# THE CUBIC GROUP AND SOME OTHER GROUPS

#### 14.1. The cubic group

WE shall study this group in much greater detail than any other finite group, not only because cubic symmetry occurs quite often but even more so because it is the only type of symmetry for which the theory of group representations is really indispensable in paramagnetic resonance. This theory can often be dispensed with for environments of lower symmetry. Many of the results derived can be extended in a straightforward manner to other groups.

A level of a free ion with a given value J of its angular momentum and therefore a degeneracy of order (2J+1) is spanned by a representation  $D^J$  of the rotation group with characters given by (13.16):

$$\chi^{J}(\varphi) = \sin\{(J+\frac{1}{2})\varphi\}/\sin(\frac{1}{2}\varphi).$$

In order to discover how this level is split in an environment of cubic symmetry we must obtain the irreducible representations of the cubic group O. We consider first the case when J is an integer. As we saw earlier, there is then a one-to-one correspondence between a rotation R and a matrix  $D^J(R)$ .

The cubic group O is the group of rotations that leaves invariant a cube or a regular octahedron. It contains the following classes:

- E, the identity operation (1 element),
- $C_2$ , rotations through an angle  $\pi$  around the three axes perpendicular to the faces of the cube (3 elements),
- $C_4$ , rotations through the angles  $\pm \pi/2$  around the same axes (6 elements),
- $C_2'$ , rotations through  $\pi$  around the 6 axes passing through the centre points of opposite edges; these axes are parallel to the face-diagonals (6 elements),
- $C_3$ , rotations through angles  $\pm (2\pi/3)$  around the 4 body-diagonals (8 elements).

We have altogether 24 elements and 5 classes. In contrast to the situation in the full rotation group, two rotations through the same angle but around two different axes X and Y do not belong to the same

class if the rotation C that brings X to Y is not an element of the group. This is why the two rotations through an angle  $\pi$ ,  $C_2$ , and C', belong to two different classes.

Since a regular octahedron is a figure obtained by joining the centres of the six faces of a cube it is clear that it is left invariant by the same group. Note also that each operation of O amounts to a permutation of the four body-diagonals. Hence the cubic group is isomorphic to the group of permutations  $S_4$ .

Since there are 5 classes and 24 elements, the cubic group has 5 irreducible representations with dimensions  $l_1, \ldots, l_5$  which obey the relation

$$l_1^2 + l_2^2 + l_3^2 + l_4^2 + l_5^2 = 24. (14.1)$$

It is easy to check that the only solution of (14.1) is the set of 5 integers 1, 1, 2, 3, 3. The corresponding representations are denoted in the literature by the symbols  $\Gamma_1$ ,  $\Gamma_2$ ,  $\Gamma_3$ ,  $\Gamma_4$ ,  $\Gamma_5$  or  $A_1$ ,  $A_2$ , E,  $T_1$ ,  $T_2$ . The characters can be obtained by the method described in paragraph 12.4 and their values are listed in Table 1.

We shall see shortly that it is possible to choose the basis functions of the irreducible representations of O to be real. Then the unitary matrices of these representations become real orthogonal matrices (that the characters are all real in Table 1 is only a necessary condition). The calculation of matrix elements of the form  $(\Psi_{\alpha}|V|\Psi_{\alpha'})$ , where  $\Psi_{\alpha}$  and  $\Psi_{\alpha'}$  belong to representations  $\Gamma$  and  $\Gamma'$  of O, is facilitated by the knowledge of the reducibility of the direct products  $\Gamma^* \times \Gamma'$  or, since all the  $\Gamma$  can be made real, of  $\Gamma \times \Gamma'$ . The results are given in Table 2. For diagonal direct products  $\Gamma \times \Gamma$  we have indicated by a superscript S or A whether an irreducible representation  $\Gamma_i$  belongs to the symmetric or antisymmetric part of  $\Gamma \times \Gamma$ . This can be established by using the formulae (12.43) for the characters.

The formula (13.16) yields the following values for the characters of  $D^{J}(R)$  where R is a rotation belonging to the cubic group,

$$\varphi = 0 \chi(E) = 2J + 1 
\varphi = \pi \chi(C_2) = \chi(C'_2) = (-1)^J 
\varphi = \pm \frac{\pi}{2} \chi(C_4) = (-1)^{I(J/2)} 
\varphi = \pm \frac{2\pi}{3} \chi(C_3) = \frac{\sin(\frac{2J+1}{3}\pi)}{\sin(\pi/3)}$$
(14.2)

where the symbol I(J/2) means the integer part of J/2. With the help of

(14.2) and of the formulae (12.16), we obtain Table 3 for the reduction of  $D^J$  by the cubic group for integer values of J up to 10.

All free ions with an even number of electrons naturally have an integral value of J. However, even for an odd number of electrons, we saw earlier that in fields of intermediate strength such as occur in the iron group, the relevant quantum number of the free ion was not the total angular momentum J but the total orbital momentum L, which is always an integer. The wave-functions that span a representation  $D^J$ , where J is an integer, transform as the usual spherical harmonics. We observe in Table 3 that, up to and including J=4, no representation appears more than once in  $D^J$ . The 'correct' zero-order wave-functions that span the various representations  $\Gamma_i$  are linear combinations of eigenfunctions of the free ion and can be obtained without explicit knowledge of the cubic Hamiltonian V for  $J \leqslant 4$ .

