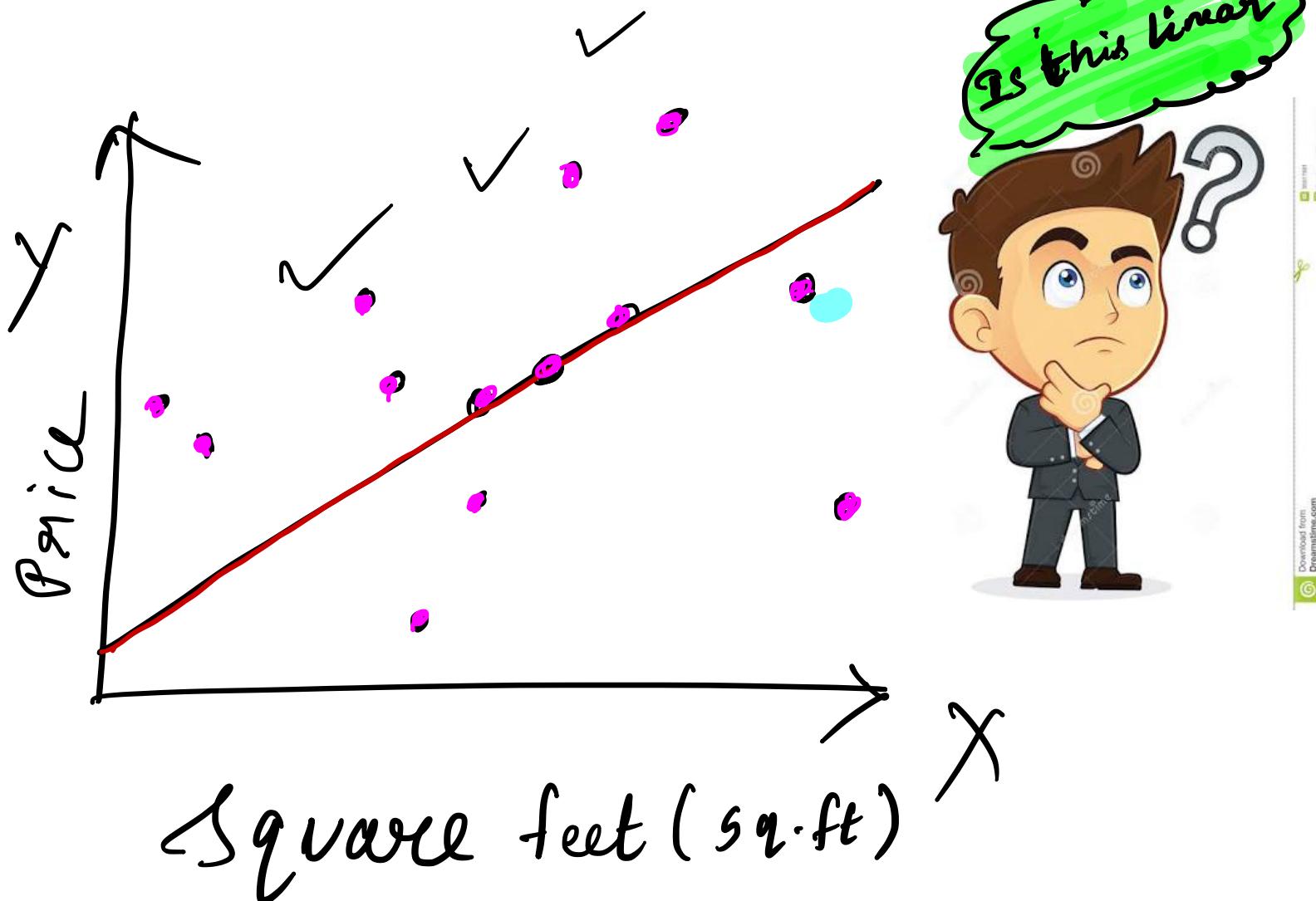


Regression

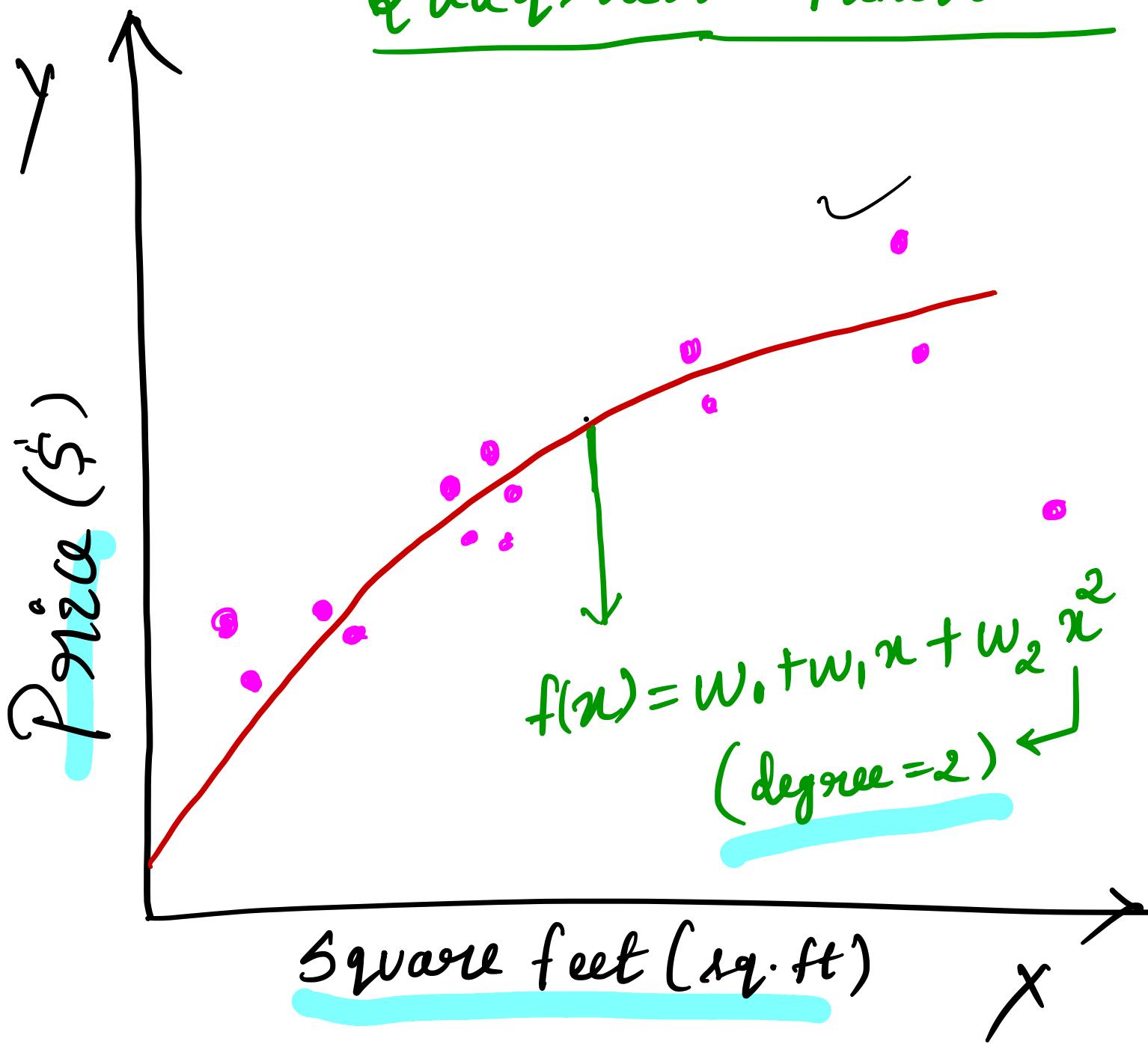
Polynomial Regression



may be a
quadratic fit



Quadratic function:



