 \ \omega_2] \quad [x_1 \ x_2]$$

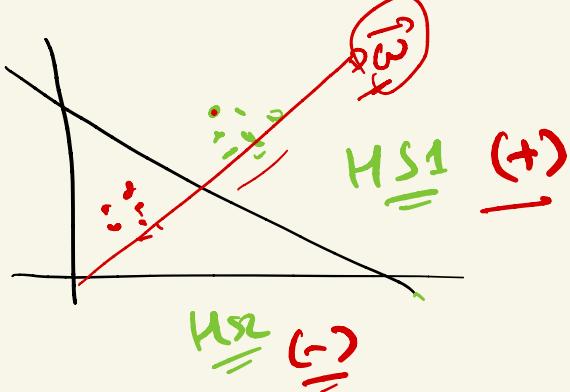
$$\boxed{\omega^T x + \omega_0 = 0} \Leftrightarrow$$

\Rightarrow What if we only care about

$$\underline{\cos \theta = \frac{x^T y}{\|x\| \|y\|}}$$



\Rightarrow Half Spaces \rightarrow



$\Rightarrow \vec{\omega}$ are perpendicular to decision boundary.

dist b/w a point and a line \Rightarrow

$$d = \frac{\omega^T x + \omega_0}{\|\omega\|}$$

Weight $\rightarrow [\omega_1, \omega_2]$

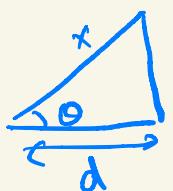
dist b/w origin and a line \rightarrow

\Rightarrow Projection of x in y direction



projection of x in
J direction

$$\frac{x^T y}{\|y\|} = x^T \hat{y}$$



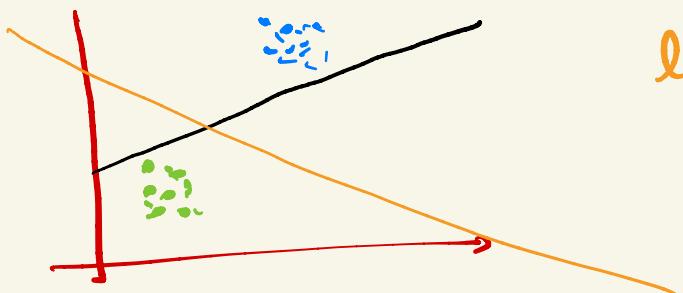
$$\frac{d}{x} = \cos\theta = \frac{x^T y}{\|y\|}$$

best
classification

\Rightarrow end goal of any ml algorithm to identify

$$\omega^T x + \omega_0 = 0$$

best classifier weight vector



line with maximum total distance
from all the points

$$d = \frac{\omega^T x + \omega_0}{\|\omega\|}$$

+ve \rightarrow +ve MS
-ve \rightarrow -ve MS

- use absolute value \rightarrow fcl
- use square distance

if w_p Convex labels \rightarrow $\begin{matrix} +1 \\ -1 \end{matrix}$

$$\text{Total distance} = \sum \frac{\omega^T x_i + \omega_0}{\|\omega\|} \times y_i$$

suppose we have two vectors

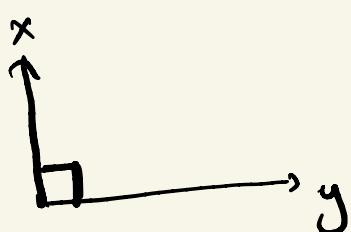
vector $x = [2, 1, -3]$

vector $y = [5, 8, 6]$

- What is the length of the projection of x onto y ?

projection of x on $y \rightarrow \frac{x^T y}{\|y\|}$

$$\begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix} \begin{bmatrix} 5 & 8 & 6 \end{bmatrix}$$



$$2 \times 5 + 1 \times 8 + 6 \times -3 = 0$$

$$10 + 8 - 18 = 0$$

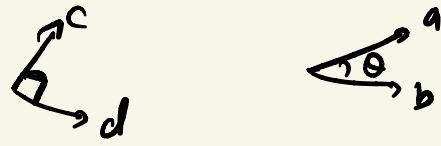
length of projection = 0

given a and b are two unit vectors such that,

$$c = a + 2b$$

$$d = 5a - 4b$$

these two are perpendicular, then what is the angle between a and b ?