They are determined most conveniently by considering the functions

$$(p,q,r) = r^{2l+1} \frac{\partial^l (1/r)}{\partial x^p \partial y^q \partial z^r}, \qquad (14.3)$$

with p+q+r=l. These functions are homogeneous polynomials of degree l which satisfy the Laplace equation. Equation (14.3) defines (l+1)(l+2)/2 such polynomials but the Laplace equation introduces l(l-1)/2 relations between them, leaving (2l+1) independent polynomials.

$$l = 1$$

The three functions corresponding to (14.3) are (100), (010), (001), which are proportional to x, y, z. They clearly span a three-dimensional representation of the cubic group. A rotation of  $\pi/2$  around Oz changes them into -(010), (100), (001), and the trace of the transformation matrix is  $\chi(C_4) = 1$ , which from Table 1 shows that we are dealing with the representation  $\Gamma_4$  and not with  $\Gamma_5$ . This can be seen directly from Table 3 since the representation  $D^1$  reduces to  $\Gamma_4$  under cubic symmetry.

$$l=2$$

The functions (011), (101), (110) proportional to yz, zx, xy provide a three-dimensional representation of O that can only be  $\Gamma_5$  since  $D^2$  is split by O into  $\Gamma_3$  and  $\Gamma_5$ .

The two-dimensional representation  $\Gamma_3$  is spanned by the two orthogonal combinations (002) and  $(1/\sqrt{3})$ {(200) – (002)} proportional

to  $3z^2-r^2$  and  $\sqrt{(3)(x^2-y^2)}$ . (The  $\sqrt{3}$  factor ensures the same normalization for both functions.)

It is quite easy to see how the three wave-functions  $\eta_x \propto yz$ ,  $\eta_y \propto zx$ ,  $\eta_z \propto xy$  transform under the cyclic permutations of (x,y,z), R and  $R^2$ ; that is, under rotations through angles  $2\pi/3$  and  $4\pi/3$  respectively round the threefold axis (111). It is less easy to see how  $\theta \propto (3z^2-r^2)$  and  $\varepsilon \propto \sqrt{(3)(x^2-y^2)}$  transform under these conditions; we therefore quote the results

$$R\theta = -\frac{1}{2}\theta + \frac{\sqrt{3}}{2}\varepsilon; \qquad R^2\theta = -\frac{1}{2}\theta - \frac{\sqrt{3}}{2}\varepsilon; \ R\varepsilon = -\frac{\sqrt{3}}{2}\theta - \frac{1}{2}\varepsilon; \qquad R^2\varepsilon = \frac{\sqrt{3}}{2}\theta - \frac{1}{2}\varepsilon.$$
 (14.4)

The first of these can easily be verified, for example, by noting that  $(3z^2-r^2)=(2z^2-x^2-y^2)$  transforms into

$$(2x^2-y^2-z^2) = \frac{3}{2}(x^2-y^2) - \frac{1}{2}(2z^2-x^2-y^2).$$

l = 3

(111) proportional to (xyz) provides the unidimensional representation  $\Gamma_2$ .  $\Gamma_4$  is spanned by the three functions (300), (030), (003) proportional to  $x(3y^2+3z^2-2x^2)$ , etc.

 $\Gamma_5$  is spanned by the three orthogonal functions (102)–(120), (210)–(012), (021)–(201), proportional respectively to  $x(y^2-z^2)$ , etc.

$$l=4$$

Here we quote just the results:

$$\begin{split} &\Gamma_{1} \left\{ (x^{4} + y^{4} + z^{4} - \frac{3}{5}r^{4}), \\ &\Gamma_{3} \left\{ \begin{matrix} [z^{4} - \frac{1}{2}(x^{4} + y^{4}) - \frac{6}{7}r^{2}\sqrt{(5)}\{z^{2} - \frac{1}{2}(x^{2} + y^{2})\}] \\ \frac{\sqrt{3}}{2} \left\{ x^{4} - y^{4} - \frac{6}{7}\frac{\sqrt{(15)}}{2}(x^{2} - y^{2})r^{2} \right\}, \end{matrix} \\ &\Gamma_{5} \left\{ xy \left( z^{2} - \frac{r^{2}}{7} \right) \text{ and two cyclic permutations,} \right. \end{split}$$

 $\Gamma_4 \left\{ xy(x^2-y^2) \right\}$  and two cyclic permutations.

## 14.2. The fictitious angular momentum

Let V be a vector and consider the set of matrix elements  $(\xi_i|V_k|\xi_j)$  where  $\xi_x$ ,  $\xi_y$ ,  $\xi_z$  are the three wave-functions spanning a representation  $\Gamma_4$ , which transform under O like x, y, z.