$$f(x) = w_0 + w_1 x + w_2 x^2 + \dots + w_p x^p$$

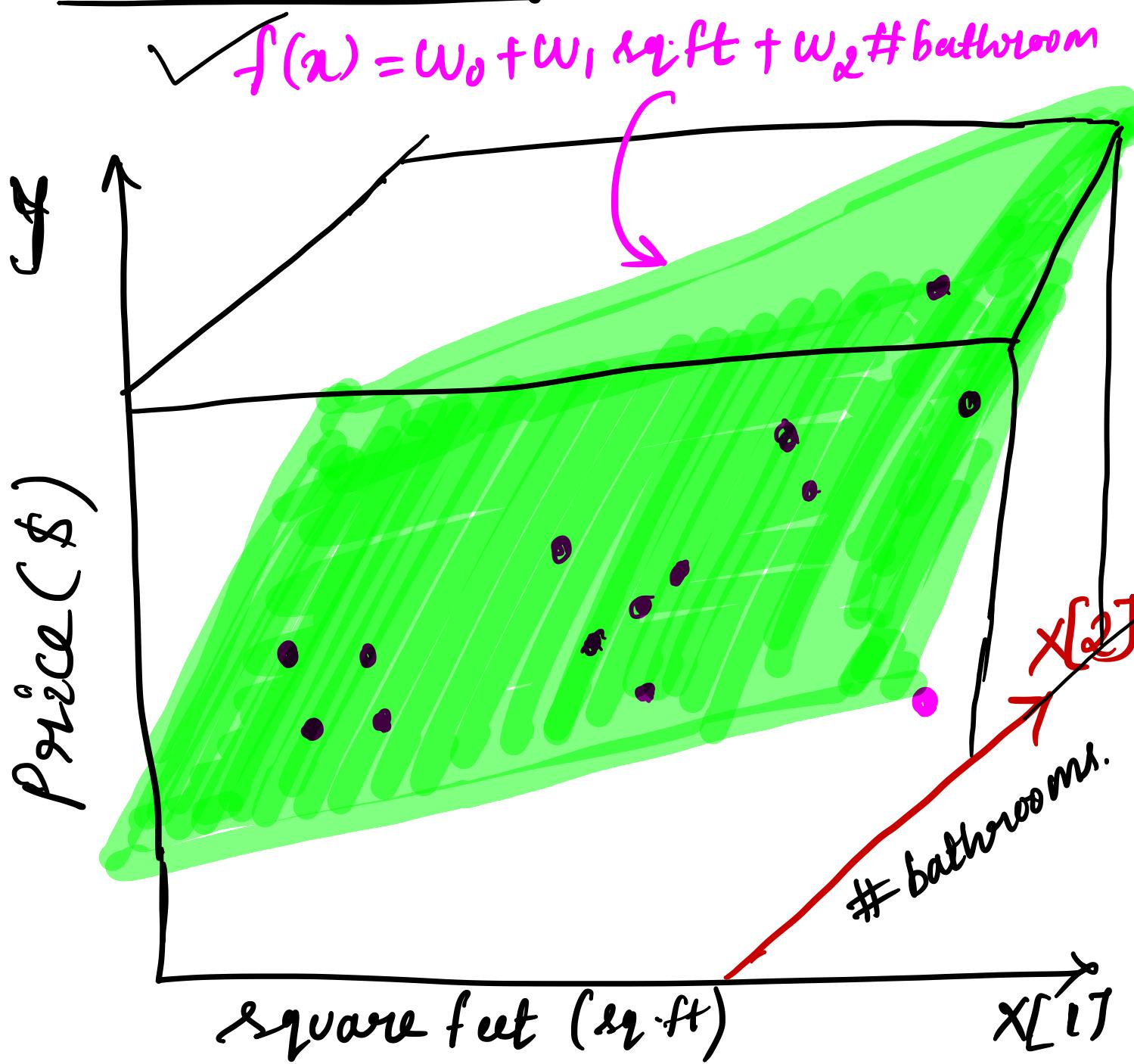
→ Higher order polynomial.

Polynomial regression:

$$\hat{y}_i = w_0 + w_1 x_i + w_2 x_i^2 + \dots + w_p x_i^p + \epsilon_i$$

\hookrightarrow (error)

Incorporating multiple inputs:



General Notation:

Output = y ✓

Input = $x \doteq (x[1], x[2], \dots, x[d])$

$x[j] = j^{\text{th}}$ input

$h_j(x) = j^{\text{th}}$ feature

$x_i = \text{input of } i^{\text{th}}$ datapoint (vector)

$x_{i,j} = j^{\text{th}}$ input of \therefore i^{th} point

Simple hyperplane:

model:

$$y_i = w_0 + w_1 n_i[1] + \dots + w_d n_i[d] + \epsilon_i$$

noise term

✓ feature 1 = 1

✓ feature 2 = $n_i[1]$ --- eg - sq. ft

✓ feature 3 = $n_i[2]$ --- eg - # bath

✓ feature $d+1 = n_i[d]$ --- eg - lot size.

