# C2\_W4\_Lab\_2\_multi-GPU-mirrored-strategy

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## 1 Multi-GPU Mirrored Strategy

In this ungraded lab, you'll go through how to set up a Multi-GPU Mirrored Strategy. The lab environment only has a CPU but we placed the code here in case you want to try this out for yourself in a multiGPU device.

**Notes:** - If you are running this on Coursera, you'll see it gives a warning about no presence of GPU devices. - If you are running this in Colab, make sure you have selected your runtime to be GPU. - In both these cases, you'll see there's only 1 device that is available.

- One device is sufficient for helping you understand these distribution strategies.

### 1.1 Imports

```
[1]: import tensorflow as tf import numpy as np import os
```

#### 1.2 Setup Distribution Strategy

```
[2]: # Note that it generally has a minimum of 8 cores, but if your GPU has

# less, you need to set this. In this case one of my GPUs has 4 cores
os.environ["TF_MIN_GPU_MULTIPROCESSOR_COUNT"] = "4"

# If the list of devices is not specified in the

# `tf.distribute.MirroredStrategy` constructor, it will be auto-detected.

# If you have *different* GPUs in your system, you probably have to set up

→ cross_device_ops like this

strategy = tf.distribute.MirroredStrategy(cross_device_ops=tf.distribute.

→ HierarchicalCopyAllReduce())

print ('Number of devices: {}'.format(strategy.num_replicas_in_sync))
```

```
INFO:tensorflow:Using MirroredStrategy with devices
('/job:localhost/replica:0/task:0/device:CPU:0',)
Number of devices: 1
```

### 1.3 Prepare the Data

```
[3]: # Get the data
    fashion_mnist = tf.keras.datasets.fashion_mnist
    (train_images, train_labels), (test_images, test_labels) = fashion_mnist.
     →load data()
    # Adding a dimension to the array -> new shape == (28, 28, 1)
    # We are doing this because the first layer in our model is a convolutional
    # layer and it requires a 4D input (batch size, height, width, channels).
    # batch size dimension will be added later on.
    train images = train images[..., None]
    test_images = test_images[..., None]
    # Normalize the images to [0, 1] range.
    train_images = train_images / np.float32(255)
    test_images = test_images / np.float32(255)
    # Batch the input data
    BUFFER_SIZE = len(train_images)
    BATCH_SIZE_PER_REPLICA = 64
    GLOBAL_BATCH_SIZE = BATCH_SIZE_PER_REPLICA * strategy.num_replicas_in_sync
    # Create Datasets from the batches
    train dataset = tf.data.Dataset.from tensor slices((train images,
     →train_labels)).shuffle(BUFFER_SIZE).batch(GLOBAL_BATCH_SIZE)
    test_dataset = tf.data.Dataset.from_tensor_slices((test_images, test_labels)).
     →batch(GLOBAL_BATCH_SIZE)
    # Create Distributed Datasets from the datasets
    train_dist_dataset = strategy.experimental_distribute_dataset(train_dataset)
    test_dist_dataset = strategy.experimental_distribute_dataset(test_dataset)
    Downloading data from https://storage.googleapis.com/tensorflow/tf-keras-
    datasets/train-labels-idx1-ubyte.gz
    32768/29515 [============ ] - Os Ous/step
    Downloading data from https://storage.googleapis.com/tensorflow/tf-keras-
    datasets/train-images-idx3-ubyte.gz
    Downloading data from https://storage.googleapis.com/tensorflow/tf-keras-
    datasets/t10k-labels-idx1-ubyte.gz
    8192/5148 [=======] - Os Ous/step
    Downloading data from https://storage.googleapis.com/tensorflow/tf-keras-
    datasets/t10k-images-idx3-ubyte.gz
    4423680/4422102 [============ ] - Os Ous/step
```

#### 1.4 Define the Model

```
[4]: # Create the model architecture

def create_model():
    model = tf.keras.Sequential([
        tf.keras.layers.Conv2D(32, 3, activation='relu'),
        tf.keras.layers.MaxPooling2D(),
        tf.keras.layers.Conv2D(64, 3, activation='relu'),
        tf.keras.layers.MaxPooling2D(),
        tf.keras.layers.Flatten(),
        tf.keras.layers.Dense(64, activation='relu'),
        tf.keras.layers.Dense(10)
    ])
    return model
```

### 1.5 Configure custom training

Instead of model.compile(), we're going to do custom training, so let's do that within a strategy scope.

```
[5]: with strategy.scope():
         # We will use sparse categorical crossentropy as always. But, instead of \Box
      → having the loss function
         # manage the map reduce across GPUs for us, we'll do it ourselves with a_{\sqcup}
      \rightarrow simple algorithm.
         # Remember -- the map reduce is how the losses get aggregated
         \# Set reduction to `none` so we can do the reduction afterwards and divide \sqcup
      \rightarrow byglobal batch size.
         loss_object = tf.keras.losses.
      →SparseCategoricalCrossentropy(from_logits=True, reduction=tf.keras.losses.
      → Reduction . NONE)
         def compute loss(labels, predictions):
             # Compute Loss uses the loss object to compute the loss
             # Notice that per_example_loss will have an entry per GPU
             # so in this case there'll be 2 -- i.e. the loss for each replica
             per_example_loss = loss_object(labels, predictions)
             # You can print it to see it -- you'll get output like this:
             # Tensor("sparse_categorical_crossentropy/weighted_loss/Mul:0", __
      → shape=(48,), dtype=float32, device=/job:localhost/replica:0/task:0/device:
      \hookrightarrow GPU:0)
              # Tensor("replica_1/sparse_categorical_crossentropy/weighted_loss/Mul:
      →0", shape=(48,), dtype=float32, device=/job:localhost/replica:0/task:0/
      \rightarrow device: GPU: 1)
              # Note in particular that replica_0 isn't named in the weighted_loss --
      → the first is unnamed, the second is replica_1 etc
```

```
print(per_example_loss)
    return tf.nn.compute_average_loss(per_example_loss,___

pglobal_batch_size=GLOBAL_BATCH_SIZE)

# We'll just reduce by getting the average of the losses
    test_loss = tf.keras.metrics.Mean(name='test_loss')

# Accuracy on train and test will be SparseCategoricalAccuracy
    train_accuracy = tf.keras.metrics.

SparseCategoricalAccuracy(name='train_accuracy')
    test_accuracy = tf.keras.metrics.

SparseCategoricalAccuracy(name='test_accuracy')

# Optimizer will be Adam
    optimizer = tf.keras.optimizers.Adam()

# Create the model within the scope
    model = create_model()
```