The vector components  $V_x$ ,  $V_y$ ,  $V_z$  that transform under rotations

like x, y, z, also transform according to  $\Gamma_4$  under O. Since the reduction of  $\Gamma_4 \times \Gamma_4$  contains  $\Gamma_4$  only once (see Table 2), it follows that all the matrix elements  $(\xi_i|V_k|\xi_j)$  are uniquely determined within a proportionality factor. The same is true of the matrix elements  $(\eta_i|V_k|\eta_j)$  where  $\eta_x$ ,  $\eta_y$ ,  $\eta_z$  span  $\Gamma_5$  and transform like yz, zx, xy, since  $\Gamma_5 \times \Gamma_5$  also contains  $\Gamma_4$  only once. If we introduce the new functions  $|\tilde{m}\rangle$  by the formulae

$$|\pm\tilde{1}\rangle = \mp \frac{\xi_x \pm i \xi_y}{\sqrt{2}}, \qquad |\tilde{0}\rangle = \xi_z,$$

$$(14.5)$$

 $\mathbf{or}$ 

$$|\pm ilde{1}
angle = \mp rac{\eta_x \pm \mathrm{i} \eta_y}{\sqrt{2}}, \qquad | ilde{0}
angle = \eta_z,$$

the matrix elements of  $\langle \tilde{m} | A_k | \tilde{m}' \rangle$  will be proportional to those of an angular momentum  $\tilde{l}$  with  $\tilde{l}=1$ , sometimes called the fictitious angular momentum, that is,

$$\langle m | A_k | \tilde{m}' \rangle = \alpha \langle \tilde{l}, m | \tilde{l}_k | \tilde{l}, m' \rangle.$$
 (14.6)

Table 2 shows that the reduction of the direct product  $\Gamma_3 \times \Gamma_3$  does not contain  $\Gamma_4$  and therefore a vector has no matrix elements within the doublet  $\Gamma_3$ , a fact sometimes expressed by saying that this doublet is non-magnetic. As above, we shall denote by  $\theta$  and  $\varepsilon$  the two functions that span  $\Gamma_3$  and transform under O like  $3z^2-r^2$  and  $\sqrt{(3)(x^2-y^2)}$ .

For many purposes it is convenient to express the various states  $|\tilde{m}\rangle$  that originate in the decomposition of a representation  $D^J$  as a linear combination of eigenstates  $|J,m\rangle$ , where  $m=J_z$ , the axis Oz being one of the  $C_2$  axes of the cube. Table 4 gives these expressions up to J=4. We have written  $|m\rangle$  instead of  $|J,m\rangle$  for brevity, since the value of J is indicated unambiguously in the table. Besides each representation  $\Gamma_4$  and  $\Gamma_5$  we have written the value  $\alpha$  of the proportionality coefficient between J and the fictitious moment  $\tilde{\bf 1}$ : that is,  $J=\alpha\tilde{\bf 1}$ .

## 14.3. The multiplets $\Gamma_4$ and $\Gamma_5$ in trigonal axes

If the cubic environment of an ion is distorted along the direction of one of the  $C_2$  axes of the cube, say Oz, it is fairly obvious that the triplet  $\Gamma_4$  will be split into a doublet spanned by  $\xi_x$ ,  $\xi_y$  (or  $|\tilde{1}\rangle$  and  $|-\tilde{1}\rangle$ ) and a singlet  $\xi_z = |\tilde{0}\rangle$ . The same will be true for  $\Gamma_5$ , with the functions  $\eta$  instead of  $\xi$ . The functions  $\xi_i$  for  $\Gamma_4$  and  $\eta_i$  for  $\Gamma_5$  (or the functions  $|\tilde{m}\rangle$  for both) are thus the 'correct' zero-order wave-functions for this distortion of cubic symmetry. On the other hand, for a trigonal distortion, that is a distortion along a body diagonal, it is preferable to use

the following functions which will be the 'correct' zero-order functions:

$$\begin{split} |\tilde{1}\rangle_{T} &= a(\xi_{x} + \mathrm{e}^{2\pi \mathrm{i}/3}\xi_{y} + \mathrm{e}^{4\pi \mathrm{i}/3}\xi_{z}), \\ |\tilde{0}\rangle_{T} &= a(\xi_{x} + \xi_{y} + \xi_{z}), \\ |-\tilde{1}\rangle_{T} &= a(\xi_{x} + \mathrm{e}^{-2\pi \mathrm{i}/3}\xi_{y} + \mathrm{e}^{-4\pi \mathrm{i}/3}\xi_{z}), \end{split}$$
(14.7)

where a is a normalization constant (for  $\Gamma_5$ , we use  $\eta_x$ ,  $\eta_y$ ,  $\eta_z$  instead of  $\xi_x$ ,  $\xi_y$ ,  $\xi_z$ ). The functions (14.7) can be obtained from Table 4, but it is preferable then to quantize  $J_z$  along a body diagonal. The results for this are given in Table 5 for the representation  $\Gamma_5$  contained in J=2, and for both  $\Gamma_4$  and  $\Gamma_5$  originating in J=3.