More generally,

D-dimensional curve:

model:

$$y_i = w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i) + \epsilon_i$$
$$= \sum_{j=0}^D w_j h_j(x_i) + \epsilon_i$$

feature 1 = $h_0(x) = \dots$ e.g. 1

✓ feature 2 = $h_1(x) = \dots$ e.g. $x[1] = \text{sq ft}$

✓ feature 3 = $h_2(x) = \dots$ e.g. $x[2] = \# \text{ bath}$
or $\log(x[4]) \times [2] = \log(\# \text{ bed}) \times \# \text{ bath}$

...
feature $D+1 = h_D(x) = \dots$ some other
function of $x[1] = \dots x[d]$

Interpreting the co-efficients

Simple linear regression:

✓ Price = $\hat{w}_0 + \hat{w}_1$ (square feet)

when $\hat{w}_1 = 1$, predicted change
in the price for 1 square feet
change

How to interpret
the co-efficients if
we have two variables



Interpreting the Co-efficients.

Two linear features :-

$$\hat{y} = \hat{w}_0 + \hat{w}_1 x[1] + \hat{w}_2 x[2].$$

fix. the 1st input i.e
number of square feet of the
house and think about what's
the effect of number of bathrooms
on price.

Simplly, for the same fixed
size house if i increase the
number of bathrooms how price
is going to be effected.

Interpreting the co-efficients - multiple linear features.

$$\hat{y} = \hat{w}_0 + \hat{w}_1 x[1] + \dots + \hat{w}_j x[j] + \dots + \hat{w}_d x[d]$$

Annotations:

- Curly orange lines highlight the terms $\hat{w}_1 x[1]$, \dots , $\hat{w}_j x[j]$, and $\hat{w}_d x[d]$.
- A green bracket underlines the term $\hat{w}_j x[j]$.
- An arrow points from the underlined term to the label "no. of bedrooms".
- The label "no. of bedrooms" is written next to the green bracket.
- A handwritten note "fix x" is written below the first highlighted term.

what is the predicted change in price if i add one more bedroom keeping all other constant.

Interpreting the co-efficients polynomial regression -

$$\hat{y} = \hat{w}_0 + \hat{w}_1 x + \dots + \hat{w}_j x^j + \dots + \hat{w}_p x^p$$