$$\underline{\cos 90^\circ = 0}$$

$$c^T d \Rightarrow \underline{c \cdot d} = \underline{0}$$

$$\underline{\cos \theta} = \frac{\underline{c^T d}}{\|c\| \|d\|} =$$

$$(a+2b) \cdot (5a-4b) = 0$$

$$5\|a\|^2 + 6a \cdot b - 8\|b\|^2 = 0$$

$$5 + 6a \cdot b - 8 = 0$$

$$a \cdot b = \frac{3}{6} = \frac{1}{2}$$

$\underline{a \cdot b} = \text{dot product}$

$$\|a\| \|b\| \cos \theta = \frac{1}{2} = a \cdot b$$

$$\cos \theta = \frac{1}{2}$$

$$\underline{\theta = 60^\circ}$$

a is a vector

b is a vector

$$\underline{a+b} \Rightarrow \underline{\|a+b\|} = \underline{\sqrt{\|a\|^2 + \|b\|^2 + \dots}}$$



40

$$\underline{a} = [2, 3, 4]$$

$$\underline{b} = [1, 2, 3]$$

$$\|\underline{a}\| = \sqrt{2^2 + 3^2 + 4^2} = \sqrt{29}$$

$$\|\underline{b}\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{14}$$

$$\underline{c} = \underline{a} + \underline{b} = [3, 5, 7]$$

$$\begin{aligned}\|\underline{c}\| &= \sqrt{9 + 25 + 49} \\ &= \sqrt{83}\end{aligned}$$

$$(5\underline{a} + 3\underline{d}) \cdot (6\underline{b} + 7\underline{c})$$

$$30 \boxed{\underline{a} \cdot \underline{b}} \quad \dots$$

$$\cos \theta = \frac{\underline{x}^T \underline{y}}{\|\underline{x}\| \|\underline{y}\|}$$

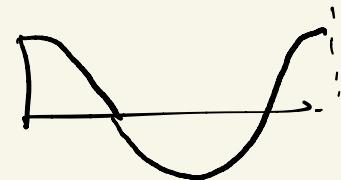
$$\underline{x}^T \underline{y} = \|\underline{x}\| \|\underline{y}\| \cos \theta$$

$$\underline{x} \cdot \underline{y} = \underline{x}^T \underline{y} = \|\underline{x}\| \|\underline{y}\| \cos \theta$$

$$\underline{a} \cdot \underline{b} = \|\underline{a}\| \|\underline{b}\| \cos \theta$$

$$\underline{a} \cdot \underline{a} = \|\underline{a}\| \|\underline{a}\| \cos 0^\circ, \quad \underline{\theta_1 = 0} \quad \underline{a, a}$$

$$\cos 0^\circ = 1$$



$$\underline{\underline{a} \cdot \underline{a} = (\|\underline{a}\|)^2}$$

$$\underline{\underline{a} \cdot \underline{b} = (\|\underline{a}\|) (\|\underline{b}\|) \cos \theta}$$

$$\underline{\underline{x}^T y}$$

Revisit

$$\underline{\underline{c} \cdot d = 0} = \|\underline{c}\| \|\underline{d}\| \cos 90^\circ = 0$$

$$(a+2b) \cdot (5a-7b) = 0$$

$$5\underline{a} \cdot \underline{a} + 10 \underline{a} \cdot \underline{b} - 4 \underline{a} \cdot \underline{b} - 8 \underline{b} \cdot \underline{b} = 0$$

$$5\|\underline{a}\|^2 + 6 \underline{a} \cdot \underline{b} - 8\|\underline{b}\|^2 = 0$$

$$\underline{a} \cdot \underline{b} = \frac{3}{6} = \frac{1}{2}$$

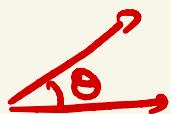
$$\underline{a} \cdot \underline{b} = \frac{1}{2}$$

$$\underline{\|\underline{a}\|} \quad \underline{\|\underline{b}\|} \quad \cos \theta = \frac{1}{2}$$

$$\cos \theta = \frac{1}{2}$$

$$\boxed{\theta = 60^\circ}$$

Quid $\underline{a} = [3, 4]$ $\underline{b} = [5, 0]$



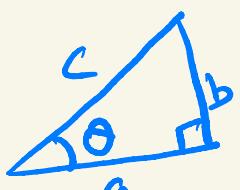
$$\underline{\cos \theta} = \frac{\underline{a} \cdot \underline{b}}{\|\underline{a}\| \|\underline{b}\|} = \frac{\underline{a}^T \underline{b}}{\|\underline{a}\| \|\underline{b}\|}$$