#### 14.4. The double cubic group

In order to find how a half-integer J-level of the free ion splits in an environment of cubic symmetry we must introduce the so-called double cubic group  $O^+$ . We recall that  $D^J$  with J half-integer is not strictly speaking a representation of the spatial rotation group G but rather a representation of the unimodular group  $U=D^{\frac{1}{2}}$ , and that to each rotation belonging to G there correspond two matrices  $\pm u$  of U. The double cubic group is then defined unambiguously as follows: consider the 24 rotations in G that belong to G, subgroup of G; to these correspond twice as many, namely 48, matrices of G, which form a subgroup  $G^+$  of G. The abstract group that has the same multiplication table as  $G^+$  is, by definition, the double cubic group  $G^+$ . The group  $G^+$  is obtained by adding to G the element G which is represented in G0 the matrix G1. G2. G3. G4. G4. G4. G5. G5. G4. G5. G6. G6. G6. G7. G8. G8. G9. G

If A is an element of O, every element of  $O^+$  is either A or RA = AR. This definition of the double group  $O^+$  can clearly be extended to any finite rotation group.

The irreducible representations  $\Gamma_1$  to  $\Gamma_5$  of O are also irreducible representations of  $O^+$ . They are representations where R is represented by the unit matrix, but there are others. To elucidate them we must find the classes of  $O^+$ . One might think naïvely that as  $O^+$  has twice as many elements as O it has twice as many classes, those already listed for O plus

$$R = RE, RC_2, RC_2, RC_3, RC_4.$$

Actually this is not so:  $C_2$  and  $RC_2$  belong to the same class and similarly  $C_2$  and  $RC_2$ . This can be shown as follows (Opechowski 1940).

Since the two elements C and RC of a double group have characters of opposite sign it is a necessary condition that these must vanish if C and RC belong to the same class. From (13.16) the rotation that corresponds to these two elements is therefore through an angle  $\pi$ . Let us choose its axis as the z-axis. According to (13.8) with  $\alpha = \pi$ ,

$$eta=\gamma=0$$
 we can represent  $C$  by the matrix  $c=\begin{pmatrix} -i & 0 \ 0 & i \end{pmatrix}$  and  $RC$ 

by -c. If there is in the group a twofold axis perpendicular to the z-axis let us choose it as the y-axis, the corresponding rotation  $\alpha = \gamma = 0$ ,  $\beta = \pi$  according to (13.8) can be represented by

$$b = \begin{pmatrix} 0 & -1 \\ +1 & 0 \end{pmatrix}$$

(or by -b) and one verifies immediately that  $bcb^{-1} = -c$ , which means that c and -c belong to the same class.

We have thus shown that in a double group two elements, C and RC, corresponding to a rotation  $\pi$  around a certain axis Z, will belong to the same class provided that the group contains another twofold axis perpendicular to Z. This is clearly the case for the elements of  $O^+$  belonging to  $C_2$  or  $C_2'$ .  $O^+$  has then 8 classes and 8 irreducible representations. Since we already know five of them, there must be three more with dimensions  $l_6$ ,  $l_7$ ,  $l_8$  given by the relation

$$l_s^2 + l_r^2 + l_s^2 = 48 - (l_1^2 + \dots + l_s^2) = 24,$$
 (14.8)

which admits of a single solution,

$$l_6 = 2, \qquad l_7 = 2, \qquad l_8 = 4.$$

These representations, known in the literature as  $\Gamma_6$ ,  $\Gamma_7$ ,  $\Gamma_8$  or E', E'', U (and possibly many other names), and sometimes called specific representations, differ from the first 5 through the fact that the element R is represented by the negative of the unit matrix. It is therefore clear that  $D^J$  for half-integral values of J contains specific representations only. Their characters are given in Table 6. The breakdown of  $D^J$  into specific representations is computed in the usual manner and the results are given for  $J = \frac{1}{2}$  up to  $J = \frac{15}{2}$  in Table 7.

From the character tables we can calculate the decomposition of the direct products. Table 8 contains results for the whole of the double group  $O^+$  and thus incorporates Table 2.

We have not written out explicitly the matrices of the different representations  $\Gamma_1$  to  $\Gamma_8$ . For the non-specific representations  $\Gamma_1$  to  $\Gamma_5$ 

the fact that xyz is a basis function for  $\Gamma_2$ , x, y, z for  $\Gamma_4$ , xy, yz, zx for  $\Gamma_5$ ,  $3z^2-r^2$  and  $\sqrt{(3)(x^2-y^2)}$  for  $\Gamma_3$ , makes it easy to write them down if desired, using simple geometrical considerations. For the specific representations, we see from Table 7 that  $D^{\frac{1}{2}}$  reduces just to  $\Gamma_6$ . The matrices of  $\Gamma_6$  are thus simply the 48 matrices of  $D^{\frac{1}{2}}$  that correspond to the 24 rotations of the cubic group. We shall represent the basis functions of  $\Gamma_6$  as  $|\pm \frac{\tilde{\gamma}}{2}\rangle$ , the tilde being there to remind us that these are not actually, except for  $J=\frac{1}{2}$ , the states  $|J,\pm \frac{1}{2}\rangle$ . Similarly since  $D^{\frac{3}{2}}$  reduces to  $\Gamma_8$  we can take as the basis functions of  $\Gamma_8$ , the functions  $|\pm \frac{\tilde{\gamma}}{2}\rangle$ ,  $|\pm \frac{\tilde{\gamma}}{2}\rangle$  that will transform under the rotations S of the cubic group in the same way as the functions  $|\frac{\tilde{\gamma}}{2}\rangle$ ,  $|\frac{\tilde{\gamma}}{2}\rangle$ ,  $|\frac{1}{2}\rangle$  would transform under  $D^{\frac{3}{2}}(S)$ .