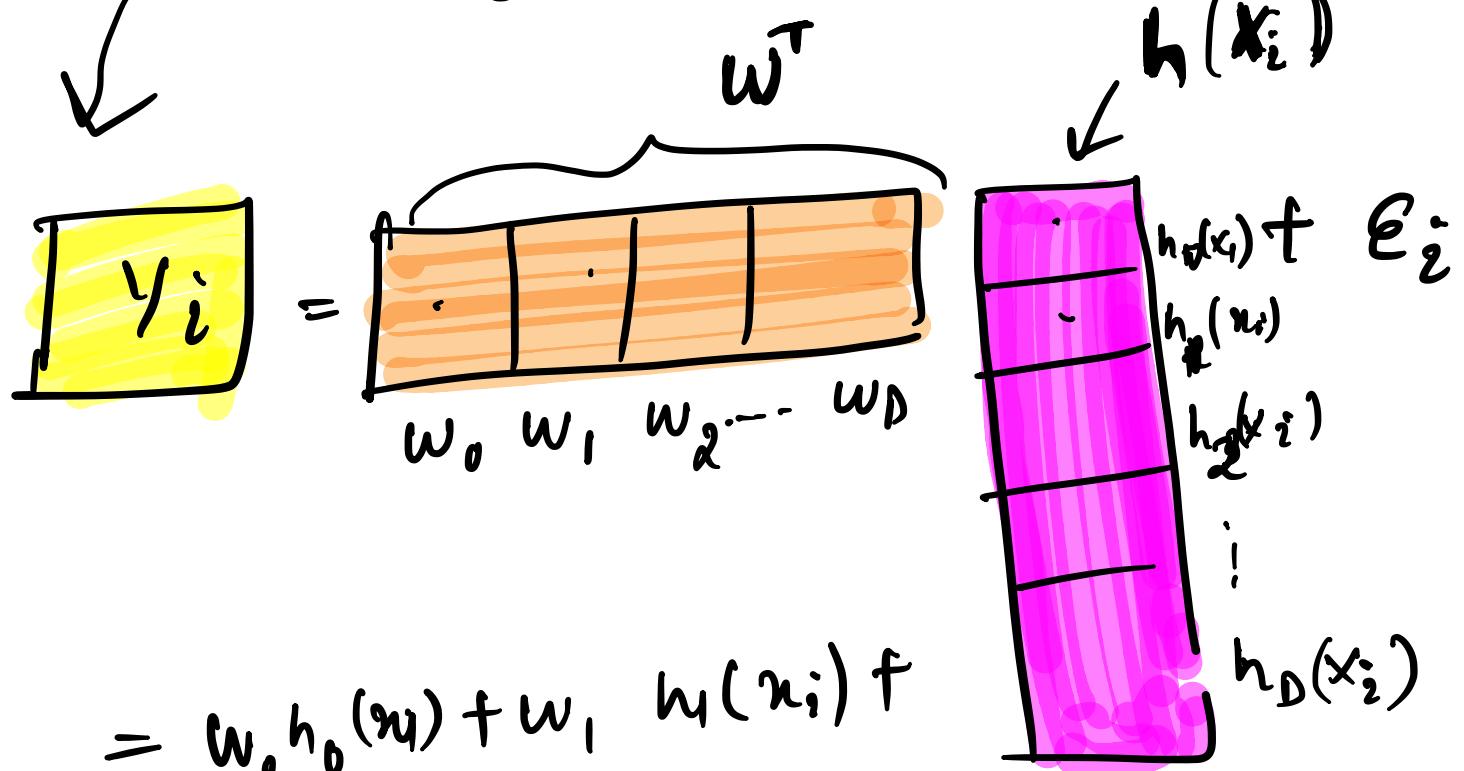
Can not hold
other features fixed.

Computing the least square fit:

Step-1:

for observation i

$$y_i = \sum_{j=0}^D w_j h_j(x_i) + \epsilon_i$$



$$= w_0 h_0(x_i) + w_1 h_1(x_i) + \dots + w_D h_D(x_i) + \epsilon_i$$

$$= w^T h(x_i) + \epsilon_i \checkmark$$

$$Y_i = \begin{matrix} h^T(x_i) \\ \cdot h_0(x_i) \ h_1(u) \ \dots \end{matrix} + \epsilon_i$$

$h^T(x_i)$

Exactly same as
previous

$$= h_0(x_i)w_0 + h_1(x_i)w_1 + \dots + h_D(x_i)w_D + \epsilon_i$$

→ equation for single observation

What about all observations?

Rewrite matrix notation for all observations together!

$$\begin{matrix}
 & h^T(x_1) \\
 & \downarrow \\
 \begin{matrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{matrix} & = & \begin{matrix} h_0(x_1) & h_1(x_1) & \dots & h_D(x_1) \\ h_0(x_2) & h_1(x_2) & \dots & h_D(x_2) \\ \vdots & \vdots & \ddots & \vdots \\ h_0(x_n) & h_1(x_n) & \dots & h_D(x_n) \end{matrix} & \begin{matrix} w_0 \\ w_1 \\ w_2 \\ w_3 \\ \vdots \\ w_D \end{matrix} & + & \begin{matrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \vdots \\ \epsilon_n \end{matrix}
 \end{matrix}$$

\Rightarrow

$$Y = HW + \epsilon$$

Residual sum of square (RSS)

for linear regression →

$$\text{RSS}(w_0, w_1) = \sum_{i=1}^N (y_i - [w_0 + w_1 x_i])^2$$

RSS for multiple regression

regression

$$\text{RSS}(w) = \sum_{i=1}^N (y_i - \hat{y}_i)^2$$
$$= \sum_{i=1}^N (y_i - h^T(x_i) w)^2$$

$$\hat{y}_i = \begin{bmatrix} h^T(x_i) \\ h_0(x_i) h_1(x_i) \dots h_d(x_i) \end{bmatrix} w$$