#### 1.6 Train and Test Steps Functions

Let's define a few utilities to facilitate the training.

```
[6]: # `run` replicates the provided computation and runs it
     # with the distributed input.
     @tf.function
     def distributed_train_step(dataset_inputs):
      per_replica_losses = strategy.run(train_step, args=(dataset_inputs,))
       #tf.print(per_replica_losses.values)
      return strategy.reduce(tf.distribute.ReduceOp.SUM, per_replica_losses,_
     ⇒axis=None)
     def train_step(inputs):
       images, labels = inputs
      with tf.GradientTape() as tape:
         predictions = model(images, training=True)
         loss = compute_loss(labels, predictions)
       gradients = tape.gradient(loss, model.trainable variables)
       optimizer.apply_gradients(zip(gradients, model.trainable_variables))
       train_accuracy.update_state(labels, predictions)
       return loss
     ########################
     # Test Steps Functions
```

## 1.7 Training Loop

We can now start training the model.

```
[7]: EPOCHS = 10
     for epoch in range(EPOCHS):
       # Do Training
      total_loss = 0.0
      num_batches = 0
      for batch in train_dist_dataset:
         total_loss += distributed_train_step(batch)
        num_batches += 1
       train_loss = total_loss / num_batches
       # Do Testing
       for batch in test dist dataset:
         distributed_test_step(batch)
      template = ("Epoch {}, Loss: {}, Accuracy: {}, Test Loss: {}, " "Test_\( \)
      →Accuracy: {}")
      print (template.format(epoch+1, train_loss, train_accuracy.result()*100,
      →test_loss.result(), test_accuracy.result()*100))
      test_loss.reset_states()
       train_accuracy.reset_states()
       test_accuracy.reset_states()
```

WARNING:tensorflow:From /opt/conda/lib/python3.7/site-packages/tensorflow/python/data/ops/multi\_device\_iterator\_ops.py:601: get\_next\_as\_optional (from tensorflow.python.data.ops.iterator\_ops) is deprecated and will be removed in a future version.

Instructions for updating: Use `tf.data.Iterator.get\_next\_as\_optional()` instead. Tensor("sparse\_categorical\_crossentropy/weighted\_loss/Mul:0", shape=(64,), dtype=float32, device=/job:localhost/replica:0/task:0/device:CPU:0) Tensor("sparse categorical crossentropy/weighted loss/Mul:0", shape=(64,), dtype=float32, device=/job:localhost/replica:0/task:0/device:CPU:0) Tensor("sparse categorical crossentropy/weighted loss/Mul:0", shape=(32,), dtype=float32, device=/job:localhost/replica:0/task:0/device:CPU:0) Epoch 1, Loss: 0.5163341164588928, Accuracy: 81.12666320800781, Test Loss: 0.3874766528606415, Test Accuracy: 86.2699966430664 Epoch 2, Loss: 0.33945831656455994, Accuracy: 87.79167175292969, Test Loss: 0.3563588857650757, Test Accuracy: 87.2699966430664 Epoch 3, Loss: 0.29861509799957275, Accuracy: 89.06666564941406, Test Loss: 0.3127383589744568, Test Accuracy: 88.62000274658203 Epoch 4, Loss: 0.26764586567878723, Accuracy: 90.25499725341797, Test Loss: 0.28975072503089905, Test Accuracy: 89.66000366210938 Epoch 5, Loss: 0.24403969943523407, Accuracy: 90.9749984741211, Test Loss: 0.2830083668231964, Test Accuracy: 89.79000091552734 Epoch 6, Loss: 0.2239074558019638, Accuracy: 91.73999786376953, Test Loss: 0.26116400957107544, Test Accuracy: 90.37000274658203 Epoch 7, Loss: 0.2065580040216446, Accuracy: 92.32666778564453, Test Loss: 0.25411492586135864, Test Accuracy: 90.88999938964844 Epoch 8, Loss: 0.18806180357933044, Accuracy: 93.10333251953125, Test Loss: 0.2621306777000427, Test Accuracy: 90.6500015258789 Epoch 9, Loss: 0.17561957240104675, Accuracy: 93.45999908447266, Test Loss: 0.25451552867889404, Test Accuracy: 91.16999816894531 Epoch 10, Loss: 0.16132628917694092, Accuracy: 94.12833404541016, Test Loss: 0.25070327520370483, Test Accuracy: 91.0999984741211