The nature of  $\Gamma_7$  is less obvious. Since  $\Gamma_7 = \Gamma_6 \times \Gamma_2$  let us introduce the functions

$$|lpha
angle = |+rac{ ilde{1}}{2}
angle
ho, \ |eta
angle = |-rac{ ilde{1}}{2}
angle
ho,$$
 (14.9)

where  $\rho$  transforms according to  $\Gamma_2$ , that is as the function xyz, and let the functions  $|\pm\frac{\tilde{i}}{2}\rangle$  transform according to  $\Gamma_6$ .  $\alpha$  and  $\beta$  will then transform according to  $\Gamma_7$ . The matrices of  $\Gamma_7$  are  $\pm$  those of  $\Gamma_6$ . The matrices of  $\Gamma_6$ ,  $\Gamma_7$ ,  $\Gamma_8$  cannot all be made real (see § 15.9, following eqn (15.53)). However, as appears from Table 6, their characters are all real and the  $\Gamma_i$  (i=6,7,8) are equivalent to their complex conjugates. This is why in Table 8 we are able to consider direct products  $\Gamma_i \times \Gamma_j$  rather than  $\Gamma_i^* \times \Gamma_j$ .

We see in Table 7 that, in the decomposition of  $D^J$ ,  $\Gamma_6$  and  $\Gamma_7$  appear only once up to  $J=\frac{15}{2}$ , except for  $J=\frac{13}{2}$  where  $\Gamma_7$  appears twice, and that  $\Gamma_8$  appears only once up to  $J=\frac{7}{2}$ . We can therefore write a priori the corresponding 'good' zero-order wave-functions as linear combinations of  $|J, M\rangle$ . This is done in Table 9.  $(J=\frac{11}{2}$  and  $\frac{13}{2}$  are omitted for they do not occur in practice as the ground states of paramagnetic ions.)

The reader perusing Tables 4 and 9 may well ask from what hat these rabbits have been extracted. A brief indication of the method used to obtain these tables will now be given. Consider a ket  $|J, M\rangle$  belonging to a representation  $D^J$  of the rotation group. If S is an operator belonging to O (or  $O^+$ ) we know how to calculate the ket  $S|J, M\rangle$ ; it will be given by

$$S|J, M\rangle = \sum_{M'} |J, M'\rangle D_{M'M}^{J}(S), \qquad (14.10)$$

where the  $D_{M'M}^{J}(S)$  are certain matrix elements of the representation  $D^{J}$  of the rotation group, which are known in principle (see § 13.2). We also know in principle the matrices  $A_{\mu\nu}^{k}$  of the various irreducible representations  $\Gamma_{1}$  to  $\Gamma_{8}$  of the cubic group, as explained above. In the cubic group k stands for the index 1 to 8 of the irreducible representation concerned and  $\mu$  and  $\nu$  refer to the various basis functions inside each representation  $\Gamma_{k}$ . Each representation  $\Gamma_{k}$  is spanned by  $l_{k}$  functions  $\Psi_{\mu}^{k}$  which, under an operation S of the group, will transform accordingly to

$$S\Psi^k_{\mu} = \sum_{\nu} \Psi^k_{\nu} A^k_{\nu\mu}(S). \tag{14.11}$$

The various  $\Psi^k_{\mu}$  will be the linear combinations of the  $|J, M\rangle$ , given in Tables 4 and 9 for the cubic group, which we wish to obtain. Conversely each ket  $|J, M\rangle$  will be a linear combination of the  $\Psi^k_{\mu}$ 

$$|J, M\rangle = \sum_{k', \mu'} \Psi_{\mu'}^{k'} C_{\mu'}^{k'} (J, M).$$
 (14.12)

Let us define now the operator

$$P_{\mu}^{k} = \frac{l_{k}}{g} \sum_{S} A_{\mu\mu}^{k*}(S) \cdot S, \qquad (14.13)$$

where g is the number of elements of the group (48 for  $O^+$ ) and the sum  $\sum_{S}$  is over all the operations of the group. According to (14.10) we know how to express  $P_{\mu}^{k}|J,M\rangle$  as a sum of  $|J,M'\rangle$ . On the other hand, if we take for  $|J,M\rangle$  the expression (14.12), we get

$$P_{\mu}^{k}|J,M\rangle = \frac{l_{k}}{g} \sum_{S,\mu',\mu'} A_{\mu\mu}^{k*}(S)(S\Psi_{\mu'}^{k'})C_{\mu'}^{k'}(J,M)$$
 (14.14)

or, using (14.11),

$$P_{\mu}^{k}|J,M\rangle = \frac{\zeta_{k}}{g} \sum_{S,k',\mu',\nu'} A_{\mu\mu}^{k*}(S) \Psi_{\nu'}^{k'} A_{\nu'\mu'}^{k'}(S) C_{\mu'}^{k'}(J,M) \qquad (14.15)$$

which, taking into account the orthogonality relations (12.9), reduces to

$$P_{\mu}^{k}|J,M\rangle = \Psi_{\mu}^{k}C_{\mu}^{k}(J,M).$$
 (14.16)

We can thus generate all the  $\Psi^k_\mu$  of Tables 4 and 9 (apart from normalization factors). The operation (14.14) will yield zero if  $C^k_\mu(J,M)=0$ , that is if the expansion (14.12) of the ket  $|J,M\rangle$  does not contain the function  $\Psi^k_\mu$ . One then starts from another ket  $|J,M'\rangle$  until all the  $\Psi^k_\mu$  are obtained.