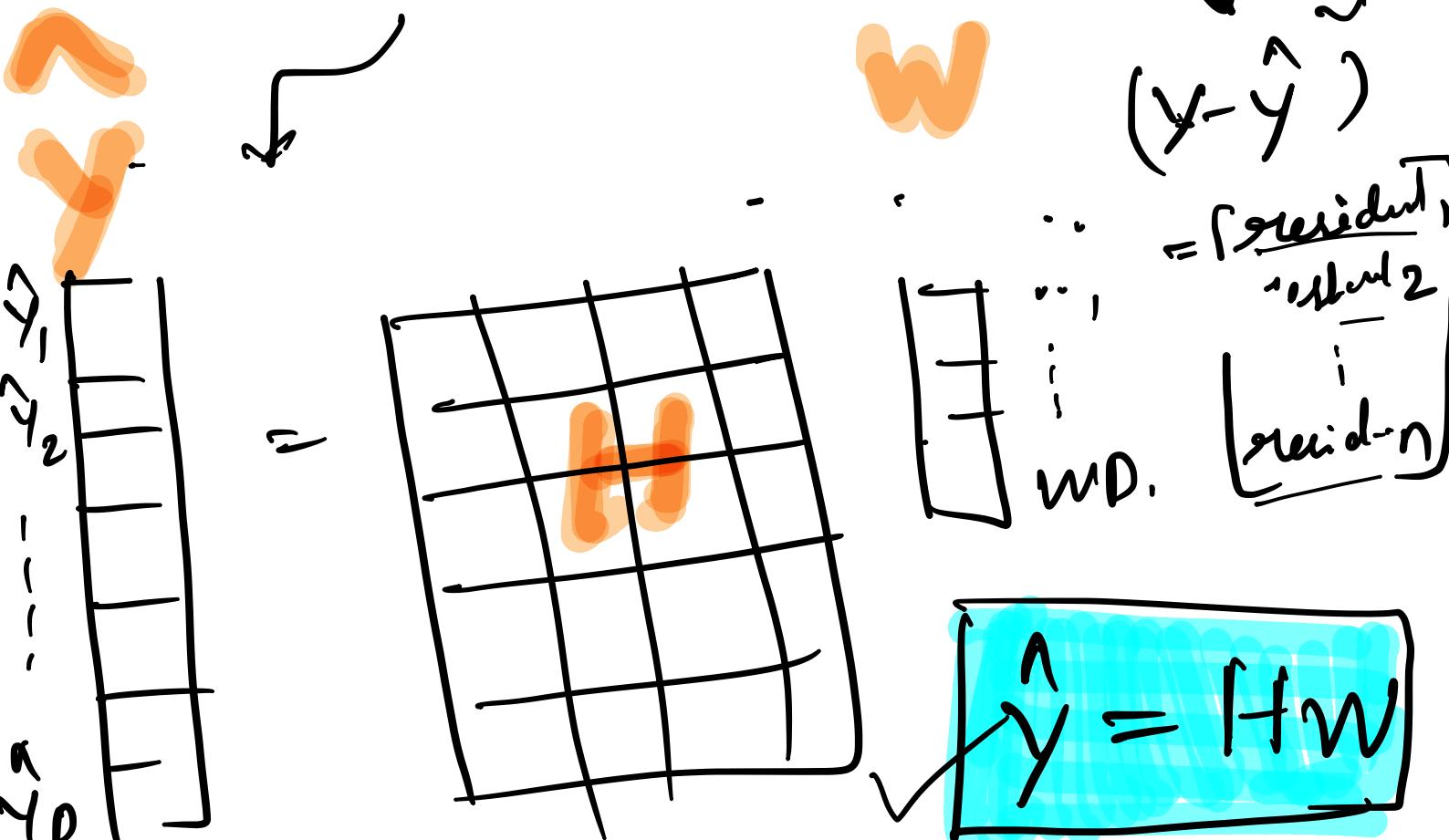
Diagram illustrating the vector \hat{y}_i as a linear combination of basis functions $h_j(x_i)$ and weights w_j :

The diagram shows a vector \hat{y}_i represented as a horizontal line segment. Above it, a curved arrow points from the term $h^T(x_i) w$ to the vector. Below the vector, a bracket indicates it is a sum of terms: $h_0(x_i) w_0 + h_1(x_i) w_1 + \dots + h_d(x_i) w_d$. The terms $h_j(x_i)$ are shown as vertical segments of the vector, and the weights w_j are shown as vertical segments of a column vector w .