$$\|\underline{a}\| = \sqrt{3^2 + 4^2} = 5$$

$$\|\underline{b}\| = \sqrt{5^2 + 0^2} = 5$$

$$\underline{a}^T \underline{b} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \begin{bmatrix} 5 & 0 \end{bmatrix} = \frac{3 \times 5 + 4 \times 0}{5 \times 5} = 15$$

$$\cos \theta = \frac{15}{5 \cdot 5} = \frac{3}{5}$$



$$\cos \underline{\theta} = \frac{1}{2}$$

$$\boxed{\cos \theta = \frac{3}{5}}$$

$$\alpha_c =$$

$$\boxed{\theta = \cos^{-1} \frac{3}{5}}$$



$$\begin{aligned} \theta \\ L_1 &\Rightarrow \underline{\omega_1^T x + \omega_{01}} = 0 \\ L_2 &\Rightarrow \underline{\omega_2^T x + \omega_{02}} = 0 \end{aligned}$$

Both lines are parallel

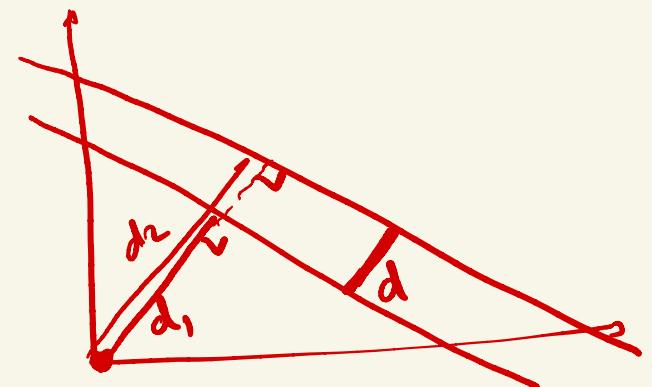
$$\omega_1 = [\underline{4}, \underline{3}]^T \quad] \text{ in same direction,}$$

$$\omega_2 = [16, 12]^T$$

$$\underline{\omega_{01}} = 3$$

$$\underline{\omega_{02}} = 7$$

$$\omega^T x + \omega_0 = 0 \Rightarrow \frac{\omega_0}{\|\omega\|}$$



$$\underline{d_1} = \frac{\omega_{01}}{\|\omega_1\|}$$

$$\underline{d} = \underline{d_2 - d_1}$$

$$d_2 = \frac{\omega_{02}}{\|\omega_2\|}$$

$$\underline{d_1} = \frac{3}{\sqrt{4+3^2}} = \frac{3}{5}$$

$$\underline{d_2} = \frac{7}{\sqrt{16^2+12^2}} = \frac{7}{20}$$

$$|d_1 - d_2| = \frac{3}{5} - \frac{7}{20} = \frac{12}{20} - \frac{7}{20} = \frac{5}{20} = \boxed{\frac{1}{4}}$$