In practice our previous advice is the best: as somebody has prepared the tables, why not use them?

#### 14.5. Groups of lower symmetry

The tetragonal group, also known in the literature as the group  $D_4$ , is the group that leaves invariant a cube or an octahedron that has been distorted along a  $C_2$  axis called the tetragonal axis.

It contains the following elements and classes:

E, the identity operation,

 $C_2$ , rotation by an angle  $\pi$  around the tetragonal axis Oz (1 element),

 $C_4$ , rotation by  $\pm \pi/2$  around the same axis (2 elements),

 $C_2'$ , rotation by  $\pi$  around two axes Ox, Oy perpendicular to Oz (2 elements),

 $C_2''$ , rotation by  $\pi$  around two axes OX, OY at angles  $\pi/4$  to Ox and Oy (2 elements).

Altogether we have 8 elements and 5 classes; whence (see § 12.3) there will be just 5 irreducible representations which we call  $\Gamma_1^t$ ,  $\Gamma_2^t$ ,  $\Gamma_3^t$ ,  $\Gamma_4^t$ ,  $\Gamma_5^t$  (the index t is a weak attempt to avoid confusion with the representations of the cubic group), and which are also known in the literature by other names. From eqn (12.14) it is readily apparent that they are all unidimensional except the last, which has two dimensions. The characters are given in Table 10.

We shall not write down the decomposition of  $D^J$  into the irreducible representations  $\Gamma_k^t$  of  $D_4$  but be content to indicate the correspondence between the representations  $\Gamma_k$  of the cubic group and those  $\Gamma_k^t$  of the tetragonal group that is a subgroup of O. Using the character tables, it is possible to find, with the help of (12.16), that

$$\begin{cases} \Gamma_1 = \Gamma_1^t, & \Gamma_2 = \Gamma_3^t, & \Gamma_3 = \Gamma_3^t + \Gamma_1^t, \\ \Gamma_4 = \Gamma_2^t + \Gamma_5^t, & \Gamma_5 = \Gamma_4^t + \Gamma_5^t. \end{cases}$$
(14.17)

It is apparent that there is no logic whatsoever in this choice of indices (due to Bethe) but we shall not add to the confusion by proposing a new notation of our own differing from the many that already exist.

As far as the 'good' zero-order wave-functions are concerned we can see the following (taking the z-axis to be the tetragonal axis):

For J=1, the cubic triplet  $\Gamma_4$  spanned by x, y, z is split into the singlet  $\Gamma_2^t$  spanned by z and the doublet  $\Gamma_5^t$  spanned by x and y.

For J=2, the cubic triplet  $\Gamma_5$  spanned by xy, yz, zx is split into the singlet  $\Gamma_4^t$  spanned by xy and the doublet  $\Gamma_5^t$  spanned by yz and zx.

The cubic doublet  $\Gamma_3$  is split into the singlet  $\Gamma_1^t$  spanned by  $3z^2-r^2$  and the singlet  $\Gamma_3^t$  spanned by  $x^2-y^2$ .

For J=3, the cubic singlet  $\Gamma_2$  becomes the singlet  $\Gamma_3$  spanned by xyz, the cubic triplet  $\Gamma_5$  becomes the doublet  $\Gamma_5^t$  spanned by  $x(y^2-z^2)$ 

and  $y(z^2-x^2)$ , and the singlet  $\Gamma_t^t$  spanned by  $z(x^2-y^2)$ ; the cubic triplet  $\Gamma_4$  becomes the singlet  $\Gamma_2^t$  spanned by  $z(3x^2+3y^2-2z^2)$ , and a doublet  $\Gamma_5^t$  spanned by  $x(3y^2+3z^2-2x^2)$  and  $y(3z^2+3x^2-2y^2)$ .

It will be noticed from (14.17) that already in the decomposition of  $D^3$ ,  $\Gamma_5$  appears twice and that the correct zero-order functions spanning  $\Gamma_5^t$  cannot be obtained without explicit knowledge of the tetragonal potential. The off-diagonal matrix elements of a tetragonal field between the cubic manifolds  $\Gamma_4$  and  $\Gamma_5$  are given explicitly in Fig. 7.5.