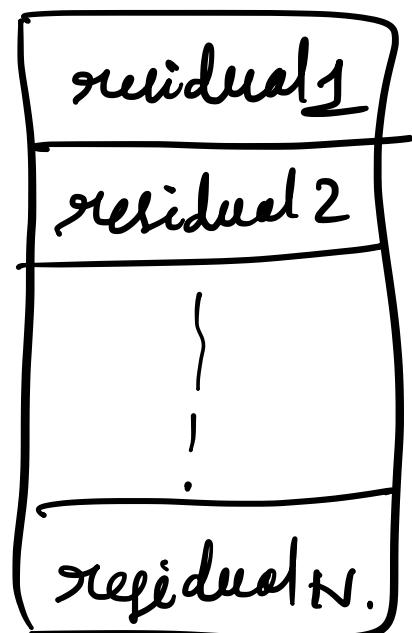
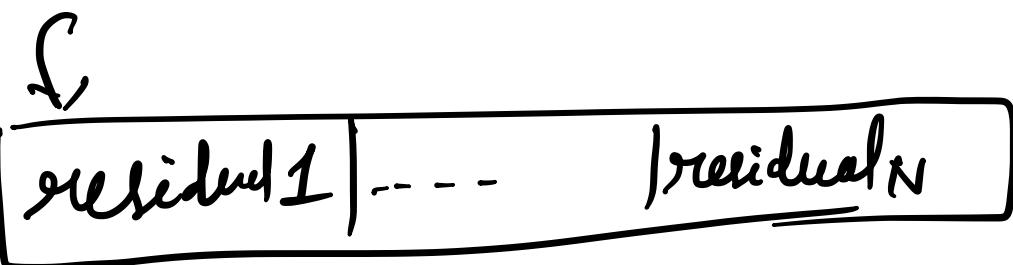
RSS in Matrix notation!

$$RSS(w) = \sum_{i=1}^N (y_i - h(u_i)^T w)^2$$

$$= (\mathbf{Y} - \mathbf{H}w)^T (\mathbf{Y} - \mathbf{H}w)$$



$$= (\hat{Y} - (I + W))^T \cdot (\hat{Y} - HW) \quad \checkmark$$



$$= (\text{residual}_1)^2 + (\text{residual}_2)^2 + \dots + (\text{residual}_N)^2$$

$$= \sum_{i=1}^N \text{residual}_i^2$$

\triangleq RSS(W)

C

Gradient of RSS:

$$\nabla_{\mathbf{w}} \text{RSS}(\mathbf{w}) = \nabla \left[(\mathbf{y} - \mathbf{H}\mathbf{w})^T (\mathbf{y} - \mathbf{H}\mathbf{w}) \right]$$
$$= -2 \mathbf{H}^T (\mathbf{y} - \mathbf{H}\mathbf{w})$$

$$\boxed{\nabla_{\mathbf{w}} \text{RSS}(\mathbf{w}) = -2 \mathbf{H}^T (\mathbf{y} - \mathbf{H}\mathbf{w}) = 0}$$

✓

$$\frac{d}{d\mathbf{w}} (\mathbf{y} - \mathbf{H}\mathbf{w}) (\mathbf{y} - \mathbf{H}\mathbf{w})^2$$

$$\frac{d}{d\mathbf{w}} (\mathbf{y} - \mathbf{H}\mathbf{w})^2 = 2(\mathbf{y} - \mathbf{H}\mathbf{w})^T (-\mathbf{H})$$
$$= -2\mathbf{H} (\mathbf{y} - \mathbf{H}\mathbf{w})$$

$$\nabla_{\mathbf{w}} \text{RSS}(\mathbf{w}) = -2\mathbf{H}^T(\mathbf{y} - \mathbf{H}\mathbf{w})$$