Ques

$$4x - 3y = 5 \Rightarrow 4x - 3y - 5 = 0$$

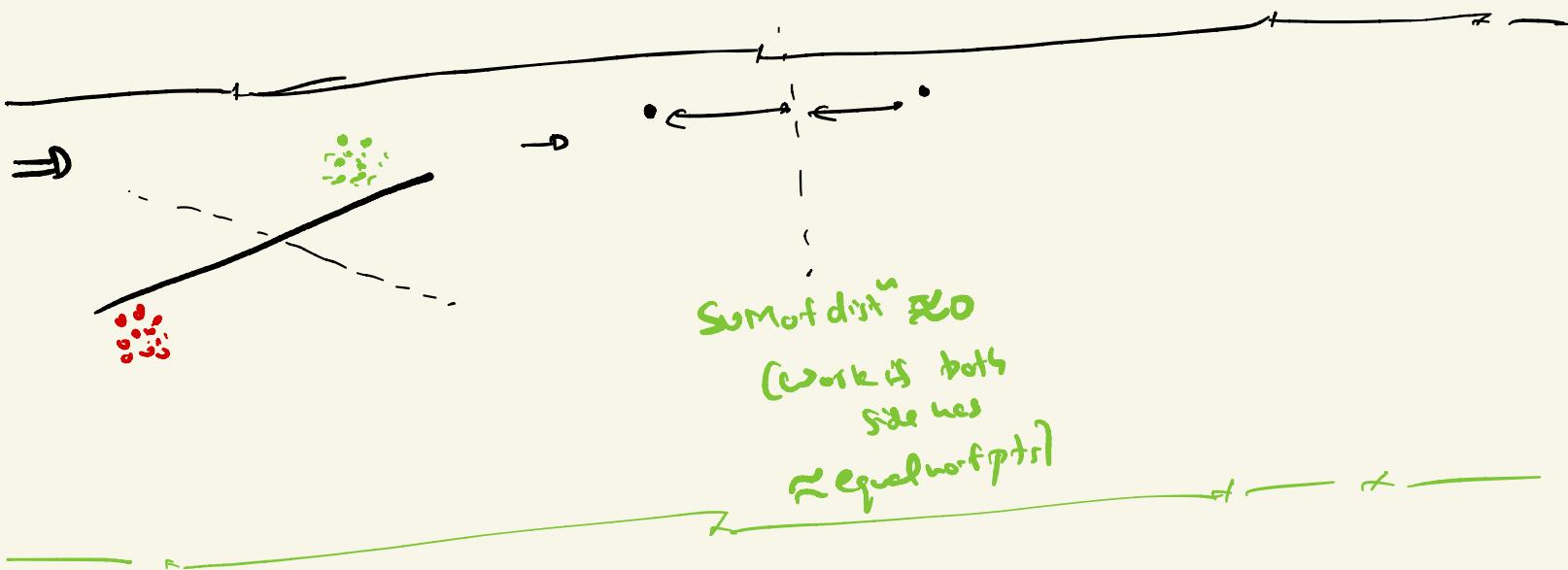
$$4x - 3y = 9 \Rightarrow 4x - 3y - 9 = 0$$

$$\frac{-5}{\sqrt{4^2 + 3^2}}$$

$$\frac{-9}{\sqrt{4^2 + 3^2}}$$

$$\Rightarrow -\frac{a}{s}$$

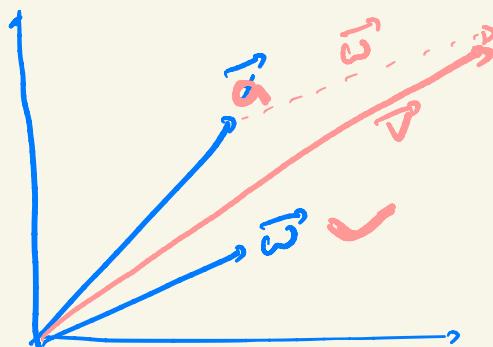
$$-\sqrt{\frac{4}{3}}$$



In the classification context we have two vectors x and w . Define $v = x + w$

In which direction should we move w to reach v , options are:

- clockwise
- anti-clockwise

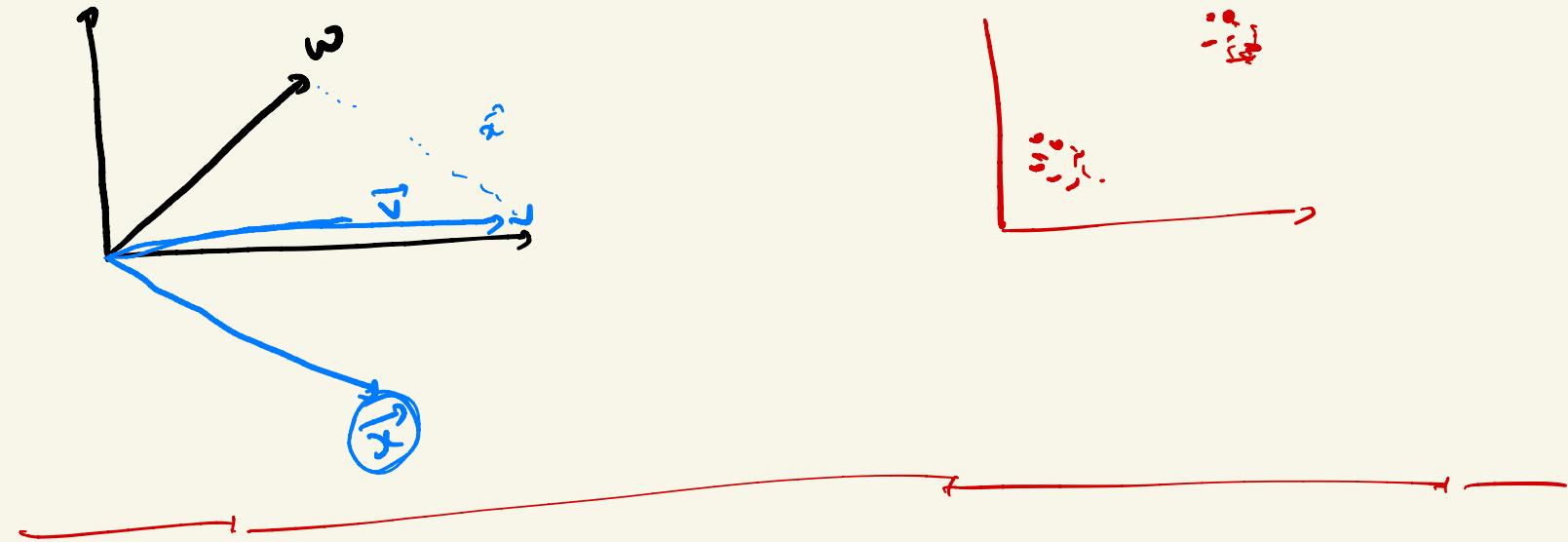


$$\begin{aligned} \vec{a} &\rightarrow \frac{3x}{\|x\|} \\ \vec{w} &\rightarrow \frac{4x}{\|x\|} \end{aligned}$$

if both \vec{w} & \vec{x} are positive

then

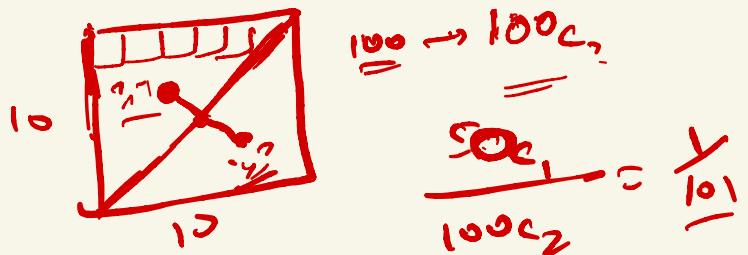
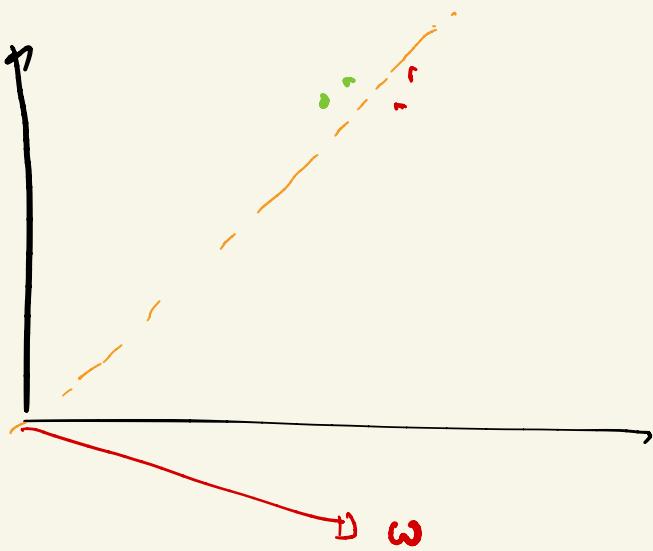
if $v = \vec{w} + \vec{x}$ \Rightarrow anti-clockwise



Suppose we have points with very little data points and the boundary is w with $w_0 = 0$

- will this be a good classifier?
- in which direction should w rotate to make it better