The properties of the double tetragonal group are obtained in the same manner as for the cubic group. It has 16 elements, twice as many as the simple group, but two more classes only, R and  $RC_4$ , since the classes  $RC_2$ ,  $RC_2'$ ,  $RC_2''$  are not distinct from  $C_2$ ,  $C_2'$ ,  $C_2''$  in accordance with the theorem in § 14.4. There are two specific representations  $\Gamma_6^t$  and  $\Gamma_7^t$  with dimensions,  $l_6$  and  $l_7$ , such that

$$l_6^2 + l_7^2 = 16 - 8 = 8$$

whence  $l_6 = l_7 = 2$  showing that both  $\Gamma_6$  and  $\Gamma_7^t$  are bidimensional. We omit their character table and shall be content to notice that the decomposition of the specific representations of  $O^+$  into those of the double tetragonal group is

$$\Gamma_6 = \Gamma_6^t, \qquad \Gamma_7 = \Gamma_7^t, \qquad \Gamma_8 = \Gamma_6^t + \Gamma_7^t.$$
 (14.18)

The *rhombic group* or  $D_2$  contains, besides the unit operation, just three binary orthogonal axes x, y, z and thus four classes and four unidimensional representations. For an integral value of J there is no degeneracy left in a rhombic field.

The double group has 8 elements and 5 classes, R being the only extra one. It has one specific representation of dimension 2. A multiplet J of the free ion with half-integral J will thus split into  $J + \frac{1}{2}$  doublets.

The trigonal group or  $D_3$  leaves invariant a cube distorted along a body-diagonal. Its elements and classes are as follows:

the identity E,

the rotations  $C_3$  of angle  $\pm 2\pi/3$  around the threefold axis Oz (2 elements),

the rotations  $C_2'$  of angle  $\pi$  around three axes perpendicular to Oz (3 elements).

Altogether we have 3 classes and 6 elements, which shows that there must be two one-dimensional representations that we call  $\Gamma_1^T$  and  $\Gamma_2^T$  and one bidimensional representation  $\Gamma_3^T$ . The characters are given in Table 11. The decomposition of  $D^J$  by the trigonal group is given in Table 12.

The connection between cubic and trigonal groups is as follows:

$$\begin{split} &\Gamma_1 \rightarrow \Gamma_1^T, & \Gamma_2 \rightarrow \Gamma_2^T, & \Gamma_3 \rightarrow \Gamma_3^T, \\ &\Gamma_4 \rightarrow \Gamma_2^T + \Gamma_3^T, & \Gamma_5 \rightarrow \Gamma_1^T + \Gamma_3^T. \end{split}$$

It is worth noticing that the degeneracy of the cubic doublet  $\Gamma_3$  is not lifted by a trigonal distortion though it is by a tetragonal distortion.

The double trigonal group has 12 elements and 6 classes. ( $C_2'$  and  $RC_2'$  are distinct since there is no binary axis perpendicular to the binary axes of  $C_2'$ .) We find readily that there are two unidimensional specific representations  $\Gamma_4^{\bar{T}}$ ,  $\Gamma_5^{\bar{T}}$ , and one bidimensional  $\Gamma_6^{\bar{T}}$ . Their characters are given in Table 13. The decomposition of  $D^J$  by the trigonal group for half integer J is given in Table 14.

As the representations  $\Gamma_4^T$  and  $\Gamma_5^{\bar{T}}$  are unidimensional one might think that the decomposition of a half-integer J could contain singlets. We shall soon see (§ 15.4), that there is a very general theorem due to Kramers which proves that this can never occur. Therefore the two representations  $\Gamma_4^{\bar{T}}$  and  $\Gamma_5^T$  (which are complex conjugates) must always correspond to the same energy of the system.

The decomposition of specific representations of  $O^+$  into those of the trigonal group is the following:

$$\Gamma_6 = \Gamma_6^T, \qquad \Gamma_7 = \Gamma_6^T, \qquad \Gamma_8 = \Gamma_4^T + \Gamma_5^T + \Gamma_6^T.$$
 (14.19)

## 14.6. Improper rotations

We have only considered so far symmetry groups containing pure rotations. Another type of symmetry element that occurs in nature is the improper rotation. An improper rotation is a symmetry element resulting from the combination of a rotation with an inversion with respect to a centre situated on the axis of rotation. For instance, reflection in a plane is the product of a rotation by an angle  $\pi$  with an inversion. In ordinary space an inversion corresponds to the reversal of the signs of the three space coordinates and an improper rotation is therefore represented by a real orthogonal matrix with determinant -1. It follows that the product of two improper rotations is a proper rotation and that the product of a proper and improper rotation is an improper rotation. A group  $G_i$  that contains at least one improper rotation must therefore contain as many proper as improper rotations and can be represented as the combination of a subgroup  $G_p$  of proper rotations with a set of improper rotations of the form  $g_iG_n$  where  $g_i$ is an improper rotation. We write symbolically

$$G_{i} = G_{p} + g_{i}G_{p}. \tag{14.20}$$

We shall for brevity call a group such as (14.20) a group of improper rotations, although it contains naturally proper rotations as well. A finite group of improper rotations may or may not contain the inversion operation itself. If it does, we can use for the improper rotation  $g_i$  in (14.20) the inversion I itself and write

$$G_{\mathbf{i}} = G_{\mathbf{p}} + IG_{\mathbf{p}}.\tag{14.21}$$

Since I commutes with all the elements of the group  $G_i$ , and its square  $I^2$  is just the identity operation, the matrix representing I in an irreducible representation of  $G_i$  can be either the unit matrix, for so-called even representations, or its negative for odd representations.