Solve for \mathbf{w} :

$$-2\mathbf{H}^T\mathbf{y} + 2\mathbf{H}^T\mathbf{H}\mathbf{w} = 0$$

$$\Rightarrow \mathbf{H}^T\mathbf{H}\mathbf{w} = \mathbf{H}^T\mathbf{y}$$

$$\Rightarrow (\mathbf{H}^T\mathbf{H})^{-1} \cdot \mathbf{H}^T\mathbf{y} =$$

$$(\mathbf{H}^T\mathbf{H})^{-1} \mathbf{H}^T\mathbf{y}$$

$$\hat{\mathbf{w}} = (\mathbf{H}^T\mathbf{H})^{-1}\mathbf{H}^T\mathbf{y}$$

$$\mathbf{I}\mathbf{w} = \mathbf{w}$$

$$\mathbf{I}\mathbf{w} = \mathbf{w}$$

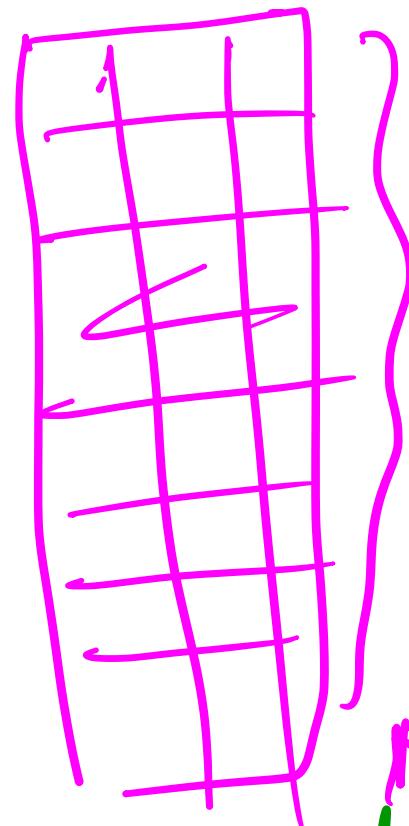
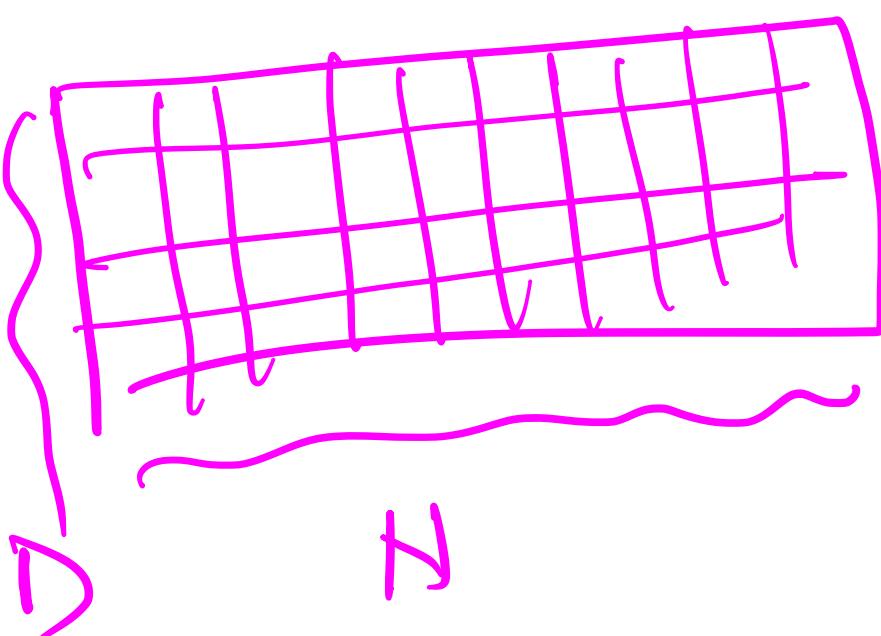
$\hat{\mathbf{w}}$ Closed form solution.

Closed form solution:

$$\hat{\omega} = \underbrace{(\mathbf{H}^T \mathbf{H})^{-1}}_{\Delta} \mathbf{H}^T \mathbf{y}$$

\mathbf{H}

\mathbf{H}



$$= \boxed{D \times D} \quad \begin{array}{l} \checkmark \\ \text{\# Features} \\ \text{Invertible if:} \\ N > D \end{array}$$

\downarrow No. of independent obs.

Complexity of inverse:

$$O(\tilde{\mathcal{N}}^3)$$

$$\hat{w} = (H^T H)^{-1} H^T y.$$

$\underbrace{D}_{= \# \text{features}}$