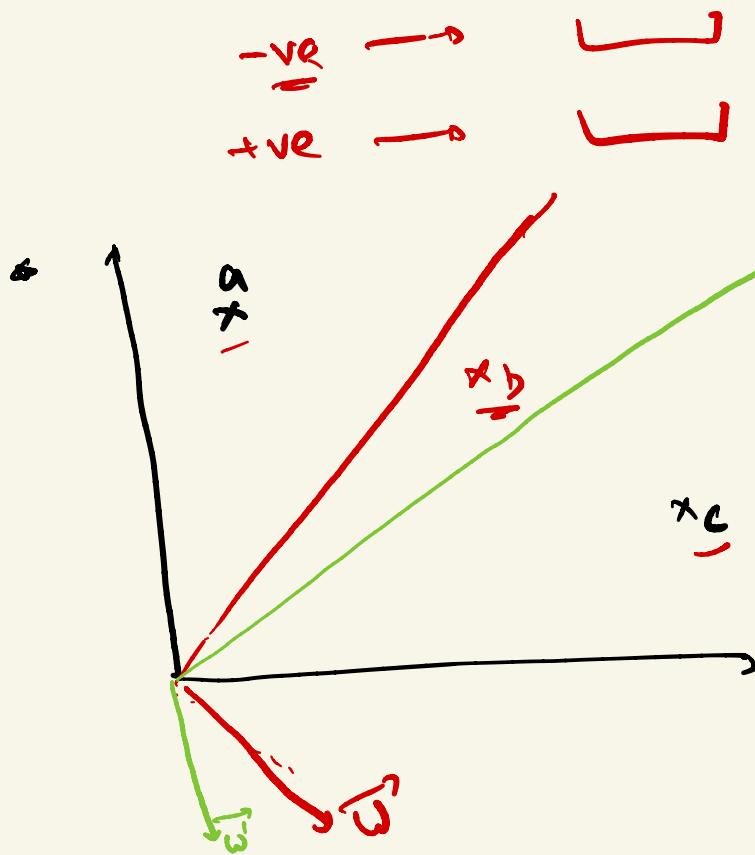
$$w_0 = 0$$



~~Good vs Bad~~ → even with small error in best fit line results should not change

if there is a small error in best fit line everything breaks

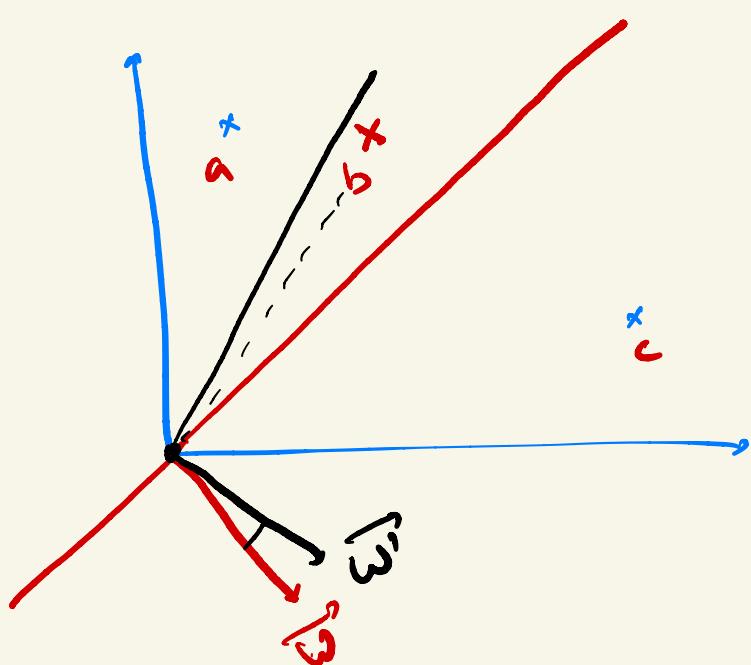
\Rightarrow Bad on misclassified point \rightarrow decide how to rotate



a \rightarrow -ve
b \rightarrow Actual -ve
but assig +ve

c \rightarrow +ve

Clockwise



a \rightarrow -ve
b \rightarrow +ve (Actual)
-ve (assig.)

c \rightarrow +ve

anticlockwise

little nodal
little shift

\Rightarrow Either rotate in direction of mi's classified
- Shift in tent direction

$$\text{Q1} \quad 3x - 4y = 5$$

$$x = (2, -3)$$

$$3x - 4y + 5 = 0$$

$$3 \times 2 - 4(-3) - 5 = 0$$

$$6 + 12 - 5 \Rightarrow \cancel{13}$$

$$\frac{\sqrt{13}}{\|w\|} \sim \sqrt{\frac{13}{3^2+4^2}} \Rightarrow \frac{\sqrt{13}}{5}$$