To each representation  $\mathscr{D}_{\mathbf{p}}$  of  $G_{\mathbf{p}}$  correspond two representations  $\mathscr{D}_{\mathbf{i}}^{\pm}$  of  $G_{\mathbf{i}}$  such that, if  $g_{\mathbf{p}}$  is a proper rotation of  $G_{\mathbf{p}}$ ,

$$\begin{cases} \mathscr{D}_{\mathbf{i}}^{\pm}(g_{\mathbf{p}}) = \mathscr{D}_{\mathbf{p}}(g_{\mathbf{p}}) \\ \mathscr{D}_{\mathbf{i}}^{\pm}(Ig_{\mathbf{p}}) = \pm \mathscr{D}_{\mathbf{p}}(g_{\mathbf{p}}). \end{cases}$$
(14.22)

In particular, if  $\mathcal{Q}_{p}$  is irreducible so is  $\mathcal{Q}_{i}^{\pm}$ .

If  $\mathscr{D}_{\mathbf{i}}$  is a *reducible* representation of  $G_{\mathbf{i}}$  of given parity there corresponds to it by (14.22) a single reducible representation  $\mathscr{D}_{\mathbf{p}}$  of  $G_{\mathbf{p}}$ . If we know how to reduce  $\mathscr{D}_{\mathbf{p}}$  into its irreducible parts

$$\mathscr{D}_{\mathrm{p}} = \sum a_{k} \mathscr{D}_{\mathrm{p}}^{(k)},$$
 (14.23)

the reduction of  $\mathcal{D}_i$  will be

$$\mathscr{D}_{\mathbf{i}} = \sum a_{k} \mathscr{D}_{\mathbf{i}}^{(k)} \tag{14.24}$$

with the same coefficients  $a_k$ .

As an example of a group of improper rotations that contains I, we may take the cubic group of improper rotations  $O_h$  defined in accordance with (14.21),

$$O_{\rm h} = O + IO.$$
 (14.25)

On the other hand, the tetrahedral group  $T_{\rm d}$ , which is the group of improper rotations that transform a regular tetrahedron into itself, does not contain the inversion I. Since each operation of  $T_{\rm d}$  amounts to a permutation of the vertices of the tetrahedron,  $T_{\rm d}$  is isomorphic with the permutation group  $S_4$  and thus also with O. It has the same set of characters and the same representations as O. Geometrically, however, it is a different group. By adding to  $T_{\rm d}$  the inversion operation we obtain again the full cubic group

$$O_{\rm h} = T_{\rm d} + IT_{\rm d}, \tag{14.26}$$

showing that  $T_{\rm d}$  and O are two isomorphic subgroups of  $O_{\rm h}$ . It should be noticed that in contradistinction to (14.25), (14.26) is not a relationship of the type (14.20) since  $T_{\rm d}$  contains improper rotations as well as proper ones.

We examine now how the introduction of improper rotations modifies the splitting of a degenerate level of the free ion by the crystal potential, as studied in the previous sections. If the group of improper rotations  $G_i$  which describes the environment of the bound ion does contain the inversion element, the crystal field splitting is the same as calculated for the pure rotation group  $G_p$  associated with  $G_i$  by (14.21). This follows from the fact that the level J of the free ion has a definite parity and that the wave-functions that span this level provide a reducible representation  $\mathcal{D}_i(G_i)$  of given parity which, as explained earlier, is reduced in the same manner as the representation  $\mathcal{D}_p(G_p)$  in the absence of inversion. Thus the splitting pattern of a level of the free ion will be the same in a field of symmetry  $O_h$  as in symmetry O.

If the group  $G_i$  does not contain the inversion I we can still predict the splitting pattern as follows. Let us call  $V(\mathbf{r})$  the crystalline potential invariant by  $G_i$  which represents the effects of the environment of the bound ion. We can write

$$V(\mathbf{r}) = \frac{1}{2} \{V(\mathbf{r}) + V(-\mathbf{r})\} + \frac{1}{2} \{V(\mathbf{r}) - V(-\mathbf{r})\} = V_{\text{even}} + V_{\text{odd}}.$$
 (14.27)

Since the states of the free ion have a definite parity the matrix elements of  $V_{\rm odd}$  vanish inside their manifold and we can in first approximation replace V by  $V_{\rm even}$ . But  $V_{\rm even}$  is invariant through I and thus through the group

$$G_{\mathbf{i}}' = G_{\mathbf{i}} + IG_{\mathbf{i}},$$

which can always be rewritten according to (14.20) as

$$G_{\rm i}' = G_{\rm p}' + IG_{\rm p}',$$

where  $G'_p$  is a certain pure rotation group. The splitting of  $D^J$  by a potential of symmetry  $G_i$  will then be the same as by one with symmetry  $G'_i$  and therefore, as we saw earlier, the same as by a potential of symmetry  $G'_p$ . As an example, from (14.26) and (14.25) we deduce that a level  $D^J$  will be decomposed in the same manner in a field of tetrahedral symmetry  $T_d$  as in a cubic field O and we need not repeat the detailed study of the last section.

The foregoing is valid provided we assume that the effects due to the environment are small compared with the distance between two configurations of the free ion with opposite parity.

The absence of a centre of inversion in the environment also modifies drastically the response to an applied electric field as we shall see in § 15.10.